

## Clustering Analysis

- Clustering is an interesting problem of **unsupervised learning** → cluster analysis does not use category labels that tag objects with prior identifiers.
- Deals with **data structure partitioning** in space.
- Forms the basis of **exploratory data analysis (EDA)**.



Figure 1. Dataset in 2D space

## Classification of Clustering Algorithms

- Flat clustering** creates a set of clusters that hold no inherent relationship to one another.
- Hierarchical clustering** creates a family of sets of clusters.
- Centroid-based/Parametric clustering** initializes centroids around which clusters form.
- Density-based/Non-Parametric clustering** prepares clusters by quantifying density.

Clustering Type	Flat	Hierarchical
Centroid	<i>K</i> -means	Ward Complete-Linkage
Density	DBSCAN	HDBSCAN

- K*-means:
  - suffers from the choice of parameter *K*
  - makes an **assumption** about the data distribution: the Gaussian-ball assumption
- DBSCAN:
  - gets rid of the Gaussian-ball assumption
  - the resolution parameter is **arbitrary** though
- Ward Complete-Linkage
  - Gaussian-ball **assumption** creeps in; the hierarchical tree needs to be cut somewhere

## Hierarchical Density-Based Spatial Clustering of Applications with Noise

The protocol for **HDBSCAN** is as follows:

- Transformation of the dataset to **mutual reachability space**
- Constructing of a **minimum spanning tree (MST)**
- Preparation of a **dendrogram** for the MST
- Pruning the dendrogram** based on **minimum cluster size**
- Extraction** of clusters

