Stochastic Constraint Propagation for Mining Probabilistic Networks

originally presented at the 28th International Joint Conference on Artificial Intelligence (IJCAI), Macao 2019

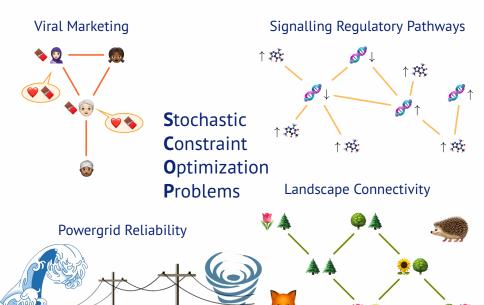
Anna Louise Latour, Behrouz Babaki, Siegfried Nijssen.



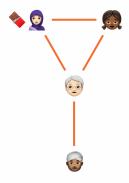


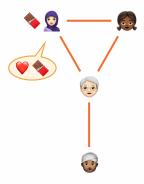
POLYTECHNIQUE Montréai

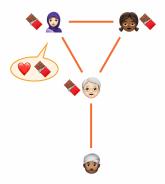


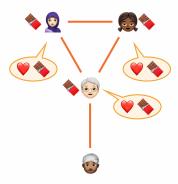


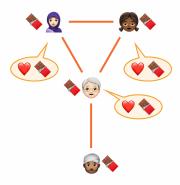


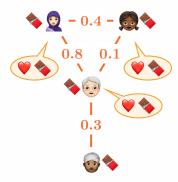




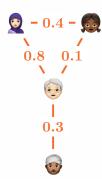


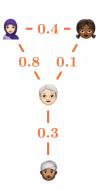






Properties





Properties

Probabilistic influence;



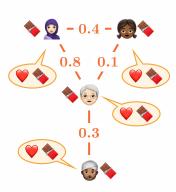
Properties

- Probabilistic influence;
- limited budget of free samples



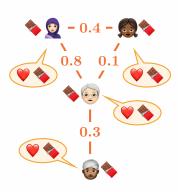
Properties

- Probabilistic influence;
- limited budget of free samples



Properties

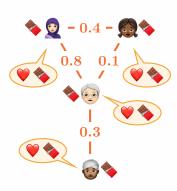
- Probabilistic influence;
- limited budget of free samples
- maximize expected # people buying your chocolate.



Properties

- Probabilistic influence;
- limited budget of free samples
 ;
- maximize expected # people buying your chocolate.

Exact solving is **NP-hard**

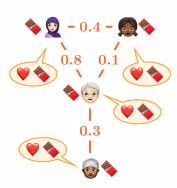


Properties

- Probabilistic influence;
- limited budget of free samples
 ;
- maximize expected # people buying your chocolate.

Exact solving is **NP-hard**

Exponential # of strategies;



Properties

- Probabilistic influence;
- limited budget of free samples
 ;
- maximize expected # people buying your chocolate.

Exact solving is **NP-hard**

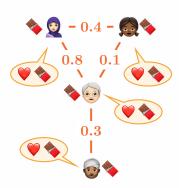
- Exponential # of strategies;
- Probabilistic inference is #P-complete.

David Kempe, Jon Kleinberg, and Éva Tardos

Maximizing the spread of influence through a social network

KDD 2003

Dan Roth The hardness of approximate reasoning Artif. Intell., 1996



Properties

- Probabilistic influence;
- maximize experiments
 buying your

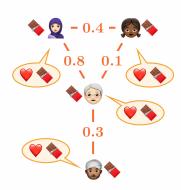
leverage
CP technology
(search & propagation)

Exact solving is **NP-hard**

- Exponential # of strategies;
- Probabilistic inference is #P-complete.

OscaR: Scala in OR, 2012 oscarlib.org

Dan Roth The hardness of approximate reasoning Artif. Intell., 1996



Properties

- Probabilistic influence;
 - limited **budget** of free samples
- maximize expe

#P-complete.

