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MTH 4311

Dr. Pei Liu

Due: 4/3/2025

Part A.

For the Poisson-Boltzmann equation, the boundary value problem is written out in the work below:

$$\begin{cases} \phi_{xx} = z \sinh(z\phi) \\ \phi(0) = 0 \\ \phi(L) = V \end{cases}$$

First we should check if it is unique

$$y'' = z \sinh(zy)$$

$z^2 > 0$ and \cosh is

strictly positive function

so $f_y > 0$

$$f_x = 0$$

$$f_y = z^2 \cosh(zy)$$

$$f_y' = 0$$

All are continuous

and $f_y \leq M$ is true

due to $M > 0$

Finite Difference Method

$$y''(x) = \frac{y(x+h) + y(x-h) - 2y(x)}{h^2}$$

$$\begin{cases} \frac{\phi_{i-1} + \phi_{i+1} - 2\phi_i}{h^2} = z \sinh(z\phi_i) \\ \phi_0 = 0 \\ \phi_L = V \end{cases}$$

$$\phi_{i-1} + \phi_{i+1} - 2\phi_i = z \sinh(z\phi_i) h^2$$

$$\phi_{i-1} - 2\phi_i - z \sinh(z\phi_i) h^2 + \phi_{i+1} = 0$$

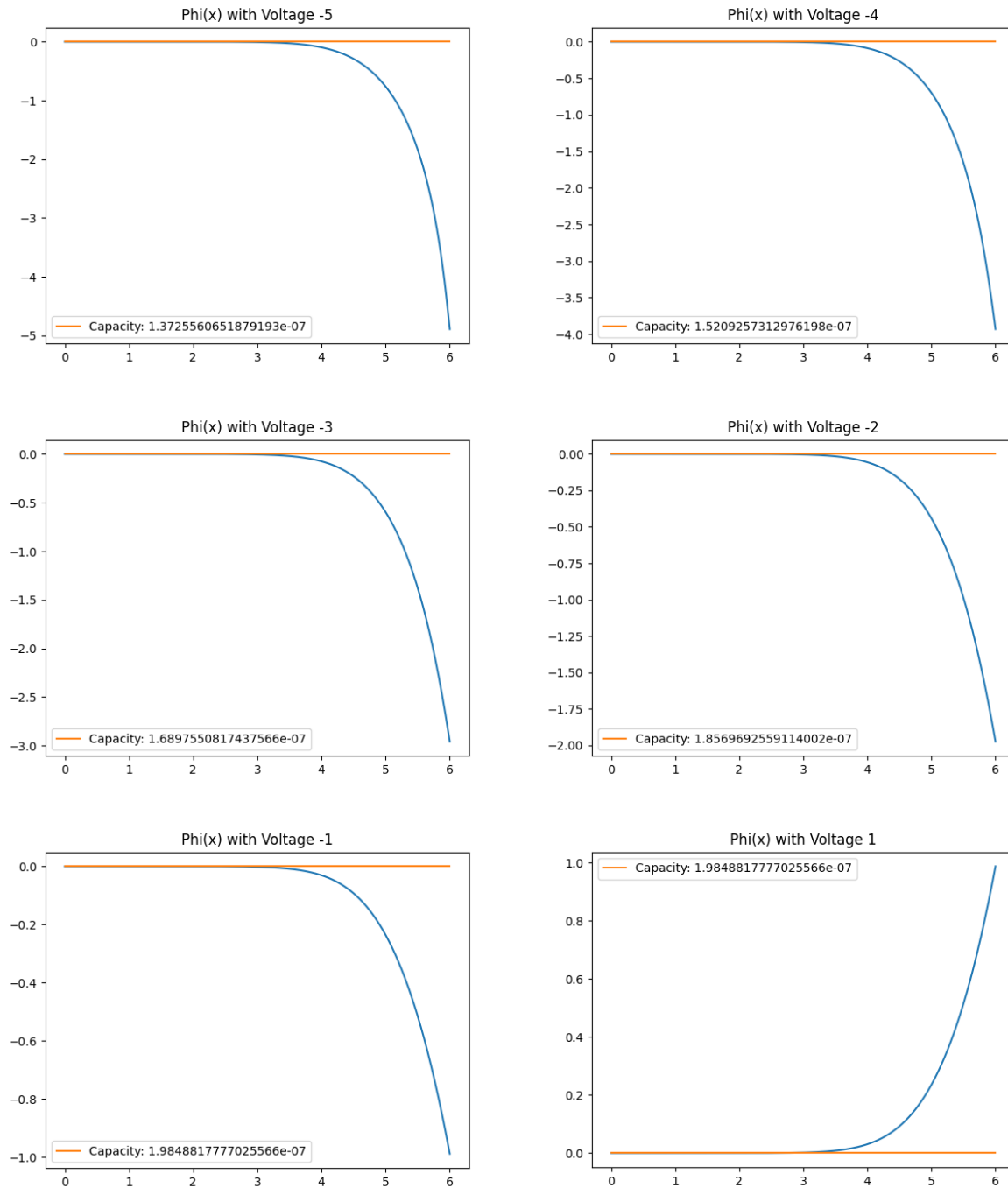
$$\phi_{i-1} - 2\phi_i - z h^2 \sinh(z\phi_i) + \phi_{i+1} = 0$$

