

## Abstract

Modern machine learning systems achieve impressive performance but rely on offline training, static weights,

This work presents an alternative architecture, built over several iterations of empirical experimentation, that

- OLA – the Organic Learning Architecture, an agent framework built around evolving genomes, intrinsic si
- OLM – the Organic Learning Model, a perceptual and predictive layer (e.g., VAEs and temporal models)
- OLC – the Organic Learning Cortex, a spiking, synaptic, continuously plastic substrate that implements m

The paper describes how these components emerged, how early versions were stressed and broken in pr

## 1. Introduction

Most contemporary AI systems are defined by three properties:

1. Static training regime: Models are trained offline on large datasets and then frozen.
2. Centralized memory in weights: All long-term knowledge is stored in dense parameters updated via gra
3. Lack of continuous adaptation: Once deployed, models do not learn in real time without retraining.

These properties make engineering straightforward but fundamentally conflict with the behavior of biologic

- learn continuously from sparse, noisy, and non-stationary streams,
- maintain long-lived memories without catastrophic erasure, and
- adapt without ever “restarting training.”

This work evolves an alternative: an Organic Learning Architecture (OLA) that treats an agent as a living c

- OLM, a perceptual module that compresses raw sensory input into usable latent codes;
- OLC, a synaptic, spiking cortex that provides continuous memory and temporal learning without gradient

The architecture did not arise from theory first. It emerged from iterative, often frustrating experiments on:

- genome-based logic systems solving math and game tasks,
- real-time agents playing environments like Snake,
- chat-shaping models that wrapped a frozen language model with an adaptive controller,
- continuous next-frame prediction systems (OLM) that performed well at one-step horizons but collapsed

Through these tests, the core issue repeatedly reappeared: weight-based memory is unstable under contin

## 2. Background and Motivation

### 2.1 Continuous learning and representational instability

In a traditional gradient-based model, all knowledge is stored in weight matrices. Continuous online training

- the same weights are updated on every new sample,

- every new update can overwrite old information,
- distributional shifts translate directly into representational drift.

This is catastrophic forgetting in practice. Attempts to mitigate it (replay buffers, regularization, dual-networks)

During the development of OLA and OLM, several recurring pathologies appeared:

- Horizon collapse in prediction: OLM models could predict the next frame or step, but performance degraded over time
- Attractor lock-in: Agents would fall into strong behavioral attractors; once a pattern was reinforced, the system would get stuck
- Non-local interference: Updates required for one task or environment configuration damaged behavior on other tasks

These behaviors suggested that weight-based representation, updated continuously, was fundamentally mismatched for the task

## 2.2 Biological learning as a design reference

Biological nervous systems do not store all knowledge in a single trainable matrix. Instead, they:

- represent information in spiking patterns,
- adjust synapses locally based on spike timing and neuromodulators,
- distribute memory across circuits and assemblies,
- separate timescales: fast synaptic changes, slower consolidation, ultra-slow structural/evolutionary changes

Existing research on spiking neural networks (SNNs) and Spike-Timing-Dependent Plasticity (STDP) shows promise

However, such systems were historically limited by:

- lack of structured sensory input (raw pixels or toy symbolic sequences),
- small scale and toy tasks,
- limited integration with perception and action,
- poor tooling and weak hardware support in earlier decades.

The OLA/OLM/OLC stack aims to bridge this gap: using modern latent encoders (OLM) to provide structured input

## 3. The OLA Stack: OLA, OLM, and OLC

### 3.1 OLA – Organic Learning Architecture (Agent Layer)

OLA is the agent-level framework responsible for:

- managing the organism's state variables (energy, sleep, hunger, etc.),
- evolving and selecting genomes (discrete logic-like programs) that define action policies,
- integrating intrinsic signals such as trust, novelty, boredom, and survival metrics.

Key properties:

- Genomes as logic programs: Instead of a monolithic policy network, OLA uses genome-like structures encoding discrete action rules
- Trust-based selection: Genomes are evaluated via a “trust” signal: patterns that consistently lead to survival
- Exploration through mutation: Genomes mutate and recombine over time, allowing new strategies to be discovered

OLA was initially tested in:

- math tasks (e.g., simple equations where genomes mapped inputs to outputs),
- the Snake game (where genomes controlled movement strategies),
- chat shaping (where genomes influenced how a frozen language model responded).

