

Note on the Turning function and Non-linear term

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1 What is the Non-linear Term

$$\int_{\phi'=-\pi}^{\pi} S\left(T(x, \phi', \phi)\right) u(x, \phi', t) d\phi' \quad (1.1)$$

S : saturation function

$T(x, \phi, \phi')$ is the rate of individuals at position \vec{x} changes their direction from ϕ' to ϕ .

The turning rate function

$$T(x, \phi, \phi') = T_{al}(x, \phi, \phi') + T_r(x, \phi, \phi') + T_a(x, \phi, \phi') \quad (1.2)$$

The turning rate function under **Alignment, Repulsion and Attraction** will be listed in the following subsection.

The functions inside of each turning function is:

1. Distance Kernel

$$K_j^d(\mathbf{x}) = \frac{1}{A_j} e^{-\left(\sqrt{x^2+y^2}-d_j\right)^2/m_j^2}$$

with $j = r, al, a$ and d_j describe the repulsion ($j = r$), alignment ($j = al$) and attraction ($j = a$) interaction ranges, and m_j gives the width of these ranges. A_j ensures that each kernel integrates to 1 :

$$A_j = \pi m_j \left(m_j e^{-d_j^2/m_j^2} + \sqrt{\pi} d_j + \sqrt{\pi} d_j \operatorname{erf}\left(d_j/m_j\right) \right)$$

where erf is error rate function.

2. Orientation Kernel

For alignment, the K_{al}^o is:

$$K_{al}^o(\theta; \phi) = \frac{1}{2\pi}(-\cos(\phi - \theta) + 1)$$

For the attraction and repulsion, the Kernel is:

$$K_a^o(\mathbf{s}; \mathbf{x}, \phi) = \frac{1}{2\pi}(-\cos(\phi - \psi) + 1)$$

$$K_r^o(\mathbf{s}; \mathbf{x}, \phi) = \frac{1}{2\pi}(\cos(\phi - \psi) + 1)$$

3. Possibility function

$$w(\phi' - \phi, \phi' - \theta) = g_\sigma(\phi' - \phi - v(\phi' - \theta))$$

where g_σ is a periodic Gaussian or a normalized step function:

$$g_\sigma(\theta) = \frac{1}{\sqrt{\pi}\sigma} \sum_{z \in \mathbb{Z}} e^{-\left(\frac{\theta + 2\pi z}{\sigma}\right)^2}, \quad \theta \in (-\pi, \pi),$$

$$g_\sigma(\theta) = \begin{cases} \frac{1}{2\sigma} & |\theta| < \sigma \\ 0 & \sigma < |\theta| \leq \pi \end{cases}$$

with the turning function v equals to:

$$v(\theta) = \kappa \sin \theta$$

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1.1 Alignment

The equation for T_{al} is:

$$T_{al}(x, \phi, \phi') = q_{al} \int_{\mathbb{R}^2} \int_{-\pi}^{\pi} K_{al}^d(\vec{x} - \vec{s}) K_{al}^o(\phi - \theta) w_{al}(\phi' - \phi, \phi' - \theta) u(\vec{s}, \theta) d\theta d\vec{s} \quad (1.1.1)$$

θ : neighbour's moving direction

s : neighbour's position

ϕ : original angle

ϕ' : new angle

Where

ω : possibility function of turning rate from direction ϕ' to ϕ as a result of interactions

with individuals moving at direction θ

Before start apply Fourier Transform to the function, the wave number are explained below:

1. k_1 : wave number for ϕ .
2. k_2 : wave number for ϕ' .
3. k_3 : wave number for x_1 .
4. k_4 : wave number for x_2 .

Let's started with direction kernel first:

$$T_{al}(x, \phi, \phi') = q_{al} \int_{\mathbb{R}^2} K_{al}^d(\vec{x} - \vec{s}) \int_{-\pi}^{\pi} K_{al}^o(\phi - \theta) w_{al}(\phi' - \phi, \phi' - \theta) u(\vec{s}, \theta) d\theta d\vec{s} \quad (1.1.2)$$

Then take out the part:

$$\int_{-\pi}^{\pi} K_{al}^o(\phi - \theta) w_{al}(\phi' - \phi, \phi' - \theta) u(\vec{s}, \theta) d\theta \quad (1.1.3)$$

Then if we would like to find the Fourier transform of 1.1.3, over ϕ and ϕ' we can get:

$$\int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} K_{al}^o(\phi - \theta) w_{al}(\phi' - \phi, \phi' - \theta) u(\vec{x}, \theta) e^{-ik_1\phi} e^{-ik_2\phi'} d\theta d\phi d\phi' \quad (1.1.4)$$

Let $p_1 = \phi - \theta$, $p_2 = \phi' - \theta$, and $p_3 = \theta$. The Jacobian is

$$\begin{vmatrix} & \phi & \phi' & \theta \\ p_1 & 1 & 0 & -1 \\ p_2 & 0 & 1 & -1 \\ p_3 & 0 & 0 & 1 \end{vmatrix} = 1$$

Then the equation becomes

$$\int_{\theta=-\pi}^{\pi} \int_{p_1=-\pi-\theta}^{\pi-\theta} \int_{p_2=-\pi-\theta}^{\pi-\theta} K_{al}^o(p_1) w_{al}(p_2 - p_1, p_2) u(\vec{x}, p_3) e^{-ik_1(p_1+p_3)} e^{-ik_2(p_2+p_3)} dp_2 dp_1 dp_3 \quad (1.1.5)$$