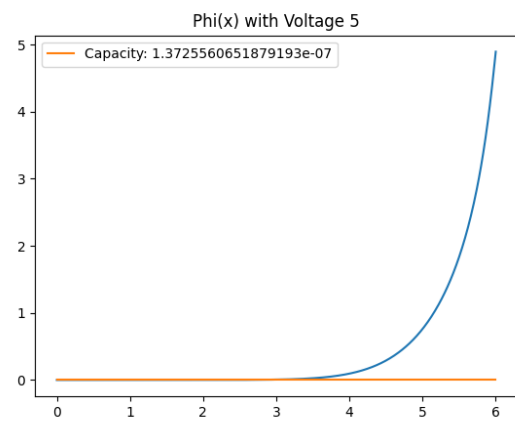
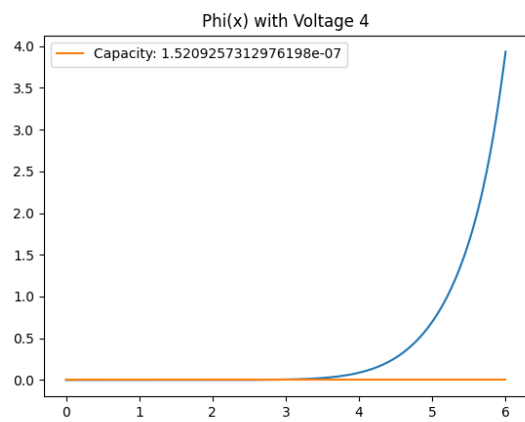
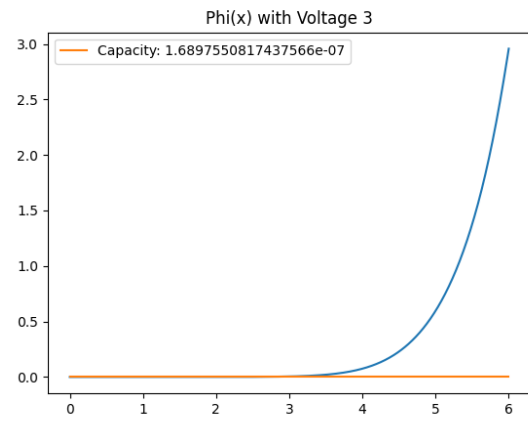
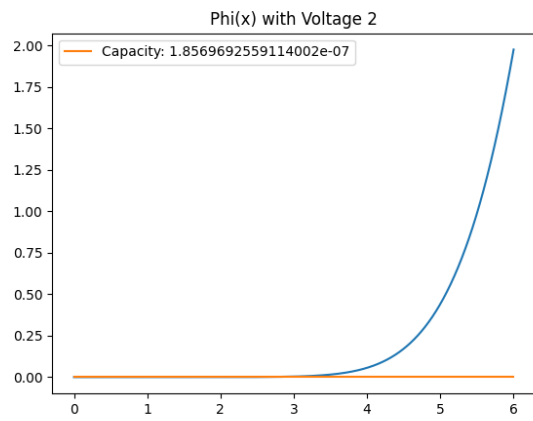
Using DF

$$\begin{pmatrix} -2 - z^2 \cosh(z\phi_i) h^2 & 1 & 0 \\ 1 & & \\ 0 & & \end{pmatrix}$$

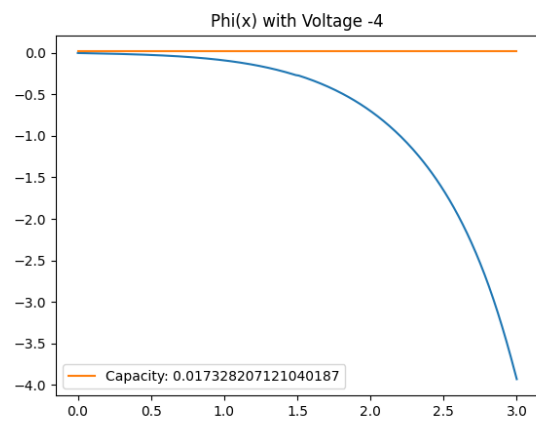
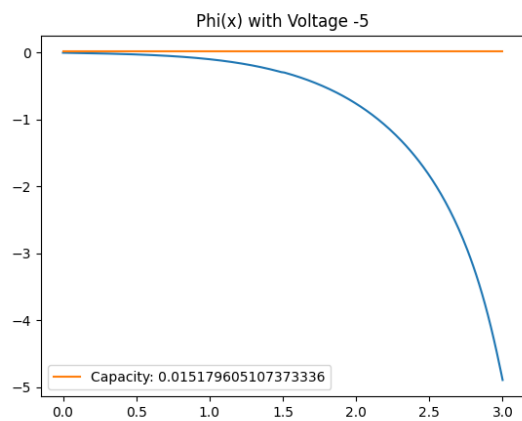
The matrix at the bottom of the work is the jacobian matrix we will be using for Newton's iterative method to calculate the y-values. The program creates the jacobian matrix mentioned above, then the $F(X_K)$ vector which we will use to solve during the iterations. When the Python code is running, the Finite Difference method takes a decent amount of time, due to it being an iterative method.