## Transformation of Space

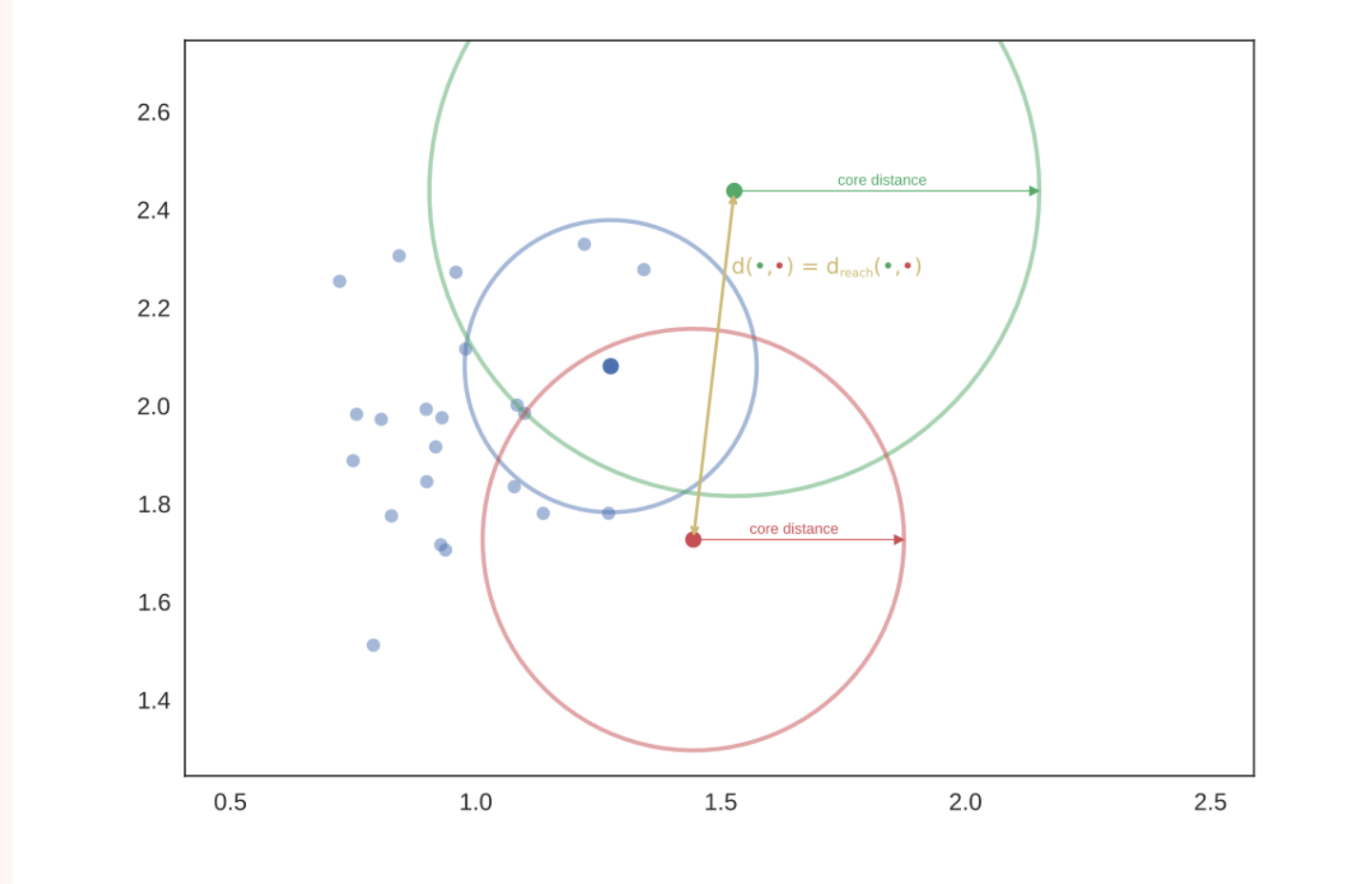


Figure 2. Visualization of the Distance Transformation

$$d_{mreach-k}(a, b) = \max\{core_k(a), core_k(b), d(a, b)\}$$

- The entire dataset transformed to **mutual reachability space** by defining the distance between any two points as  $d_{mreach-k}(a, b)$ .
- This transformation has the effect of **tightening** clusters, rendering the algorithm more robust to noise.
- This transformation also has the effect of closely **approximating the the hierarchy of level sets** of whatever true density distribution the points were sampled from [1].

## Preparation of the Minimum Spanning Tree

- A **minimum spanning tree** is a subset of the edges of a connected, edge-weighted undirected graph that **connects all the vertices without cycles** and **ensures minimum possible total edge weight**.
- Standard algorithms to do so include **Prim's [2]** and **Kruskal's [3]** algorithms.

