

Hyperparameter tuning, Batch Normalization, Programming Frameworks

10/10 points (100%)

Quiz, 10 questions

Congratulations! You passed!	Next Item
1/1 points 1. If searching among a large number of hyperparameters, you should try values random values, so that you can carry out the search more systematically and nor False? True False Correct	
 1/1 points 2. Every hyperparameter, if set poorly, can have a huge negative impact on trainir hyperparameters are about equally important to tune well. True or False? True 	g, and so all
False	
Correct Yes. We've seen in lecture that some hyperparameters, such as the learning critical than others.	rate, are more
1/1 points	
3. During hyperparameter search, whether you try to babysit one model ("Panda" of models in parallel ("Caviar") is largely determined by:	strategy) or train a lot
Whether you use batch or mini-batch optimization	
The presence of local minima (and saddle points) in your neural network	k
The amount of computational power you can access	
Correct	

The number of hyperparameters you have to tune

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1/1 points

4.

If you think β (hyperparameter for momentum) is between on 0.9 and 0.99, which of the following is the recommended way to sample a value for beta?

```
1 r = np.random.rand()
2 beta = r*0.09 + 0.9
```

```
1 r = np.random.rand()
2 beta = 1-10**(- r - 1)
```

Correct

```
1 r = np.random.rand()
2 beta = 1-10**(- r + 1)
```

```
1 r = np.random.rand()
2 beta = r*0.9 + 0.09
```

/

1/1 points

5.

Finding good hyperparameter values is very time-consuming. So typically you should do it once at the start of the project, and try to find very good hyperparameters so that you don't ever have to revisit tuning them again. True or false?

True



False

Correct



1/1 points

6.

In batch normalization as presented in the videos, if you apply it on the lth layer of your neural network, what are you normalizing?

 \bigcirc $W^{[l]}$

 \bigcirc $a^{[l]}$

 $\int z^{[l]}$

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 \bigcirc $b^{[l]}$



1/1 points

7.

In the normalization formula $z_{norm}^{(i)}=\frac{z^{(i)}-\mu}{\sqrt{\sigma^2+\varepsilon}}$, why do we use epsilon?

- In case μ is too small
- To avoid division by zero

Correct

- To have a more accurate normalization
- To speed up convergence



1/1 points

8.

Which of the following statements about γ and β in Batch Norm are true?

There is one global value of $\gamma \in \Re$ and one global value of $\beta \in \Re$ for each layer, and applies to all the hidden units in that layer.

Un-selected is correct

igcap and γ are hyperparameters of the algorithm, which we tune via random sampling.

Un-selected is correct

They can be learned using Adam, Gradient descent with momentum, or RMSprop, not just with gradient descent.

Correct

They set the mean and variance of the linear variable $z^{[I]}$ of a given layer.

Correct

The optimal values are $\gamma = \sqrt{\sigma^2 + \varepsilon}$, and $\beta = \mu$.

Un-selected is correct

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Correct



