## Problem 6. Solution.

(i) [8 points] This is standard and only uses the fact that W is T-invariant. Take a basis  $\beta_W$  for W and extend it to a basis  $\beta$  for V. Then the matrix  $[T]_{\beta}$  has the form

$$\begin{pmatrix} [T_W]_{\beta_W} & B \\ 0 & C \end{pmatrix},$$

and

$$P_T(t) = \det\left(\begin{bmatrix} [T_W]_{\beta_W} - tI_m & B\\ 0 & C - tI_{n-m} \end{bmatrix}\right)$$

$$= \det\left([T_W]_{\beta_W} - tI_m\right) \cdot \det(C - tI_{n-m})$$

$$= P_{T_W}(t) \cdot g(t)$$

so that  $P_{T_W}(t) \mid P_W(t)$ .

(ii) [7 points] Show that  $u \neq 0$ . By the theorem in the book about cyclic subspaces,

$$\{v, T(v), \dots, T^{m-1}(v)\} \qquad (\star)$$

is a basis for W where  $m = \dim W = \deg P_{T_W}(t)$  and the set

$$\{v, T(v), \ldots, T^m(v)\}$$

is linearly dependent. Now

$$(-1)^m g(t) = a_0 + a_1 t + \dots + t^{m-1}$$

and

$$(-1)^m u = a_0 v + a_1 T(v) + \dots + T^{m-1}(v).$$

But then u=0 would contradict the fact that the set  $(\star)$  is linearly independent.

[10 points] Show that u is an eigenvector. The Hamilton-Cayley Theorem says that

$$P_{T_W}(T_W) = 0$$
, as a linear transformation of  $W$ .

In particular, if x is any vector in W, then  $P_{T_W}(T)(x) = 0$ , because  $T(x) = T_W(x)$ . Thus

$$0 = P_{T_W}(T)(v) = ((T - aI)g(T))(v) = (T - aI)(g(T)(v)) = (T - aI)(u) = T(u) - au$$

i.e., T(u) = au. Since  $u \neq 0$ , this says that u is an eigenvector with eigenvalue a.