
Double tracking antennas for drone communication

- Automation and control -

Project Report
Group 832

Aalborg University
Electronics and IT

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AALBORG UNIVERSITY STUDENT REPORT

Title:

Double tracking antennas for drone communication

Abstract:

Here is the abstract

Theme:

Multivariable control

Project Period:

Spring Semester 2016

Project Group:

Group: 832

Participant(s):

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Copies: 1**Page Numbers:** 20**Date of Completion:**

February 4, 2016

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Double tracking antennas for drone communication

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Her er resuméet

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Multivariable control

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Deltager(e):

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Oplagstal: 1**Sidetal:** 20**Afleveringsdato:**

4. februar 2016

Rapportens indhold er frit tilgængeligt, men offentliggørelse (med kildeangivelse) må kun ske efter aftale med forfatterne.

Contents

Preface	xi
1 Introduction	1
2 Scenario	3
2.1 Rescue missions	3
2.1.1 What do they do today?	3
2.1.2 Compare the rescue missions	3
2.2 Pipeline survey	3
3 Hardware setup	5
3.1 Drone (eBee)	5
3.2 Basestation	6
3.2.1 Laptop	6
3.2.2 Antennas	6
3.2.3 Gimbals (Camera)	6
4 Telecommunication	7
4.1 Telemetry	7
4.2 MavLink (protocol)	7
4.3 Link Budget	7
5 Verification	9
6 Simulation	11
6.1 Drone model	11
6.2 Controller	11
6.3 V-Rep	11
6.4 Drone in real life (real data)	11
7 Discussion	13

8 Conclusion	15
Bibliography	17
A Appendix LaTeX Tips	19
A.1 Example 1	19
A.2 How Does Sections, Subsections, and Subsections Look?	19
A.2.1 This is a Subsection	19
A.3 Example 2	20

Todo list

■ Is it possible to add a subsubparagraph?	20
■ I think that a summary of this exciting chapter should be added.	20
■ I think this word is misspelled	20
Figure: We need a figure right here!	20

Preface

Here is the preface. You should put your signatures at the end of the preface.

Aalborg University, February 4, 2016

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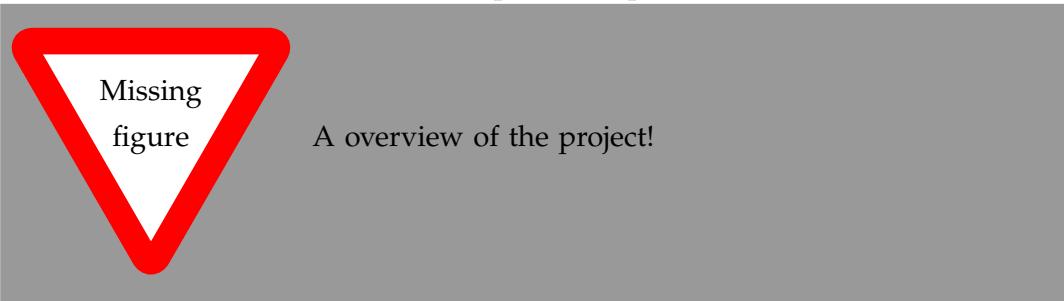
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Chapter 1

Introduction

Here is the introduction. The next chapter is chapter 2.



Chapter 2

Scenario

So what is this all about?

2.1 Rescue missions

2.1.1 What do they do today?

2.1.2 Compare the rescue missions

2.2 Pipeline survey

The pipeline survey could be to transport oil from a factory to another facility. To ensure that there is no thieves that want to steal the oil, they have to hire people to patrol. Instead they could use a drone to search the area. Potential danger



Figure 2.1: Pipeline survey

- Terrorist

- Thiefs

Chapter 3

Hardware setup

Our hardware setup.

3.1 Drone (eBee)



Figure 3.1: The professional mapping drone *eBee* (www.sensefly.com). Fully autonomous drone to capture high-resolution aerial photos that can transform into accurate 2D orthomosaics & 3D models.

3.2 Basestation

3.2.1 Laptop

3.2.2 Antennas

3.2.3 Gimbals (Camera)

Chapter 4

Telecommunication

Our telecommunication.

4.1 Telemetry

4.2 MavLink (protocol)

4.3 Link Budget

Chapter 5

Verification

Our verification.

Chapter 6

Simulation

Our simulations.

6.1 Drone model

6.2 Controller

6.3 V-Rep

6.4 Drone in real life (real data)

Chapter 7

Discussion

Our discussion.

Chapter 8

Conclusion

Our conclusion.

Bibliography

- [1] Lars Madsen. *Introduktion til LaTeX*. <http://www.imf.au.dk/system/latex/bog/>. 2010.
- [2] Frank Mittelbach. *The LATEX companion*. 2. ed. Addison-Wesley, 2005.
- [3] Tobias Oetiker. *The Not So Short A Introduction to LaTeX2e*. <http://tobi.oetiker.ch/lshort/lshort.pdf>. 2010.

Appendix A

Appendix LaTeX Tips

A.1 Example 1

You can also have examples in your document such as in example A.1.

Example A.1 (An Example of an Example)

Here is an example with some math

$$0 = \exp(i\pi) + 1 . \quad (\text{A.1})$$

You can adjust the colour and the line width in the `macros.tex` file.

A.2 How Does Sections, Subsections, and Subsections Look?

Well, like this

A.2.1 This is a Subsection

and this

This is a Subsubsection

and this.

A Paragraph You can also use paragraph titles which look like this.

A Subparagraph Moreover, you can also use subparagraph titles which look like this. They have a small indentation as opposed to the paragraph titles.

I think that a summary of this exciting chapter should be added.

Is it possible to add
subparagraph?

A.3 Example 2

I think this word is misspelled

Here is chapter 2. If you want to learn more about $\text{\LaTeX} 2\epsilon$, have a look at [1], [3] and [2].

