

深度學習 之 Keras 高級技巧

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Outline

- Sequential Review
- Model (Functional API)
- Final Challenge

Sequential Review

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

```
In [2]: model = Sequential()
```

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

model

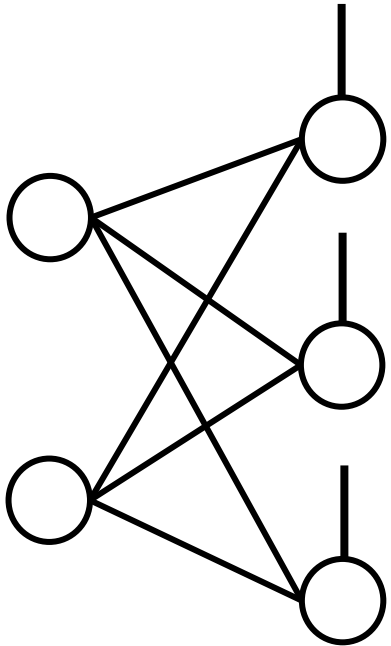
```
In [2]: model = Sequential()
```

```
In [3]:
```

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

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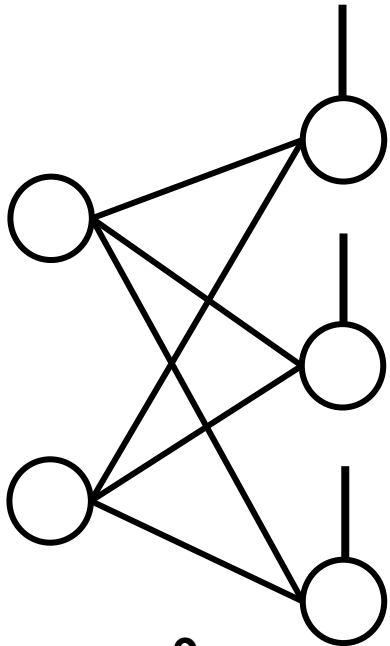
```
In [2]: model = Sequential()
```

```
In [3]: model.add(Dense(3, input_shape=(2, )))
```

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

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```
In [2]: model = Sequential()
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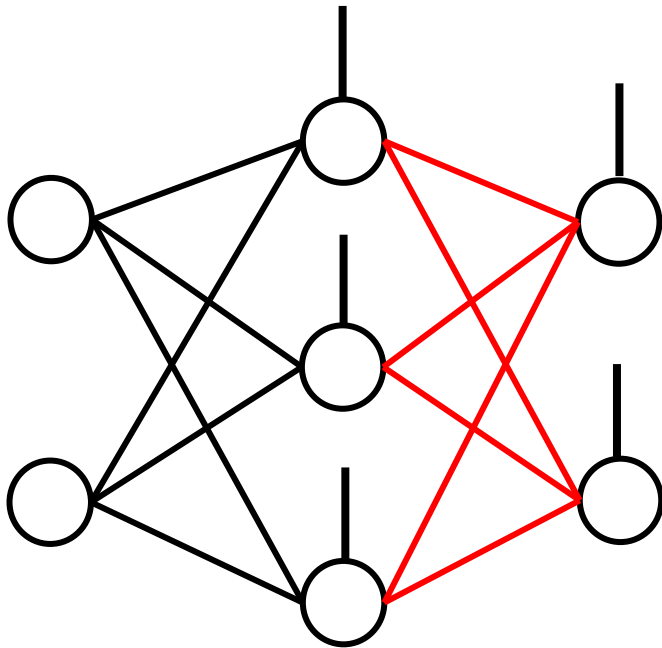
```
In [3]: model.add(Dense(3, input_shape=(2, )))
```

```
In [4]: model.summary()
```


Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

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In [2]: model = Sequential()
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```
In [3]: model.add(Dense(3, input_shape=(2, )))
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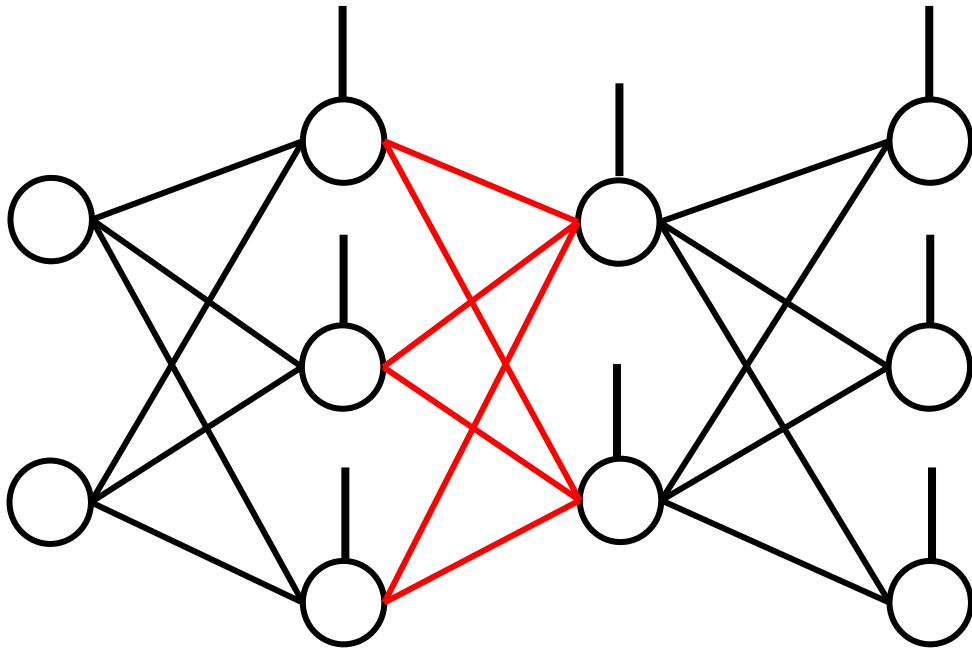
```
In [4]: model.summary()
```

```
In [5]: model.add(Dense(2))
```

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

model



```
In [2]: model = Sequential()
```

```
In [3]: model.add(Dense(3, input_shape=(2, )))
```

```
In [4]: model.summary()
```

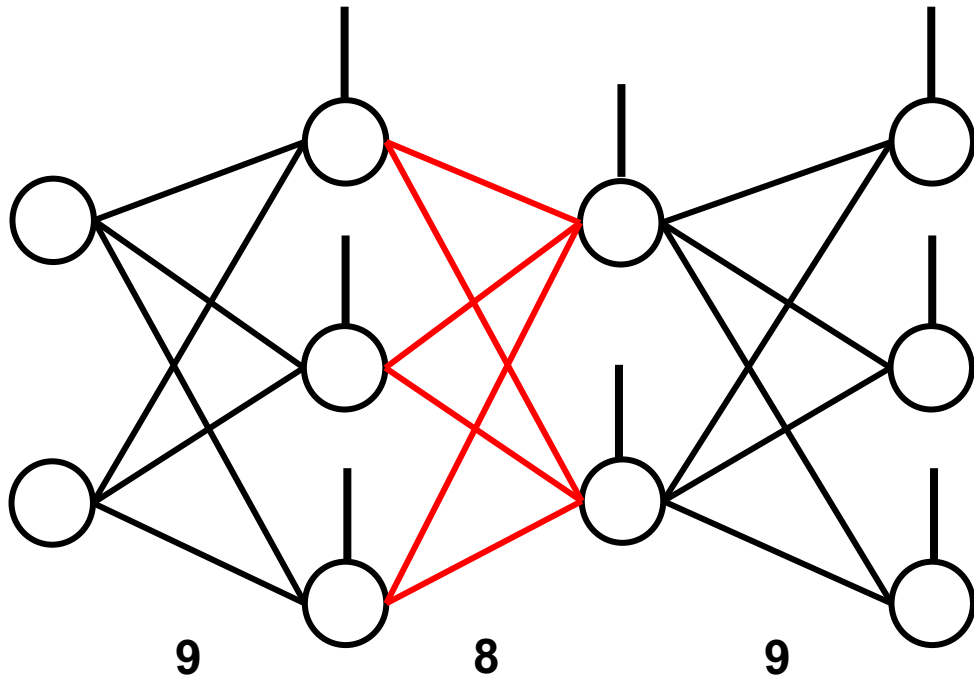
```
In [5]: model.add(Dense(2))
```

```
In [6]: model.add(Dense( 3 ))
```

Syntax to Neural Network

- When enter a Keras syntax and execute it, what would you think?

model



```
In [2]: model = Sequential()
```

```
In [3]: model.add(Dense(3, input_shape=(2, )))
```

```
In [4]: model.summary()
```

```
In [5]: model.add(Dense(2))
```

```
In [6]: model.add(Dense( 3 ))
```

```
In [7]: model.summary()
```

Parameter Counting

- How many parameters we have when a layer is added?
 - e.g., Dense, Conv1D, Conv2D, SimpleRNN, LSTM
- To simplify your observation, use simple model w/o hidden layer and set unit = 1, 2 or 3 to see how the # of parameters changed?