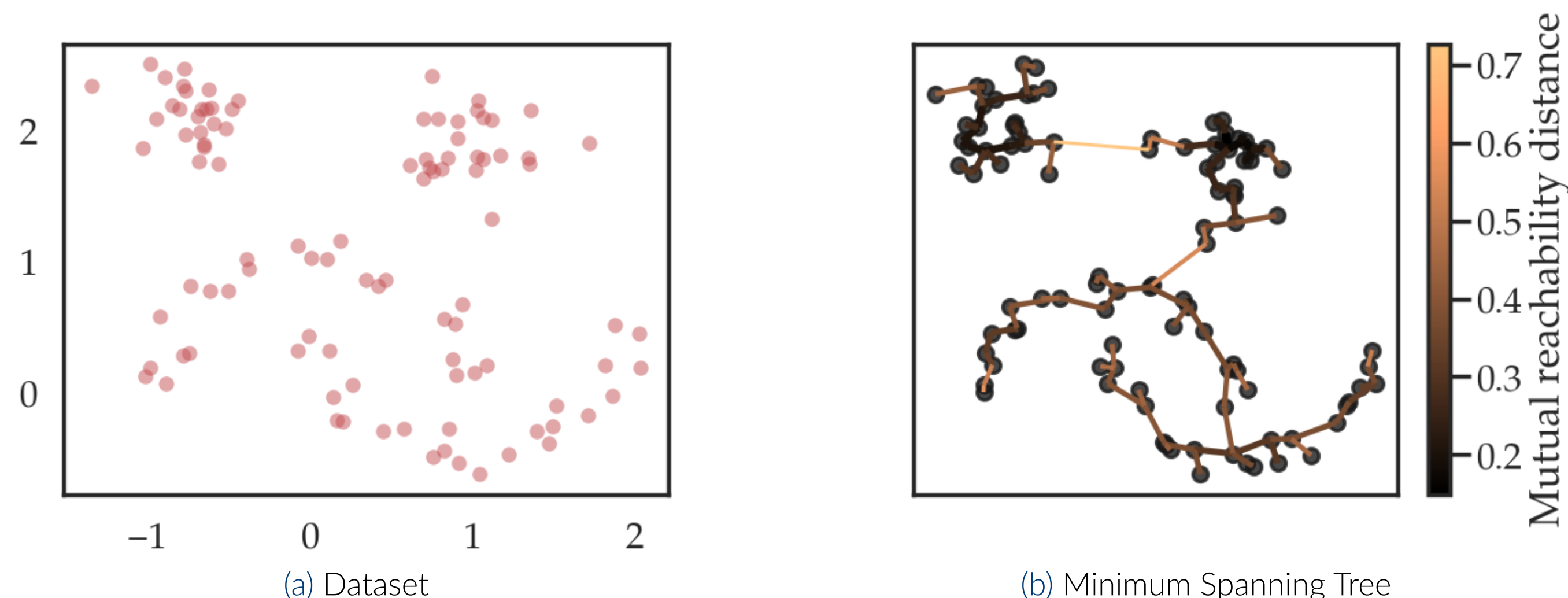


Figure 3. Conversion of the Dataset to the Minimum Spanning Tree

## Condensing the Cluster Tree

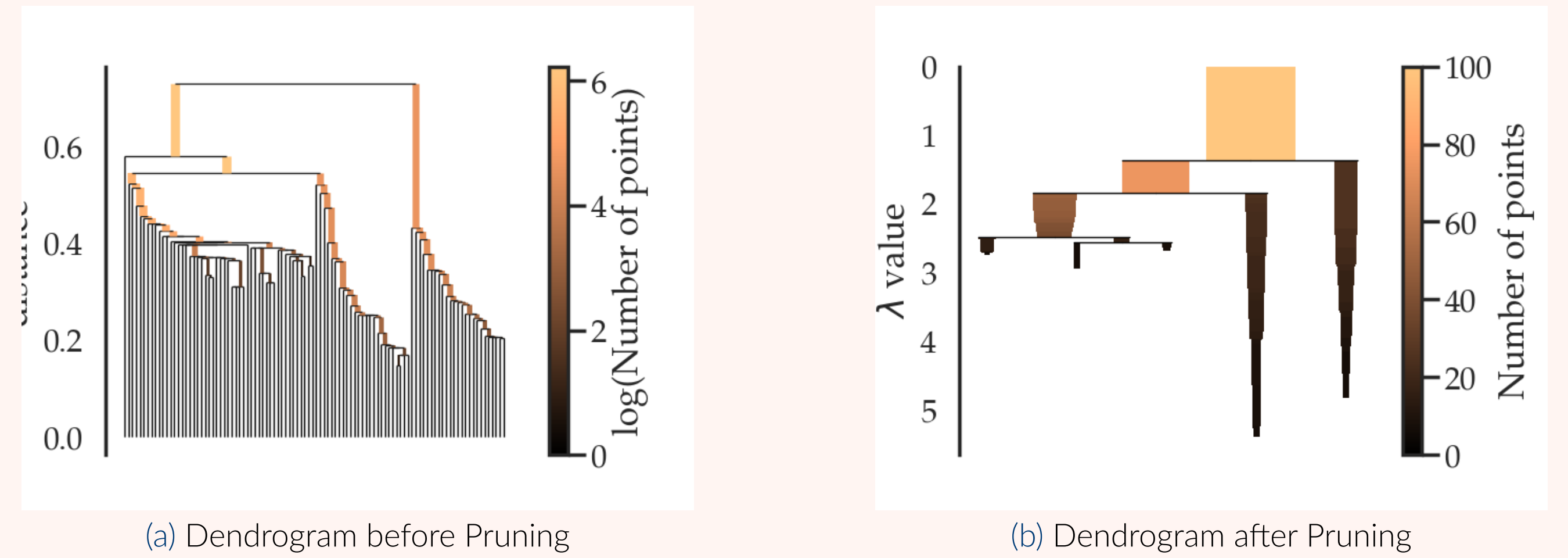


Figure 4. Pruning the Dendrogram based on Minimum Cluster Size

This step **condenses** down the large and complicated cluster hierarchy into a smaller tree.

- To do this, the algorithm takes in a parameter: the **minimum number of points that constitute a cluster (min\_cls\_size)**.
- Starting from the root, it is checked if one of the new clusters created by a split has **fewer points than min\_cls\_size**:
  - If yes, the larger cluster **retains the cluster identity**
  - If no, it is a **true cluster split**

## Extraction of Clusters

We want to choose clusters that have a **long lifetime**.

