

Figure 26.6 The execution of the basic Ford-Fulkerson algorithm. (a)–(e) Successive iterations of the while loop. The left side of each part shows the residual network G_f from line 3 with a shaded augmenting path p. The right side of each part shows the new flow f that results from augmenting f by f_p . The residual network in (a) is the input network G.

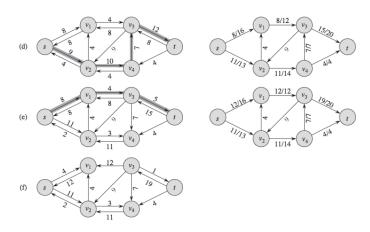


Figure 26.6, continued (f) The residual network at the last while loop test. It has no augmenting paths, and the flow f shown in (e) is therefore a maximum flow. The value of the maximum flow found is 23.

1 26.2 - 4: Min cut/Max flow

In the example of Figure 26.6, what is the minimum cut corresponding to the maximum flow shown? Of the augmenting paths appearing in the example, which one cancels flow?

Answer:

2 26.2 - 11 : connectivity

The edge connectivity of an undirected graph is the minimum number k of edges that must be removed to disconnect the graph. For example, the edge connectivity of a tree is 1, and the edge connectivity of a cyclic chain of vertices is 2. Show how to determine the edge connectivity of an undirected graph G=(V,E) by running a maximum-flow algorithm on at most |V| flow networks, each having O(V) vertices and O(E) edges.

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3 Perfect Matchings

A bipartite graph is a graph that contains no cycle with an odd number of edges. Recall from the wrestler problem that a graph, G=(V,E) is bipartite iff V can be partitioned into two sets L,R such that all edges in E have one endpoint in L and one endpoint in R. A matching in a graph is a set of edges $E' \in E$ such that each vertex in V is matched at most once, i.e. it is incident to a most one edge in E'. A perfect matching is a matching where every vertex is matched, i.e. is incident to exactly one edge in E'. For a set of vertices $S \in V$, let N(S) be the set of all neighbors of S, i.e. $\{y \in V : (x,y) \in E \text{ for some } x \in S\}$ Assume we are given a bipartite graph where |L| = |R|. Prove that there is a perfect matching in G iff $|N(S)| \ge |S|$ for all $S \in L$. Hint: Use the Max flow/Min Cut Theorem

Answer:

4 Image segmentation

Consider the following problem related to segmenting the pixels of an image between foreground and background. We have a picture that consists of n pixels. We represent this as an undirected graph G = (V, E) where V is the set of pixels and there is an edge $(i, j) \in E$ iff pixel i and pixel j are neighbors in the image 1.

We want to find a good segmentation, which is an assignment of each pixel to either the foreground or the background. For each pixel i, we have a likelihood a_i that i belongs to the foreground and a likelihood b_i that i belongs to the background. These likelihood values are all non-negative. Additionally, for each edge $(i,j) \in E$, we have a non-negative separation penalty p_i , j which is charged if one of i or j is assigned to the foreground and the other is assigned to the background. Our problem then is to find a partition of the set of pixels into sets A and B so as to maximize:

$$L(A,B) = \sum_{i \in A} a_i + \sum_{i \in B} b_i \sum_{(i,j) \in E, |A \cap \{i,j\}| = 1} p_{i,j}$$
(1)

Give an efficient algorithm to solve this problem

Answer:

This maximization problem stated in 1 can be formulated as a minimization problem instead, that is,

$$\max(a) = \sum_{i \in A} a_i + \sum_{i \in B} b_i \sum_{(i,j) \in E, |A \cap \{i,j\}| = 1} p_{i,j}$$
(2)

$$\min(g') = \sum_{i \in Q} f_i + \sum_{i \in P} b_i + \sum_{i \in P | j \in Q} p_{ij}.$$
(3)

The above minimization problem can be formulated as a minimum-cut problem by constructing a network where the source is connected to all the pixels with capacity f_i and the sink is connected by all the pixels with capacity b_i Two

¹Note that we'd commonly expect this graph to be a grid, but in fact we want to handle any arbitrary graph (to handle, e.g., 3-D images, wrapped and warped images, etc)

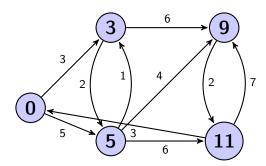


Figure 1: Figure 24.2 from CLRS

edges i, j and j, i with p_{ij} capacity are added between two adjacent pixels. The s-t cut-set then represents the pixels assigned to the foreground in A and pixels assigned to background in B.

5 Exercise 29.2-2 (Linear Program)

Write out explicitly the linear program corresponding to finding the shortest path from node s to node y in Figure 24.2(a).

Answer:

6 Exercise 29.2-4 (Network Flow as an LP)

Write out explicitly the linear program corresponding to finding the maximum flow in Figure 26.1(a).