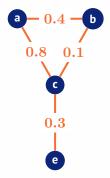
leverage
CP technology
(search & propagation)

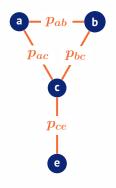
Exact solving is NP-hard

- Exponential # of strategies;
- Probabilistic inference is

OscaR: Scala in OR, 2012 oscarlib.org

leverage PP technology Dan Roth pproximate reasoning Artif. Intell., 1996

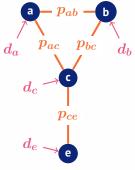




$$P(t_{xy} = 1) = p_{xy}$$

 $P(t_{xy} = 0) = (1 - p_{xy})$

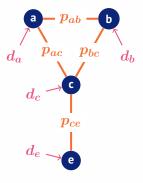
Boolean influence relationships are independent.



 $P(t_{xy} = 1) = p_{xy}$ $P(t_{xy} = 0) = (1 - p_{xy})$

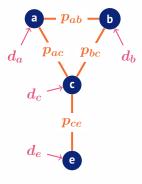
 $d_i \in \{0,1\}$

Boolean influence relationships are **independent**.



 $P(t_{xy} = 1) = p_{xy}$ $P(t_{xy} = 0) = (1 - p_{xy})$ $d_i \in \{0, 1\}$ **Boolean** influence relationships are **independent**.

Simplifying assumptions

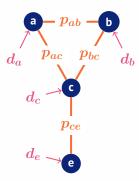


$$\begin{split} P(t_{xy} = 1) &= p_{xy} \\ P(t_{xy} = 0) &= (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{split}$$

Boolean influence relationships are **independent**.

Simplifying assumptions

 influence relationships are symmetric;

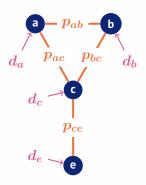


$$\begin{split} P(t_{xy} = 1) &= p_{xy} \\ P(t_{xy} = 0) &= (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{split}$$

Boolean influence relationships are **independent**.

Simplifying assumptions

- influence relationships are symmetric;
- if person i gets a free sample
 (d_i = 1), they will buy it in the
 future;



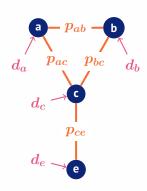
$$P(t_{xy} = 1) = p_{xy}$$

 $P(t_{xy} = 0) = (1 - p_{xy})$
 $d_i \in \{0, 1\}$

Boolean influence relationships are **independent**.

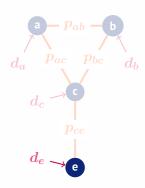
Simplifying assumptions

- influence relationships are symmetric;
- if person i gets a free sample
 (d_i = 1), they will buy it in the
 future;
- if person i buys chocolate and they have influence over j ($t_{ij}=1$), then j will buy chocolate.



$$\begin{split} P(t_{xy} = 1) &= p_{xy} \\ P(t_{xy} = 0) &= (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{split}$$

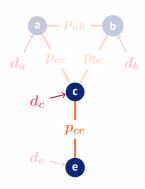
$$\phi_e =$$



$$P(t_{xy} = 1) = p_{xy}$$

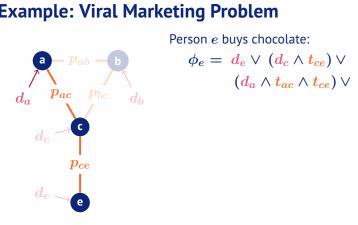
 $P(t_{xy} = 0) = (1 - p_{xy})$
 $d_i \in \{0, 1\}$

$$\phi_e = d_e \vee$$



$$\begin{aligned} P(t_{xy} &= 1) = p_{xy} \\ P(t_{xy} &= 0) = (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{aligned}$$

