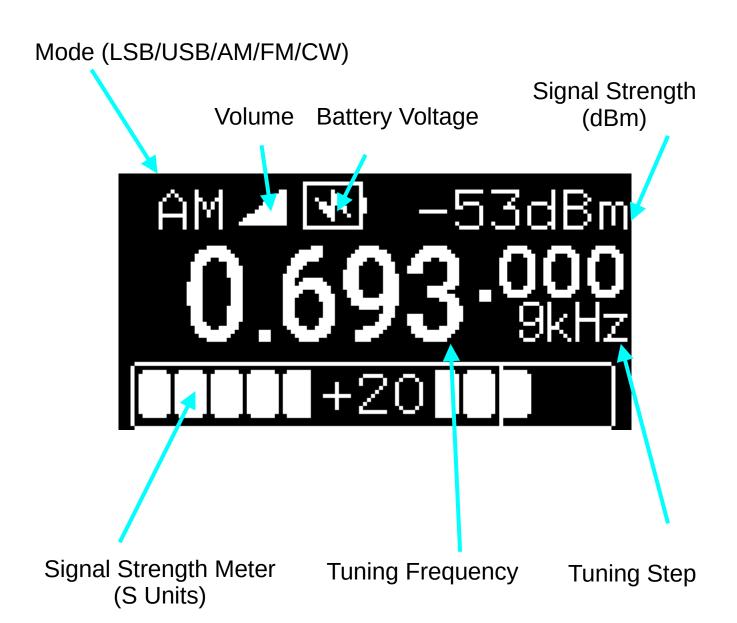
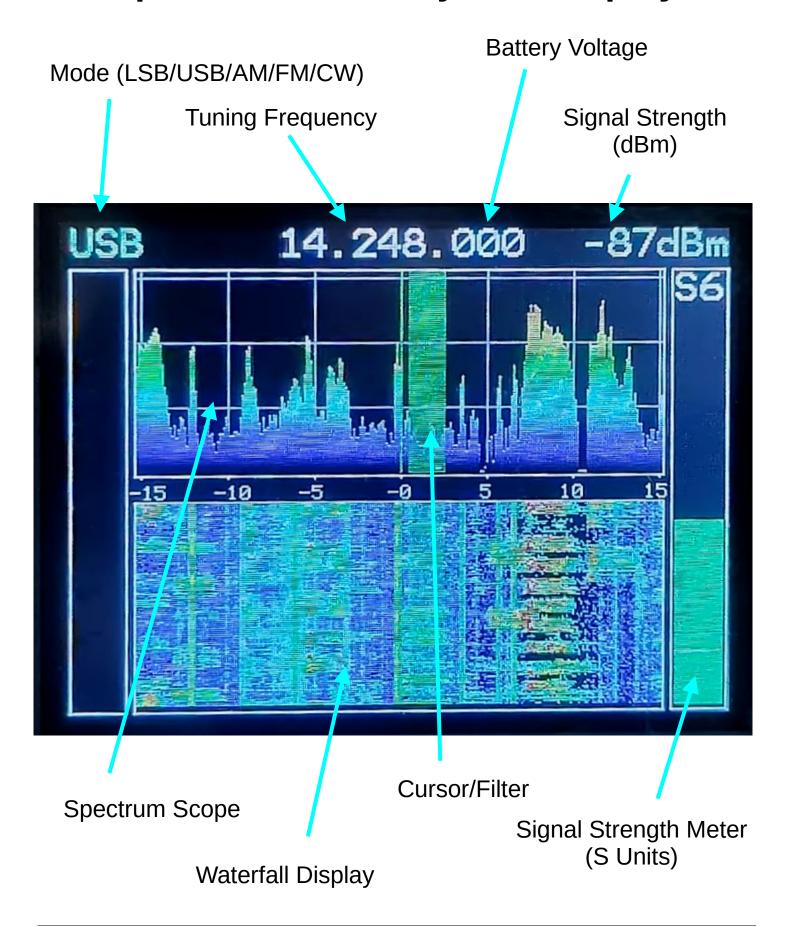
# Pi Pico Rx User Manual



