(1) 假设f是一个凸函数,证明f的全局最小点的集合是一个凸集。 Denote S as the set of all global minima of f, need to prove that S is convex.  $\forall x^*, y^* \in S$ , since J is a convex function,  $\forall \lambda \in (0.1)$  $f(\lambda x^* + (1-\lambda) y^*) \leq \lambda f(x^*) + (1-\lambda) f(y^*)$ (1) Meanwhile, note that  $x^*$ ,  $y^*$  are global minima,  $\forall x, y \in dom(f)$ ,  $\exists M$ .  $f(x^*) \leq f(x), \ f(y^*) \leq f(y), \ f(x^*) = f(y^*) = M$ Let  $x = \lambda x^* + (1-\lambda)y^* \in \text{dom}(f)$ ,  $y = y^* \in \text{dom}(f)$ , then  $f(\lambda x^* + (1-\lambda)y^*) \ge f(x^*)$  $= \lambda f(x^*) + (1-\lambda) f(y^*)$ From equation (1), (2) we know  $f(\lambda x^* + (1-\lambda) y^*) = \lambda f(x^*) + (1-\lambda) f(y^*)$ Meaning that  $\lambda x^* + (1-\lambda) y^* \in S$ , therefore S is convex. (2) 证明函数 $f(x) = 8x_1 + 12x_2 + x_1^2 - 2x_2^2$ 只有一个稳定点,并且它既不是一个最大点也 不是一个最小点,而是一个鞍点。  $\frac{\partial f(x)}{\partial x_1} = 2x_1 + 8 - \frac{\partial f(x)}{\partial x_2} = -4x_2 + 12 \Rightarrow \nabla f(x) = (2x_1 + 8, -4x_2 + 12)$ Let  $\nabla f(x) = 0$ , he have  $|\Re x = -4$ , so f has only 1 stationary point  $|\Re x = 3$ Note that  $\nabla^2 f_{(X)} = H = \begin{pmatrix} 2 & 0 \\ 0 & 4 \end{pmatrix}$  Let  $\chi = (|_{(1)}|_{1})$ , then  $\chi^T H \chi = -2 < 0$ Let  $\chi = (|_{(0)}|_{1})$ , then  $\chi^T H \chi = 2 > 0$ Therefore \$\sigma^2 fix is an indefinite matrix, so (\frac{1}{6}, 3) is a saddle point. (3) 考虑函数 $f(x_1,x_2) = (x_1 + x_2^2)^2$ ,在点x = (1,0)的位置上考虑搜索方向p = (-1,1),证明 p为一个下降方向,并且找到这个方向上的精确线搜索步长。  $\nabla f(\chi_{1},\chi_{2}) = (2(\chi_{1}+\chi_{2}^{2}), 4\chi_{2}(\chi_{1}+\chi_{2}^{2}))$ Note that  $\nabla f(\chi_{1},\chi_{2})^{T} \rho \Big|_{(\chi_{1},\chi_{2}) = (1,0)} = (2,0)^{T}(1,1) = -2 < 0, 50, \rho = (1,1) \text{ is a}$ descent direction. To solve for step  $d_k$ , we aim to optimize:  $d_k^* = \arg\min f(x + dp)$ Let  $f(\lambda) = f(x+ap) = f(1-a,d) = (1-a+a^2)^2$ , then  $\frac{\partial g(d)}{\partial d} = 2(1-d+d^2)(-1+2d) = 0 \Rightarrow d = \frac{1}{2}$ Obviously 9(2) is convex, so the step of exact linear search is  $d = \frac{1}{2}$ 

(4) 已知序列 $x_k = \frac{1}{k!}$ ,该序列是二次收敛,还是超线性收敛?

