

Functions

Functions are fundamental concepts in calculus, representing a rule that assigns an output to an input. They are particularly useful for describing relationships between quantities that change, which is a core concept in calculus. There are two main types of functions we deal with in calculus: scalar functions and vector-valued functions.

Scalar Functions

A scalar function takes one or more numbers as inputs (which can be scalars or vectors themselves) and outputs a single number (a scalar).

- The input can be one number (like a simple function of x), or it can be multiple numbers grouped into a vector.
- The output is always a single number.
- Examples of scalar functions include:
 - $f(x) = x^2$ (univariable)
 - $g(x, y) = x^2 + y^2$ (multivariable)
 - $h(t) = \sin(t)$ (univariable)

Vector-Valued Functions

Vector-valued functions, on the other hand, can take one or more numbers as inputs (similar to scalar functions) but output a vector as the result.

- The input can be a scalar or a vector.
- The output is always a vector, with a dimension equal to the number of elements it contains.
- Here are a few examples of vector-valued functions:
 1. Position vector of a moving object: Suppose a particle is moving in a 2D plane with its x-coordinate given by the function $f(t) = 2t$ and its y-coordinate given by the function $g(t) = 3t^2$. The position vector of the particle at time t can be represented as a vector-valued function:

$$r(t) = \langle f(t), g(t) \rangle = \langle 2t, 3t^2 \rangle$$

2. Parametric equations of a curve: Consider the curve defined by the parametric equations:

$$x(t) = \cos(t), y(t) = \sin(t)$$

The vector-valued function representing this curve is:

$$r(t) = \langle x(t), y(t) \rangle = \langle \cos(t), \sin(t) \rangle$$

3. Space curve: In 3D space

$$r(t) = \langle f(t), g(t), h(t) \rangle$$

4. Motion of a particle in 3D space :

$$x(t) = 2\cos(t), y(t) = 2\sin(t), z(t) = 3t$$

The vector-valued function representing the motion of the particle is:

$$r(t) = \langle x(t), y(t), z(t) \rangle = \langle 2\cos(t), 2\sin(t), 3t \rangle$$