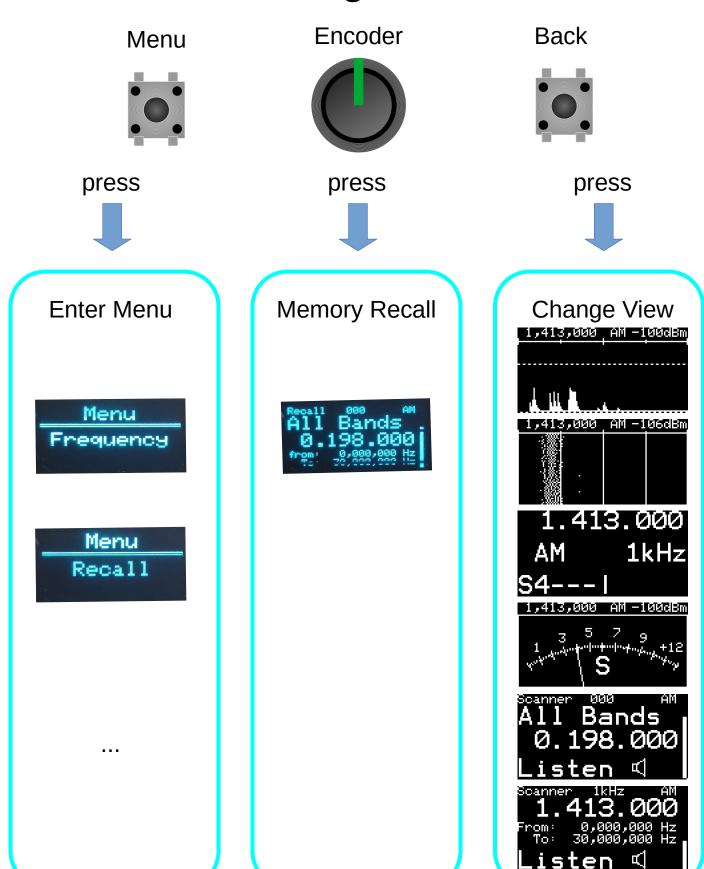
#### **Default Home Screen**



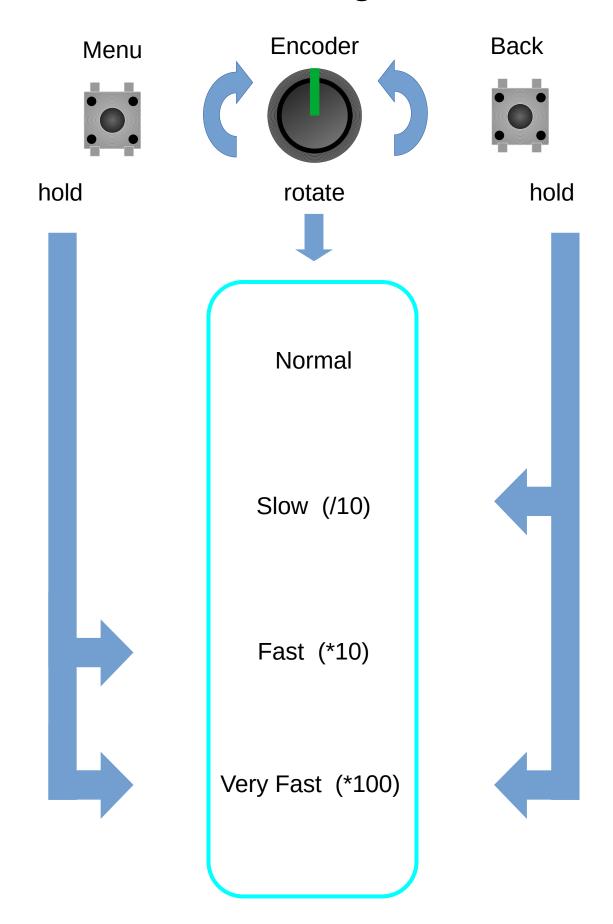
## **Optional Secondary TFT Display**



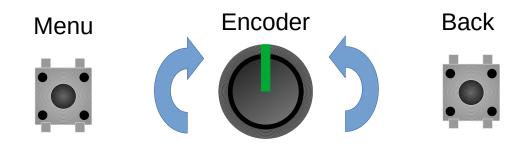
## **Home Page Actions**



## **Tuning**



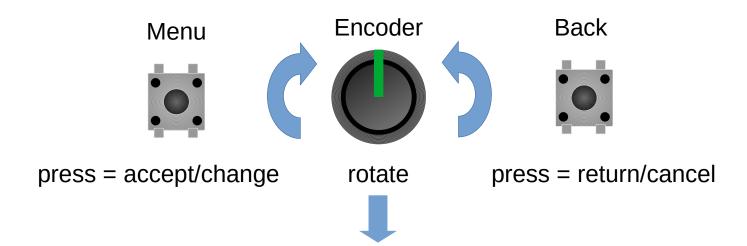
## **Shortcuts**



hold

Shortcut	Description
Encoder Rotate	Tuning Up/Down
Encoder Rotate + Menu held	Tuning Up/Down x10
Encoder Rotate + Menu held + Back held	Tuning Up/Down /10
Encoder Rotate + Menu held + Back held	Tuning Up/Down x100
Encoder Rotate + Encoder Held	Volume Up/Down
Encoder Rotate + Encoder Held + Menu Held	Mode Select (AM/AMS/FM/CW/LSB/USB)
Encoder Rotate + Encoder Held + Back Held	Frequency Step Up/Down