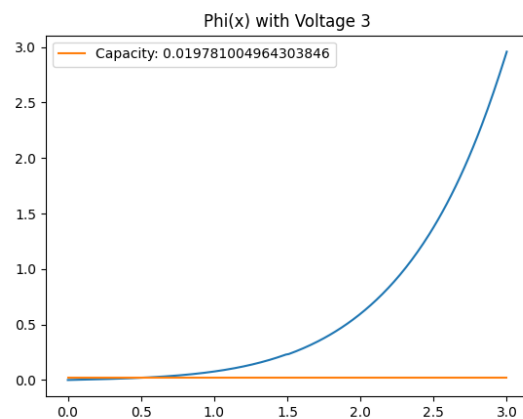
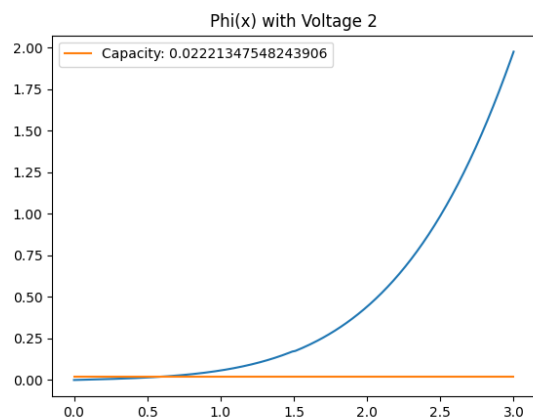
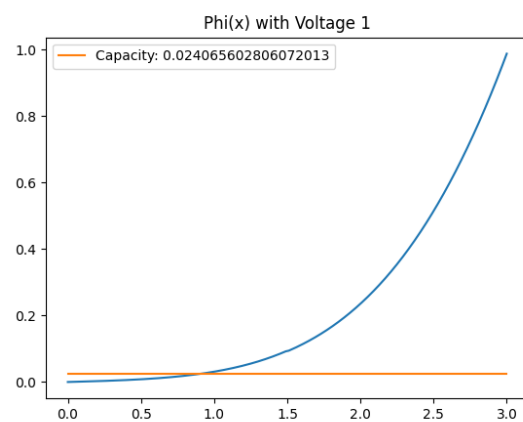
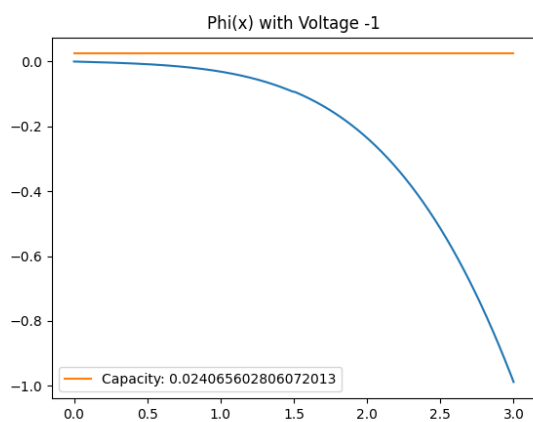
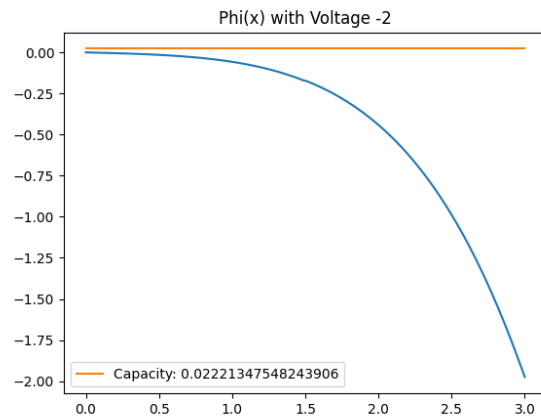
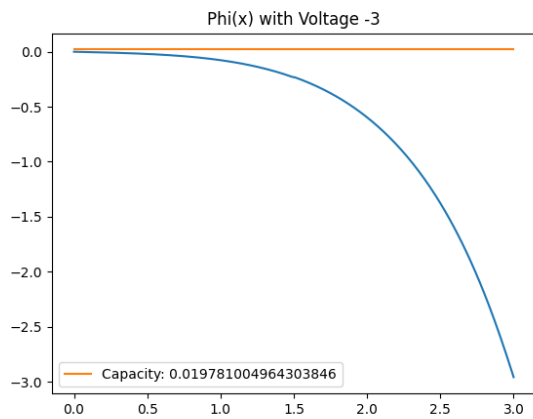
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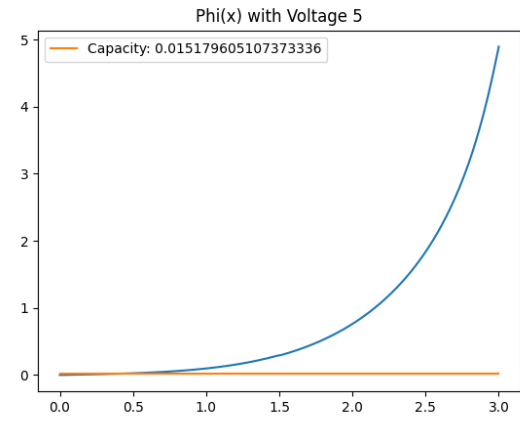
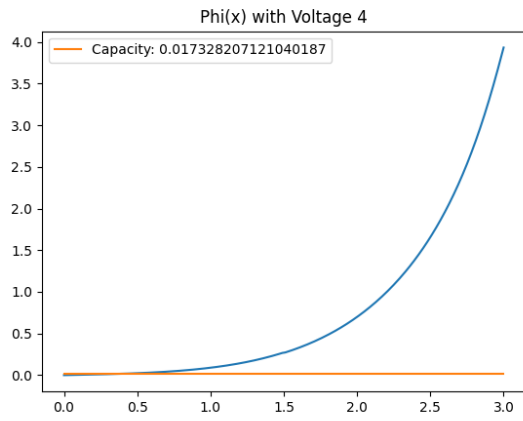




