

# Structure of pHs ThieleSmall

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## 1 System netlist

line	label	dictionary.component	nodes	parameters
$\ell_1$	IN	electronics.source	('A', 'ref')	{ type voltage
$\ell_2$	R	electronics.resistor	('A', 'B')	{ R ('R', 1000.0)
$\ell_3$	L	electronics.inductor	('B', 'C')	{ L ('L', 0.05)
$\ell_4$	G	connectors.gyrator	('C', 'ref', 'D', 'ref')	{ alpha ('Bl', 5)
$\ell_5$	M	mechanics.mass	('D', 'E')	{ M ('M', 0.1)
$\ell_6$	K	mechanics.stiffness	('E', 'F')	{ K ('K', 5000.0)
$\ell_7$	A	mechanics.damper	('F', 'ref')	{ A ('A', 1)

$\dim(\mathbf{x}) = n_{\mathbf{x}} = 3;$

$\dim(\mathbf{w}) = n_{\mathbf{w}} = 2;$

$\dim(\mathbf{y}) = n_{\mathbf{y}} = 1;$

$\dim(\mathbf{p}) = n_{\mathbf{p}} = 0;$

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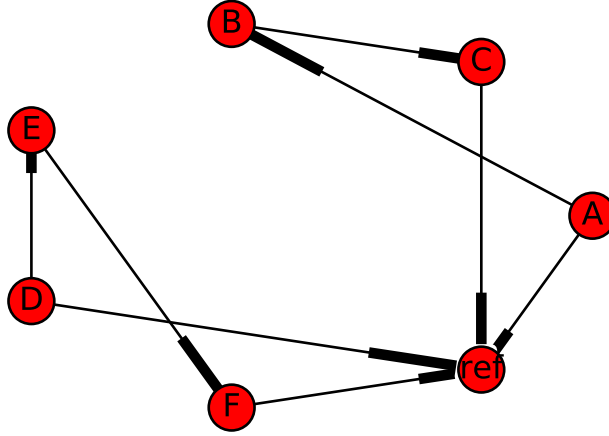


Figure 1: Graph of system ThieleSmall.

## 2 System variables

State variable  $\mathbf{x} = \begin{pmatrix} x_M \\ x_L \\ x_K \end{pmatrix}$ ;

Dissipation variable  $\mathbf{w} = \begin{pmatrix} w_R \\ w_A \end{pmatrix}$ ;

Input  $\mathbf{u} = (u_{IN})$ ;

Output  $\mathbf{y} = (y_{IN})$ ;

### 3 Constitutive relations

$$\text{Hamiltonian } \mathbb{H}(\mathbf{x}) = 0.5 \cdot K \cdot x_K^2 + \frac{0.5}{M} \cdot x_M^2 + \frac{0.5}{L} \cdot x_L^2;$$

$$\text{Hamiltonian gradient } \nabla \mathbb{H}(\mathbf{x}) = \begin{pmatrix} \frac{1.0}{M} \cdot x_M \\ \frac{1.0}{L} \cdot x_L \\ 1.0 \cdot K \cdot x_K \end{pmatrix};$$

$$\text{Dissipation function } \mathbf{z}(\mathbf{w}) = \begin{pmatrix} R \cdot w_R \\ A \cdot w_A \end{pmatrix};$$

$$\text{Jacobian of dissipation function } \mathcal{J}_{\mathbf{z}}(\mathbf{w}) = \begin{pmatrix} R & 0 \\ 0 & A \end{pmatrix};$$

### 4 System parameters

#### 4.1 Constant

parameter	value (SI)
Bl :	5
R :	1000.0
L :	0.05
A :	1
K :	5000.0
M :	0.1

$$\mathbf{M} = \begin{pmatrix} 0 & 0 & -1.0 & 0 & -1.0 & 0 & 0 & 1.0 \\ 0 & 0 & 0 & -1.0 & 0 & 1.0 & -1.0 & 0 \\ 1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix};$$

$$\mathbf{J} = \begin{pmatrix} 0 & 0 & -1.0 & 0 & -1.0 & 0 & 0 & 1.0 \\ 0 & 0 & 0 & -1.0 & 0 & 1.0 & -1.0 & 0 \\ 1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1.0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1.0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix};$$

$$\mathbf{R} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix};$$