

Higher Institute of Engineering & Technology, El-Beheira

Computer Engineering Department

Third assignment in numerical analysis

The numerical solution of a system of non-linear equations using Newton's Method.)

Under supervision of Dr. Mahmoud Gamal

Team	ID
Mohamed Yosry El-Zarka	19100
Youssef Mohamed El-Sheheimy	19124
Omar Abd Al-Halim Khalil	19138

Source code in python: -

```
1 import math
2 from sympy import * #for differentiation & mathematical functions
3 import numpy as np #matrix operations
5 pi=3.141592653589793
6 e=2.718281828459045
8 print('Project for "Numerical analysis". under the supervision of
    Dr. Mahmoud Gamal')
9 print('by:')
10 print('\t\tMohamed Yosry ElZarka 19100')
11 print('\t\tYoussef Mohamed Elsheheimy 19124')
12 print('\t\tOmar Abd Al-Halim Khalil 19138\n')
13
14 print("This is a program to calculate the numerical solution of
   a system of non-linear equations using (Newton's method).\n")
15
16 print("""
17 you can use parentheses () in addition to the following mathemat
   ical operators:
18 (+ Add), (- Subtract), (* Multiply), (/ Divide), (% Modulus), (/
   / Floor division), (** Exponent)
19 you can also use the following constants:
20 \t pi=3.141592653589793
21 \t e=2.718281828459045
22 note: Trigonometric functions sin(x), asin(x), cos(x), acos(x),
   tan(x), atan(x) 'equivalent of tan-1(x)' use radian values.
         log(x,y) = log(x) / log(y) ,,, ln(x)
23
24 """)
25
26 def check equalization(recent_x,previous_x):
       for i in range (0, len(recent_x)):
27
28
           if recent x[i] != previous x[i]:
29
               return False
30
       return True
31
32 decimal point precision=4
33
34 while True:
       n=int( input('Enter the number of equations: ') )
35
       equations, equations values, jacobian matrix, jacobian value
36
   s= [] , [0]*n , [] , []
37
       for i in range(0,n):
38
```

```
39
           equations.append( str(input("Enter the equation #{}:
   0 = ".format(i+1))) )
40
           jacobian matrix.append([])
41
           jacobian_values.append([0]*n)
       last_x , current_x= [] , []
42
       for i in range(0,n):
43
           last_x.append( float(input("Enter the initial x{} = ".fo
44
   rmat(i+1))) )
45
46
       for i in range(0,n): #partial differntiaion matrix
           for j in range(0,n):
47
               jacobian_matrix[i].append( diff( equations[i] ,
48
   +str(j+1) ) )
49
       print("\njacobian matrix=",jacobian_matrix)
50
51
       print("\n
                        ",end="")
52
53
       for i in range(0,n):
                                ".format(i+1),end="")
           print("x{}
54
       print("")
55
       print("i=0",end="")
56
57
       for i in range(0,n):
           last_x[i]=round( last_x[i] , decimal_point_precision )
58
           print(" | %.4f | "%last_x[i],end="")
59
       print("")
60
61
62
       dictionary_of_last_x={}
63
       for iterations in range(1,500): #maximum number of iteration
64
   s is 500
           for i in range(0,n): #updating the values of matrices
65
               dictionary_of_last_x['x'+str(i+1)]=last_x[i]
66
           for i in range(0,n):
67
               equations values[i]=round( eval(equations[i], diction
68
   ary_of_last_x) , decimal_point_precision)
69
           for i in range(0,n):
               for j in range(0,n):
70
                   jacobian_values[i][j]=round( eval(str(jacobian_m)
71
   atrix[i][j]),dictionary_of_last_x) , decimal_point_precision )
72
73
           A = np.array(last x) #matrix declarations
           B = np.array(jacobian_values)
74
75
           C = np.array(equations values)
76
           current x=np.subtract(A, np.dot( np.linalg.inv(B)
77
    ) #matrix operations
```

```
78
           print("i={}".format(iterations),end="")
79
           for i in range(0,n):
80
               current_x[i]=round( current_x[i] , decimal_point_pre
81
   cision )
               print(" | %.4f | "%current_x[i],end="")
82
           print("")
83
           if check_equalization(current_x,last_x):
84
85
               break
86
           last_x=current_x
87
       print("\nAfter",iterations,"iterations, The solution is at")
88
       for i in range(0,n):
89
           print("\t\tx{} =".format(i+1),last_x[i])
90
       print("\n
91
       print("Try another system of non-linear equations.")
92
```

