$$k$$
 $m$ 
 $c$ 

$$m\ddot{x} + c\dot{x} + kx = 0$$

$$\ddot{x} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{c}{m} \end{bmatrix} \ddot{x} + \begin{bmatrix} 0 \\ \frac{1}{m} \end{bmatrix} u$$

$$m, c, k = 1$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \tilde{x}$$

$$T_s = 0.05 \,\mathrm{sec}$$
  
Discretization in Time

$$x(t+1) = Ax(t) + Bu(t)$$
$$y(t+1) = Cx(t)$$

$$Y = \begin{bmatrix} y(t+1) \\ \vdots \\ y(t+N) \end{bmatrix} \qquad U = \begin{bmatrix} u(t+1) \\ \vdots \\ u(t+N) \end{bmatrix}$$

$$G = \begin{bmatrix} CA \\ \vdots \\ CA^n \end{bmatrix} \quad H = \begin{bmatrix} 0 & 0 & \dots & 0 \\ CB & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ CA^{N-2}B & CA^{N-3}B & \dots & 0 \end{bmatrix} = \begin{bmatrix} h(1) & 0 & \dots & 0 \\ h(2) & h(1) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ h(N) & h(N-1) & \dots & h(1) \end{bmatrix} \quad F = \begin{bmatrix} h(2) \\ h(3) \\ \vdots \\ h(N+1) \end{bmatrix}$$

$$Y = Gx + Fu + HU$$

$$J(Y,U) = Y^T Y + r U^T D^T D U$$

min 
$$J(Y,U)$$

$$sbj: Y = Gx + Fu + HU$$

$$J = (Gx + Fu + HU)^{T} (Gx + Fu + HU) + rU^{T}D^{T}DU$$

$$J = ((Gx + Fu)^{T} + U^{T}H^{T})(Gx + Fu + HU) + rU^{T}D^{T}DU$$

$$J = (Gx + Fu)^{T} (Gx + Fu) + U^{T}H^{T}HU + (Gx + Fu)^{T}HU + U^{T}H^{T} (Gx + Fu) + rU^{T}D^{T}DU$$

$$J = (Gx + Fu)^{T} (Gx + Fu) + U^{T} (H^{T}H + rD^{T}D)U + 2(Gx + Fu)^{T}HU$$

$$J = \frac{1}{2}U^{T} (H^{T}H + rD^{T}D)U + (Gx + Fu)^{T}HU$$

$$J = \frac{1}{2}U^{T}QU + f^{T}U \rightarrow Q = H^{T}H + rD^{T}D, f = H^{T} (Gx + Fu)$$

$$\frac{dJ}{dU} = 0 \rightarrow QU + f^{T} = 0 \rightarrow U = -Q^{-1}f^{T}$$