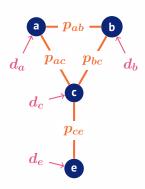
$$\phi_e = d_e \lor (d_c \land t_{ce}) \lor$$



$$P(t_{xy} = 1) = p_{xy}$$

 $P(t_{xy} = 0) = (1 - p_{xy})$
 $d_i \in \{0, 1\}$

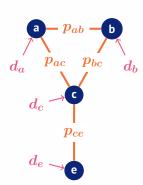
$$\phi_e = d_e \lor (d_c \land t_{ce}) \lor (d_a \land t_{ac} \land t_{ce}) \lor$$



$$P(t_{xy} = 1) = p_{xy}$$

 $P(t_{xy} = 0) = (1 - p_{xy})$
 $d_i \in \{0, 1\}$

$$egin{aligned} \phi_e = & d_e ee (d_c \wedge t_{ce}) ee \ & (d_a \wedge t_{ac} \wedge t_{ce}) ee \ & (d_b \wedge t_{bc} \wedge t_{ce}) ee \ & (d_a \wedge t_{ab} \wedge t_{bc} \wedge t_{ce}) ee \ & (d_b \wedge t_{ab} \wedge t_{ac} \wedge t_{ce}) ee \end{aligned}$$



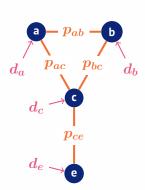
$$\begin{aligned} P(t_{xy} &= 1) = p_{xy} \\ P(t_{xy} &= 0) = (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{aligned}$$

Person e buys chocolate:

$$egin{aligned} \phi_e = & d_e ee (d_c \wedge t_{ce}) ee \ & (d_a \wedge t_{ac} \wedge t_{ce}) ee \ & (d_b \wedge t_{bc} \wedge t_{ce}) ee \ & (d_a \wedge t_{ab} \wedge t_{bc} \wedge t_{ce}) ee \ & (d_b \wedge t_{ab} \wedge t_{ac} \wedge t_{ce}) ee \end{aligned}$$

find strategy σ :

$$\argmax_{\pmb{\sigma}} \; \sum_{i \in \{a,b,c,e\}} P(\phi_i \mid \pmb{\sigma})$$



$$\begin{aligned} P(t_{xy} &= 1) = p_{xy} \\ P(t_{xy} &= 0) = (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{aligned}$$

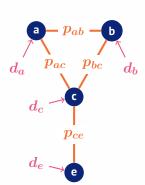
Person *e* buys chocolate:

$$egin{aligned} \phi_e = & d_e ee (d_c \wedge t_{ce}) ee \ & (d_a \wedge t_{ac} \wedge t_{ce}) ee \ & (d_b \wedge t_{bc} \wedge t_{ce}) ee \ & (d_a \wedge t_{ab} \wedge t_{bc} \wedge t_{ce}) ee \ & (d_b \wedge t_{ab} \wedge t_{ac} \wedge t_{ce}) ee \end{aligned}$$

find strategy σ :

$$rg \max_{m{\sigma}} \; \sum_{i \in \{a,b,c,e\}} P(\phi_i \mid m{\sigma})$$

subject to: $\sum_{i \in \{a,b,c,e\}} d_i \leq k$



$$\begin{aligned} P(t_{xy} = 1) &= p_{xy} \\ P(t_{xy} = 0) &= (1 - p_{xy}) \\ \frac{d_i}{} &\in \{0, 1\} \end{aligned}$$

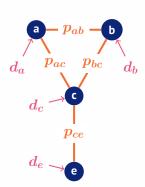
Person *e* buys chocolate:

$$egin{aligned} \phi_e = & d_e ee (d_c \wedge t_{ce}) ee \ & (d_a \wedge t_{ac} \wedge t_{ce}) ee \ & (d_b \wedge t_{bc} \wedge t_{ce}) ee \ & (d_a \wedge t_{ab} \wedge t_{bc} \wedge t_{ce}) ee \ & (d_b \wedge t_{ab} \wedge t_{ac} \wedge t_{ce}) ee \end{aligned}$$

repeatedly solve:

$$\sum_{i \in \{a,b,c,e\}} P(\phi_i \mid {\color{red} m{\sigma}}) > {\color{red} m{ heta}}$$

subject to:
$$\sum_{i \in \{a,b,c,e\}} d_i \leq k$$



$$P(t_{xy} = 1) = \frac{p_{xy}}{p_{xy}}$$

 $P(t_{xy} = 0) = (1 - p_{xy})$
 $d_i \in \{0, 1\}$

Person e buys chocolate:

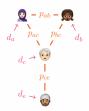
$$egin{aligned} \phi_e = & d_e ee (d_c \wedge t_{ce}) ee \ & (d_a \wedge t_{ac} \wedge t_{ce}) ee \ & (d_b \wedge t_{bc} \wedge t_{ce}) ee \ & (d_a \wedge t_{ab} \wedge t_{bc} \wedge t_{ce}) ee \ & (d_b \wedge t_{ab} \wedge t_{ac} \wedge t_{ce}) ee \end{aligned}$$

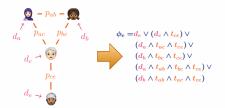
repeatedly solve:

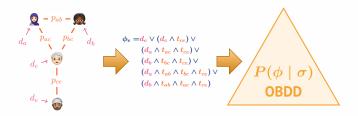
$$\sum_{i \in \{a,b,c,e\}} P(\phi_i \mid {\color{red} m{\sigma}}) > {\color{blue} m{ heta}}$$

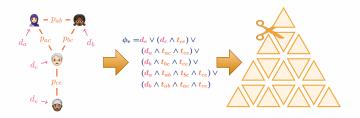
subject to: $\sum_{i \in \{a,b,c,e\}} d_i \leq k$

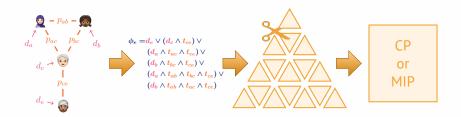
Existing (generic) method

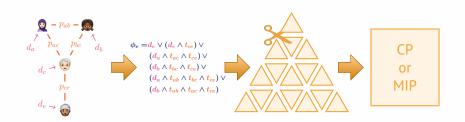








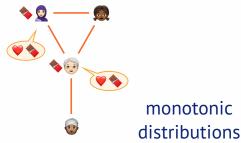




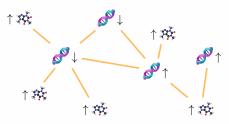
Decomposition method.

Observation 1: existing method does **not guarantee** Generalized Arc Consistency (**GAC**) → **inefficient**;

Viral Marketing



Signalling Regulatory Pathways



Landscape Connectivity



Observation 1: existing method does **not guarantee** Generalized Arc Consistency (**GAC**) → **inefficient**;

Observation 2: probability distribution is **monotonic**;

Observation 1: existing method does **not guarantee** Generalized Arc Consistency (**GAC**) \rightarrow **inefficient**;

Observation 2: probability distribution is **monotonic**;

Recall: optimization is repeated **constraint solving**:

solve
$$\sum_{\phi \in \Phi} P(\phi \mid \sigma) > \theta$$
 for increasing θ ;

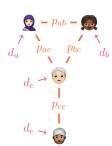
Observation 1: existing method does **not guarantee** Generalized Arc Consistency (**GAC**) \rightarrow **inefficient**;

Observation 2: probability distribution is **monotonic**;

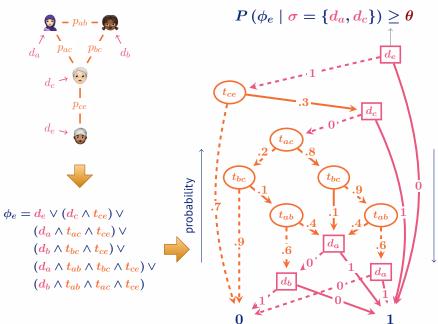
Recall: optimization is repeated **constraint solving**:

solve
$$\sum_{\phi \in \Phi} P(\phi \mid \sigma) > \theta$$
 for increasing θ ;

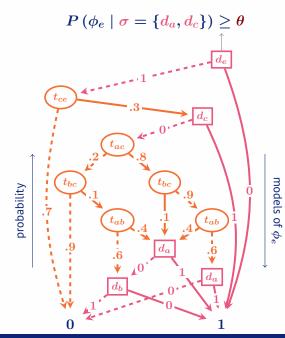
GOAL: create constraint propagation algorithm for Stochastic Constraints on Monotonic Distributions (SCMDs), which quarantees GAC.