Parameter Counting

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 - e.g., Dense, Conv1D, Conv2D, SimpleRNN, LSTM
- To simplify your observation, use simple model w/o hidden layer and set unit = 1, 2 or 3 to see how the # of parameters changed?

```
In [ ]: model_1 = Sequential()
In [ ]: model_1.add(Dense(2, input_shape=(2, )))
In [ ]: model_1.summary()

In [ ]: model_2 = Sequential()
In [ ]: model_2.add(Dense(3, input_shape=(2, )))
In [ ]: model_2.summary()
```

Parameter Counting

- How many parameters we have when a layer is added?
 - e.g., Dense, Conv1D, Conv2D, SimpleRNN, LSTM
- To simplify your observation, use simple model w/o hidden layer and set unit = 1, 2 or 3 to see how the # of parameters changed?

```
In [ ]: model_3 = Sequential()
In [ ]: model_3.add(Dense(3, input_shape=(2, )))
In [ ]: model_3.summary()

In [ ]: model_4 = Sequential()
In [ ]: model_4.add(Dense(2, input_shape=(3, )))
In [ ]: model_4.summary()
```

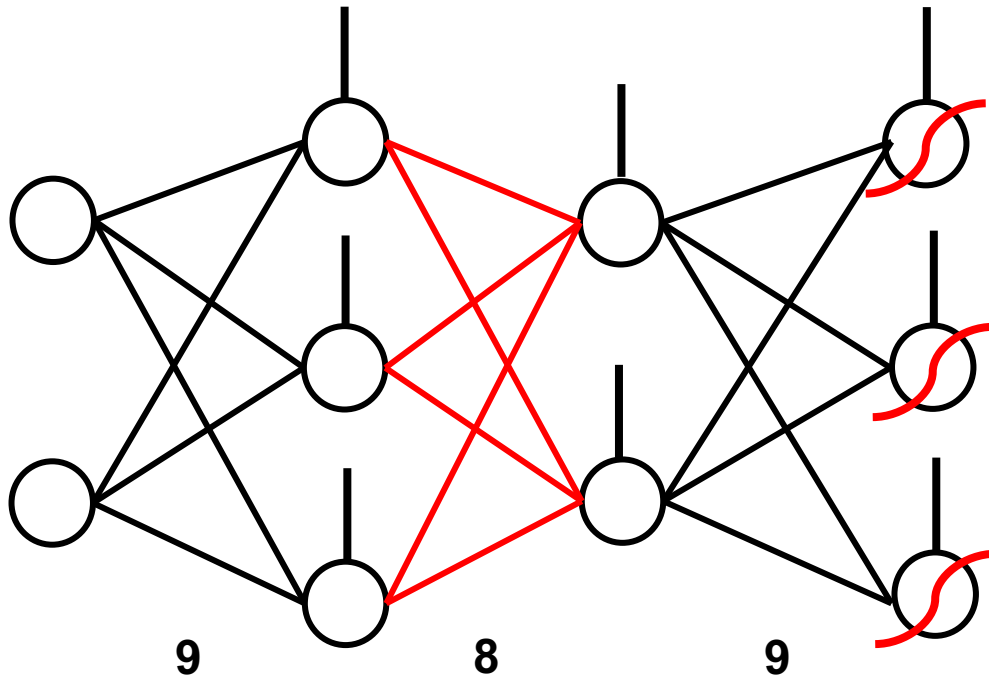
Parameter Counting

- You must try conv1D and Conv2D to see how they work in your model.
- SimpleRNN and LSTM is relative easy to understand.
- However, I suggest you to go through it by yourself.

Parameter Counting

- Activation unction doesn't affect the # of parameters.

model



```
In [ ]: model = Sequential()

In [ ]: model.add(Dense(3, input_shape=(2, )))

In [ ]: model.add(Dense(2))

In [ ]: model.add(Dense( 3 ))

In [ ]: model.add(Activation('sigmoid'))

In [ ]: model.summary()
```

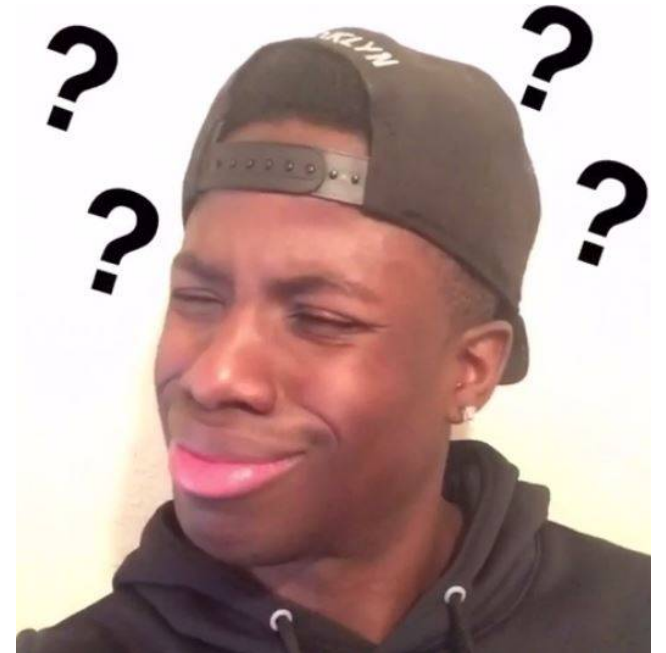
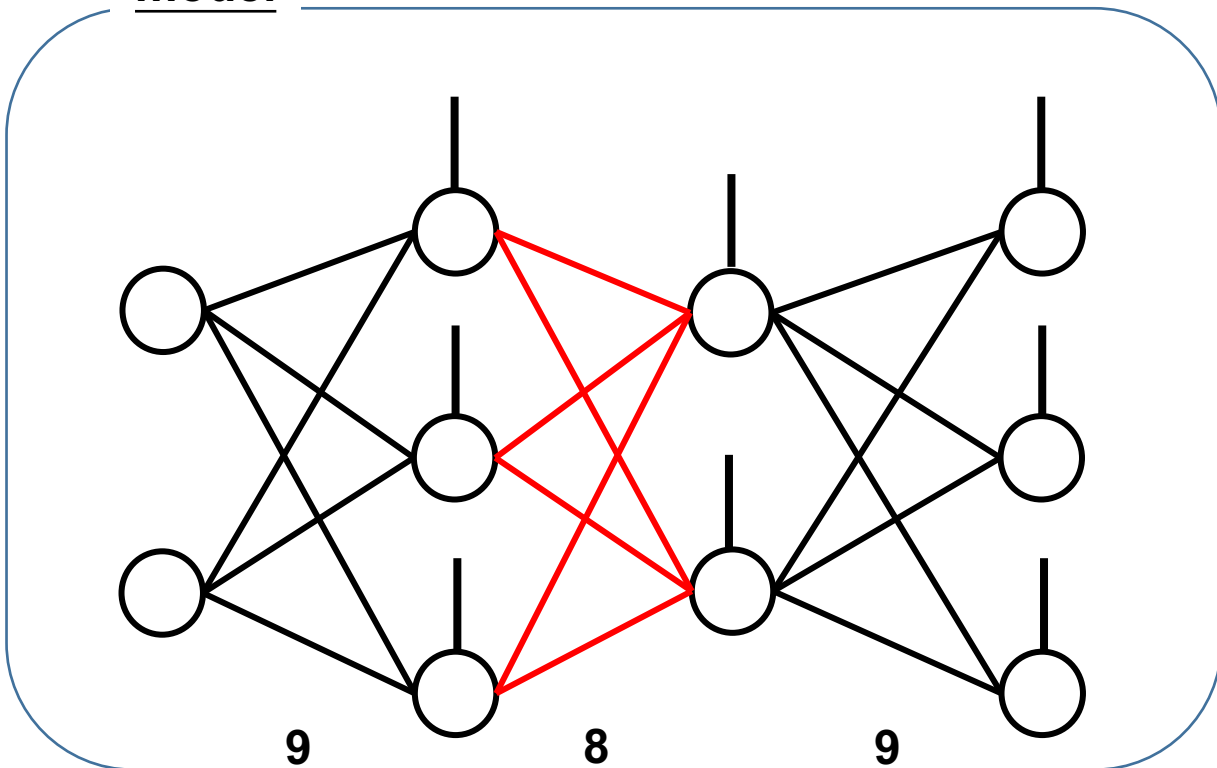

Conclusion

- The **Sequential** model is a linear stack of layers.
- Pros: You can define your network layer-by-layer, you don't need to take care those layers we have already defined.
- Cons: When you want to modified some layers, you need to re-defined **EVERYTHING** in your model from the very beginning !

Some Black Magic – Shared Layer

- If we want first 9 weights and last 9 weights to be the same.
- We have no idea how to formulate using Sequential API.

