Programming in IDRIS: a tutorial

Edwin Brady eb@cs.st-andrews.ac.uk

January 5, 2012

1 Introduction

In conventional programming languages, there is a clear distinction between *types* and *values*. For example, in Haskell [6], the following are types, representing integers, characters, lists of characters, and lists of any value respectively:

• Int, Char, [Char], [a]

Correspondingly, the following values are examples of inhabitants of those types:

```
• 42, 'a', "Hello world!", [2, 3, 4, 5, 6]
```

In a language with *dependent types*, however, the distinction is less clear. Dependent types allow types to "depend" on values. The standard example is the type of lists of a given length¹, $Vect\ a\ n$, where a is the element type and n is the length of the list and can be an arbitrary term.

When types can contain values, and where those values describe properties (e.g. the length of a list) the type of a function can begin to describe its own properties. For example, concatenating two lists has the property that the resulting list's length is the sum of the lengths of the two input lists. We can therefore give the following type to the app function, which concatenates vectors:

```
app : Vect a n -> Vect a m -> Vect a (n + m);
```

This tutorial introduces IDRIS, a general purpose functional programming language with dependent types. The goal of the IDRIS project is to build a dependently typed language suitable for verifable *systems* programming. To this end, IDRIS is a compiled language which aims to generate efficient executable code. It also has a lightweight foreign function interface which allows easy interaction with external C libraries.

1.1 Intended Audience

This tutorial is intended as a brief introduction to the language, and is aimed at readers already familiar with a functional language such as Haskell or OCaml. In particular, a certain amount of familiarity with Haskell syntax is assumed, although most concepts will at least be explained briefly. The reader is also assumed to have some interest in using dependent types for writing and verifying systems software.

1.2 Example Code

This tutorial includes some example code. The files are available in the IDRIS distribution, so that you can try them out easily, under tutorial/examples. However, it is strongly recommended that you type them in yourself, rather than simply loading and reading them.

¹Typically, and perhaps confusingly, referred to in the dependently typed programming literature as "vectors"

2 Getting Started

2.1 Prerequisites

Before installing IDRIS, you will need to make sure you have all of the necessary libraries and tools. You will need:

- A fairly recent Haskell platform. Version 2010.1.0.0.1 is currently sufficiently recent.
- The Boehm-Demers-Weiser garbage collector library. This is available in all major Linux distributions, or can be installed from source, available from http://www.hpl.hp.com/personal/Hans_Boehm/gc/. Installing from source is painless on MacOS.
- The GNU multiprecision arithmetic library, GMP, available from MacPorts and all major Linux distributions.

2.2 Downloading and Installing

The easiest way to install IDRIS, if you have all of the prerequisites, is to type:

```
cabal install idris
```

This will install the latest version released on Hackage², along with any dependencies. If, however, you would like the most up to date development version, you can find it on GitHub at https://github.com/edwinb/Idris-dev.

To check that installation has succeeded, and to write your first IDRIS program, create a file called "hello.idr" containing the following text:

```
module main;
main : IO();
main = putStrLn "Hello world";
```

If you are familiar with Haskell, it should be fairly clear what the program is doing and how it works, but if not, we will explain the details later. You can compile the program to an executable by entering idris hello.idr -o hello at the shell prompt. This will create an executable called hello, which you can run:

```
$ idris hello.idr -o hello
$ ./hello
Hello world
```

Note that the \$ indicates the shell prompt! Some useful options to the idris command are:

- -o prog to compile to an executable called prog.
- --check type check the file and its dependencies without starting the interactive environment.

2.3 The interactive environment

Entering idris at the shell prompt starts up the interactive environment. You should see something like the following:

²However version 0.9, which this tutorial describes, is not yet there, so don't do this. Finishing this tutorial is the last requirement before releasing it:-).

Idris version 0.9

This gives a ghci-style interface which allows evaluation of expressions, as well as type checking expressions, theorem proving, compilation, editing and various other operations. :? gives a list of supported commands, as shown in Figure 1. Figure 2 shows an example run in which hello.idr is loaded, the type of main is checked and then the program is compiled to the executable hello.

Figure 1: Interactive environment commands

Figure 2: Sample interactive run

Type checking a file, if successful, creates a bytecode version of the file (in this case hello.ibc) to speed up loading in future. The bytecode is regenerated if the source file changes.

3 Types and Functions

3.1 Primitive Types

IDRIS defines several primitive types: Int, Integer and Float for numeric operations, Char and String for text manipulation, and Ptr which represents foreign pointers. There are also several data types declared in the library, including Bool, with values True and False. We can declare some constants with these types. Enter the following into a file prims.idr and load it into the IDRIS interactive environment by typing idris prims.idr:

```
module prims;

x : Int;
x = 42;

foo : String;
foo = "Sausage machine";

bar : Char;
bar = 'Z';

quux : Bool;
quux = False;
```

An IDRIS file consists of an optional module declaration (here module prims) followed by an optional list of imports (none here, however IDRIS programs can consist of several modules, and the definitions in each module each have their own namespace, as we will discuss shortly) and a collection of declarations and definitions. Each definition must have a type declaration (here, x:Int,foo:String,etc). Each component is separated by a semi-colon.

A library module prelude is automatically imported by every IDRIS program, including facilities for IO, arithmetic, data structures and various common functions. The prelude defines several arithmetic and comparison operators, which we can use at the prompt. Evaluating things at the prompt gives an answer, and the type of the answer. For example:

```
*prims> 6*6+6
42 : Int
*prims> x == 6*6+6
True : Bool
```

All of the usual arithmetic and comparison operators are defined for the primitive types. They are overloaded using type classes, as we will discuss in Section 4 and can be extended to work on user defined types. Boolean expressions can be tested with the if...then...else construct:

```
*prims> if (x==6*6+6) then "The answer!" else "Not the answer" "The answer!" : String
```

3.2 Data Types

Data types are declared in a similar way to Haskell data types, with a similar syntax. The main difference is that Idris syntax is not whitespace sensitive, and declarations must end with a semi-colon. Natural numbers and lists, for example, can be declared as follows:

The above declarations are taken from the standard library. Unary natural numbers can be either zero (O - that's a capital letter 'o', not the digit), or the successor of another natural number (S k). Lists can either be empty (Nil) or a value added to the front of another list (x :: xs). In the declaration for List, we used an infix operator ::. New operators such as this can be added using a fixity declaration, as follows:

```
infixr 7 :: ;
```

Functions, data constructors and type constuctors may all be given infix operators as names. They may be used in prefix form if enclosed in brackets, e.g. (::). Infix operators can use any of the symbols:

```
:+-*/=_.?|&><!@$%^~.
```

3.3 Functions

Functions are implemented by pattern matching, again using a similar syntax to Haskell. The main difference is that IDRIS requires type declarations for all functions, using a single colon: (rather than Haskell's double colon:). Some natural number arithmetic functions can be defined as follows, again taken from the standard library:

The standard arithmetic operators + and * are also overloaded for use by Nat, and are implemented using the above functions. Unlike Haskell, there is no restriction on whether types and function names must begin with a capital letter or not. Function names (plus and mult above), data constructors (O, S, Nil and ::) and type constructors (Nat and List) are all part of the same namespace.