## **Main Menu**



Frequency **Memory Recall Memory Store** Volume Mode **AGC Speed** Bandwidth Squelch Auto Notch De-emphasis **IQ** Correction Spectrum Zoom **Band Start Band Stop** Frequency Step **CW Tone HW Config** 

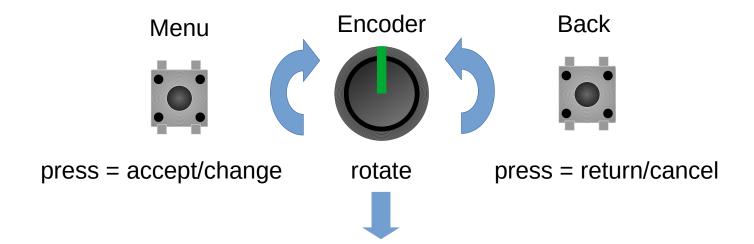
## **Menu Settings – Part 1**

Setting	Range	Description	
Frequency	0-30 MHz	Manual Frequency Entry. Selecting a frequency outside the current band will reset the band limits to allow free-tuning across the full frequency range.	
Memory Recall	0-511	Select One of 512 memory channels (A channel can be a single frequency or a band of interest)	
Memory Store	0-511	Save the current frequency, mode etc. in one of 512 memory channels	
Volume	0-9	Audio Volume 0=mute	
Mode		Receiver mode (AM, AMS, FM, LSB, USB, CW)	
AGC Speed	Very Slow – Fast  (Manual Gain 0dB to 60dB)	Automatic gain control adjusts the gain so that weak and strong stations have a similar volume level. Fast settings respond quickly to changes in signal level, slow settings change more gradually. A slow setting might prevent adjustments to gain during gaps in speech. Manual gain control is also possible, this might be useful when a constant gain is desirable, e.g. when working with digital modes.	
Bandwidth	Very Narrow – Very Wide	Adjust the filter bandwidth, a narrow setting reduces background noise and can improve intelligibility of weak signals. A wider settings allows through a greater range of frequencies giving better sound quality for strong signals.	
Squelch	S0 - S9+30dB	The squelch function gates background noise. The signal is muted unless the signal strength reaches a defined level. Squelch can be adjusted to allow signals to be audible when active, but remove background noise when inactive.	
Auto Notch	On/Off	The automatic notch filter can be used to remove interfering tones. If stable interference is detected consistently at the same frequency, a narrow notch is enabled to automatically suppress the interference.	

# **Menu Settings – Part 2**

Setting	Range	Description	
De-Emphasis	off/50us/ 75us	Enable de-emphasis filter	
IQ-Correction	On/Off	Compensates for differences in phase/magnitude in the IQ inputs. Enable this setting to improve image rejection (remove mirror frequencies).	
Spectrum Zoom	1-4	Zoom level for spectrum scope. 1=30kHz, 2=15kHz, 3=7.5kHz, 4=3.75kHz	
Band Start/Band Stop	0-30MHz	The band-start and band-stop settings define the tuning range of the current band. The band-start and band stop settings are stored in memory channels allowing memory channels to hold bands as well as individual frequencies.	
Frequency Step	10Hz- 100kHz	Set the default tuning step. Note that fast and slow tuning from /10 to *100 the nominal frequency step can be achieved by holding the menu/back buttons.	
CW Tone	100Hz - 3000Hz	When received, the CW signal has a very narrow bandwidth close to DC, lower than the range of human hearing. The CW tone increases the frequency of the CW signal to a frequency that can be heard comfortably A frequency between 500Hz and 1000Hz is typical.	
HW Configuration	0-9	The Pi Pico RX is designed to be as flexible as possible to allow different configurations and experimentation by constructors. A separate hardware configuration menu is provided to configure the hardware.	

## **Hardware Configuration Menu**



Display Timeout
Regulator Mode
Reverse Encoder
Encoder Resolution
Swap IQ
Gain Cal
Freq Cal
Flip OLED
OLED Type
TFT Settings
TFT Colour
Bands
Display Contrast
USB Upload