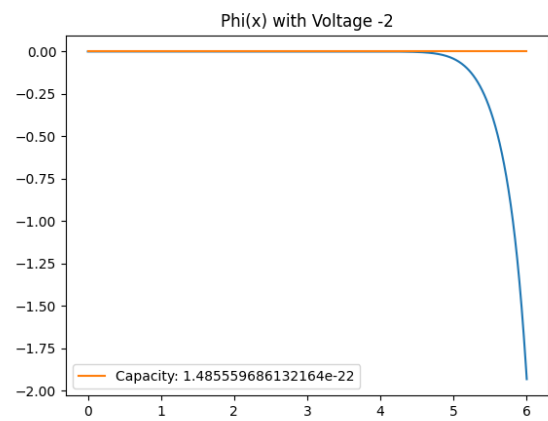
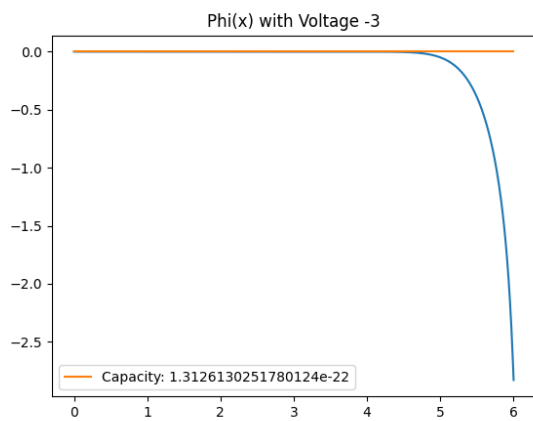
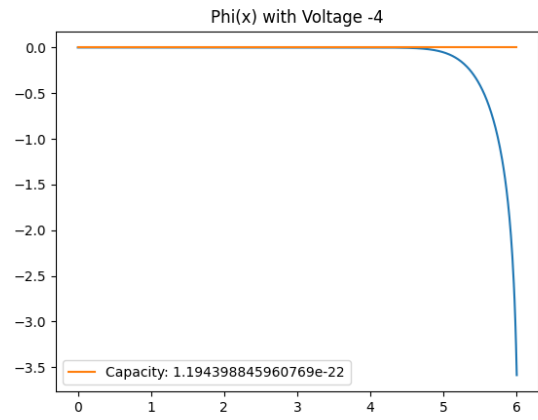
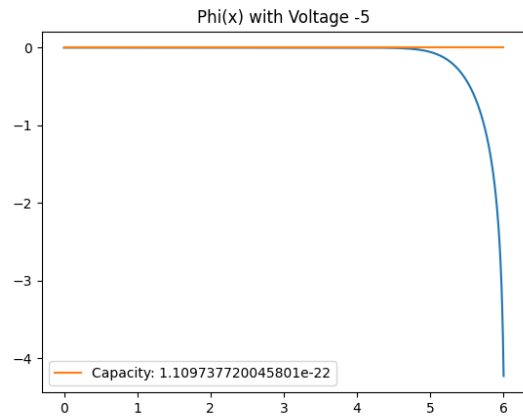
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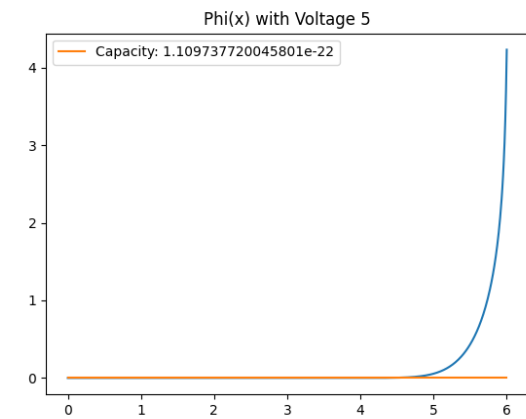