These experiments showed that OLA could, in principle, evolve useful behaviors. However, without a stable

### 3.2 OLM – Organic Learning Model (Perception and Prediction)

OLM is the perceptual and predictive layer, designed to:

- compress sensory streams (vision, text, audio) into low-dimensional latents,
- model local temporal structure (next-frame/next-step dynamics),
- provide a stable, structured input space for higher layers.

Typical OLM components include:

- Variational Autoencoders (VAEs) for vision: mapping raw frames to latent vectors, capturing spatial structure
- Temporal models (e.g., LSTMs or similar) for local sequence modeling: capturing short-term temporal context

Empirically, OLM worked well for:

- single-step prediction: given current latent, predict the next latent or frame,
- basic pattern extraction: primitive feature detectors emerged in the latent space.

However, in continuous learning settings, OLM inherited the same weight-based instabilities:

- multi-step predictions degraded rapidly over time,
- online updates caused latent representations to drift, breaking stability for downstream components,
- attempts to keep OLM plastic while maintaining performance led to either overfitting or collapse.

This indicated that OLM should be treated more like a sensory encoder (eyes/ears) than a central memory

### 3.3 OLC – Organic Learning Cortex (Synaptic Memory and Sequence Learning)

OLC is the new cortical layer designed specifically to address the continuous learning problem.

Core design

OLC is a recurrent network of spiking neurons with plastic synapses:

- Neurons: simple integrate-and-fire units with threshold and refractory periods.
- Synapses: directed connections with a persistent strength and a temporary plastic component.
- Dynamics: each time step, neurons integrate synaptic input, noise, and external stimulation; when a neuron

Learning is implemented via a local STDP-like rule:

- If a pre-synaptic neuron fires shortly before a post-synaptic neuron, the synapse is potentiated.
- If the pre-synaptic neuron fires after the post-synaptic neuron, the synapse is depressed.
- A decay term gradually relaxes temporary plastic changes, while longer-term consolidation accumulates

This yields:

- local learning: updates depend only on spike timing at each synapse,
- multi-timescale memory: fast plasticity vs slower consolidation,
- distributed memory: sequences and associations are stored across many synapses and paths rather than in a central memory.

Tiered development

To progressively validate OLC, the system was developed in tiers:

- Tier 1 – Primitive synaptic organism:
  - 8–12 neurons in a small recurrent graph.
  - Random connectivity and noise.
  - Manual stimulation of selected input neurons via keyboard.
  - Visualization of neurons as nodes and synapses as color-coded edges in Pygame.
  - Goal: demonstrate stable spiking dynamics and visible synaptic differentiation.
- Tier 2 – Sequence learning and recall:
  - An automated test harness stimulated pairs or triplets of neurons in fixed temporal sequences during a training phase.
  - In a recall phase, only the first neuron was stimulated (e.g., neuron 0), and the system observed whether it could recall the sequence.

From Weights to Synapses: Lessons from Failures

The transition from weight-based models (OLM with LSTMs, OLA controllers) to OLC was not planned from the start.

Early OLA/OLM experiments

Several classes of experiments were run:

- Math tasks: genomes in OLA tried to solve simple arithmetic equations, with a reward/trust signal for correct answers.
- Game environments: OLA-controlled agents in environments like Snake, with trust and reward tied to survival.
- Chat shaping: OLA operated as a latent controller around a frozen language model, influencing the style of generated text.

Common observations:

- The systems could learn something—partial strategies, local behaviors, short stretches of coherent responses.
- However, memory was brittle: as learning continued, new adaptations often destroyed older behaviors.
- Multi-step predictions and long-horizon planning repeatedly failed to stabilize.

The conclusion was that treating the LSTM/weight-based components as continuously plastic memory was problematic.

Realizing the weight substrate as the core bottleneck

A key shift in perspective occurred when:

- continuous learning was recognized as not just a “training problem,” but a representational stability problem.
- the issue was reframed: “the architecture is new, but the memory substrate (weights) is old,”
- the model’s failures were traced back to using weights as the only form of memory.

## Integrating OLM, OLC, and OLA

In the current design, the three components are arranged as follows:

1. OLM (Organic Learning Model): Perception
2. OLC (Organic Learning Cortex): Memory and Temporal Structure
3. OLA (Organic Learning Architecture): Action and Evolution

## Experimental Status and Future Directions

So far, the following milestones have been reached:

- Stable synaptic organism (Tier 1)
- Sequence learning and recall (Tier 2, one-step)
- Test harness and analysis

Planned steps include multi-step sequence learning, sensory integration, action coupling, and eventually la

## Conclusion

The OLA/OLM/OLC stack aims to step outside the limitations of gradient-based, static models by introduci