Then if we take the fourier transform of the equation over the orientation, we get:

$$\int_{\theta=-\pi}^{\pi} \int_{p_1=-\pi-\theta}^{\pi-\theta} \int_{p_2=-\pi-\theta}^{\pi-\theta} K_{al}^o(p_1) w_{al}(p_2 - p_1, p_2) u(\vec{x}, p_3) e^{-ik_1 p_1} e^{-ik_1 p_3} e^{-ik_2 p_2} e^{-ik_2 p_3} dp_2 dp_1 dp_3 \quad (1.1.6)$$

Therefore, we can conclude that:

$$\int_{\theta=-\pi}^{\pi} u(\vec{x}, p_3) e^{-i(k_1+k_2)p_3} dp_3 \int_{p_1=-\pi-\theta}^{\pi-\theta} \int_{p_2=-\pi-\theta}^{\pi-\theta} K_{al}^o(p_1) w_{al}(p_2 - p_1, p_2) e^{-ik_1 p_1} e^{-ik_2 p_2} dp_2 dp_1 \quad (1.1.7)$$

Which finally we get:

$$\widehat{K_{al}^o(k_1)} \widehat{w_{al}(k_1, k_2)} \widehat{u(k_1 + k_2, \vec{s})} \quad (1.1.8)$$

where the hat means Fourier transform.

Then start Fourier transform on the distance \vec{x} ,

$$\int_{\mathbb{R}^2} K_{al}^d(\vec{x} - \vec{s}) \widehat{u(k_1 + k_2, \vec{s})} d\vec{s} \quad (1.1.9)$$

Similarly we perform Fourier transform on 1.1.9, we get:

$$\int_{s_1} \int_{s_2} \int_{x_2} \int_{x_1} K_{al}^d(x_1 - s_1, x_2 - s_2) \widehat{u(k_1 + k_2, s_1, s_2)} e^{-ik_3 x_1} e^{-ik_4 x_2} dx_1 dx_2 ds_2 ds_1 \quad (1.1.10)$$

which finally ends up with:

$$\widehat{\widehat{K_{al}^d(k_3, k_4)}} \widehat{\widehat{u(k_1 + k_2, k_3, k_4)}} \quad (1.1.11)$$

Thus the Fourier form of the turning function is:

$$q_{al} \widehat{\widehat{K_{al}^d(k_3, k_4)}} \widehat{\widehat{K_{al}^o(k_1)}} \widehat{\widehat{w_{al}(k_1, k_2)}} \widehat{\widehat{u(k_1 + k_2, k_3, k_4)}}(t) \quad (1.1.12)$$

1.2 Attraction

The equation for T_a is:

$$T_a(\mathbf{x}, \phi', \phi) = q_a \int_{\mathbb{R}^2} \int_{\pi}^{\pi} K_a^d(\mathbf{x} - \mathbf{s}) K_a^o(\mathbf{s}; \mathbf{x}, \phi') \omega_a(\phi' - \phi, \phi' - \psi) u(\mathbf{s}, \theta, t) d\theta d\mathbf{s} \quad (1.2.1)$$

where ψ is the direction toward a direction, and can be calculated as:

$$\mathbf{s} - \mathbf{x} = (s_x, s_y),$$

$$\cos(\psi) = \frac{s_x}{\sqrt{s_x^2 + s_y^2}}, \sin(\psi) = \frac{s_y}{\sqrt{s_x^2 + s_y^2}} \quad (1.2.2)$$

Then the Orientation Kernel K_a^o and ω_a is a convolution in the space variable, then we can let $K_a(\mathbf{x} - \mathbf{s}, \phi') = K_a^d(\mathbf{x} - \mathbf{s}) K_a^o(\mathbf{x} - \mathbf{s}, \phi')$. Then the Fourier transform over the real space is:

$$q_a \widehat{\widehat{K_a(k_3, k_4, \phi')}} \widehat{\omega_a(\phi' - \phi, \phi', k_3, k_4)} \int_{\pi}^{\pi} \widehat{\widehat{u(k_3, k_4, \theta, t)}} d\theta \quad (1.2.3)$$

Then apply the Fourier transform over the angle ϕ and ϕ' , we get

$$q_a \widehat{\widehat{\widehat{K_a(k_3, k_4, k_2)}}} \widehat{\omega_a(k_1, k_1 + k_2, k_3, k_4)} \int_{\pi}^{\pi} \widehat{\widehat{u(k_3, k_4, \theta, t)}} d\theta \quad (1.2.4)$$

which is equal to

$$K_a \overbrace{(k_3, k_4, k_2)} \omega_a \overbrace{(k_1, k_1 + k_2, k_3, k_4)} u \overbrace{(k_3, k_4, 0)}(t) \quad (1.2.5)$$

1.3 Repulsion

The repulsion part should be similar to the attraction part, but the orientation kernel has the opposite sign.

$$K_r \overbrace{(k_3, k_4, k_2)} \omega_r \overbrace{(k_1, k_1 + k_2, k_3, k_4)} u \overbrace{(k_3, k_4, 0)}(t) \quad (1.3.1)$$