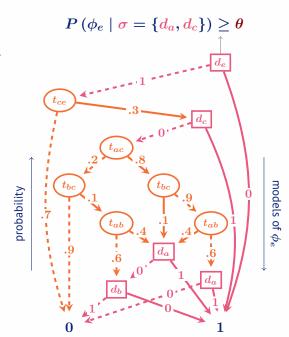


$$\phi_{e} = d_{e} \lor (d_{c} \land t_{ce}) \lor (d_{a} \land t_{ac} \land t_{ce}) \lor (d_{b} \land t_{ab} \land t_{bc} \land t_{ce}) \lor (d_{b} \land t_{ab} \land t_{ac} \land t_{ce})$$

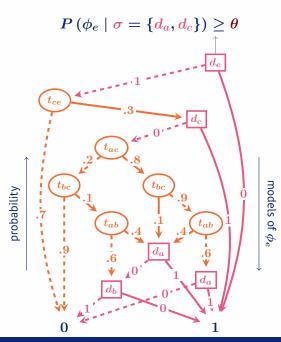


Ordered Binary Decision Diagram (**OBDD**) encodes **probability distribution**



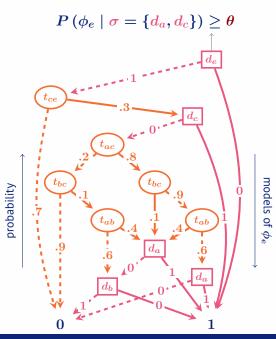


solve
$$\sum_{\phi \in \Phi} P(\phi \mid \sigma) \geq \theta$$



solve
$$\sum_{\phi \in \Phi} P(\phi \mid {\color{red} \sigma}) \geq {\color{red} heta}$$

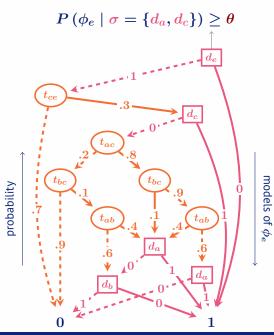
Use OBDD to evaluate strategy σ . Complexity of one sweep: O(m), with $m = |\mathsf{OBDD}|$.



solve
$$\sum_{\phi \in \Phi} P(\phi \mid {\color{red} \sigma}) \geq {\color{red} heta}$$

Use OBDD to evaluate strategy σ . Complexity of one sweep: O(m), with $m = |\mathsf{OBDD}|$.

Naïve method has complexity $O(m \cdot n)$, where n is the number of unbound variables

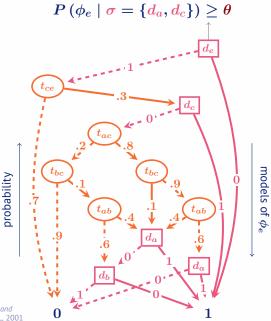


solve
$$\sum_{\phi \in \Phi} P(\phi \mid {\color{red} \sigma}) \geq {\color{red} heta}$$

Use OBDD to evaluate strategy σ . Complexity of one sweep: O(m), with $m = |\mathsf{OBDD}|$.

Smart, incremental (full sweep) method has complexity O(m+n), using derivatives.

