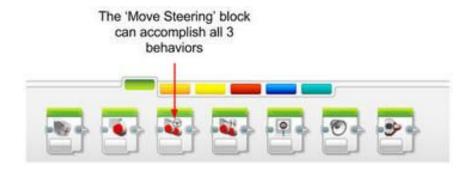
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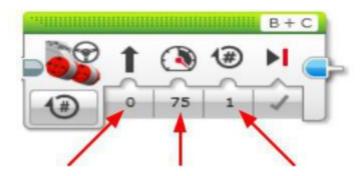
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# THE MOVE STEERING BLOCK

In the EV3 software, moving and turning are programmed using the **Move Steering** block.



There are three parts to the **Move Steering** block. Label them below.



#### **DESIGN THINKING**

IDEATE	EMPATHIZE:
EMPATHIZE DEFINE  PROTOTYPE	DEFINE:
TEST	IDEATE:
	PROTOTYPE:
	TEST:

#### devBots Sumo

#### Building the ultimate sumo robot

Your job is to design a sumo wrestling robot. Before you begin building, you must go through the design thinking process to design and create the best sumo wrestling robot. The three most important aspects you should consider are: defense, offense, and simple attachments. That means your robot should be able to defend itself from attacking robots, effectively knock over, wedge, or push its opponent, and be able to clip its attachments on and off in less than 3 minutes.

#### **EMPATHIZE**

Watch the robot battle then answer the following questions.

What happened in your battle? What problems did you encounter?

#### **DEFINE**

WHAT PROBLEM ARE YOU SOLVING?

### **IDEATE**

Develop a game plan for building your robot. Sketch a sample of your attachments below. (What type of attachments does your robot need? Will that help defend your robot from attackers? How can your robot attack other robots?)					

## **PARTNER IDEATE**

With your partner, develop an idea that uses the best parts of each design.					

### **PROTOTYPE**

Time to finalize your design! Grab a robot parts box and build a prototype of your design. Then, write a paragraph explaining how your design includes defense, offense, and simple attachments.

Explain your design in the space below:

## **TEST**

Let's put your design to the test! We will battle other groups in a mini sumo competition.
How did your attachments hold up during the competition? Did any parts fall off?
Were your defense attachments able to protect your robot from its opponent?
3. How did your offense attachments perform in attacking the other robot?

4. Are you able to rebuild your robot in less than 3 minutes?

# COMPARE THE MOVE BLOCKS

Look at the image below and answer the questions.





- 1. In the example above, which move block is similar to what you have used so far?
- 2. What is different about the two move blocks above?
- 3. How do you think that difference changes the move block?

# WORKING ON YOUR CODE

#### devBots Sumo Wrestling

Let's take a few minutes to reflect on our sumo wrestling robot and see if there are ways to improve our code. Talk through the questions below with your group.

- 1) Did your robot find the other robot first?
- 2) Was your robot able to attack before the other robot saw it?
- 3) What sensors are on your robot?
- 4) Do they work properly?
  - a) If not, what is not working?
- 5) What is slowing down your group during the competition? Typing? Waiting for ultrasonic sensor to see a robot? Getting stuck in a jam?

Now, let's think about ways to improve our code.

Offense - How can we update our coding offense to better attack other robots?

1) What can you adjust in the code so your sensors work better or faster?

2) Can you change anything for your robot to be quicker and more powerful when attacking?

Defense - How can we improve our defense to protect ourselves?

1) How can you keep the other robot from attacking you?

2) How can you fix the part that most slowed you down during the competition?

# WORKING ON YOUR BUILD

#### devBots Sumo Wrestling

Let's take a few minutes to reflect on our sumo wrestling robot and see if there are ways to improve our build. Talk through the questions below with your group.

1) Did the robots get jammed or tangled?
a) Where did it get jammed?
2) Did your robot get lifted off the ground?
a) If so, which side?
3) Were you able to push or lift the other robot? How?
4) Was the opposing robot able to knock you over? How?
5) Did any of your parts fall off?
Now, let's think about ways to improve our build.
Offense - How can we build our offense for sumo wrestling?
1) What can you build to better attack or push the other robot?
2) Can you build anything to lift the other robot?
<b>Defense</b> - How can we improve our defense to protect ourselves?
1) How can you prevent your robot from being lifted off the ground?
2) What can you build to protect areas of your robot that get jammed?

# ROBOTICS ITERATION LOG

Our goal is
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Test #	What worked well?	What needs to be fixed?