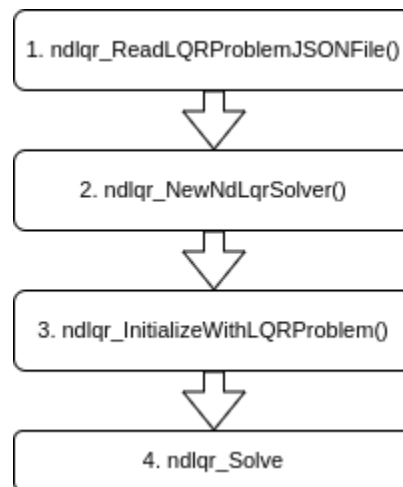


Data flow before ndlqr_Solve()

As stated in our report, the flow of function calls in the rsLQR algorithm can be summarized, on a high-level, as follows:



The main function of the rsLQR algorithm looks like this:

```
int main() {
    printf("This is the example using an installed rsLQR package!.\n\n");
    // Read an LQRProblem from a json file
    const char* filename = LQRPROBFILE;
    LQRProblem* lqrprob = ndlqr_ReadLQRProblemJSONFile(filename);
    int nstates = lqrprob->lqrdata[0]->nstates;
    int ninputs = lqrprob->lqrdata[0]->ninputs;
    int nhorizon = lqrprob->nhorizon;

    // Initialize the solver and solve
    NdLqrSolver* solver = ndlqr_NewNdLqrSolver(nstates, ninputs, nhorizon);
    if (ndlqr_InitializeWithLQRProblem(lqrprob, solver) == 0) {
        ndlqr_Solve(solver);
    }

    // Print the solve summary
    ndlqr_PrintSolveSummary(solver);

    // Free the problem data and the solver
    ndlqr_FreeLQRProblem(lqrprob);
    ndlqr_FreeNdLqrSolver(solver);
    return 0;
}
```

In a separate file, we already discussed the data flow in `4. ndlqr_Solve()`. Thus, we now discuss the data flow in the first three functions. For the sake of understanding, we will take an example case to discuss the data flow. In our example, $ninputs = m = 5$, $nstates = n = 100$, and $nhorizon = N = 4$.

1. `ndlqr_ReadLQRProblemJSONFile()`: The known values in the equations of the LQR problem get populated into an object of the `LqrProblem` class.
2. `ndlqr_NewNdLqrSolver()`: Contiguous memory is allocated for the following:
 - a. `diagonals`: An array of size $2N$. `diagonals[2k]` and `diagonals[2k+1]` together make one block. Thus, `diagonals` has 4 blocks. The first element in the block is of size $n \times n = 100 \times 100$. The second element in the block is of size $m \times m = 5 \times 5$.
 - b. `data` (`NdData`): $nsegments = N - 1 = 3$, $depth = \log_2(N) = 2$, `factors` = an array of size $N * depth = 8$. Each element in `factors` is an `NdFactor`, in which `lambda` matrix is of size 100×100 , `state` matrix is of size 100×100 , and `input` matrix is of size 5×100 .
 - c. `fact` (`NdData`): same memory allocation size as `data`.
 - d. `soln` (`NdData`): same memory allocation size as `data`, except that $depth = 1$ and `factors` = an array of size $N * depth = 4$.
3. `ndlqr_InitializeWithLQRProblem()`: This is used to initialize the `factors` array, of both `data` and `soln`.
 - a. `data` (`NdData`): Indices 0, 1, 2, 3, 5, and 6 of `factors` get initialized with values from `LqrProblem`. Indices 4 and 7 are skipped. This is due to the structure of the `LqrProblem` `H` matrix. Further, `lambda` matrices are not initialized. Only `state` and `input` matrices are.
 - b. `soln` (`NdData`): All indices (0, 1, 2, and 3) get initialized. And, all the `lambda`, `state`, and `input` matrices are initialized, except for the `input` matrix of index 3. This is because $N = 4$, meaning, **index 3 corresponds to the final time step, which does not require an input.**