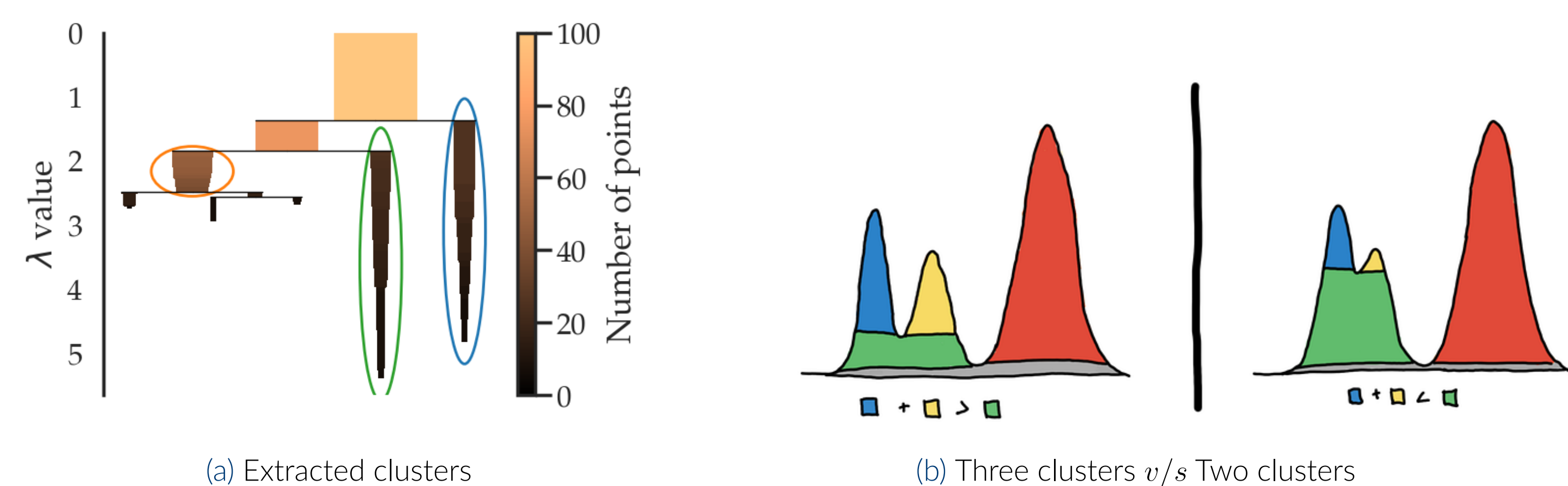


Figure 5. Extracting stable clusters

The **stability of a cluster** is defined as:  $S = \sum_{p \in \text{cluster}} (\lambda_p - \lambda_{\text{birth}})$

- $\lambda$  denotes  $\frac{1}{\text{distance}}$
- $\lambda_p$  denotes the  $\lambda$  value when the **point fell out of the cluster**.
- $\lambda_{\text{birth}}$  denotes the  $\lambda$  value when the **cluster split off and became independent**.
- Starting from the leaf, it is checked if  $S_{\text{left}}^i + S_{\text{right}}^i > S^{i-1}$ :
  - If yes, **the children are true clusters**
  - Otherwise, **the parent cluster is true**