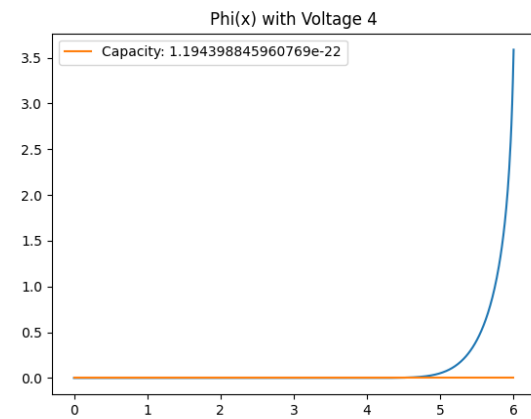
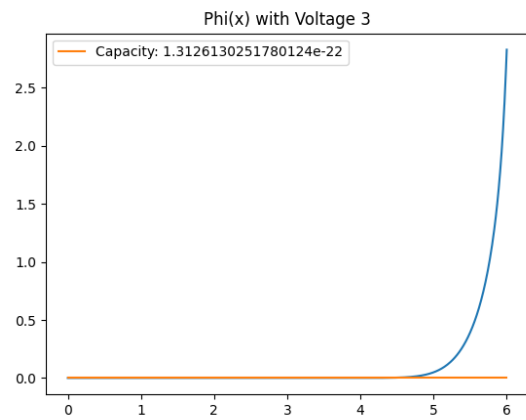
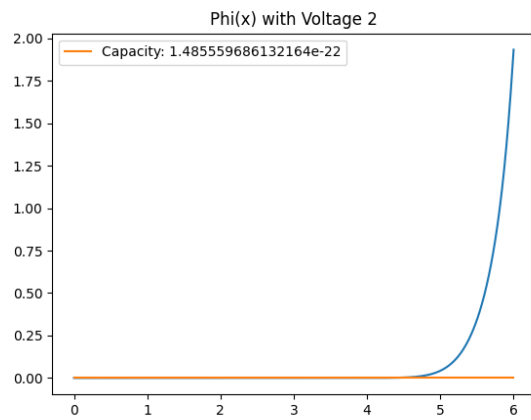
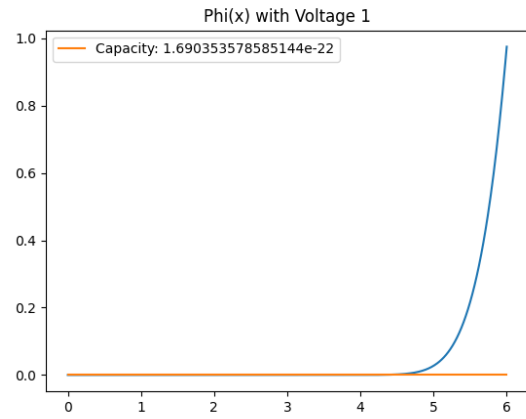
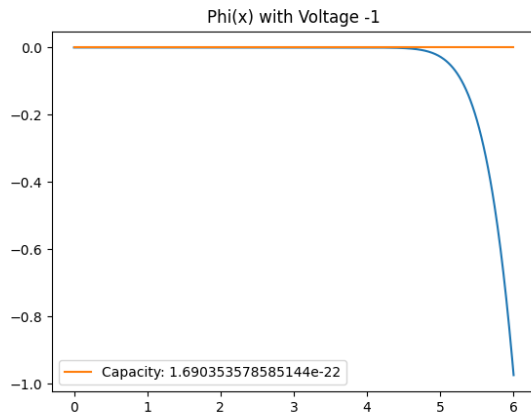