model

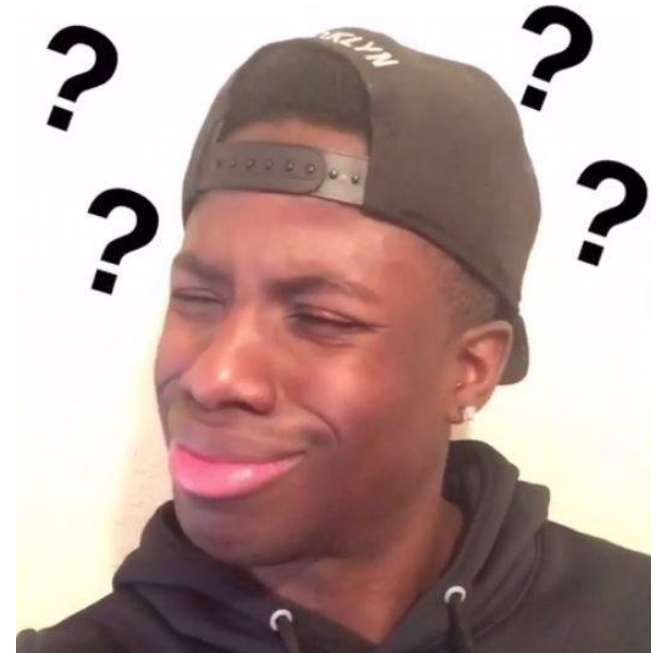
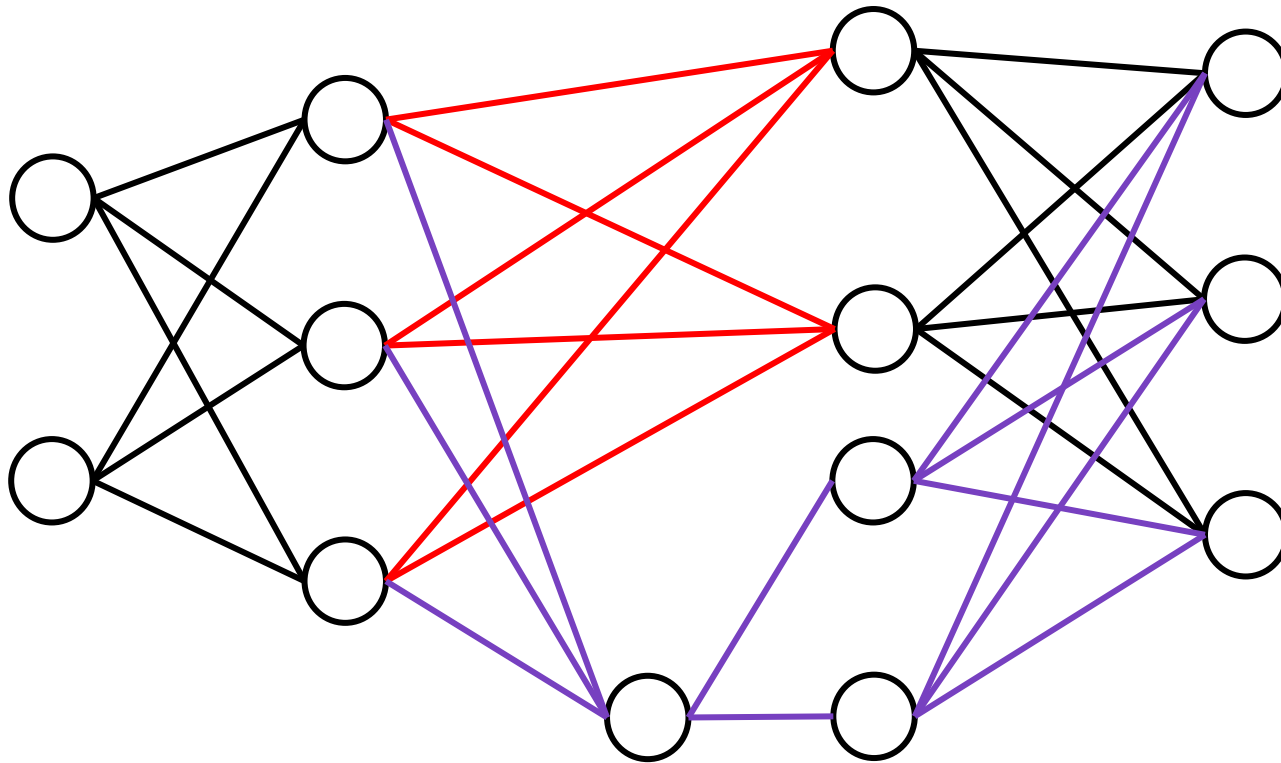


Some Black Magic – Branch or Merge

- If we want our model has branch in some place and merge together in other place.
- We have no idea how to formulate using Sequential API.

Some Black Magic – Branch or Merge

model



Model (Functional API)

Sequential v.s. Model

- Sequential: create a “sandbox”, then build your NN model layer-by-layer.
- Model: create the connection between layers (and I/O on each layer), then “model” them as a NN model.
- Some Pros: only need to define the relation of I/O on each layer, easy to create sub-models.

What does Functional means?

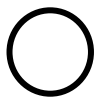
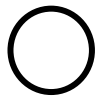
- We can use Keras syntax as well as function composition!
- If you like mathematical notations (especial, functions) more than Keras syntax.

You're welcome !

Syntax to Neural Network Revisit

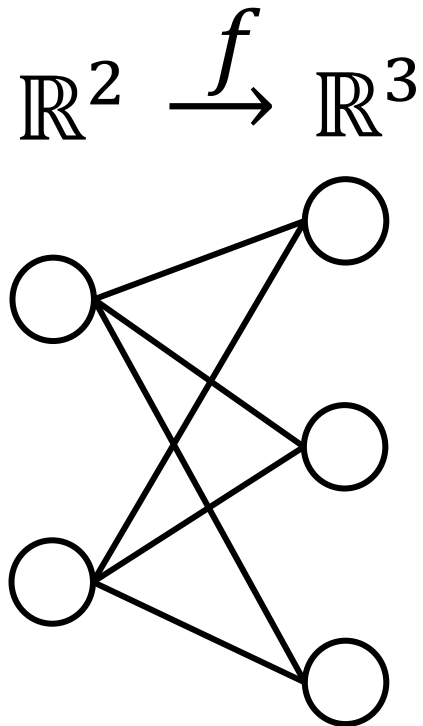
- When enter a Keras syntax and execute it, what would you think?

\mathbb{R}^2



Syntax to Neural Network Revisit

- When enter a Keras syntax and execute it, what would you think?

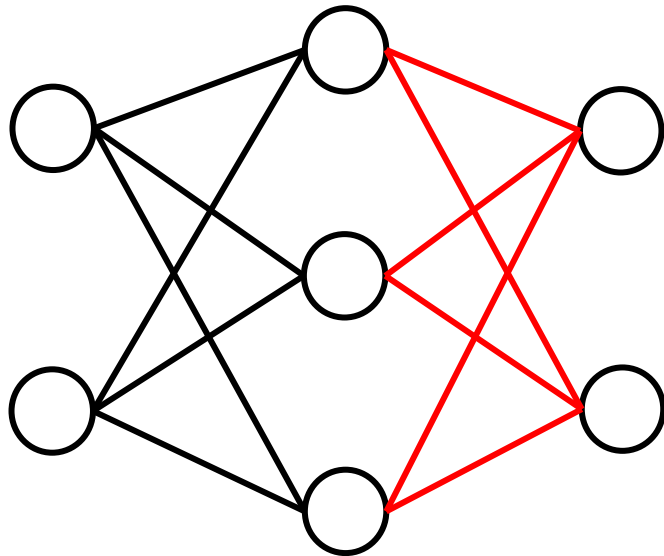


$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$u = f(x) = \sigma(\mathbf{W}^{(1)}x + \mathbf{b}^{(1)})$$

Syntax to Neural Network Revisit

- When enter a Keras syntax and execute it, what would you think?

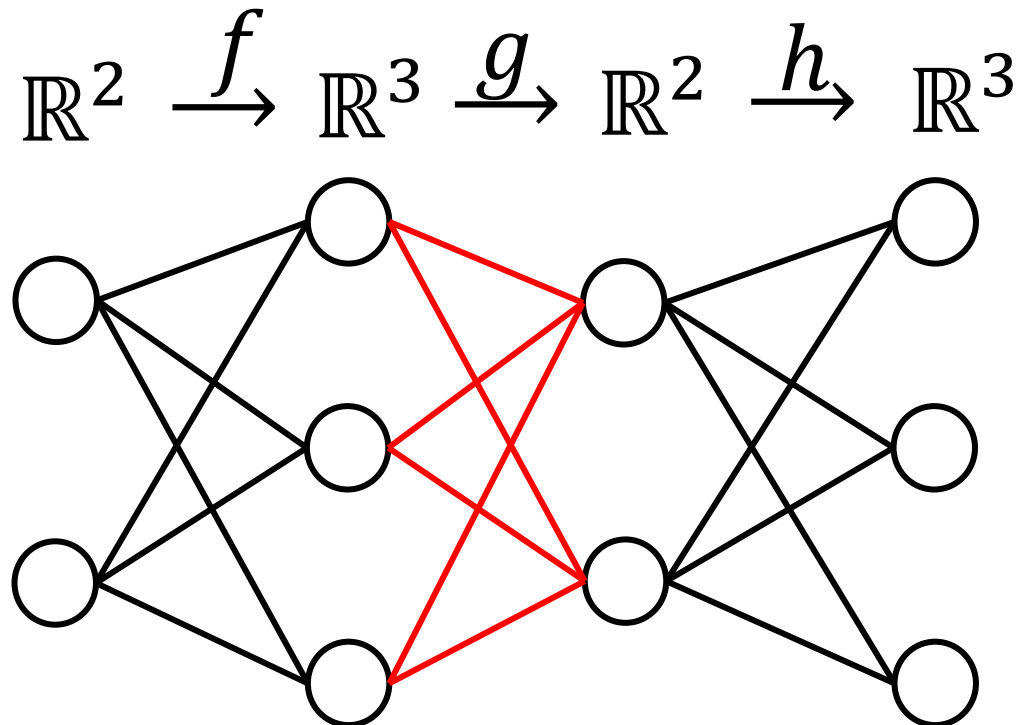
$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2$$



$$g: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$
$$v = g(u) = \sigma(\mathbf{W}^{(2)}u + \mathbf{b}^{(2)})$$

Syntax to Neural Network Revisit

- When enter a Keras syntax and execute it, what would you think?



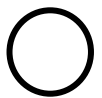
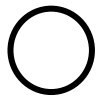
$$h: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$y = h(v) = \sigma(\mathbf{W}^{(3)}v + \mathbf{b}^{(3)})$$

Let's see how it works!