We can test these functions at the Idris prompt:

```
Idris> plus (S (S O)) (S (S O))
S (S (S (S O))) : Nat
Idris> mult (S (S (S O))) (plus (S (S O)) (S (S O)))
S (S (S (S (S (S (S (S O))))))))))))) : Nat
```

Like arithmetic operations, integer literals are also overloaded using type classes, meaning that we can also test the functions as follows:

```
Idris> plus 2 2
S (S (S (S O))) : Nat
Idris> mult 3 (plus 2 2)
S (S (S (S (S (S (S (S (S O)))))))))) : Nat
```

You may wonder, by the way, why we have unary natural numbers when our computers have perfectly good integer arithmetic built in. The reason is primarily that unary numbers have a very convenient structure which is easy to reason about, and easy to relate to other data structures as we will see later. Nevertheless, we do not want this convenience to be at the expense of efficiency. Fortunately, IDRIS knows about the relationship between Nat (and similarly structured types) and numbers, so optimises the representation and functions such as plus and mult.

where clauses

Functions can also be defined *locally* using where clauses. For example, to define a function which reverses a list, we can use an auxiliary function which accumulates the new, reversed list, and which does not need to be visible globally:

```
rev : List a -> List a;
rev xs = revAcc [] xs where {
  revAcc : List a -> List a -> List a;
  revAcc acc [] = acc;
  revAcc acc (x :: xs) = revAcc (x :: acc) xs;
}
```

Any names which are visible in the outer scope are also visible in the where clause (unless they have been redefined, such as xs here).

3.4 Dependent Types

3.4.1 Vectors

A standard example of a dependent type is the type of "lists with length", conventionally called vectors in the dependent type literature. In IDRIS, we declare vectors as follows:

```
data Vect : Set -> Nat -> Set where
   Nil : Vect a 0
   | (::) : a -> Vect a k -> Vect a (S k);
```

Note that we have used the same constructor names as for List. Ad-hoc name overloading such as this is accepted by IDRIS, provided that the names are declared in different namespaces (in practice, normally in different modules). Ambiguous constructor names can normally be resolved from context.

This declares a family of types, and so the form of the declaration is rather different from the simple type declarations above. We explicitly state the type of the type constructor <code>Vect</code> — it takes a type and a <code>Nat</code> as an argument, where <code>Set</code> stands for the type of types. We say that <code>Vect</code> is parameterised by a type, and indexed over <code>Nat</code>. Each constructor targets a different part of the family of types. <code>Nil</code> can only be used to construct vectors with zero length, and :: to constructor vectors with non-zero length. In the type of ::, we state explicitly that an element of type <code>a</code> and a tail of type <code>Vect</code> <code>a</code> <code>k</code> (i.e., a vector of length <code>k</code>) combine to make a vector of length <code>S</code> <code>k</code>.

We can define functions on dependent types such as Vect in the same way as on simple types such as List and Nat above, by pattern matching. The type of a function over Vect will describe what happens to the lengths of the vectors involved. For example, app, defined in the library, appends two Vects:

The type of app states that the resulting vector's length will be the sum of the input lengths. If we get the definition wrong in such a way that this does not hold, IDRIS will not accept the definition. For example:

This error message suggests that there is a length mismatch between two vectors — we needed a vector of length (S (k + m)), but provided a vector of length (S (k + k)). Note that the terms in the error message have been *normalised*, so in particular n + m has been reduced to plus n = m.

3.4.2 The Finite Sets

Finite sets, as the name suggests, are sets with a finite number of elements. They are declared as follows (again, in the prelude):

```
data Fin : Nat -> Set where
  fO : Fin (S k)
  | fS : Fin k -> Fin (S k);
```

fO is the zeroth element of a finite set with S k elements; fS n is the n+1th element of a finite set with S k elements. Fin is indexed by a Nat, which represents the number of elements in the set. Obviously we can't construct an element of an empty set, so neither constructor targets Fin O.

A useful application of the Fin family is to represent numbers with guaranteed bounds. For example, the following function which looks up an element in a Vect is defined in the prelude:

```
lookup : Fin n \rightarrow Vect a n \rightarrow a;
lookup fO (x :: xs) = x;
lookup (fS k) (x :: xs) = lookup k xs;
```

This function looks up a value at a given location in a vector. The location is bounded by the length of the vector (n in each case), so there is no need for a run-time bounds check. The type checker guarantees that the location is no larger than the length of the vector.

Note also that there is no case for Nil here. This is because it is impossible. Since there is no element of Fin O, and the location is a Fin n, then n can not be O. As a result, attempting to look up an element in an empty vector would give a compile time type error, since it would force n to be O.

3.4.3 Implicit Arguments

Let us take a closer look at the type of lookup:

```
lookup : Fin n -> Vect a n -> a
```

It takes two arguments, an element of the finite set of n elements, and a vector with n elements of type a. But there are also two names, n and a, which are not declared explicitly. These are *implicit* arguments to lookup. We could also write the type of lookup as:

```
lookup : \{a:Set\} \rightarrow \{n:Nat\} \rightarrow Fin n \rightarrow Vect a n \rightarrow a
```

Implicit arguments, given in braces {} in the type declaration, are not given in applications of lookup; their values can be inferred from the types of the Fin n and Vect a n arguments. Any name which appears as a parameter or index in a type declaration, but which is otherwise free, will be automatically bound as an implicit argument. Implicit arguments can still be given explicitly in applications, using a=value and n=value, for example:

```
lookup \{a=Int\} \{n=2\} fO (2 :: 3 :: VNil)
```

In fact, any argument, implicit or explicit, may be given a name. We could have declared the type of lookup as:

```
lookup : (i:Fin n) -> (xs:Vect a n) -> a;
```

It is a matter of taste whether you want to do this — sometimes it can help document a function by making the purpose of an argument more clear.

