# Ali Safi

© Golpayegan, Isfahan, Iran • ⋾⊠ Ali\_Safi@alumni.iust.ac.ir • © +98 (937) 806-8264 Website: ControlScience.ir/about ७ • Linkedin: Linkedin.com/in/Safi-Ali ७ • Github: https://github.com/A-Safi ७

#### **SUMMERY**

- Experienced researcher in Mechanical and Control Engineering.
- Specialized in applying control theories to practical situations.
- Proficient in programming languages such as MATLAB, Arduino, and Python.
- Skilled in electrical circuit design and fluent in English as a second language.
- Strong in presentation, problem-solving, and committed to achieving results.

#### **EDUCATION**

## Iran University of Science and Technology, Tehran, Iran

Sep 2018 – Feb 2021

- M.Sc. in Mechanical Engineering (Control, Dynamics and Vibrations)
  - Thesis: A New Controller Design Technique for Piecewise Affine Hybrid Systems
  - · Adviser: Dr. Esmaeel Khanmirza
  - Focus: Hybrid dynamical systems, Hybrid control
  - GPA: 18.06 / 20

## Golpayegan University of Technology, Golpayegan, Isfahan, Iran

Sep 2014 – Jun 2018

- B.Sc. in General Mechanical Engineering
  - Thesis: Control Design and Implementation of a Ball and Beam Device
  - · Adviser: Dr. Mostafa Nasiri
  - GPA: 18.96 / 20

#### **INTERESTS**

- Model Predictive Control (MPC)
- Linear Matrix Inequality (LMI)
- Sliding Mode Control (SMC)
- Adaptive Control

- Hybrid Dynamical Systems
- Robotics and Mechatronics
- Internet of Things (IoT)
- Automation

#### RESEARCH EXPERIENCE

## **Research And Development Specialist**

Jul 2023 - Present

- Dolfa Robotics
  - Principal Investigator: Maryam Jamali

## **Research And Development Engineer**

Jan 2021 - Jun 2021

- Electro Samane Alvand (ELSA)
  - Design, Construction, Calibration and Software Development of an Electric Motor Testing Dynamometer
  - Parameter Estimation of a Single-Phase Axial Flux Induction Motor (Hardware and Software Development)
  - Chief Executive Officer: Mohsen Fayazi

Research Assistant Winter 2020

- Iran University of Science and Technology
  - Building and Controlling of an Inverted Pendulum Device
  - Supervisor: Dr. Esmaeel Khanmirza

In cooperation with Iran's National Elites Foundation

#### **Internet of Things Developer**

Sep 2019 – Mar 2020

- Pars System Energy
  - Designing a Temperature and Pressure Monitoring System of a Powerhouse
  - Chief Executive Officer: Dr. Saeed Jani

## **Cooperative Education Student**

Fall 2019

- Iran University of Science and Technology
  - Routing and Controlling of Two-wheeled Mobile Robots and Avoiding Collisions by Using Model Predictive Control and Optimal Feedback Control
  - Supervisor: Dr. Esmaeel Khanmirza In cooperation with Iran's National Elites Foundation

#### TEACHING EXPERIENCE

Teaching Assistant Winter 2020

 Iran University of Science and Technology Adaptive Control
 In cooperation with Iran's National Elites Foundation

## **Teaching Assistant**

Golpayegan University of Engineering
 Industrial Automation
 Dynamics
 Design of Machine Components (1)
 Engineering Mathematics
 Engineering Technical Drawing (1)
 Winter 2016
 Winter 2016

#### **HONORS**

2 Times Winner of The Iran's National Elite Foundation Scholarship Award

Jan 2019, Jan 2020

1st Rank, Achieving The Highest GPA Among all Mechanical Engineering (Control, Dynamics and Vibration)
 Graduate Students

Iran University of Science and Technology, Tehran, Iran.

- 1st Rank, Achieving The Highest GPA Among all University Mechanical Engineering Students
   Golpayegan University of Technology, Golpayegan, Isfahan, Iran.
- 1st Team Rank, MATLAB Programming Contest Iran University of Science and Technology, Tehran, Iran.

2019

 Entrance to Iran University of Science and Technology Without Entrance Exam for Master's Degree as a Recognized Student.

## **PUBLICATIONS**

## **JOURNALS**

- [1] A. Safi, A. Taghavian and E. Khanmirza, A review on benchmarks Examples for dynamical hybrid systems controller synthesis to facilitate its selection process. *Space Science, Technology and Applications*, 2023. 2(2): p. 115-134. (Persian)
- [2] Nasiri, M. and A. Safi, Stability analysis of real-time hybrid simulation in consideration of time delays of actuator and shake table using delay differential equations. *Journal of Mechanical Science and Technology*, 2019. 33(4): p. 1489-1499.
- [3] Nasiri, M. and A. Safi, Stability Anaysis of Real-time Hybrid Simulation for a Multi-story Structure Considering Time-delay of Hydrolic Actuator. *Amirkabir Journal of Civil Engineering*, 2019. 51(3): p. 391-400. (Persian)

#### CONFERENCES

[4] A, Safi, and E. Khanmirza. A Criticism of Position Control of the Inverted Pendulum with Biased Angle Measurements Using Double-Loop PID. in 2020 Advances in Science and Engineering Technology International Conferences (ASET). 2020, Dubai, United Arab Emirates.

[5] A, Safi, F. Namdarpour and E. Khanmirza. On the effectiveness of Stable Model Predictive vs. Adaptive Fuzzy Sliding Mode Method in synthesizing the controller for High-Speed Trains. in 2021 9th RSI International Conference on Robotics and Mechatronics (ICRoM), Tehran, Iran, Islamic Republic of. 2021, pp. 293-300 ©

#### **PROJECTS**

- Constrained optimization-based control of nonlinear input affine systems
  - Under review paper submitted to Journal of Dynamic Systems Measurement and Control
- The design of dynamic predictive control for networked control systems subject to latency and packet loss
  - Under review paper submitted to Journal of systems and control engineering
- Constrained computational hybrid controller for input affine hybrid dynamical systems
  - Under review paper submitted to Journal of the Franklin Institute
- Distributed control of second-order multi-agent systems with bidirectional meshed topology, considering communication delays
- Control design and implementation of a three tank experimental device
- Implementation of modern control and feedback linearization methods on quadrotors

## **ENGLISH TEST**

Full Professional Proficiency
 The TOEFL exam is scheduled for December 2023

#### **SKILLS**

- Type Setting
   LATEX Microsoft Office
- Programming Language
   MATLAB C++ (Arduino variant) Python Ladder Logic
- Softwares

Git • MATLAB • Visual Studio Code • Arduino IDE • Simulink • Catia • SolidWorks • Proteus Design Suite

Other Skills

Communication Protocols (UDP, TCP/IP, Modbus, I2C) • Programmable Logic Controller (PLC) • WordPress • Adobe Photoshop • Adobe Premiere

■ Soft Skills

Dedication to Results • Eager to Learn • Effective Communication • Crafting Practical Solutions • Collaborative Team Member • Academic Writing Pro

## REFERENCES

## ■ Dr. Esmaeel Khanmirza

Associate Professor in Mechanical Engineering
Iran University of Science and Technology

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## Dr. Mostafa Nasiri

Assistant Professor in Mechanical Engineering Golpayegan University of Technology *□* Nasiri@gut.ac.ir

[CV compiled on 2023-09-24 for University Application]