Syntax to Neural Network Revisit

\mathbb{R}^2

x

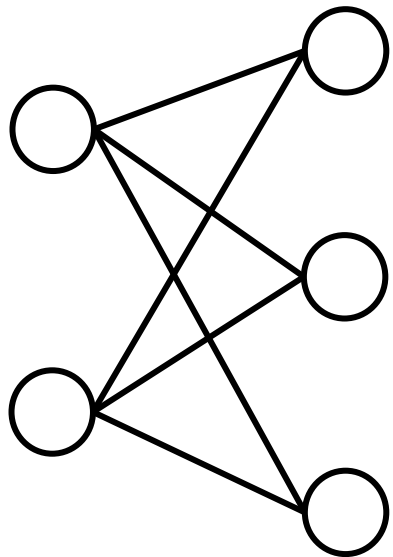


```
In [ ]: x = Input(shape=(2,))
```

Syntax to Neural Network Revisit

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3$$

$$x \mapsto u$$



$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$u = f(x) = \sigma(W^{(1)}x + b^{(1)})$$

```
In [ ]: f = Dense(3, activation='relu')
```

```
In [ ]: u = f(x)
```

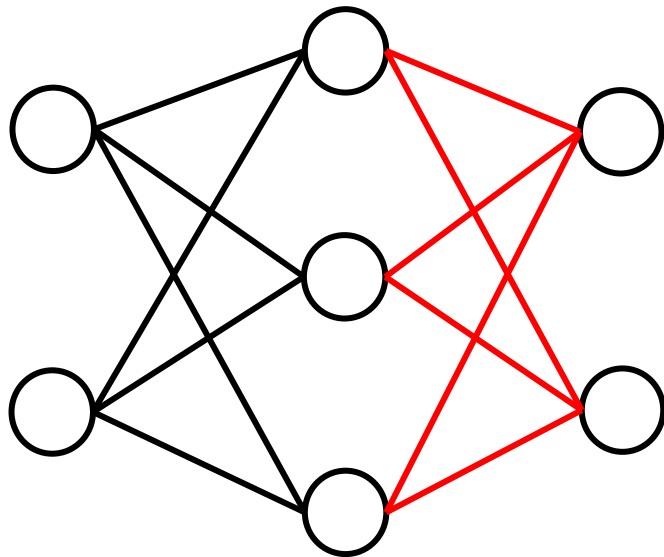
or

```
In [ ]: u = Dense(3, activation='relu')(x)
```

Syntax to Neural Network Revisit

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2$$

$$x \mapsto u \mapsto v$$



$$g: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$
$$v = g(u) = \sigma(\mathbf{W}^{(2)}u + \mathbf{b}^{(2)})$$

```
In [ ]: g = Dense(2, activation='relu')  
In [ ]: v = g(u)
```

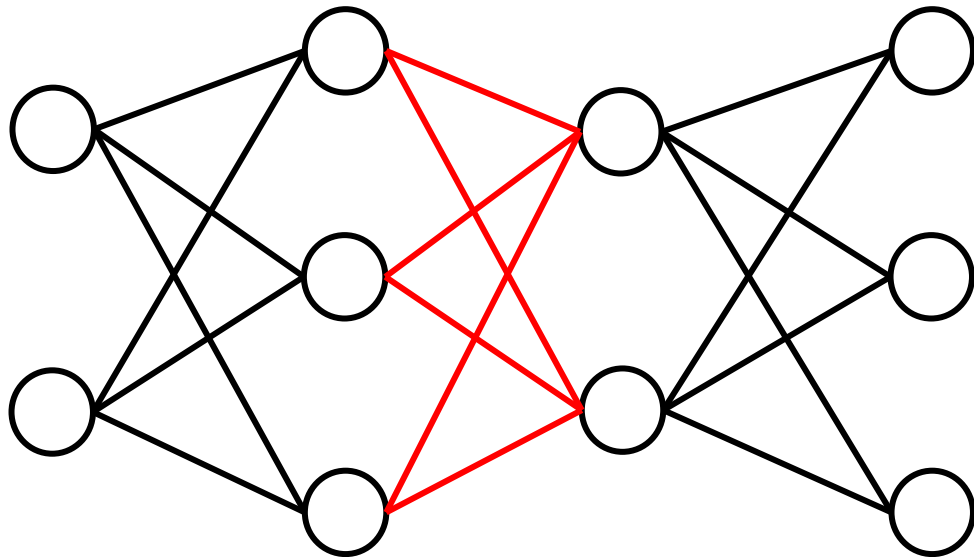
or

```
In [ ]: v = Dense(2, activation='relu')(u)
```

Syntax to Neural Network: Revisit

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{h} \mathbb{R}^3$$

$$x \mapsto u \mapsto v \mapsto y$$



$$h: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$y = h(v) = \sigma(\mathbf{W}^{(3)}v + \mathbf{b}^{(3)})$$

```
In [ ]: h = Dense(3, activation='sigmoid')
```

```
In [ ]: y = h(v)
```

or

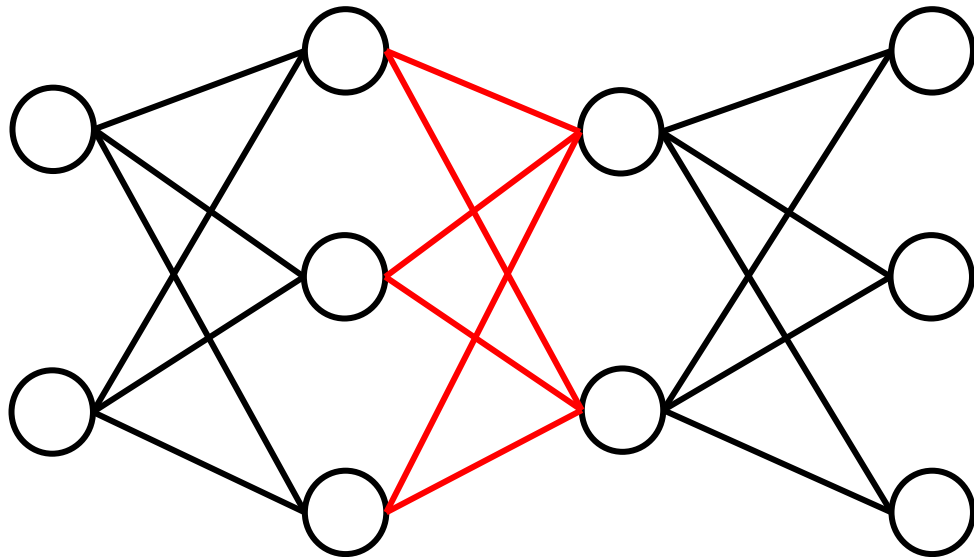
```
In [ ]: y = Dense(3, activation='sigmoid')(v)
```


Syntax to Neural Network Revisit

model

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{h} \mathbb{R}^3$$

$$x \mapsto u \mapsto v \mapsto y$$



$$h: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$y = h(v) = \sigma(\mathbf{W}^{(3)}v + \mathbf{b}^{(3)})$$

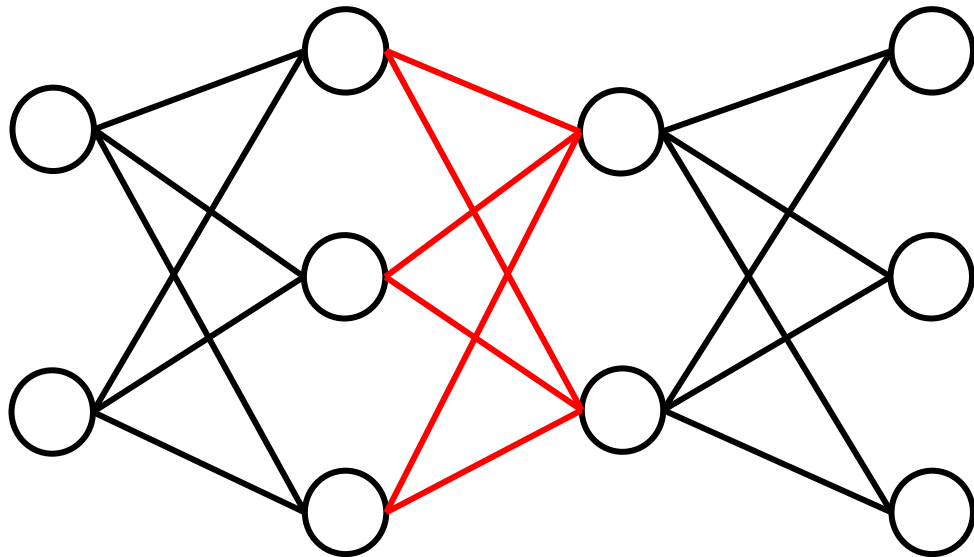
```
In [ ]: model = Model(x, y)
```

Syntax to Neural Network Revisit

model

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{h} \mathbb{R}^3$$

$$x \mapsto u \mapsto v \mapsto y$$



```
In [ ]: x = Input(shape=(2,))
```

```
In [ ]: f = Dense(3, activation='relu')
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```
In [ ]: u = f(x)
```

```
In [ ]: g = Dense(2, activation='relu')
```

```
In [ ]: v = g(u)
```

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In [ ]: h = Dense(3, activation='sigmoid')
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```
In [ ]: y = h(v)
```

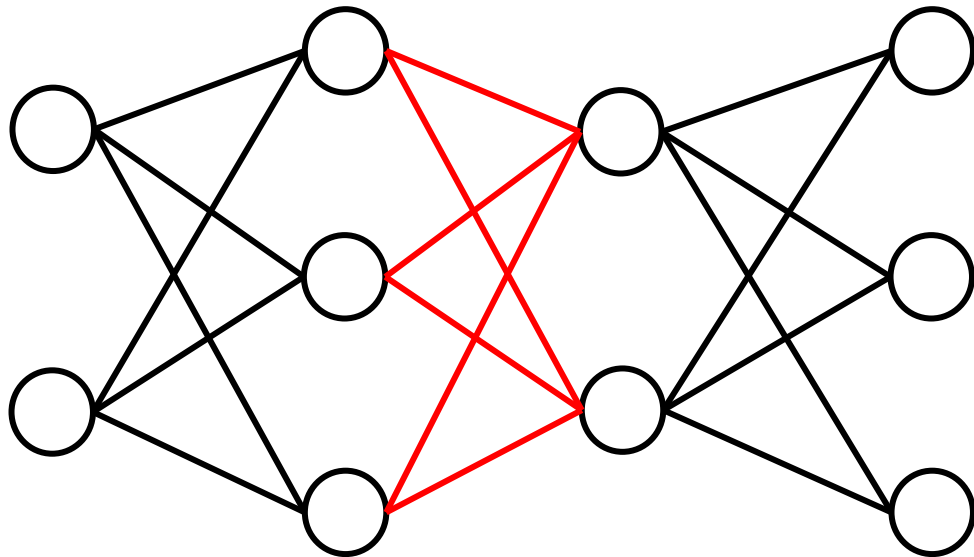
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In [ ]: model = Model(x, y)
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Syntax to Neural Network Revisit

model

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{h} \mathbb{R}^3$$

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In [ ]: x = Input(shape=(2,))
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```
In [ ]: u = Dense(3, activation='relu')(x)
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```
In [ ]: v = Dense(2, activation='relu')(u)
```

```
In [ ]: y = Dense(3, activation='sigmoid')(v)
```

```
In [ ]: model = Model(x, y)
```