## HDBSCAN in Action: An Application to Noisy, Nested Data

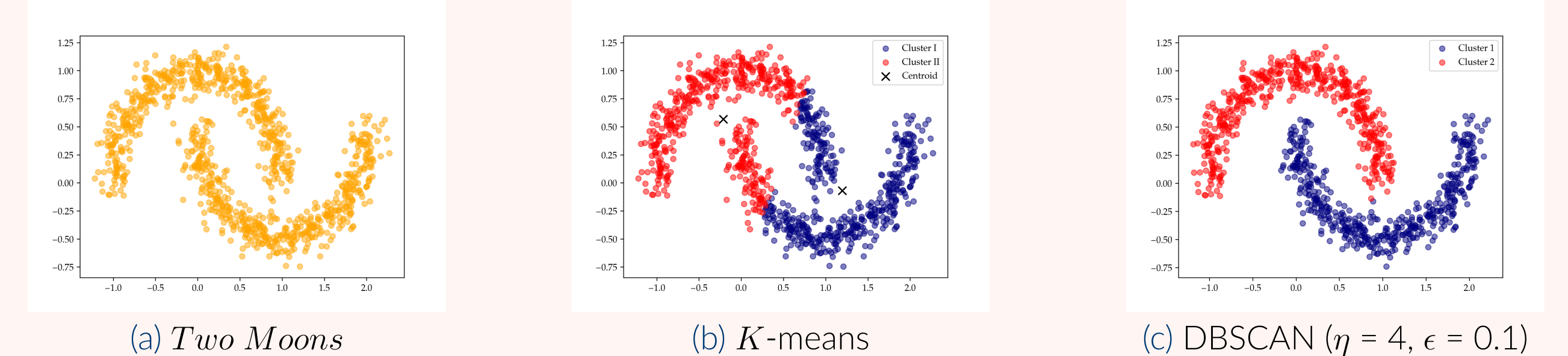


Figure 6. Performance of *K*-means & DBSCAN on *Two Moons*

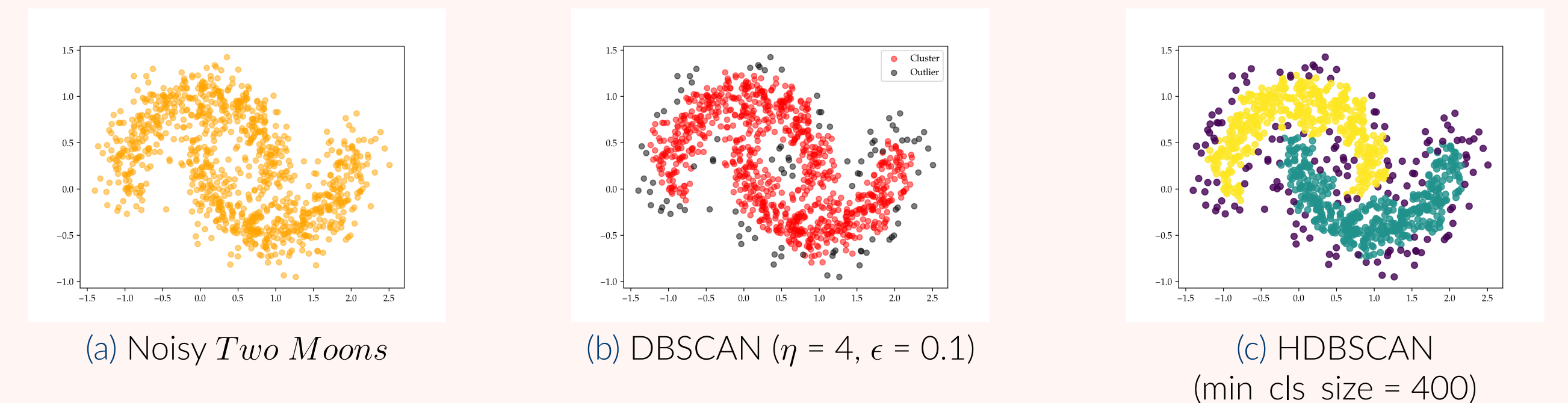


Figure 7. Performance of DBSCAN & HDBSCAN on Noisy *Two Moons*

## Closing Remarks

- K*-means fails to cluster nested datasets due to the Gaussian-ball assumption.
- DBSCAN handles nested datasets well. However, it is not robust to noise.
- HDBSCAN can handle noisy, nested data. It also performs well for clusters of varying densities.

## References

- J. Eldridge, M. Belkin, and Y. Wang, "Beyond hartigan consistency: Merge distortion metric for hierarchical clustering," in *Proceedings of The 28th Conference on Learning Theory*, vol. 40 of *Proceedings of Machine Learning Research*, pp. 588–606, PMLR, 2015.
- R. C. Prim, "Shortest Connection Networks And Some Generalizations," *Bell System Technical Journal*, vol. 36, pp. 1389–1401, Nov. 1957.
- J. B. Kruskal, "On the shortest spanning subtree of a graph and the traveling salesman problem," *Proceedings of the American Mathematical society*, vol. 7, no. 1, pp. 48–50, 1956.