



```
1  #include <Servo.h>
2  int pinled=13;
3  int servopin=9;
4  Servo Door;
5
6  int pinPin=3;
7  int val=0;
8
9  void setup()
10 {
11     pinMode(pinPin, INPUT);
12     pinMode(pinled, OUTPUT);
13     Door.attach(servopin);
14     Door.write(90);
15 }
16
17 void loop()
18 {
19     val=digitalRead(pinPin);
20     if(val==HIGH)
21     {
22         Door.write(0);
23         digitalWrite(pinled, HIGH);
24     }
25     else
26     {
27         Door.write(90);
28         digitalWrite(pinled, LOW);
29     }
30 }
31
```