Part D.





Part E.

For the finite element method, the work is shown below:

$$\begin{cases} \phi_{xx} = z^2 \phi \\ \phi_0 = 0 \\ \phi_L = V \end{cases} \quad \text{Weak Form}$$

$$-\int_0^L \phi'(t) g'(t) dt = \int_0^L (z^2 \phi) g(t) dt$$

$$-\int_0^L \sum_{i=1}^N c_i g_i'(t) g_j'(t) dt = z^2 \int_0^L \sum_{i=1}^N c_i g_i(t) g_j(t) dt$$

$$\frac{c_{j-1}}{h} - \frac{2c_j}{h} + \frac{c_{j+1}}{h} = z^2 \left(\frac{h c_{j-1}}{6} + \frac{2h c_j}{3} + \frac{h c_{j+1}}{6} \right)$$

$$\frac{c_{j-1}}{h} - z^2 \frac{h c_{j-1}}{6} - \frac{2c_j}{h} - \frac{2z^2 h c_j}{3} + \frac{c_{j+1}}{h} - \frac{z^2 h c_{j+1}}{6}$$

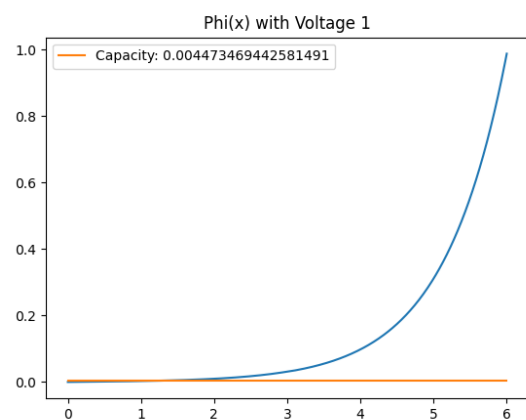
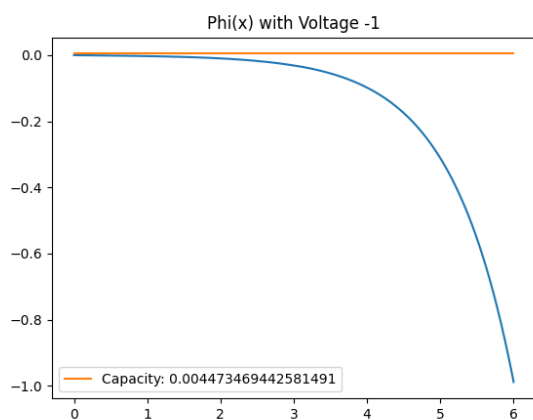
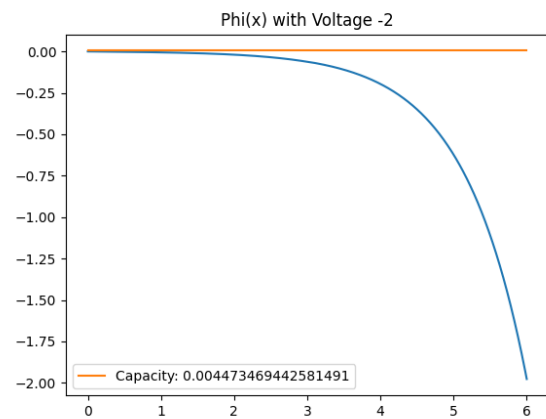
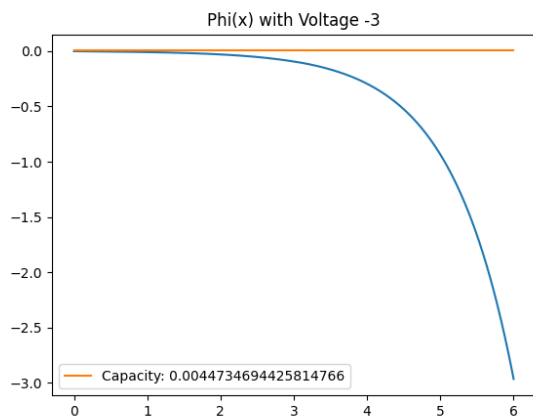
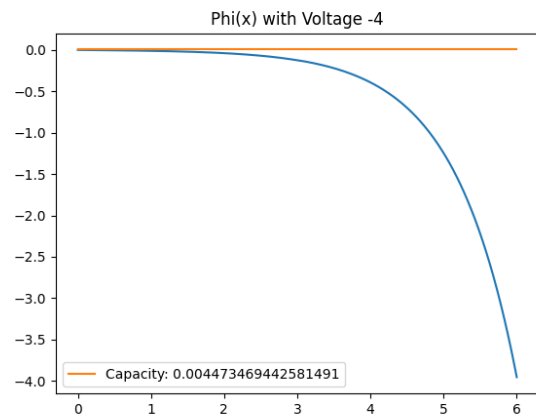
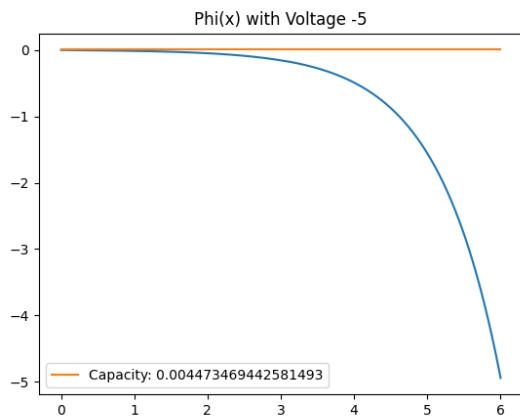
$$c_{j-1} \left(\frac{1}{h} - \frac{z^2 h}{6} \right) - c_j \left(\frac{2}{h} + \frac{2z^2 h}{3} \right) + c_{j+1} \left(\frac{1}{h} - \frac{z^2 h}{6} \right) = 0$$