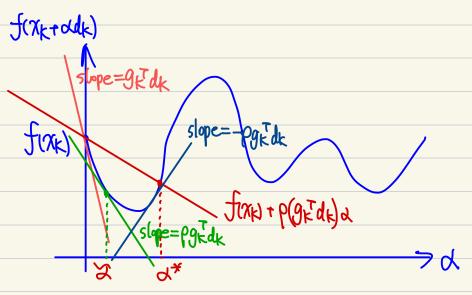
One can easily tell that 
$$\lim_{k\to\infty} \Re k = 0$$
. To study the convergence of  $|\Re k|$ , we look into 
$$\lim_{k\to\infty} \frac{|\Re k+1|}{|\Re k+1|} = 0$$

So [XK] Converges to 0 superbnearly

$$\lim_{k \to \infty} \frac{|\chi_{k+1} - 0|}{|\chi_{k} - 0|^2} = \lim_{k \to \infty} \frac{(k!)^2}{(k+1)!} = \lim_{k \to \infty} \frac{k!}{k+1} = \infty$$

So (XK) does not converge guadratically

(5) 证明: 假设f连续可微,  $f(x_k + \alpha d_k)$ 在 $\alpha > 0$ 时有下界, 且 $g_k^{\mathsf{T}} d_k < 0$ , 则必存在 $\alpha_k$ 使得  $x_k + \alpha_k d_k$ 满足 Wolfe 准则和强 Wolfe 准则。



By Taylor expansion,  $f(x_k+dx_k) = f(x_k) + d \nabla f(x_k)^T d_k + o(d||d_k||)$  at d=0, the tangent slope of  $f(x_k+dd_k)$  is

Since fec, 4270, 3870, 5.t.

i.e., fixk+d'dk) < L'E+d'>f(xk) dk+fixk), Omitting the 2'E term, for ocp
he have

 $f(x_k+d'dk) < f(x_k)+d' \nabla f(x_k)^T d_k < f(x_k)+\rho (\nabla f(x_k)^T d_k) d'$ Note that When  $d' \rightarrow \infty$ ,  $f(x_k)+\rho \nabla f(x_k)^T d_k d' \rightarrow -\infty$  since  $\nabla f(x_k^T) d_k < 0$ While  $f(x_k+dd_k)$  has a (over bound when d>0, i.e.  $\exists M \in \mathbb{R}$  s.t  $f(x_k+dd_k) \geq M$ ,  $\forall d \in (0,+\infty)$ 

therefore, \(\precedef{\precedef}\) Sufficient large \(\precedef{\precedef}\) \(\precedef{\precedef}\), \(\precedef{\precedef}\), \(\precedef{\precedef}\), \(\precedef{\precedef}\).

 $f(x_k + a''d_k) = f(x_k) + \rho \nabla f(x_k)^T d_k a''$ By the Intermediate value thereon,  $\exists a^* \in (a', a'')$ , s.t.  $f(x_k + a^*d_k) = f(x_k) + \rho \nabla f(x_k)^T d_k a^*$ Denote  $R(a) = f(x_k + ad_k) - [f(x_k) + \rho \nabla f(x_k)^T d_k a]$  note that R(o) = o,  $R(a^*) = o$ , by Rolle's theorem,  $\exists \alpha \in (o, a^*)$  s.t.

 $R'(3^*) = \nabla f(3_{k+1} + 3_{dk})^T d_k - \rho \nabla f(3_{k})^T d_k = 0$   $\Rightarrow \qquad \nabla f(3_{k+1} + 3_{dk})^T d_k = \rho \nabla f(3_{k})^T d_k$ Therefore, for  $0 < \rho < \sigma < 1$ , given that  $\nabla f(3_{k})^T d_k < 0$   $|\nabla f(3_{k+1} + 3_{dk})^T d_k| = \rho |\nabla f(3_{k})^T d_k|$   $< \sigma |\nabla f(3_{k+1} + 3_{dk})^T d_k|$   $= -\sigma \nabla f(3_{k}) d_k$ 

Meaning that  $\exists d_k \in (0, d^*)$  s.t.  $x_k + d_k d_k$  sortisfies the strong Wolfe Condition ( Wolfe condition included)