# SANDEEP N MENON

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## **EDUCATION**

## New York University (NYU) Courant Institute of Mathematical Sciences

2022 - 2024

Masters in Computer Science

New York, USA

## National Institute of Technology Karnataka, Surathkal, India (NITK)

2014 - 2018

Bachelor of Technology in Computer Science

Karnataka, India

• President of Web Enthusiasts Club NITK. Organized mock interviews, CTFs, and Linux installation drives.

• Core executive member at IEEE NITK Student Chapter. Conducted hackathons and programming contests.

#### INDUSTRY EXPERIENCE

## Deep Learning Research Engineer | Deepen AI | Hyderabad, India

Sept 2020 - Jul 2022

- Developed 3D PointNet model that performs temporal smoothing of segmentation predictions over point cloud sequences, improving mean Intersection over Union (mIoU) by 20%.
- Built Sparse Point-Voxel CNN model for semantic segmentation of 3D point cloud sequences. Improved data annotation speed by 30% and achieved 76% mIoU score.
- Implemented object-aware anchor-free tracking for 2D visual object tracking and VPGNet model for lane segmentation and classification.
- Devised algorithm for targetless Camera-IMU and stereo camera calibration.

## Software Development Engineer II | Microsoft | Hyderabad, India

Jun 2018 - Sept 2020

- Co-authored new Machine Learning method to identify similar won deals in CRM context for Relationship Analytics in Dynamics 365, received patent award on the same.
- Developed GDPR query handling service for email insights infrastructure that handles up to 1 million daily service requests.
- Shipped Dynamics 365 sales insights connector in Microsoft Flows that manages more than 9 million monthly service requests.

#### SELECTED PUBLICATIONS AND PROJECTS

## Removing noise from Optical Coherence Tomography (OCT) Images [published]

Aug 2017 - May 2018

• **Sandeep N Menon**, VB Vineeth Reddy, A Yeshwanth, BN Anoop, and Jeny Rajan. A novel deep learning approach for the removal of speckle noise from optical coherence tomography images using gated convolution–deconvolution structure. In *Proceedings of 3rd International Conference on Computer Vision and Image Processing*, pages 115–126. Springer, Singapore, 2020

#### **Point Cloud Oversegmentation using Superpoint Graphs** | PyTorch, Boost

May - Jun 2021

• Adapted Superpoint Graph implementation to Argoverse point cloud dataset to achieve over-segmentation results of overall accuracy of 96% and Boundary Recall of 92%.

#### Online calibration of Surround-view Camera system | OpenCV, Sophus, Boost

Apr - May 2021

• Online calibration of the four surround-view camera systems by minimizing photometric loss in the overlapping regions of the bird-eye view. Calibration is possible with just one snapshot from the four cameras.

### **Asymmetric 3D Convolutions in Torchsparse** | *PyTorch*

Feb 2021

• Contributed Asymmetric 3D Convolutions implementation for the open source repository TorchSparse

#### **Virtual Gym Trainer** | *PyTorch*, *Azure*, *OpenCV*, *Pose Estimation* | Demo link

May - Jun 2019

• Platform for guiding users through trainer-specified exercises using automatic audio and visual cues.

#### TECHNICAL SKILLS

**Strengths**: Deep Learning (PyTorch, TensorFlow, Keras), Cloud Computing (Azure, Google Cloud Platform) **Languages/Platforms**: C++, C#, Python, Go, React, Docker, MongoDB, RocksDB, MySQL, Cosmos DB