



Course Name: Machine Learning

Weekly Report: 7

Group Name: XYZ

Submitted to faculty:

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WORK DONE THIS WEEK

- The UAV-based MOT platform requires development of the tracklet merging algorithm through successive iterations.
- Used previously collected feature extraction insights to change the tracklet merging protocol.
- Systematically tested new configurations:
 - Different temporal-spatial weightings
 - Fusion of appearance and motion-based features
- A detailed assessment took place through advanced benchmarking scripts which evaluated fresh segments from video content.
- Measures for evaluation includes logged results for comparison through metrics that followed.
 - Merge accuracy
 - False merges and missed merges
 - Computational time per evaluation cycle
- Periodic modifications take place for association scoring mechanics and threshold parameters to address various circumstances:
 - Overlapping tracks
 - Short tracklets
 - Gaps due to missed detections