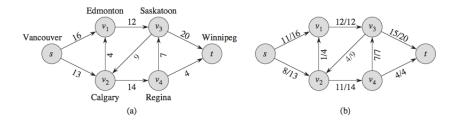


Figure 26.1 (a) A flow network G = (V, E) for the Lucky Puck Company's trucking problem. The Vancouver factory is the source s, and the Winnipeg warehouse is the sink t. The company ships pucks through intermediate cities, but only c(u, v) crates per day can go from city u to city v. Each edge is labeled with its capacity. (b) A flow f in G with value |f| = 19. Each edge (u, v) is labeled by f(u, v)/c(u, v). The slash notation merely separates the flow and capacity; it does not indicate division

Answer:

7 Rock, Paper, Scissors

Rock, Paper, Scissors is a simple 2 person game. In a given round, both players simultaneously choose either Rock, Paper or Scissors. If they both choose the same object, its a tie. Otherwise, Rock beats Scissors; Scissors beats Paper; and Paper beats Rock. Imagine youre playing the following betting variant of this game with a friend. When Scissors beats Paper, or Paper beats Rock, the loser gives the winner \$1. However, in the case when Rock beats Scissors, this is called a smash, and the loser must give the winner \$10.

(a) Say you know that your friend will choose Rock, Scissors or Paper, each with probability $\frac{1}{3}$. Write a linear program to calculate the probabilities you should use of choosing each object in order to maximize your expected winnings. Let p_1, p_2, p_3 be variables associated with the best way of choosing Rock, Scissors and Paper respectively. Note: If you want to check your work, there are several free linear program solvers on the Internets: check the Wikipedia page on linear programming.

Answer:

if p_1 , p_2 , p_3 are the probabilities of choosing the

$$\sum_{blah}^{blah} = winnings \tag{4}$$

(5)

(b) Now say that your friend is smart and, also, clairvoyant: she will magically know the exact probabilities you are using and will respond optimally. Write another linear program to calculate the probabilities you should now use in order to maximize your expected winnings. Hint 1: If your opponent knows your strategy, her strategy will be to choose one of the three objects with probability 1.

Hint 2: Review the LP you wrote for the shortest paths problem.

Answer:

Let P = our profit and Q = our friend's profit. Let P_r, P_p, P_s be our probabilities of choosing rock, paper, or scissors. Let Q_r, Q_p, Q_s be our friend's winnings when she chooses rock, paper, or scissors, respectively. Then let her winnings be defined as

$$Q_r = P_p - 10P_s$$
 she picks rock
 $Q_p = P_s - P_r$ she picks paper (6)
 $Q_s = 10P_r - P_p$ she picks scissors

Then we want to maximize her winnings in 6 in such a way to minimize our winnings.

$$\max(Q) = \max \begin{cases} Q_r = P_p - 10P_s \\ Q_p = P_s - P_r \\ Q_s = 10P_r - P_p \end{cases}$$

$$0 \le p_1, p_2, p_3 \le 1$$

$$\sum_{i=1}^p p_i = 1$$
(7)

8 Independent-Set

The problem INDEPENDENT-SET asks: Does there exist a set of k vertices in a graph G with no edges between them? Show that this problem is NP-Complete. (hint: Reduce from CLIQUE)

Answer:

Proof. Via reduction from CLIQUE

Part one:NP

INDEPENDENT-SET is in NP. Given a vertex set S returned from the algorithm we can indeed check that S is an independent set of vertices by checking that each vertex in S is in the graph and that there are no edges between any two vertices in S. A simple BFS or DFS will handle this in O(V + E) time and INDEPENDENT-SET \in NP.

Part two: NP-Hard

INDEPENDENT-SET is NP-Hard. Recall that an instance of CLIQUE is a graph G and an integer k. We can convert an instance of CLIQUE to INDEPENDENT-SET as such: Let G_c be the complement graph of G and pass G_c , k to INDEPENDENT-SET. Assume that there is a clique G of size G of s

9 Exercise 34.5-1 (Subgraph Isomorphism)

The subgraph-isomorphism problem takes two undirected graphs G_1 and G_2 , and it asks whether G_1 is isomorphic to a subgraph of G_2 . Show that the subgraph-isomorphism problem is NP-complete.

Answer:

In order to show NP-completeness, we must state the problem as a decision problem. We can ask if a given graph is isomorphic to a subgraph of another graph, and in this case, if G_1 is isomorphic to a subgraph of G_2 , the answer is "true" and "false" otherwise. Let it be stated that to be isomorphic to another graph, a graph G = (V, E) must have a subgraph $G_0 = (V_0, E_0) : V_0 \subseteq V$, $E_0 = E \cap (V_0 \times V_0)$ such that $G_0 \cong H$? Does a mapping $f : V_0 \to V'$ exist such that vertices $v_1, v_2 \in E_0 \Leftrightarrow (f(v_1), f(v_2)) \in E'$?

Proof. By reduction from CLIQUE.

CLIQUE \leq_P SUBGRAPH ISOMORPHISM. Let (G = (V, E)k) be an input for CLIQUE and let G_1 to be the complete graph on k vertices and G_2 to be the graph G. G_1 , $G_2 \in$ SUBGRAPH ISOMORPHISM iff G, $k \in CLIQUE$.