



Course Name: Machine Learning

Weekly Report: 6

Group Name: XYZ

Submitted to faculty:

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WORK DONE THIS WEEK

Work Done This Week

- The development of tracklet merging software for UAV-based multi-object tracking (MOT) continues in offline operations.
- The research performed feature extraction tests with multiple spatio-temporal description methods such as speed along with direction consistency and appearance similarity.
- An assessment was performed to determine how variable features affect the precision of tracklet association.
- We executed evaluation scripts to study the successful integration rate under demanding circumstances consisting of:
 - Occlusion
 - Abrupt motion changes
 - Missed detections and identity switches

Refined association logic using:

- Temporal distance thresholds
- Spatial overlap scoring
- Cosine distance along with color histograms served as the feature similarity scoring method.
- First tests of tracklet association methods took place with provided vehicle tracklet examples.

WORK TO BE DONE NEXT WEEK

- Further fine-tune and benchmark the merging algorithm across more UAV test videos.
- Multiple features should be integrated into a single scoring function.
- Create a Python system framework which combines tracklets while developing visual outcome display methods.
- The system should receive updates to allow separate evaluation of individual system components.
- Collect metrics on:
 - Tracklet merge precision and recall
 - Number of correct associations
 - Impact of each feature extraction technique