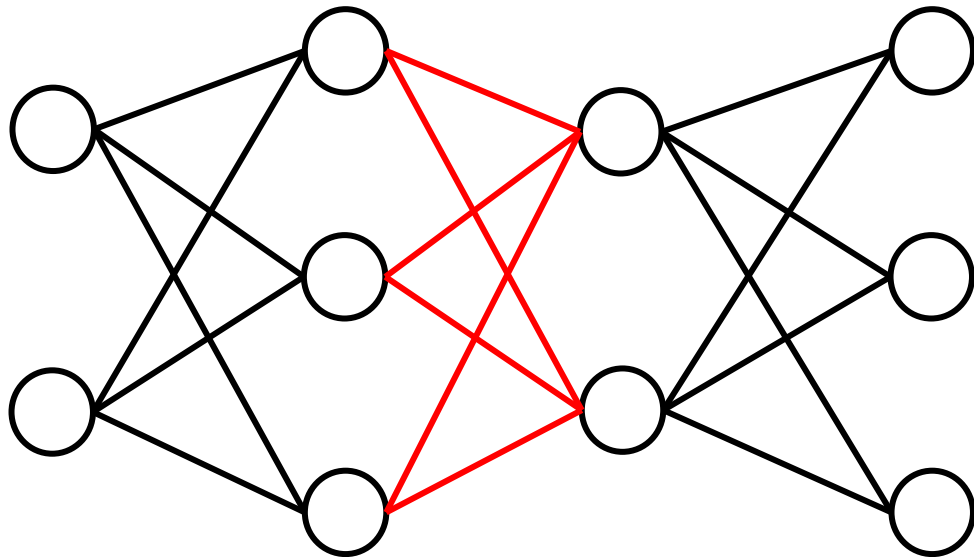
This is the same as what you did when using Sequential API

Syntax to Neural Network Revisit

model

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In [ ]: y = Dense(3, activation='sigmoid')(v)
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In [ ]: model = Model(x, y)
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This is the same as what you did when using Sequential API

Conclusion

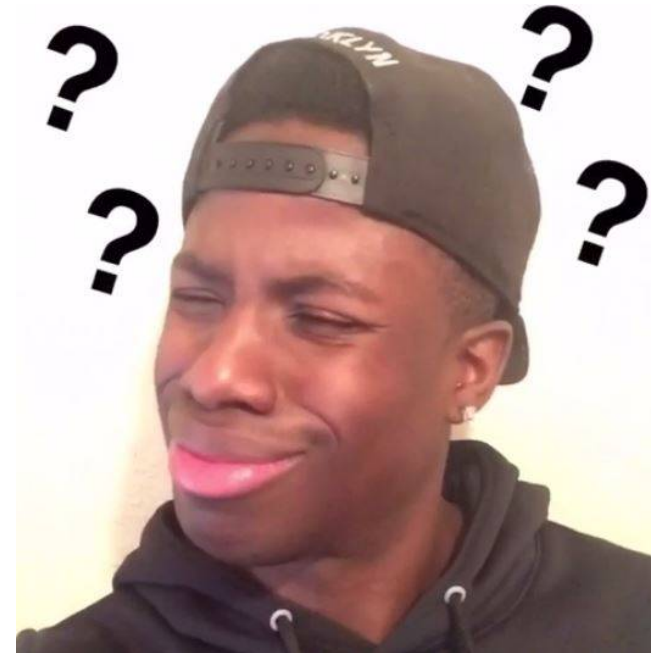
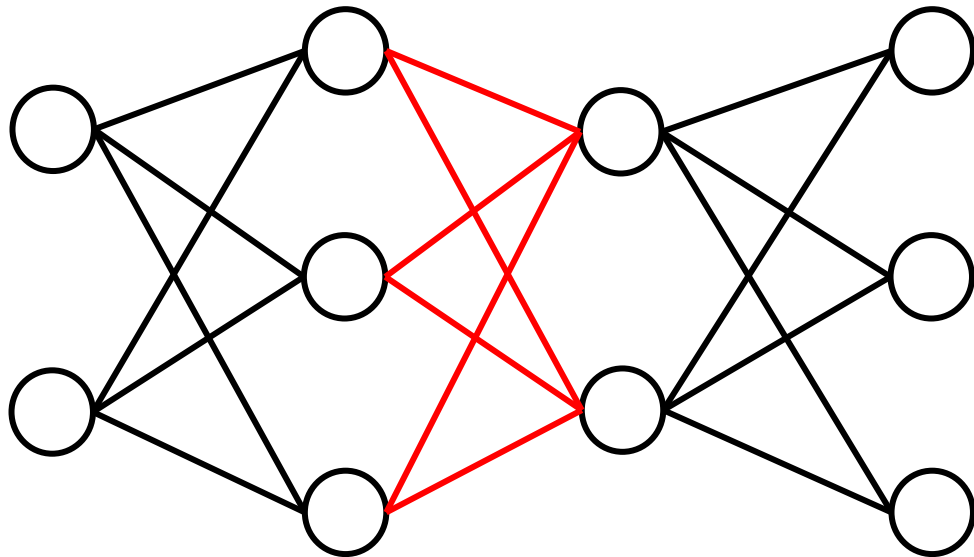
- **Model** Functional API defines the relation of I/O of each layer as well as a function.
- Variables from each layer are all available in Model case other than only I/O in Sequential case.
- Latent variables can be manipulated by user.

Black Magic Revisit – Shared Layer

- If we want first 9 weights and last 9 weights to be the same.
- How to formulate using Model API?

model

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3$$

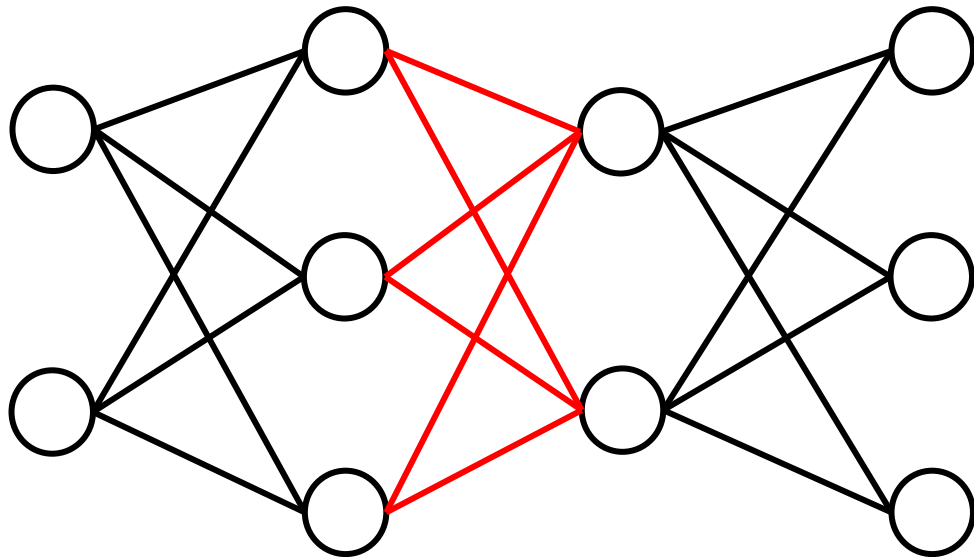


Black Magic Revisit – Shared Layer

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$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$u = f(x) = \sigma(W^{(1)}x + b^{(1)})$$

$$g: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$
$$v = g(u) = \sigma(W^{(2)}u + b^{(2)})$$

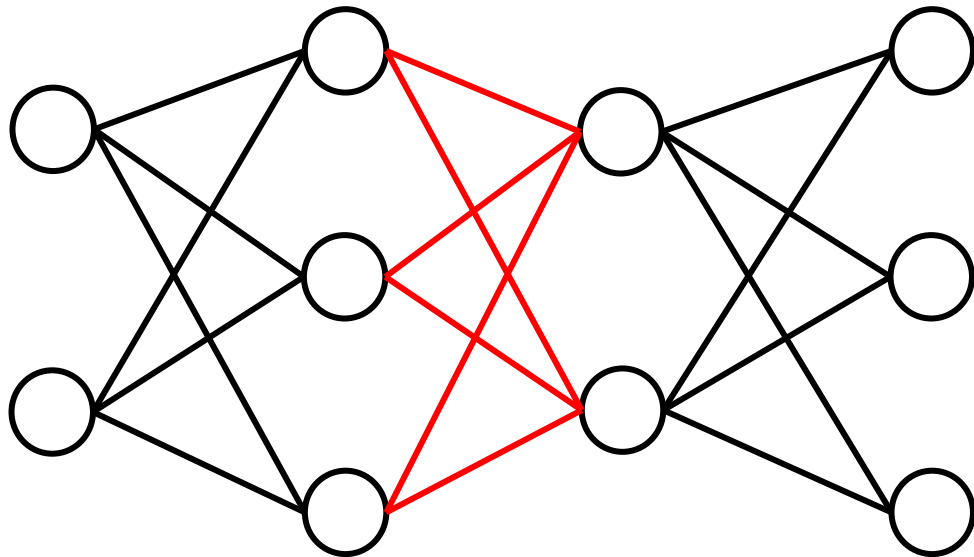
$$y = f(v) = \sigma(W^{(3)}v + b^{(3)})$$

