

UNIVERSITY OF INFORMATION TECHNOLOGY & SCIENCES



ASSIGNMENT
on
INTERNET OF THINGS LAB

◀Submitted To▶
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↻ Department	⇒ CSE
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Signature

Temperature and Ultrasonic Sensor

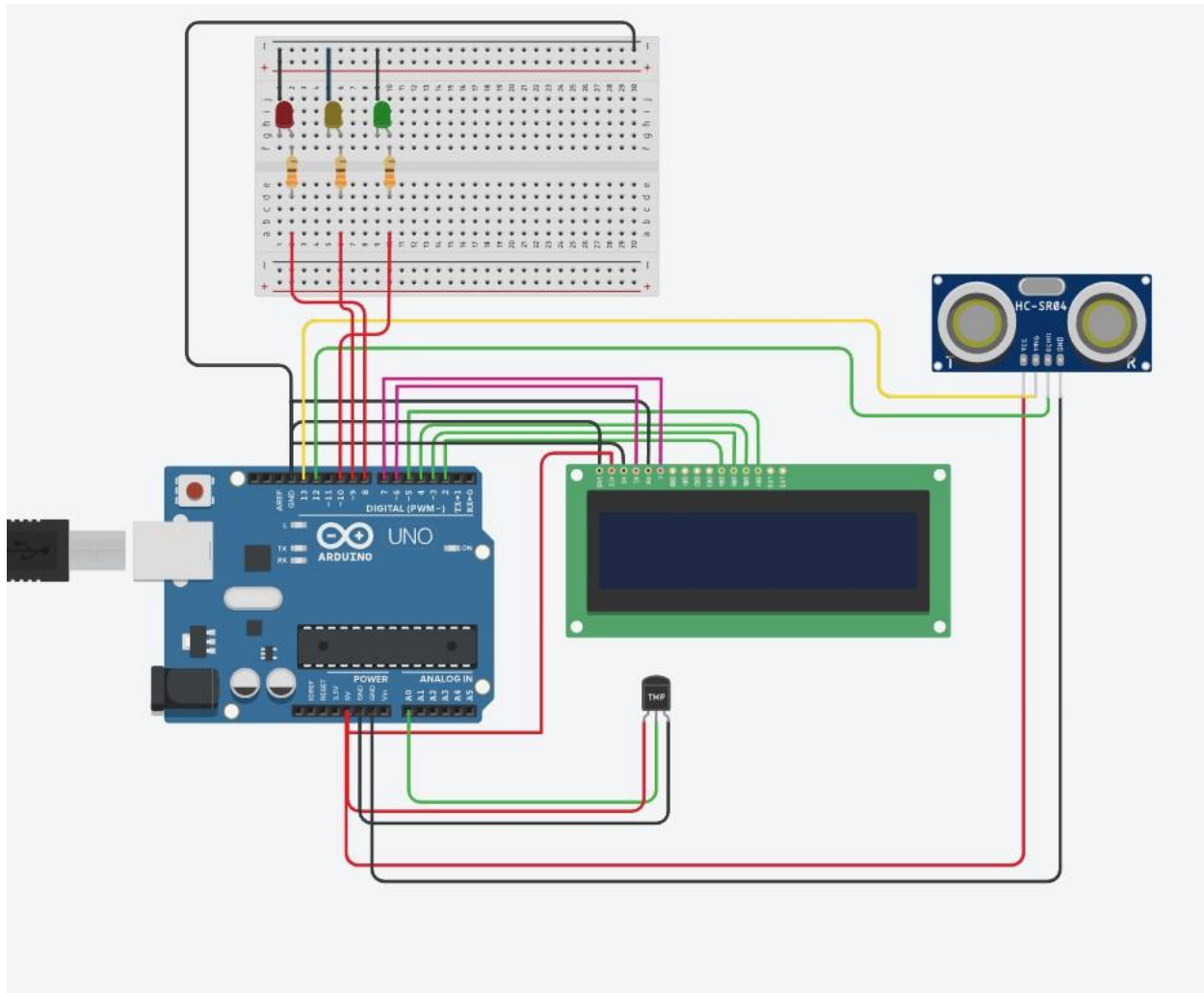
Title: Take input from ultrasonic sensor and temperature sensor. Show the distance in cm and temperature in celsius in LCD. Also show the distance and temperature in serial monitor.

Necessary Equipment:

1. Arduino UNO R3
2. Breadboard
3. 330 Ohm resistor
4. 3 LED
5. Ultrasonic distance sensor
6. LCD

Objectives:

1. Temperature ≥ 75 degree celsius and Distance ≥ 175 cm, Turn on RED LED only.
2. Temperature ≥ 50 and < 75 and Distance ≥ 150 cm and < 175 cm, Turn on YELLOW LED only.
3. Temperature < 50 and Distance < 150 cm, Turn on GREEN LED only.



Code:

```
#include <LiquidCrystal.h>
char temp[]
="Temprature_c:"; char
dist[] = "Distance: ";
int trigPin=13;
int
echoPin=12;
int ledPin[] = {8,9,10};
int pinCount = 3;
LiquidCrystal lcd(6,7,2,3,4,5); // Rs, E, D4, D5 D6, D7

void setup()
{
  pinMode(A0,INPUT);
```

```
pinMode(trigPin,  
OUTPUT);  
pinMode(echoPin,  
INPUT);
```

```
for(int i=0;i<pinCount;i++){  
pinMode(ledPin[i],  
OUTPUT);  
}
```

```
lcd.begin(16,2);  
Serial.begin(9600);  
delay(1000);  
}
```

```
void loop()  
{
```

```
int sensorValue =  
analogRead(A0); float  
mV=(sensorValue/1023.0)*5000;  
int tempCel=mV/10;  
Serial.println(tempCel);
```

```
digitalWrite(trigPin,  
LOW);  
delayMicroseconds(2);  
digitalWrite(trigPin,  
HIGH);  
delayMicroseconds(10);  
digitalWrite(trigPin,  
LOW);
```

```
long duration = pulseIn(echoPin, HIGH);  
float distance = (0.0332*duration)/2;
```

```
if(tempCel >= 75 && distance >=  
175){ digitalWrite(ledPin[0],  
HIGH); delay(500);  
digitalWrite(ledPin[0], LOW);
```

```
}else if(tempCel >= 50 && distance >= 150){
```

```
digitalWrite(ledPin[1],  
HIGH); delay(500);  
digitalWrite(ledPin[1],  
LOW);  
}else{  
digitalWrite(ledPin[2],  
HIGH); delay(500);  
digitalWrite(ledPin[2],  
LOW);  
}
```

```
lcd.setCursor(0,0);  
lcd.print(temp);
```

```
lcd.setCursor(13,0);  
lcd.print(tempCel);
```

```
Serial.println(temp);  
lcd.setCursor(0,1);  
lcd.print(dist);
```

```
lcd.setCursor(9,1);  
lcd.print(distance);
```

```
Serial.println(distance);  
delay(1000);
```

```
}
```