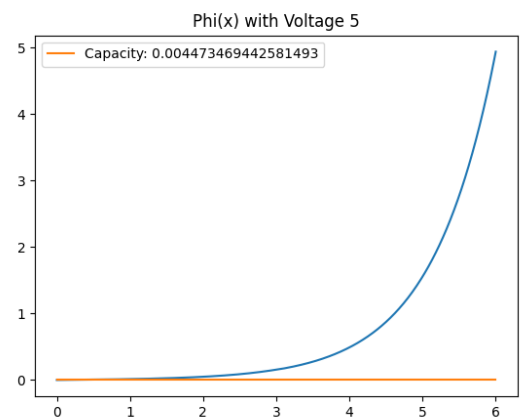
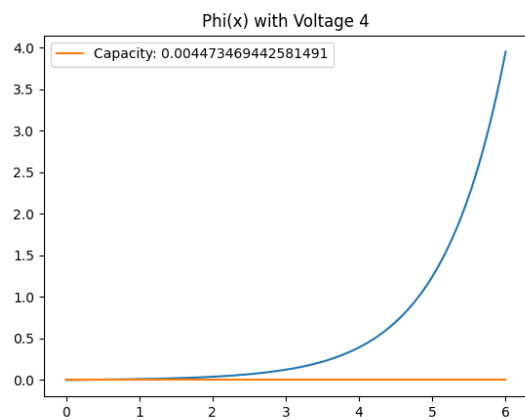
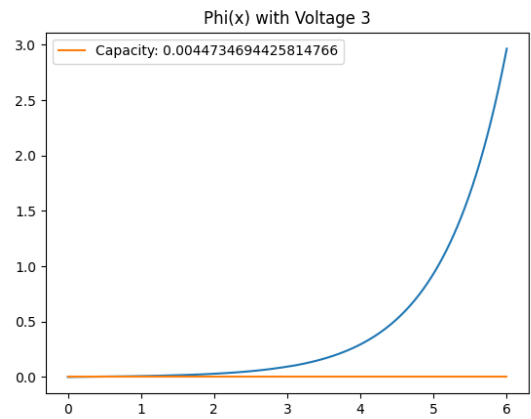
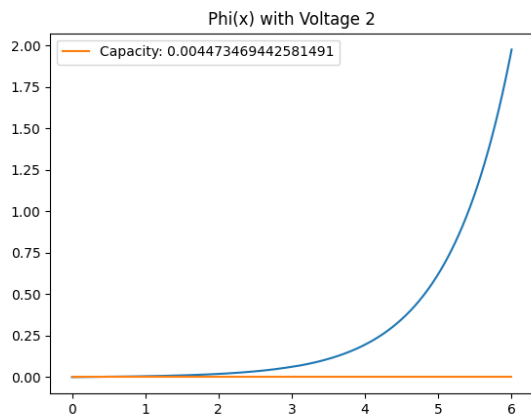
$$d = \frac{2}{h} + \frac{2z^2 h}{3} \quad \beta = \frac{1}{h} - \frac{z^2 h}{6}$$

$$\begin{pmatrix} -d & \beta & & 0 \\ \beta & -d & \beta & \\ & \ddots & \ddots & \ddots \\ 0 & & \beta & -d \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ -\beta V \end{pmatrix}$$

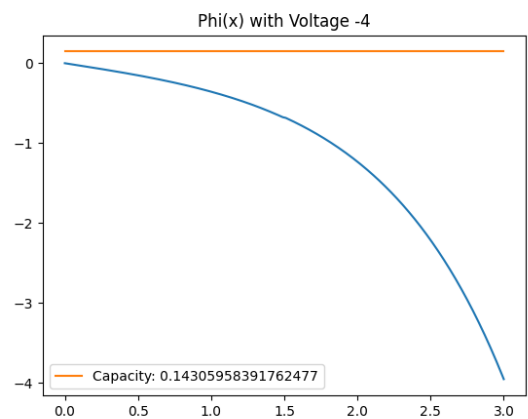
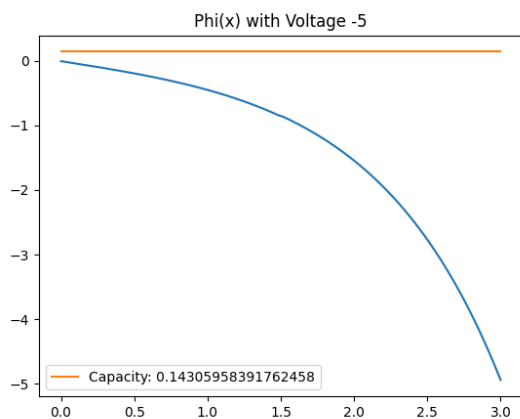
The B-Spline was used to convert the integral into a tri-diagonal matrix of alphas and betas. To compute the finite element method, all that was needed was the solving of one matrix, which ran much faster than the Finite difference method. The results of the graphs show that the curve starts to increase faster in the Finite element method because of the greater values in the matrix (alpha ~ 200, beta ~ 100).