## **Hardware Configuration Settings-Part 1**

Setting	Range	Description	
Display Timeout	Never, 5 seconds – 4 minutes	Display turns off after a period of inactivity. This can be useful for power saving when running from batteries. This may also help prevent noise being generated by the display being received.	
Regulator Mode	FM/PWM	The Pi Pico contains a switched-mode regulator. Under light loading, the regulator can switch into a FM mode to save power, this does however increase supply ripple. The PWM setting reduces supply ripple.	
Reverse Encoder	On/Off	This allows the direction of the encoder to be reversed (clockwise/anticlockwise). This allows for variations in hardware construction where the encoder is wired in a different configuration.	
Swap IQ	On/Off	Swap the I/Q ADC input channels. Can be used to correct for a difference in wiring of the LO inputs, or IQ inputs. It causes the received spectrum to be reversed so that positive frequencies become negative and vice-versa. This is also useful for checking image rejection.	
Gain Cal	1-100dB	Specifies the gain of the receiver, this is used by the software to calculate the signal strength for the Smeter and dBm signal strength. The breadboard version of the receiver with default components has a gain of 57dB. Constructors may use alternative gain values, additional filters or preamplifiers. This setting also allows the S-meter to be calibrated so that it reads the correct signal strength with a known input signal.	
Freq Cal	-100 to +100 ppm	Allows oscillator frequency to be calibrated to account for process variations in the pi-pico crystal oscillator. Frequency can be tuned using a reference oscillator or frequency counter. It may also be possible to calibrate by "zero-beating" a station with a known carrier frequency e.g. WWV.	
Flip OLED	On/Off	Allows the display to be flipped horizontally, this may be useful to constructors who need to place the display in a different orientation. Only landscape orientations are supported.	

## **Hardware Configuration Settings-Part 2**

			•
Setting	Range	Description	
OLED Type	SSD1306 /SH1106	Allows different types of OLED display to be used. I2C OLED displays using SD1306 and SH1106 driver chips are supported.	
Display Contrast	0 to 15	Allows contrast of OLED display to be adjusted. Lower values reduce power consumption, higher values improve readability in bright surroundings.	
TFT Settings	Off, Rotation 1-8.	An optional SPI TFT (ili9341) display can be connected to provide an enhanced waterfall/spectrum scope. By default the secondary TFT display is disabled. To allow for variations in hardware, 8 different rotation settings are provided.	
TFT Colour	RGB/ BGR	To allow for variations in has settings are provided.	hardware, 2 different colour
Bands	Band 1-5 0 to 32MHz	band filters. The default s with the PCB version and for a general coverage re	onfigured through this menu, o define their own custom
USB Upload (Memory)		Allows user specified menting bulk via USB replacing channels. A simple Pytho upload settings from a CS interface.	n utility can be used to
USB Upload (Firmware)			<u> </u>

## **Scanning**





Pi Pico RX provides a scan feature, the scan feature can be accessed as a separate "home screen view". (Different views can be selected by pressing the "back" button on the home screen.

There are 2 scanning modes, *frequency scan* and *memory scan*. In frequency scan mode, the receiver searches for signals in the current band frequency range (e.g. 20m SSB band). In *memory scan* mode, the receiver searches memory channels for active signals.

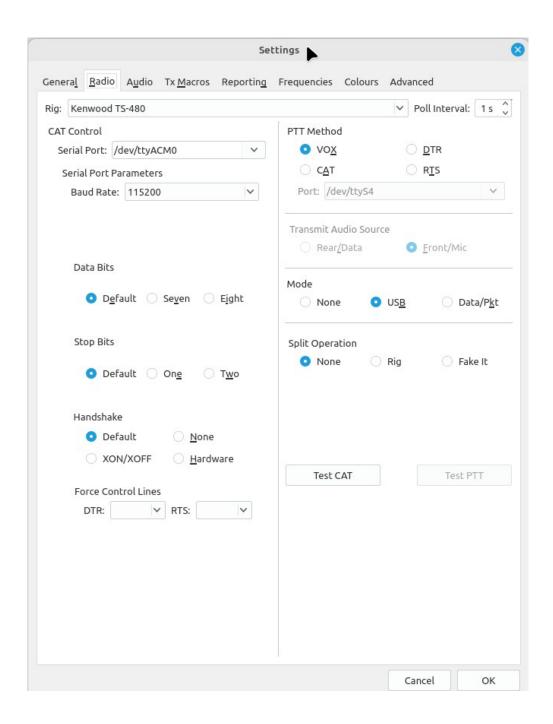
The encoder controls both the direction and speed of the search.

In both modes, the squelch setting is used to determine the threshold level, if the signal strength exceeds the squelch threshold, the search is halted. Searching can be continued by rotating the encoder.

The current signal strength and squelch level are indicated by a vertical bar on the right hand side.

#### **CAT Control**

Cat control is provided through a USB serial port interface. The Pi Pico Rx emulates a subset Kenwood TS-480. The CAT interface allows the receiver to be controlled via a host device by software such as grig, wsjtx and fldigi.



#### **USB** Audio

The Pi Pico Rx supports USB audio, and when connected should appear as a USB microphone. This allows a host device to easily make audio recordings (e.g. using audacity), and is compatible with software such as wsjtx, fldigi and QSSTV. When combined with USB cat control allows a fully functional PC connection using only a single USB cable. The direct digital audio connection provides superior audio quality compared to an analogue connection using a sound card.

