

$R(T) = G.I$

Minimize this cost function during training

This can lead to complex tree having all leaves pure (overfitting)

→ We can add a penalty term

$R_\alpha(T) = R(T) + \alpha |\tilde{T}|$

Complexity parameter; controls the strength of the penalty.

Objective function

Type of cost function i.e. $G.I$

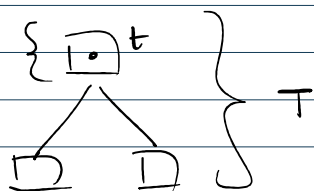
Type of penalty, but here it is the # of terminal nodes in T .

opposite focus

→ Now instead of D.T. having minimal $R(T)$, we are interested in D.T. " " $R_\alpha(T)$.

→ T with minimum $R_\alpha(T)$ compare to all other trees

→ w.r.t different values of α , different tree T will have minimal $R_\alpha(T)$
we will get another T .



$$R(t) > R(T) \text{ i.e. } G.I(\text{parent}) > G.I(\text{childs})$$

$$R_\alpha(t) = R(t) + \alpha(1)$$

$$R_\alpha(T) = R(T) + \alpha|\tilde{T}|$$

At which value of α , $R_\alpha(T) = R_\alpha(t)$

$$R(T) + \alpha|\tilde{T}| = R(t) + \alpha$$

$$\alpha |\tilde{I}| - \alpha = R(H) - R(T)$$

$$\alpha = \frac{R(H) - R(T)}{|\tilde{I}| - 1}$$

for α

- less decrease in impurities when we split parent into child.
- high complexity added to the DT when parent is split into child

→ can lead to overfitting
[weakest link]