3.4.4 "using" notation

Sometimes it is necessary to provide types of implicit arguments where the type checker can not work them out itself. This can happen if there is a dependency ordering — obviously, a and n must be given as arguments above before being used — or if an implicit argument has a complex type. For example, we will need to state the types of the implicit arguments in the following definition, which defines a predicate on vectors:

```
data Elem : a -> (Vect a n) -> Set where
  here : {x:a} -> {xs:Vect a n} -> Elem x (x :: xs)
  | there : {x,y:a} -> {xs:Vect a n} -> Elem x xs -> Elem x (y :: xs);
```

An instance of $Elem \times xs$ states that x is an element of xs. We can construct such a predicate if the required element is here, at the head of the vector, or there, in the tail of the vector. For example:

```
testVec : Vect Int 4;
testVec = 3 :: 4 :: 5 :: 6 :: VNil;
inVect : Elem 5 testVec;
inVect = there (there here);
```

If the same implicit arguments are being used a lot, it can make a definition difficult to read. To avoid this problem, a using block gives the types and ordering of any implicit arguments which can appear within the block:

```
using (x:a, y:a, xs:Vect a n) {
  data Elem : a -> (Vect a n) -> Set where
    here : Elem x (x :: xs)
    | there : Elem x xs -> Elem x (y :: xs);
}
```

3.5 I/O

Computer programs are of little use if they do not interact with the user or the system in some way. The difficulty in a pure language such as IDRIS — that is, a language where expressions do not have side-effects — is that I/O is inherently side-effecting. Therefore in IDRIS, such interactions are encapsulated in the type IO:

```
data IO a; -- IO operation returning a value of type a
```

We'll leave the definition of IO abstract, but effectively it describes what the I/O operations to be executed are, rather than how to execute them. The resulting operations are executed externally, by the runtime system. We've already seen one IO program:

```
main : IO ();
main = putStrLn "Hello world";
```

The type of putStrln explains that it takes a string, and returns an element of the unit type () via an I/O action. There is a variant putStr which outputs a string without a newline:

We can also read strings from user input:

```
getLine : IO String;
```

A number of other I/O operations are defined in the prelude, for example for reading and writing files, including:

```
data File; -- abstract
data Mode = Read | Write | ReadWrite;

openFile : String -> Mode -> IO File;
closeFile : File -> IO ();

fread : File -> IO String;
fwrite : File -> String -> IO ();

feof : File -> IO Bool;

readFile : String -> IO String;
```

3.6 "do" notation

I/O programs will typically need to sequence actions, feeding the output of one computation into the input of the next. IO is an abstract type, however, so we can't access the result of a computation directly. Instead, we sequence operations with do notation:

The syntax x < - iovalue executes the I/O operation iovalue, of type IO a, and puts the result, of type a into the variabel x. In this case, getLine returns an IO String, so name has type String. The return operation allows us to inject a value directly into an IO operation:

```
return : a -> IO a;
```

As we will see later, do notation is more general than this, and can be overloaded.

3.7 Useful Data Types

IDRIS includes a number of useful data types and library functions (see the lib/ directory in the distribution). This chapter describes a few of these. The functions described here are imported automatically by

every IDRIS program, as part of prelude.idr.

3.7.1 List and Vect

We have already seen the List and Vect data types:

```
data List a = Nil | (::) a (List a);

data Vect : Set -> Nat -> Set where
   Nil : Vect a 0
   | (::) : a -> Vect a k -> Vect a (S k);
```

Note that the constructor names are the same for each — constructor names (in fact, names in general) can be overloaded, provided that they are declared in different namespaces (see Section 5), and will typically be resolved according to their type. As syntactic sugar, any type with the constructor names Nil and : : can be written in list form. For example:

- [] means Nil
- [1,2,3] means Cons 1 (Cons 2 (Cons 3 Nil))

The library also defines a number of functions for manipulating these types. map is overloaded both for List and Vect and applies a function to every element of the list or vector.

For example, to double every element in a vector of integers:

```
intVec : Vect Int 5;
intVec = [1, 2, 3, 4, 5];
double : Int -> Int;
double x = x * 2;
```

You'll find these examples in usefultypes.idr in the examples / directory:

```
*usefultypes> show (map double intVec) "[2, 4, 6, 8, 10]" : String
```

For more details of the functions available on List and Vect, look in the library, in prelude/list.idr and prelude/vect.idr respectively. Functions include filtering, appending, reversing, and so on. Also remember that IDRIS is still in development, so if you don't see the function you need, please feel free to add it and submit a patch!

Aside: Anonymous functions and operator sections

There are actually neater ways to write the above expression. One way would be to use an anonymous function:

```
*usefultypes> show (map (x = x * 2) intVec) "[2, 4, 6, 8, 10]" : String
```

The notation $\x = \xspace val$ constructs an anonymous function which takes one argument, x and returns the expression val. Anonymous functions may take several arguments, separated by commas, e.g. $\xspace x$, y, z => val. Arguments may also be given explicit types, e.g. $\xspace x$: Int => x * 2.

We could also use an operator section:

```
*usefultypes> show (map (* 2) intVec) "[2, 4, 6, 8, 10]" : String
```

(*2) is shorthand for a function which multiplies a number by 2. It expands to $x = x \times 2$. Similarly, (2*) would expand to $x = x \times 2$.

3.7.2 Maybe

Maybe describes an optional value. Either there is a value of the given type, or there isn't:

```
data Maybe a = Just a | Nothing;
```

Maybe is one way of giving a type to an operation that may fail. For example, looking something up in a List (rather than a vector) may result in an out of bounds error:

```
list_lookup : Nat -> List a -> Maybe a;
list_lookup _ Nil = Nothing;
list_lookup O (Cons x xs) = Just x;
list_lookup (S k) (Cons x xs) = list_lookup k xs;
```

The maybe function is used to process values of type Maybe, either by applying a function to the value, if there is one, or by providing a default value:

```
maybe : Maybe a \rightarrow | (default:b) \rightarrow (a \rightarrow b) \rightarrow b;
```

The vertical bar | before the default value is a laziness annotation. Normally expressions are evaluated before being passed to a function. This is typically the most efficient behaviour. However, in this case, the default value might not be used and if it is a large expression, evaluating it will be wasteful. The | annotation tells the compiler not to evaluate the argument until it is needed.

