Euan Judd

euan.judd@bristol.ac.uk euanjudd.github.io

Academic Interests			
Soft Rob	cs Morphological Computation Machine Learning Opt	timisation	
Education			
2017 – Present	2017 – Present PhD in Robotics and Autonomous Systems, FARSCOPE CRT, University of Bristol		
	hesis: Sensing Through the Body		
	or Helmut Hauser and Professor Jonathan Rossiter, University of	Bristol	
2010 – 2014 Bachelor of Engineering in Mechanical Engineering (1st Class), Universit		niversity of Aberdeen	
	Thesis: Flow-seaweed interactions at a blade scale: implications for bio-fuel aquaculture		
	Professor Vladimir Nikora, University of Aberdeen		

Publications

- E Judd, K M Digumarti, J Rossiter, and H Hauser, NeatSkin: A Discrete Impedance Tomography Skin Sensor, *IEEE International Conference on Soft Robotics (RoboSoft)* 2020.
- E Judd, G Soter, J Rossiter, and H Hauser, Sensing Through the Body-Non-Contact Object Localisation Using Morphological Computation, Lecture presentation at *IEEE International Conference on Soft Robotics (RoboSoft)* 2019.
- Y Liu, T Hu, H Ni, C Zhang, B Lin, and E Judd, Design of a PC-based Open Industrial Robot Control System Integrated with Real-Time Machine Vision, *IEEE WRC Symposium on Advanced Robotics and Automation (WRC SARA)*, 2018.

riojects and work Experience		
Sept 2019 – Jan 2020	Teaching Assistant – University of Bristol	
	EMAT10007: Introduction to Computer Programming (Python)	
Apr 2016 – Jan 2017	Management Trainee – Burgess Management Consultants Ltd	
	Developed a project management app using Visual Basic.	
June – Aug 2013	Summer Project – Aberdeen Biomedical Imaging Centre	
	Project: Switching Coil Design for a Fast Field Cycling MRI (FFC-MRI)	
Feb – April 2013	Semester Project – Environmental and Industrial Fluid Mechanics Group,	
	Aberdeen	

Awards and Achievements

Projects and Work Experience

- 1st Place, Scottish Hydraulics Study Group Undergraduate Prize, Institution of Civil Engineers, 2014
- Fundraised £3000 for Raleigh International and helped fundraised £1500 for Childreach International.

Project: Analysis of fluid flow over different riverbed compositions

Outreach and Voluntary Work

• Volunteer with Raleigh International, Borneo (June 2012 – September 2012) on building a kindergarten for disadvantaged children and a conservation project for Sun Bears.

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Technical Skills			
Tools and Technologies	Machine learning, image processing, computer-based simulation, modelling		
Software	MATLAB, COMSOL, SolidWorks, Python, C++, LabVIEW, Visual Basic		
Workshop Skills	3D printing, casting, laser cutting, soldering		

Hobbies

• Hiked a section of the Baekdudaegan mountain range in South Korea after presenting at RoboSoft