Black Magic Revisit – Shared Layer

- If we want first 9 weights and last 9 weights to be the same.
- How to formulate using Model API?

model

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3$$



```
In [ ]: x = Input(shape=(2,))
```

```
In [ ]: f = Dense(3, activation='relu')
```

```
In [ ]: u = f(x)
```

```
In [ ]: g = Dense(2, activation='relu')
```

```
In [ ]: v = g(u)
```

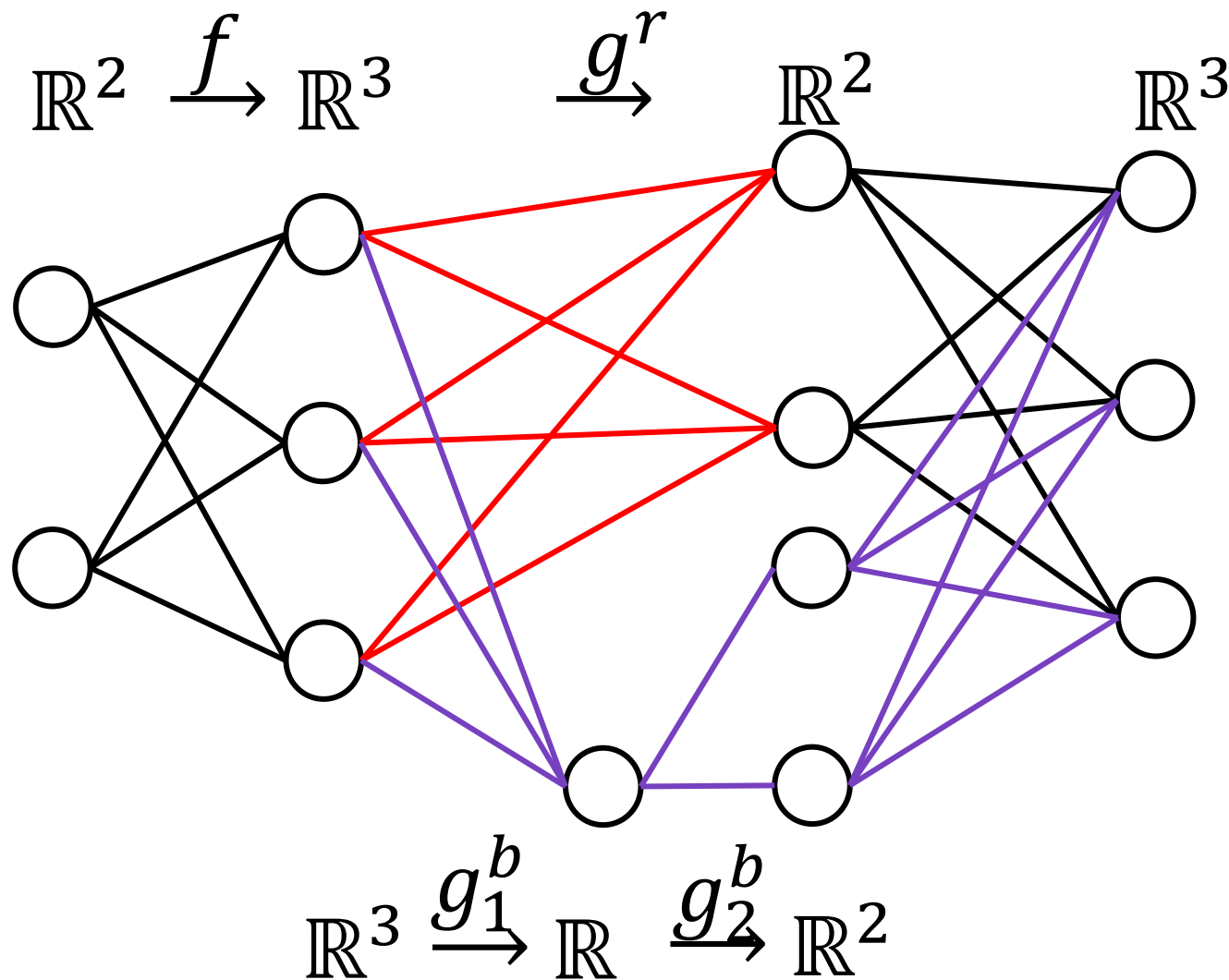
```
In [ ]: h = Dense(3, activation='sigmoid')
```

```
In [ ]: y = h(v)
```

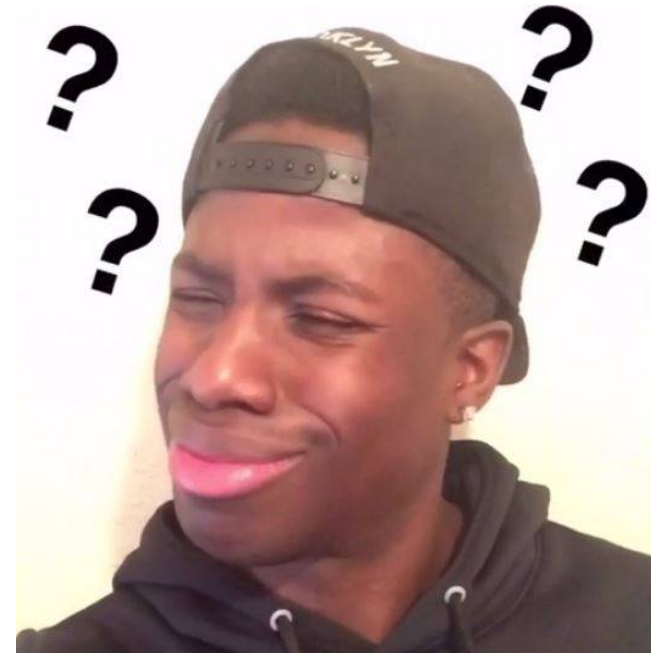
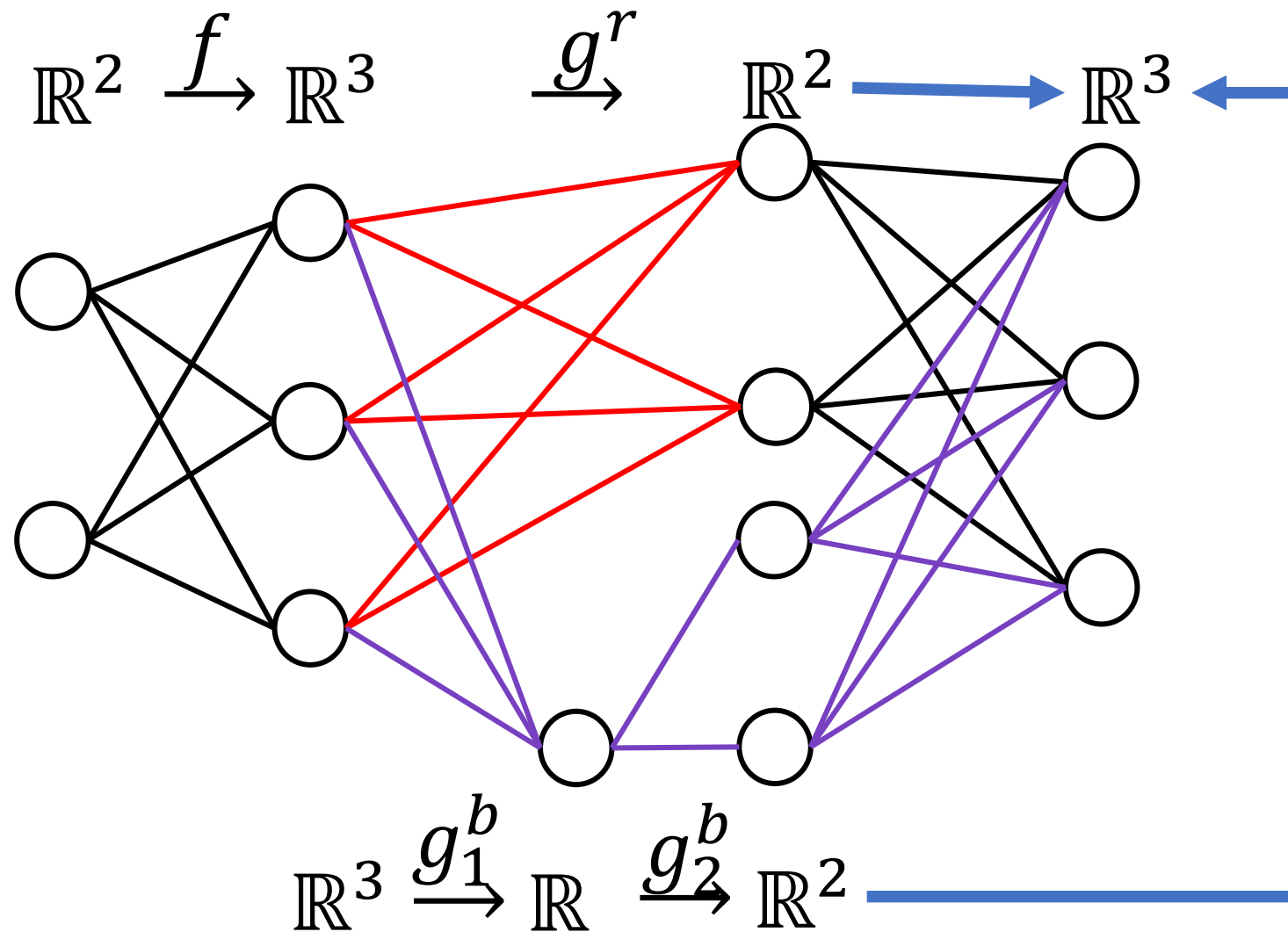
```
In [ ]: y = f(v)
```

```
In [ ]: model = Model(x, y)
```