3.7.3 Tuples and Dependent Pairs

Values can be paired with the following built-in data type:

```
data Pair a b = MkPair a b;
```

As syntactic sugar, we can write (a, b) which, according to context, means either Pair a b or MkPair a b. Tuples can contain an arbitrary number of values, represented as nested pairs:

```
fred : (String, Int);
fred = ("Fred", 42);

jim : (String, Int, String);
jim = ("Jim", 25, "Cambridge");
```

Dependent Pairs

Dependent pairs allow the type of the second element of a pair to depend on the value of the first element:

```
data Exists : (A : Set) -> (P : A -> Set) -> Set where
   Ex_intro : {P : A -> Set} -> (a : A) -> P a -> Exists A P;
```

Again, there is syntactic sugar for this. (a : A ** P) is the type of a pair of A and P, where the name a can occur inside P. (a ** p (constructs a value of this type. For example, we can pair a number with a Vect of a particular length.

```
vec : (n : Nat ** Vect Int n);
vec = (2 ** [3, 4]);
```

The type checker could of course infer the value of the first element from the length of the vector. We can write an underscore _ in place of values which we expect the type checker to fill in, so the above definition could also be written as:

```
vec : (n : Nat ** Vect Int n);
vec = (_ ** [3, 4]);
```

We might also prefer to omit the type of the first element of the pair, since, again, it can be inferred:

```
vec : (n ** Vect Int n);
vec = (_ ** [3, 4]);
```

One use for dependent pairs is to return values of dependent types where the index is not necessarily known in advance. For example, if we filter elements out of a Vect according to some predicate, we will not know in advance what the length of the resulting vector will be:

```
filter: (a -> Bool) -> Vect a n -> (p ** Vect a p);
```

If the Vect is empty, the result is easy:

```
vfilter p VNil = (_ , []);
```

In the :: case, we need to inspect the result of a recursive call to filter to extract the length and the vector from the result. To do this, we use with notation. with allows pattern matching on intermediate values:

```
filter p (x :: xs) with filter p xs {
    | (_ , xs') = if (p x) then (_ , x :: xs') else (_ , xs');
}
```

We will see more on with notation later.

4 Type Classes

We often want to define functions which work across several different data types. For example, we would like arithmetic operators to work on Int, Integer and Float at the very least. We would like == to work on the majority of data types. We would like to be able to display different types in a uniform way.

To achieve this, we use a feature which has proved to be effective in Haskell, namely *type classes*. To define a type class, we provide a collection of overloaded operations which describe the interface for *instances* of that class. A simple example is the Show type class, which is defined in the prelude and provides an interface for converting values to Strings:

```
class Show a where {
    show : a -> String;
}
```

This generates a function of the following type (which we call a *method* of the Show class):

```
show : Show a => a -> String;
```

We can read this as "under the constraint that a is an instance of Show, take an a as input and return a String." An instance of a class is defined with an instance declaration, which provides implementations of the function for a specific type. For example, the Show instance for Nat could be defined as:

```
instance Show Nat where {
    show 0 = "0";
    show (S k) = "s" ++ show k;
}
Idris> show (S (S (S 0)))
"sss0" : String
```

Instance declarations can themselves have constraints. For example, to define a Show instance for vectors, we need to know that there is a Show instance for the element type, because we are going to use it to convert each element to a String:

```
instance Show a => Show (Vect a n) where {
    show xs = "[" ++ show' xs ++ "]" where {
        show' : Show a => Vect a n -> String;
        show' VNil = "";
        show' (x :: VNil) = show x;
        show' (x :: xs) = show x ++ ", " ++ show' xs;
    }
}
```

4.1 Default Definitions

The library defines an Eq class which provides an interface for comparing values for equality or inequality, with instances for all of the built-in types:

```
class Eq a where {
    (==) : a -> a -> Bool;
    (/=) : a -> a -> Bool;
}
```

To declare an instance of a type, we have to give definitions of all of the methods. For example, for an instance of Eq for Nat:

```
instance Eq Nat where {
    O == O = True;
    (S x) == (S y) = x == y;
    O == (S y) = False;
    (S x) == O = False;
    x /= y = not (x == y);
}
```

It is hard to imagine many cases where the /= method will be anything other than the negation of the result of applying the == method. It is therefore convenient to give a default definition for each method in the class declaration, in terms of the other method:

```
class Eq a where {
    (==) : a -> a -> Bool;
    (/=) : a -> a -> Bool;

    x /= y = not (x == y);
    y == y = not (x /= y);
}
```

A minimal complete definition of an Eq instance requires either == or /= to be defined, but does not require both. If a method definition is missing, and there is a default definition for it, then the default is used instead.

4.2 Extending Classes

Classes can also be extended. A logical next step from an equality relation Eq is to define an ordering relation Ord. We can define an Ord class which inherits method from Eq as well as defining some of its own:

```
data Ordering = LT | EQ | GT;

class Eq a => Ord a where {
   compare : a -> a -> Ordering;

   (<) : a -> a -> Bool;
   (>) : a -> a -> Bool;
   (<=) : a -> a -> Bool;
   (>=) : a -> a -> Bool;
   max : a -> a -> a;
   min : a -> a -> a;
}
```

The Ord class allows us to compare two values and determine their ordering. Only the compare method is required; every other method has a default definition. Using this we can write functions such as sort, a function which sorts a list into increasing order, provided that the element type of the list is in the Ord class. We give the constraints on the type variables left of the fat arrow =>, and the function type to the right of the fat arrow:

```
sort : Ord a => List a -> List a;
```

Functions, classes and instances can have multiple constraints. Multiple constaints are written in brackets in a comma separated list, for example:

```
sortAndShow : (Ord a, Show a) => List a -> String;
sortAndShow xs = show (sort xs);
```

4.3 Monads and do-notation

So far, we have seen single parameter type classes, where the parameter is of type Set. In general, there can be any number (greater than 0) of parameters, and the parameters can have *any* type. If the type of the parameter is not Set, we need to give an explicit type declaration. For example:

```
class Monad (m : Set -> Set) where {
    return : a -> m a;
    (>>=) : m a -> (a -> m b) -> m b;
}
```

The Monad class allows us to encapsulate binding and computation, and is the basis of do-notation introduced in Section 3.6. Inside a do block, the following syntactic transformations are applied:

```
x <- v; e becomes v >>= (\x => e)
v; e becomes v >>= (\_ => e)
let x = v; e becomes let x = v in e
```

IO is an instance of Monad, defined using primitive functions. We can also define an instance for Maybe, as follows:

```
instance Monad Maybe where {
    return = Just;

Nothing >>= k = Nothing;
    (Just x) >>= k = k x;
}
```

Using this we can, for example, define a function which adds two Maybe Ints, using the monad to encapsulate the error handling:

This function will extract the values from x and y, if they are available, or return Nothing if they are not. Managing the Nothing cases is achieved by the >>= operator, hidden by the do notation.

```
*classes> m_add (Just 20) (Just 22)
Just 42 : Maybe Int
*classes> m_add (Just 20) Nothing
Nothing : Maybe Int
```

5 Modules and Namespaces

An IDRIS program consists of a collection of modules. Each module includes an optional module declaration giving the name of the module, a list of import statements giving the other modules which are to

be imported, and a collection of declarations and definitions of types, classes and functions. For example, Figure 3 gives a module which defines a binary tree type <code>BTree</code> (in a file <code>btree.idr</code>) and Figure 4 gives a main program (in a file <code>bmain.idr</code> which uses the <code>bst</code> module to sort a list.