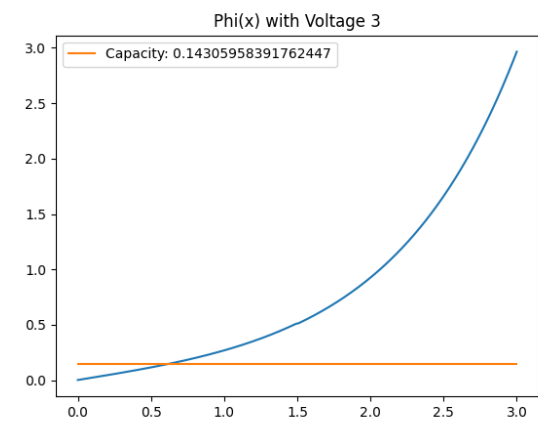
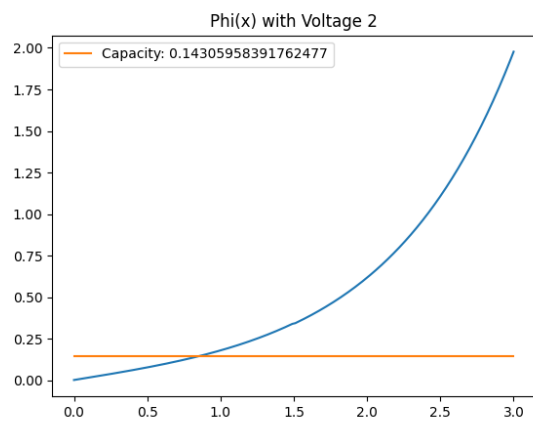
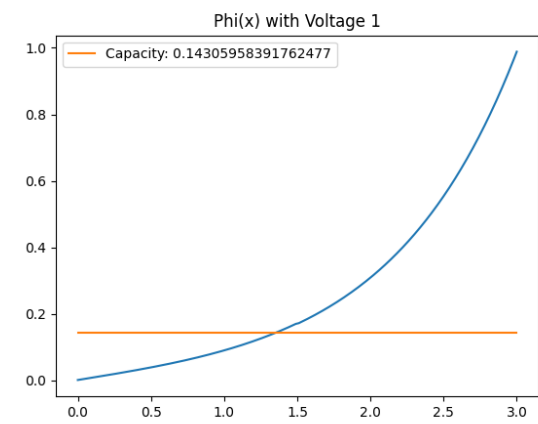
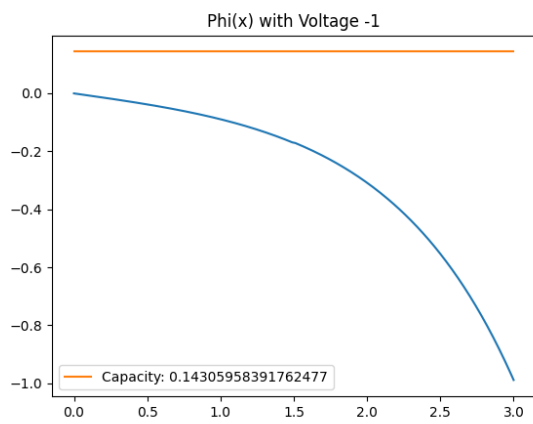
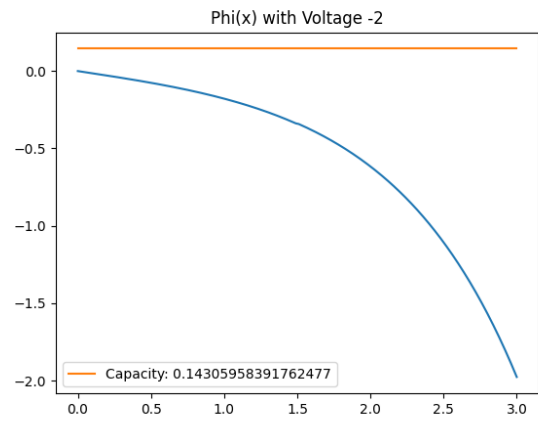
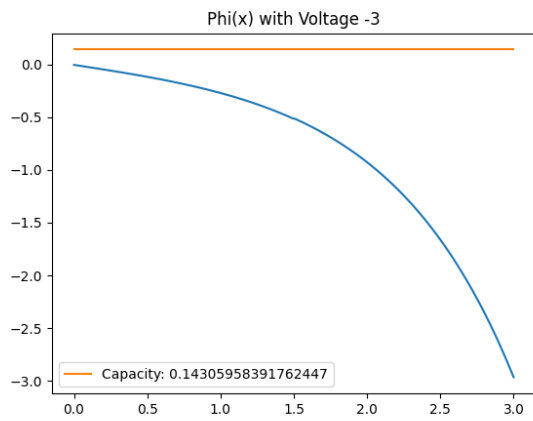
Part F1.

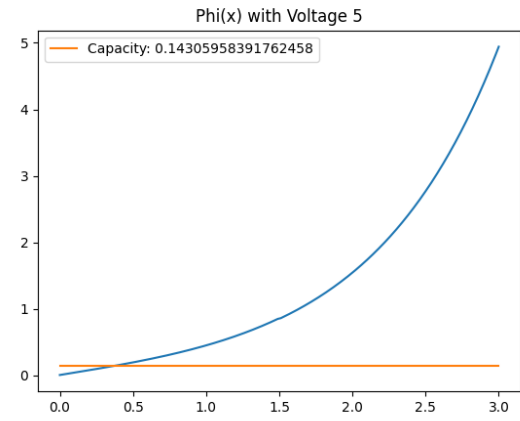
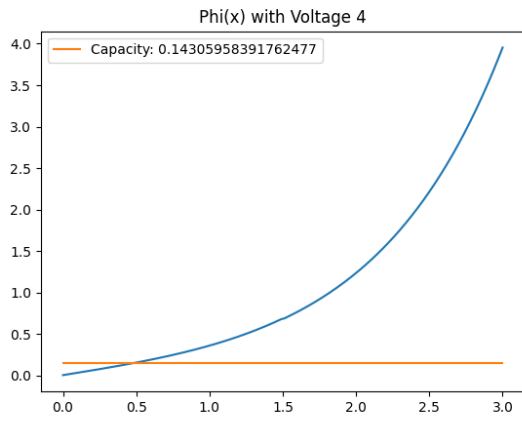




Part F2.







Part F3.