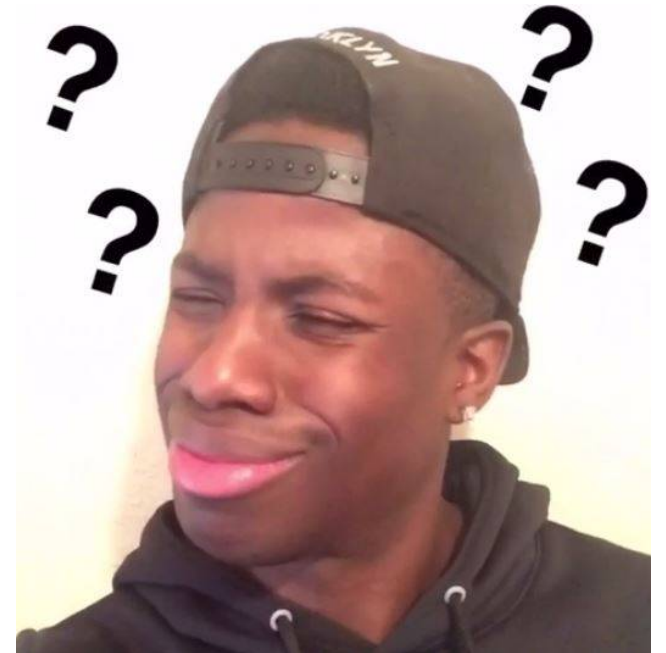
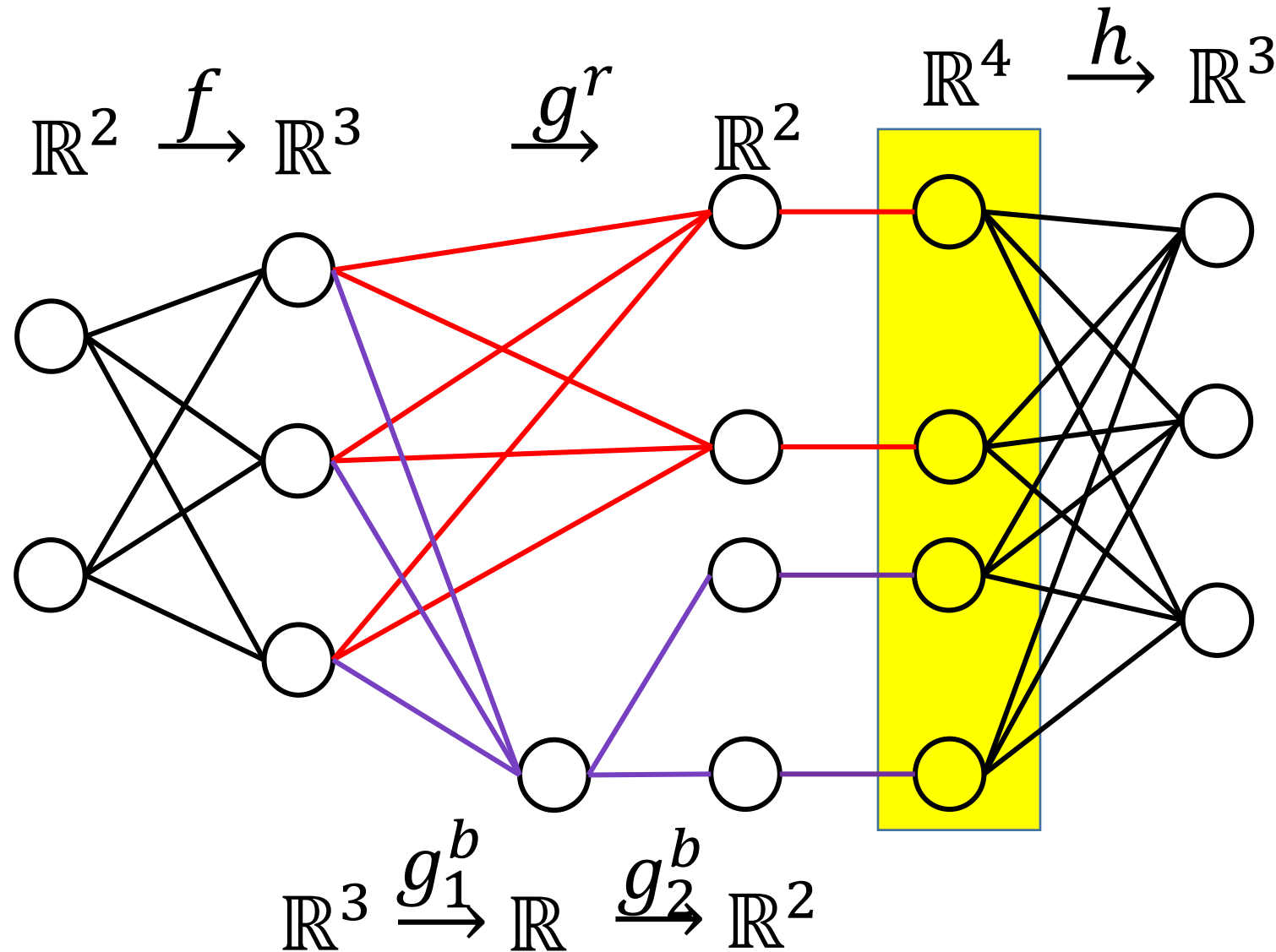

Black Magic Revisit – Branch or Merge



Black Magic Revisit – Branch or Merge



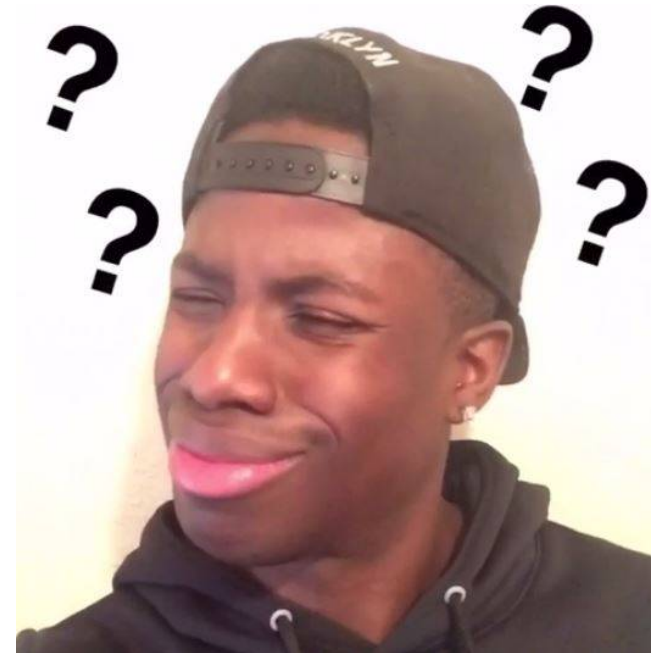
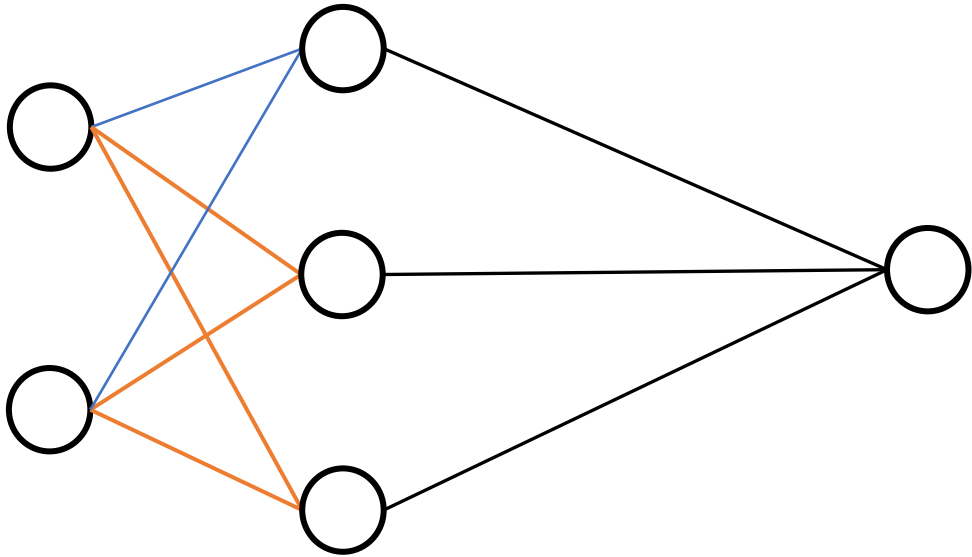
Black Magic Revisit – Branch or Merge