Figure 3: Binary Tree module

Figure 4: Binary Tree main program

The same names can be defined in multiple modules. This is possible because in practice names are *qualified* with the name of the module. The names defined in the btree module are, in full:

• btree.BTree, btree.Leaf, btree.Node, btree.insert, btree.toList and btree.toTree.

If names are otherwise unambiguous, there is no need to give the fully qualified name. Names can be disambiguated either by giving an explicit qualification, or according to their type.

There is no formal link between the module name and its filename, although it is generally advisable to use the same name for each. An import statement refers to a filename, using dots to separate directories. For example, import foo.bar would import the file foo/bar.idr, which would conventionally have the module declaration module foo.bar. The only requirement for module names is that the main module, with the main function, must be called main (though its filename need not be main.idr).

5.1 Export Modifiers

By default, all names defined in a module are exported for use by other modules. However, it is good practice only to export a minimal interface and keep internal details abstract. IDRIS allows functions, types and classes to be marked as public, abstract or private:

- public means that both the name and definition are exported. For functions, this means that the implementation is exported (which means, for example, it can be used in a dependent type). For data types, this means that the type name and the constructors are exported. For classes, this means that the class name and method names are exported.
- abstract means that only the name is exported. For functions, this means that the implementation is not exported. For data types, this means that the type name is exported but not the constructors. For classes, this means that the class name is exported but not the method names/
- private means that neither the name nor the definition is exported.

If any definition is given an export modifier, then all names with no modifier are assumed to be private. For our btree module, it makes sense for the tree data type and the functions to be exported as abstract, as we see in Figure 5.

```
module btree;
abstract data BTree a = Leaf
                       | Node (BTree a) a (BTree a);
abstract
insert : Ord a => a -> BTree a -> BTree a;
insert x Leaf = Node Leaf x Leaf;
insert x (Node l \ v \ r) = if (x < v) then (Node (insert x l) v \ r)
                                   else (Node l v (insert x r));
abstract
toList : BTree a -> List a;
toList Leaf = [];
toList (Node 1 v r) = app (toList 1) (v :: toList r);
abstract
toTree : Ord a => List a -> BTree a;
toTree [] = Leaf;
toTree (x :: xs) = insert x (toTree xs);
```

Figure 5: Binary Tree module, with export modifiers

Finally, the default export mode can be changed with the %access directive, for example:

```
%access abstract
```

In this case, any function with no access modifier will be exported as abstract, rather than left private.

5.2 Explicit Namespaces

Defining a module also defines a namespace implicitly. However, namespaces can also be given *explicitly*. This is most useful if you wish to overload names within the same module:

```
module foo;

namespace x {
  test : Int -> Int;
  test x = x * 2;
}

namespace y {
  test : String -> String;
  test x = x ++ x;
}
```

This (admittedly contrived) module defines two functions with fully qualified names foo.x.test and foo.y.test, which can be disambiguated by their types:

```
*foo> test 3
6 : Int
*foo> test "foo"
"foofoo" : String
```

6 Example: The Well-Typed Interpreter

In this chapter, we'll use the features we've seen so far to write a larger example, an interpreter for a simple functional programming language, with variables, function application, binary operators and an if...then...else construct. We will use the dependent type system to ensure that any programs which can be represented are well-typed. First, let us define the types in the language. We have integers, booleans, and functions, represented by Ty:

```
data Ty = TyInt | TyBool | TyFun Ty Ty;
```

We can write a function to translate these representations to a concrete IDRIS type:

```
interpTy : Ty -> Set;
interpTy TyInt = Int;
interpTy TyBool = Bool;
interpTy (TyFun A T) = interpTy A -> interpTy T;
```

We're going to define a representation of our language in such a way that only well-typed programs can be represented. We'll index the representations of expressions by their type and the types of local variables (the context), which we'll be using regularly as an implicit argument, so we define everything in a using block:

```
using (G: Vect Ty n)
```

The full representation of expressions is given in Figure 6. They are indexed by the types of the local variables, and the type of the expression itself:

```
data Expr : Vect Ty n -> Ty -> Set
```

Since expressions are indexed by their type, we can read the typing rules of the language from the definitions of the constructors. Let us look at each constructor in turn.

We use a nameless representation for variables — they are *de Bruijn indexed*. Variables are represented by a proof of their membership in the context, $HasType \ i \ G \ T$, which is a proof that variable i in context

Figure 6: Expression representation

 ${\tt G}$ has type ${\tt T}.$ This is defined as follows:

```
data HasType : (i : Fin n) -> Vect Ty n -> Ty -> Set where
    stop : HasType fO (t :: G) t
    | pop : HasType k G t -> HasType (fS k) (u :: G) t;
```

We can treat *stop* as a proof that the most recently defined variable is well-typed, and *pop n* as a proof that, if the nth most recently defined variable is well-typed, so is the n+1th. In practice, this means we use pop to refer to the most recently defined variable, pop stop to refer to the next, and so on, via the Var constructor:

```
Var : HasType i G t -> Expr G t
```

So, in an expression $\xspace x$ $\xspace y$, the variable $\xspace x$ would have a de Bruijn index of 1, represented as pop stop, and $\xspace y$ 0, represented as stop. We find these by counting the number of lambdas between the definition and the use.

A value carries a concrete representation of an integer:

```
Val : (x : Int) -> Expr G TyInt
```

A lambda creates a function. In the scope of a function of type a -> t, there is a new local variable of type a, which is expressed by the context index:

```
Lam : Expr (a :: G) t -> Expr G (TyFun a t)
```

Function application produces a value of type t given a function from a to t and a value of type a:

```
App : Expr G (TyFun a t) -> Expr G a -> Expr G t
```

We allow arbitrary binary operators, where the type of the operator informs what the types of the arguments must be:

```
Op : (interpTy a -> interpTy b -> interpTy c) -> Expr G a -> Expr G b -> Expr G c
```

Finally, if expressions make a choice given a boolean. Each branch must have the same type:

```
If : Expr G TyBool -> Expr G a -> Expr G a -> Expr G a;
```

When we evaluate an Expr, we'll need to know the values in scope, as well as their types. Env is an

environment, indexed over the types in scope. Since an environment is just another form of list, albeit with a strongly specified connection to the vector of local variable types, we use the usual :: and Nil constructors so that we can use the usual list syntax. Given a proof that a variable is defined in the context, we can then produce a value from the environment:

Figure 7: Intepreter definition

Given this, an interpreter (Figure 7) is a function which translates an Expr into a concrete IDRIS value with respect to a specific environment:

```
interp : Env G -> Expr G t -> interpTy t;
```

To translate a variable, we simply look it up in the environment:

```
interp env (Var i) = lookup i env;
```

To translate a value, we just return the concrete representation of the value:

```
interp env (Val x) = x;
```

Lambdas are more interesting. In this case, we construct a function which interprets the scope of the lambda with a new value in the environment. So, a function in the object language is translated to an IDRIS function:

```
interp env (Lam sc) = \x => interp (x :: env) sc;
```

For an application, we interpret the function and its argument and apply it directly. We know that interpreting f must produce a function, because of its type:

```
interp env (App f s) = (interp env f) (interp env s);
```

Operators and interpreters are, again, direct translations into the equivalent IDRIS constructs. For operators, we apply the function to its operands directly, and for If, we apply the IDRIS if...then...else construct directly.