Adnan Darwiche. On the tractable counting of theory models and its application to belief revision and truth maintenance. JANCL, 2001

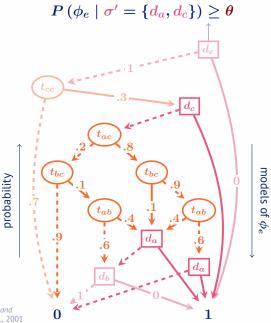


solve
$$\sum_{\phi \in \Phi} P(\phi \mid {\color{red} \sigma}) \geq {\color{red} heta}$$

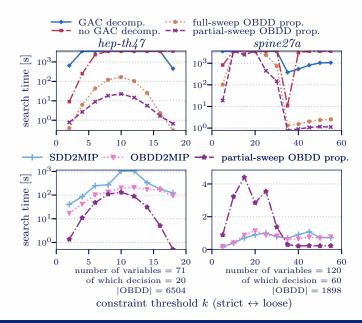
Use OBDD to evaluate strategy σ . Complexity of one sweep: O(m), with $m = |\mathsf{OBDD}|$.

Smart, incremental (partial sweep) method has complexity O(m+n), using derivatives.

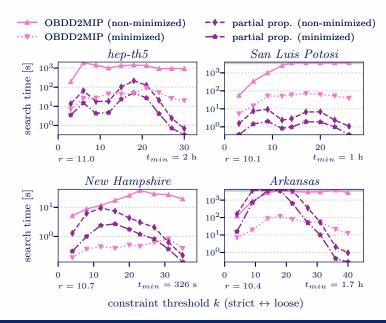
Adnan Darwiche. On the tractable counting of theory models and its application to belief revision and truth maintenance. JANCL, 2001



SCMD propagator vs existing methods



Scalability of SCMD propagator vs MIP



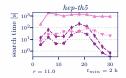
Main contribution

A new global constraint propagator for Stochastic Constraints on Monotonic Distributions (SCMDs) which:



- guarantees GAC;
- has linear complexity;
- outperforms existing CP-based methods and complements MIP-based methods;
- scales better with OBDD size than existing MIP-based methods.

contact: a.l.d.latour@liacs.leidenuniv.nl
code & more results: github.com/latower/SCMD



new work: D. Fokkinga, A.L.D. Latour, M. Anastacio, S. Nijssen, H. Hoos. *Programming a Stochastic Constraint Optimisation Algorithm, by Optimisation*. IJCAI Data Science meets Optimization workshop, 2019. ada.liacs.nl/papers/FokEtAl19.pdf

References I



Randal E. Bryant.

Graph-based algorithms for Boolean function manipulation. IEEE Trans. Computers, 1986



Adnan Darwiche.

On the tractable counting of theory models and its application to belief revision and truth maintenance.

JANCL. 2001



Adnan Darwiche.

A differential approach to inference in Bayesian Networks. ACM 2003



Luc De Raedt, Angelika Kimmig, and Hannu Toivonen A Probabilistic Prolog and its Application in Link Discovery. IJCAI 2007



David Kempe, Jon Kleinberg, and Éva Tardos

Maximizing the Spread of Influence Through a Social Network.

KDD 2003

References II



Anna L.D. Latour, Behrouz Babaki, Anton Dries, Angelika Kimmig, Guy Van den Broeck, and Siegfried Nijssen.

Combining Stochastic Constraint Optimization and Probabilistic Programming: From Knowledge Compilation to Constraint Solving.

CP 2017



Anna Louise D. Latour, Behrouz Babaki, and Siegfried Nijssen. Stochastic Constraint Propagation for Mining Probabilistic Networks. IJCAI 2019



OscaR: Scala in I

OscaR: Scala in OR. 2012



Francesca Rossi, Peter van Beek, and Toby Walsh, editors *Handbook of Constraint Programming* Elsevier. 2006



Dan Roth
On the Hardness of Approximate Reasoning
Al 1996

References III



Toby Walsh Stochastic Constraint Programming ECAI 2002

Theme by Joost Schalken. Updated by Pepijn van Heiningen & Anna Louise Latour.

Acknowledgements

We thank Hélène Verhaeghe for her input and suggestions. This work was supported by the Netherlands Organisation for Scientific Research (NWO). Behrouz Babaki is supported by a postdoctoral scholarship from IVADO through the Canada First Research Excellence Fund (CFREF) grant.