The program

```
C:\WINDOWS\py.exe
                                                                                                                              Project for "Numerical analysis". under the supervision of Dr. Mahmoud Gamal
by:
                 Mohamed Yosry ElZarka 19100
                 Youssef Mohamed Elsheheimy 19124
                 Omar Abd Al-Halim Khalil 19138
This is a program to calculate the numerical solution of a system of non-linear equations using (Newton's method).
you can use parentheses () in addition to the following mathematical operators:
(+ Add), (- Subtract), (* Multiply), (/ Divide), (% Modulus), (// Floor division), (** Exponent)
you can also use the following constants:
         pi=3.141592653589793
         e=2.718281828459045
note: Trigonometric functions \sin(x), a\sin(x), \cos(x), a\cos(x), \tan(x), a\tan(x) 'equivalent of \tan -1(x)' use radian values.
      log(x,y) = log(x) / log(y) ,,, ln(x)
Enter the number of equations: 2
Enter the equation #1: 0 = x1**2+x2**2-4
Enter the equation #2: 0 = 2*x1-x2**2
Enter the initial x1 = 1
Enter the initial x2 = 1
jacobian matrix= [[2*x1, 2*x2], [2, -2*x2]]
        x1
i=0 | 1.0000 |
               1.0000
i=1 | 1.2500
                 1.7500
i=2 | 1.2361
                1.5813
i=3 | 1.2361 | | 1.5723
i=4 | 1.2361 | | 1.5723
After 4 iterations, The solution is at
                 x1 = 1.2361
                 x2 = 1.5723
Try another system of non-linear equations.
Enter the number of equations: 3
Enter the equation #1: 0 = x1**2+x2**2+x3**2-6
C:\WINDOWS\py.exe
                                                                                                                              ×
i=1 | 1.2500 | | 1.7500
i=2 | 1.2361
                 1.5813
      1.2361
                 1.5723
i=4 | 1.2361 | | 1.5723
After 4 iterations, The solution is at
                x1 = 1.2361
x2 = 1.5723
Try another system of non-linear equations.
Enter the number of equations: 3
Enter the equation #1: 0 = x1**2+x2**2+x3**2-6
Enter the equation #2: 0 = x1**2-x2**2+2*x3**2-2
Enter the equation #3:
                           0 = 2*x1**2+x2**2-x3**2-3
Enter the initial x1 = 4
Enter the initial x2 = 4
Enter the initial x3 = 4
jacobian matrix= [[2*x1, 2*x2, 2*x3], [2*x1, -2*x2, 4*x3], [4*x1, 2*x2, -2*x3]]
        x1
                     x2
                                  х3
i=0 | 4.0000 | | 4.0000 |
                             4.0000
i=1 | 2.1250
                 2.3750
                              2.2500
i=2 | 1.2978
                 1.8191
                              1.5694
                              1.4219
i=3 | 1.0342
i=4 | 1.0006
                 1.7341
                1.7320
                              1.4142
i=5 | 1.0000 | | 1.7320 | | 1.4142
i=6 | 1.0000 | | 1.7320 | | 1.4142
After 6 iterations, The solution is at
                 x1 = 1.0
                 x2 = 1.732
                 x3 = 1.4142
Try another system of non-linear equations.
Enter the number of equations:
```