$$u_{4} = [\alpha_{4}, \beta_{4}, \gamma_{4}]$$

$$\vec{x}_{4}$$

$$u_{1} = [\alpha_{1}, \beta_{1}, \gamma_{1}]$$

$$\vec{x}_{1}$$

$$f_{i} = f(\vec{x}(\tilde{x}_{i}), u(\tilde{x}_{i}), u(\tilde{x}_{i}))$$

$$u_{2} = [\alpha_{2}, \beta_{2}, \gamma_{2}]$$

$$\vec{x}_{2}$$

$$\vec{x}_{2}$$

$$f_{i} = f(\vec{x}(\tilde{x}_{i}), u(\tilde{x}_{i}), u(\tilde{x}_{i}), u(\tilde{x}_{i}))$$

 $u_3 = [\alpha_3, \beta_3, \gamma_3]$