We can make some simple test functions. Firstly, adding two inputs $\xspace x$. $\xspace y$ + $\xspace x$ is written as follows:

```
add : Expr G (TyFun TyInt (TyFun TyInt TyInt));
add = Lam (Lam (Op (+) (Var stop) (Var (pop stop))));
```

More interestingly, we can write a factorial function. First, we write a *lazy* version of the App constructor, so that the recursive branch will only be evaluated if necessary:

To finish, we write a main program which interprets the factorial function on user input:

Here, prim_strToInt is a primitive function which converts a string to an integer, giving 0 if the input is invalid. An example run of this program at the IDRIS interactive environment is shown in Figure 8.

```
$ idris interp.idr

/ _/__ / __ (_)

/ // __ / __ (_)

/ // __ / __ / __ / Version 0.9

_/ // / / / / (__ ) http://www.idris-lang.org/

/__ /\__ ,_/_ / /__ / Type :? for help

Type checking ./interp.idr
*interp> :exec interp
Enter a number: 6
720
*interp>
```

Figure 8: Running the well-typed interpreter

7 Views and the "with" rule

7.1 Dependent pattern matching

Since types can depend on values, the form of some arguments can be determined by the value of others. For example, if we were to write down the implicit length arguments to app, we'd see that the form of the length argument was determined by whether the vector was empty or not:

```
app : Vect a n -> Vect a m -> Vect a (n + m);
app \{n=0\} [] = [];
app \{n=S k\} (x :: xs) ys = x :: app xs ys;
```

If n was a successor in the [] case, or zero in the :: case, the definition would not be well typed.

7.2 The with rule — matching intermediate values

Very often, we need to match on the result of an intermediate computation. IDRIS provides a construct for this, the with rule, inspired by views in EPIGRAM [5], which takes account of the fact that matching on a value in a dependently typed language can affect what we know about the forms of other values. In its simplest form, the with rule adds another argument to the function being defined, e.g. we have already seen a vector filter function, defined as follows:

Here, the with clause allows us to deconstruct the result of filter p xs. Effectively, it adds this value as an extra argument, which we place after the vertical bar.

If the intermediate computation itself has a dependent type, then the result can affect the forms of other arguments — we can learn the form of one value by testing another. For example, a Nat is either even or odd. If it's even it will be the sum of two equal Nats. Otherwise, it is the sum of two equal Nats plus one:

```
data Parity : Nat -> Set where
  even : Parity (n + n)
  | odd : Parity (S (n + n));
```

We say Parity is a *view* of Nat. It has a *covering function* which tests whether it is even or odd and constructs the predicate accordingly.

```
parity : (n:Nat) -> Parity n;
```

We'll come back to the definition of parity shortly. We can use it to write a function which converts a natural number to a list of binary digits (least significant first) as follows, using the with rule:

```
natToBin : Nat -> List Bool;
natToBin O = Nil;
natToBin k with parity k {
  natToBin (j + j)  | even = False :: natToBin j;
  natToBin (S (j + j)) | odd = True :: natToBin j;
}
```

The value of the result of parity k affects the form of k, because the result of parity k depends on k. So, as well as the patterns for the result of the intermediate computation (even and odd) right of the |, we also write how the results affect the other patterns left of the |. Note that there is a function in the patterns (+) and repeated occurrences of j — this is allowed because another argument has determined the form of these patterns.

We can test this function at the prompt. 42 is 101010 in binary. The binary digits are reversed with natToBin:

```
*views> show (natToBin 42)
"[False, True, False, True, False, True]" : String
```

8 Theorem Proving

8.1 Equality

IDRIS allows propositional equalities to be declared, allowing theorems about programs to be stated and proved. Equality is built in, but conceptually has the following definition:

```
data (=) : a \rightarrow b \rightarrow Set where refl : x = x;
```

Equalities can be proposed between any values of any types, but the only way to construct a proof of equality is if values actually are equal. For example:

```
fiveIsFive : 5 = 5;
fiveIsFive = refl;

twoPlusTwo : 2 + 2 = 4;
twoPlusTwo = refl;
```

8.2 Simple Theorems

When type checking dependent types, the type itself gets *normalised*. So imagine we want to prove the following theorem about the reduction behaviour of plus:

```
plusReduces : (n:Nat) -> plus O n = n;
```

We've written down the statement of the theorem as a type, in just the same way as we would write the type of a program. In fact there is no real distinction between proofs and programs. A proof, as far as we are concerned here, is merely a program with a precise enough type to guarantee a particular property of interest.

We won't go into details here, but the Curry-Howard correspondence [4] explains this relationship. The proof itself is trivial, because plus 0 n normalises to n by the definition of plus:

```
plusReduces n = refl;
```

It is slightly harder if we try the arguments the other way, because plus is defined by recursion on its first argument. The proof also works by recursion on the first argument to plus, namely n.

```
plusReduces0 : (n:Nat) -> n = plus n O;
plusReduces0 0 = refl;
plusReduces0 (S k) = eqRespS (plusReduces0 k);
```

eqRespS is a function defined in the library which states that equality respects successor:

```
eqRespS : m = n \rightarrow S m = S n;
```

We can do the same for the reduction behaviour of plus on successors:

```
plusReducesS : (n:Nat) -> (m:Nat) -> S (plus n m) = plus n (S m);
plusReducesS O m = refl;
plusReducesS (S k) m = eqRespS (plusReducesS k m);
```

Even for trival theorems like these, the proofs are a little tricky to construct in one go. When things get even slightly more complicated, it becomes too much to think about to construct proofs in this 'batch mode'. IDRIS therefore provides an interactive proof mode.

8.3 Interactive theorem proving

Instead of writing the proof in one go, we can use IDRIS's interactive proof mode. To do this, we write the general *structure* of the proof, and use the interactive mode to complete the details. We'll be constructing the proof by *induction*, so we write the cases for 0 and S, with a recursive call in the S case giving the inductive hypothesis, and insert *metavariables* for the rest of the definition:

On running IDRIS, two global names are created, plusredO_O and plusredO_S, with no definition. We can use the :m command at the prompt to find out which metavariables are still to be solved (or, more precisely, which functions exist but have no definitions). Then we can use the :t command to see what their types are:

The :p command enters interactive proof mode, which can be used to complete the missing definitions.

```
*theorems> :p plusredO_O
----- (plusredO_O) ------
{holeO} : O = plus O O
```

This gives us a list of premisses (above the line; there are none here) and the current goal (below the line; named {hole0} here). At the prompt we can enter tactics to direct the construction of the proof. In this case, we can normalise the goal with the compute tactic:

```
-plusredO_O> compute
----- (plusredO_O) ------
{hole0} : O = O
```

Now we have to prove that O equals O, which is easy to prove by refl. To apply a function, such as refl, we use the refine tactic which introduces subgoals for each of the function's explicit arguments (though refl has none):

```
-plusredO_0> refine refl
plusredO_0: no more goals
```

Here, we could also have used the trivial tactic, which tries to refine by refl, and if that fails, tries to refine by each name in the local context. When a proof is complete, we use the qed tactic to add the proof to the global context, and remove the metavariable from the unsolved metavariables list. This also outputs a trace of the proof:

```
-plusredO_O> qed
plusredO_O = proof {
    compute;
    refine refl;
};
*theorems> :m
Global metavariables:
    [plusredO_S]
```

The :addproof command, at the interactive prompt, will add the proof to the source file (effectively in an appendix). Let us now prove the other required lemma, plusredO_S:

```
*theorems> :p plusredO_S
------ (plusredO_S) ------
{hole0} : (k : Nat) -> (k = plus k O) -> S k = S (plus k O)
```

In this case, the goal is a function type, using k (the argument accessible by pattern matching) and ih (the local variable containing the result of the recursive call). We can introduce these as premisses using the intro tactic twice. This gives:

```
k: Nat
ih: k = plus k 0
-----(plusredo_S) ------
{hole2}: S k = S (plus k 0)
```

We know, from the type of ih, that k = plus k O, so we would like to use this knowledge to replace plus k O in the goal with k. We can achieve this with the rewrite tactic:

The rewrite tactic takes an equality proof as an argument, and tries to rewrite the goal using that proof. Here, it results in an equality which is trivially provable:

```
-plusredO_S> trivial
plusredO_S: no more goals
-plusredO_S> qed
plusredO_S = proof {
   intro;
   intro;
   rewrite ih;
   trivial;
};
```

Again, we can add this proof to the end of our source file using the :addproof command at the interactive prompt.

9 Provisional Definitions

Sometimes when programming with dependent types, the type required by the type checker and the type of the program we have written will be different (in that they do not have the same normal form), but nevertheless provably equal. For example, recall the parity function:

```
data Parity : Nat -> Set where
   even : Parity (n + n)
   | odd : Parity (S (n + n));

parity : (n:Nat) -> Parity n;
```

We'd like to implement this as follows:

this simply states that zero is even, one is odd, and recursively, the parity of k+2 is the same as the parity of k. Explicitly marking the value of n in even and odd is necessary to help type inference. Unfortunately, the type checker rejects this:

```
views.idr:12:Can't unify Parity (plus (S j) (S j)) with
Parity (S (S (plus j j)))
```

The type checker is telling us that (j+1)+(j+1) and 2+j+j do not normalise to the same value. This is because plus is defined by recursion on its first argument, and in the second value, there is a successor symbol on the second argument, so this will not help with reduction. These values are obviously equal — how can we rewrite the program to fix this problem?

9.1 Provisional definitions

Provisional definitions help with this problem by allowing us to defer the proof details until a later point. There are two main reasons why they are useful.

- When *prototyping*, it is useful to be able to test programs before finishing all the details of proofs.
- When *reading* a program, it is often much clearer to defer the proof details so that they do not distract the reader from the underlying algorithm.

Provisional definitions are written in the same way as ordinary definitions, except that they introduce the right hand side with a ?= rathar than =. We define parity as follows:

```
parity : (n:Nat) -> Parity n;
parity 0 = even {n=0};
parity (S 0) = odd {n=0};
parity (S (S k)) with parity k {
  parity (S (S (j + j)))  | even ?= even {n=S j};
  parity (S (S (j + j))) | odd ?= odd {n=S j};
}
```

When written in this form, instead of reporting a type error, IDRIS will insert a metavariable standing for a theorem which will correct the type error. IDRIS tells us we have two proof obligations, with names generated from the module and function names:

The first of these has the following type:

The two arguments are j, the variable in scope from the pattern match, and value, which is the value we gave in the right hand side of the provisional definition. Our goal is to rewrite the type so that we can use this value. We can achieve this using the following theorem from the prelude:

```
plusn_Sm : (n : Nat) \rightarrow (m : Nat) \rightarrow (plus n (S m)) = S (plus n m);
```

After applying intro twice, we have:

```
-views.parity_lemma_1> intro

j : Nat
    value : Parity (S (plus j (S j)))
------ (views.parity_lemma_1) -------
{hole2} : Parity (S (S (plus j j)))
```

Then we apply the plusn_Sm function to j and j, giving:

We can complete this proof using the trivial tactic, which finds value in the premisses. The proof of the second lemma proceeds in exactly the same way.

9.2 Suspension of Disbelief

IDRIS requires that proofs be complete before compiling programs (although evaluation at the prompt is possible without proof details). Sometimes, especially when prototyping, it is easier not to have to do this. It might even be beneficial to test programs before attempting to prove things about them — if testing finds an error, you know you had better not waste your time proving something!

Therefore, IDRIS provides a built-in coercion function, which allows you to use a value of the incorrect types:

```
believe_me : a -> b;
```

Obviously, this should be used with extreme caution. It is useful when prototyping, and can also be appropriate when asserting properties of external code (perhaps in an external C library). The "proof" of views.parity_lemma_1 using this is:

```
views.parity_lemma_2 = proof {
    intro;
    intro;
    exact believe_me value;
};
```

The exact tactic allows us to provide an exact value for the proof. In this case, we assert that the value we gave was correct.

9.3 Example: Binary numbers

Previously, we implemented conversion to binary numbers using the Parity view. Here, we show how to use the same view to implement a verified conversion to binary. We begin by indexing binary numbers over their Nat equivalent. This is a common pattern, linking a representation (in this case Binary) with a meaning (in this case Nat):

```
data Binary : Nat -> Set where
  bEnd : Binary 0
| b0 : Binary n -> Binary (n + n)
| bI : Binary n -> Binary (S (n + n));
```

bo and bI take a binary number as an argument and effectively shift it one bit left, adding either a zero or one as the new least significant bit. The index, n + n or S (n + n) states the result that this left shift then add will have to the meaning of the number. This will result in a representation with the least significant bit at the front.

Now a function which converts a Nat to binary will state, in the type, that the resulting binary number is a faithful representation of the original Nat:

```
natToBin : (n:Nat) -> Binary n;
```

The Parity view makes the definition fairly simple — halving the number is effectively a right shift after all — although we need to use a provisional definition in the odd case:

```
natToBin : (n:Nat) -> Binary n;
natToBin O = bEnd;
natToBin (S k) with parity k {
  natToBin (S (j + j))  | even = bI (natToBin j);
  natToBin (S (S (j + j))) | odd ?= bO (natToBin (S j));
}
```

The problem with the odd case is the same as in the definition of parity, and the proof proceeds in the same way:

```
natToBin_lemma_1 = proof {
    intro;
    intro;
    rewrite plusn_Sm j j;
    trivial;
};
```

To finish, we'll implement a main program which reads an integer from the user and outputs it in binary.

For this to work, of course, we need a Show instance for Binary n:

```
instance Show (Binary n) where {
   show (bO x) = show x ++ "0";
   show (bI x) = show x ++ "1";
   show bEnd = "";
}
```

10 Miscellany

In this section we discuss a variety of additional features: extensible syntax, literate programming, and interfacing with external libraries through the foriegn function interface.

10.1 Syntax Extensions

IDRIS supports the implementation of Embedded Domain Specific Languages (EDSLs) in several ways [3]. One way, as we have already seen, is through extending do notation. Another important way is to allow extension of the core syntax. For example, we have seen if...then...else expressions, but these are not built in — instead, we define a function in the prelude...

```
boolElim : (x:Bool) \rightarrow |(t:a) \rightarrow |(f:a) \rightarrow a;
boolElim True t = e;
boolElim False t = e;
```

...and extend the core syntax with a syntax declaration:

```
syntax if [test] then [t] else [e] = boolElim test t e;
```

The left hand side of a syntax declaration describes the syntax rule, and the right hand side describes its expansion. The syntax rule itself consists of:

- Keywords here, if, then and else, which must be valid identifiers
- **Non-terminals** included in square brackets, [test], [t] and [e] here, which stand for arbitrary expressions
- Symbols included in quotations marks, e.g. ":="

The limitations on the form of a syntax rule are that it must include at least one symbol or keyword, and there must be no repeated variables standing for non-terminals. Rules can use previously defined rules, but may not be recursive. The following syntax extensions would therefore be valid:

10.2 Literate programming

Like Haskell, IDRIS supports *literate* programming. If a file has an extension of .lidr then it is assumed to be a literate file. In literate programs, everything is assumed to be a comment unless the line begins with a greater than sign >, for example:

```
> module literate;
This is a comment. The main program is below
> main : IO ();
> main = putStrLn "Hello literate world!\n";
```

An additional restriction is that there must be a blank line between a program line (beginning with >) and a comment line (beginning with any other character).

10.3 Foreign function calls

For practical programming, it is often necessary to be able to use external libraries, particularly for interfacing with the operating system, file system, networking, etc. IDRIS provides a lightweight foreign function interface for achieving this, as part of the prelude. For this, we assume a certain amount of knowledge of C and the gcc compiler. First, we define a datatype which describes the external types we can handle:

```
data FTy = FInt | FFloat | FChar | FString | FPtr | FUnit;
```

Each of these corresponds directly to a C type. Respectively: int, float, char, char*, void* and void. There is also a translation to a concrete IDRIS type, described by the following function:

```
interpFTy : FTy -> Set;
interpFTy FInt = Int;
interpFTy FFloat = Float;
interpFTy FChar = Char;
interpFTy FString = String;
interpFTy FPtr = Ptr;
interpFTy FUnit = ();
```

A foreign function is described by a list of input types and a return type, which can then be converted to an IDRIS type:

```
ForeignTy : (xs:List FTy) -> (t:FTy) -> Set;
```

A foreign function is assumed to be impure, so ForeignTy builds an IO type, for example:

```
Idris> ForeignTy [FInt, FString] FString
Int -> String -> IO String : Set

Idris> ForeignTy [FInt, FString] FUnit
Int -> String -> IO () : Set
```

We build a call to a foreign function by giving the name of the function, a list of argument types and the return type. The built in function mkForeign converts this description to a function callable by IDRIS

```
data Foreign : Set -> Set where
   FFun : String -> (xs:List FTy) -> (t:FTy) ->
        Foreign (ForeignTy xs t);

mkForeign : Foreign x -> x;
```

For example, the putStr function is implemented as follows, as a call to an external function putStr defined in the run-time system:

```
putStr : String -> IO ();
putStr x = mkForeign (FFun "putStr" [FString] FUnit) x;
```

Include and linker directives

Foreign function calls are translated directly to calls to C functions, with appropriate conversion between the IDRIS representation of a value and the C representation. Often this will require extra libraries to be linked in, or extra header and object files. This is made possible through the following directives:

• %lib "x" — include the libx library, equivalent to passing the -lx option to gcc.

- %include "x.h" use the header file x.h.
- %obj "x.o" link with the object file x.o.

11 Further Reading

Further information about IDRIS programming, and programming with dependent types in general, can be obtained from various sources:

- The IDRIS web site (http://idris-lang.org/) and by asking questions on the mailing list.
- Examining the prelude and exploring the samples in the distribution.
- Various papers (e.g. [1, 2, 3]). These mostly describe older versions of IDRIS.

References

- [1] E. Brady. Idris systems programming meets full dependent types. In *Programming Languages meets Program Verification (PLPV 2011)*, pages 43–54, 2011.
- [2] E. Brady and K. Hammond. Scrapping your inefficient engine: using partial evaluation to improve domain-specific language implementation. In *ICFP '10: Proceedings of the 15th ACM SIGPLAN International Conference on Functional Programming*, pages 297–308, New York, NY, USA, 2010. ACM.
- [3] E. Brady and K. Hammond. Resource-safe systems programming with embedded domain specific languages. In *Practical Applications of Declarative Languages* 2012, LNCS. Springer, 2012. To appear.
- [4] W. A. Howard. The formulae-as-types notion of construction. In J. P. Seldin and J. R. Hindley, editors, *To H.B.Curry: Essays on combinatory logic, lambda calculus and formalism*. Academic Press, 1980. A reprint of an unpublished manuscript from 1969.
- [5] C. McBride and J. McKinna. The view from the left. *Journal of Functional Programming*, 14(1):69–111, 2004.
- [6] S. Peyton Jones et al. Haskell 98 language and libraries the revised report. Available from http://www.haskell.org/, December 2002.