Black Magic Revisit – Branch or Merge

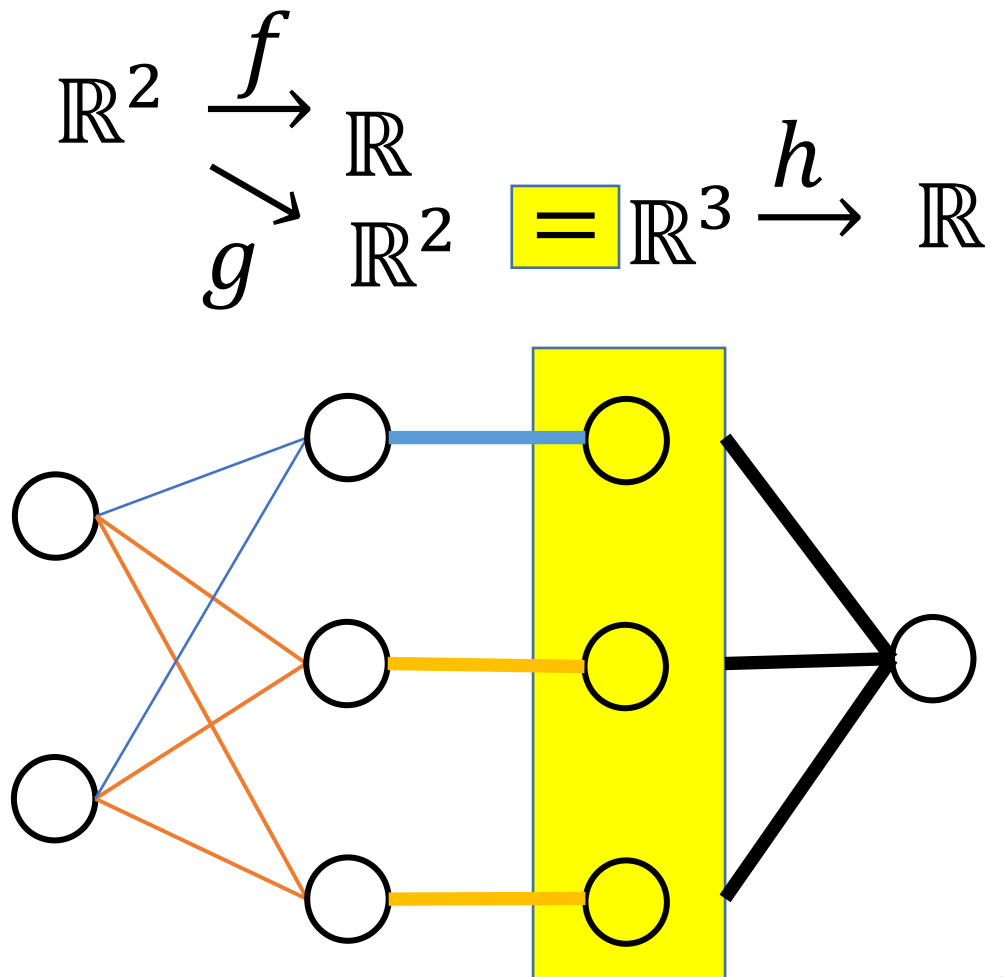
model

$$\begin{array}{ccc} \mathbb{R}^2 & \xrightarrow{f} & \mathbb{R} \\ & \searrow g & \downarrow \\ & & \mathbb{R}^2 \end{array} \quad \xrightarrow{h} \quad \mathbb{R}$$



Black Magic Revisit – Branch or Merge

model



```
In [ ]: x = Input(shape=(2,))
```

```
In [ ]: f = Dense(3, activation='relu')
```

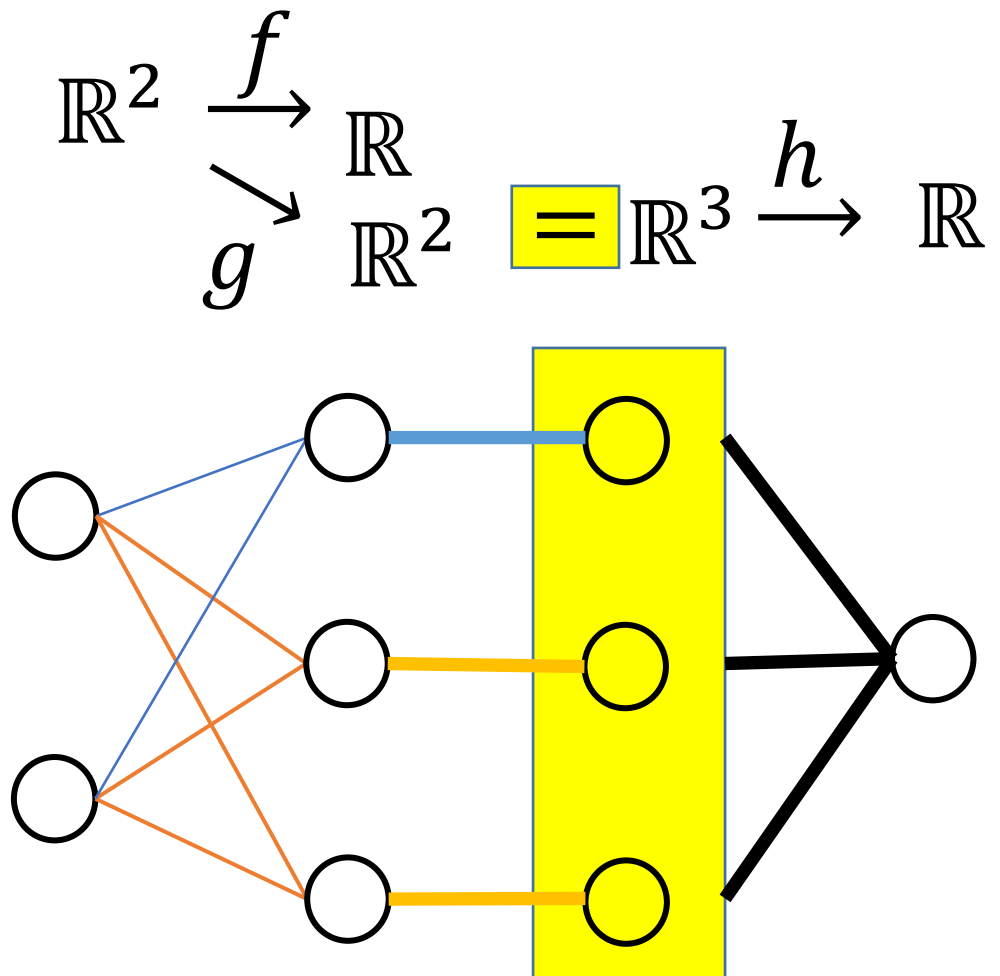
```
In [ ]: u_1 = f(x)
```

```
In [ ]: g = Dense(2, activation='relu')
```

```
In [ ]: u_2 = g(u_1)
```

Black Magic Revisit – Branch or Merge

model



```
In [ ]: x = Input(shape=(2,))
```

```
In [ ]: f = Dense(3, activation='relu')
```

```
In [ ]: u_1 = f(x)
```

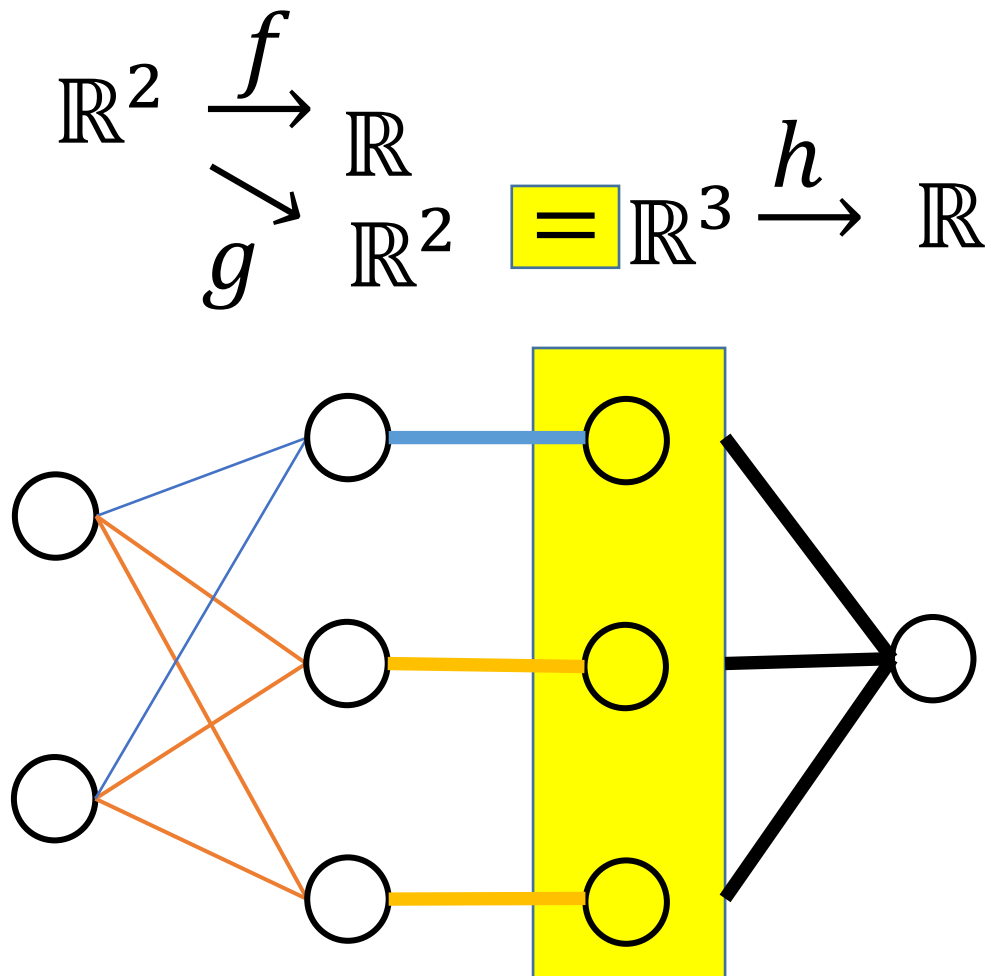
```
In [ ]: g = Dense(2, activation='relu')
```

```
In [ ]: u_2 = g(u_1)
```

```
In [ ]: merged_v = concatenate([u_1, u_2])
```

Black Magic Revisit – Branch or Merge

model



```
In [ ]: x = Input(shape=(2,))
```

```
In [ ]: f = Dense(1, activation='relu')
```

```
In [ ]: u_1 = f(x)
```

```
In [ ]: g = Dense(2, activation='relu')
```

```
In [ ]: u_2 = g(u_1)
```

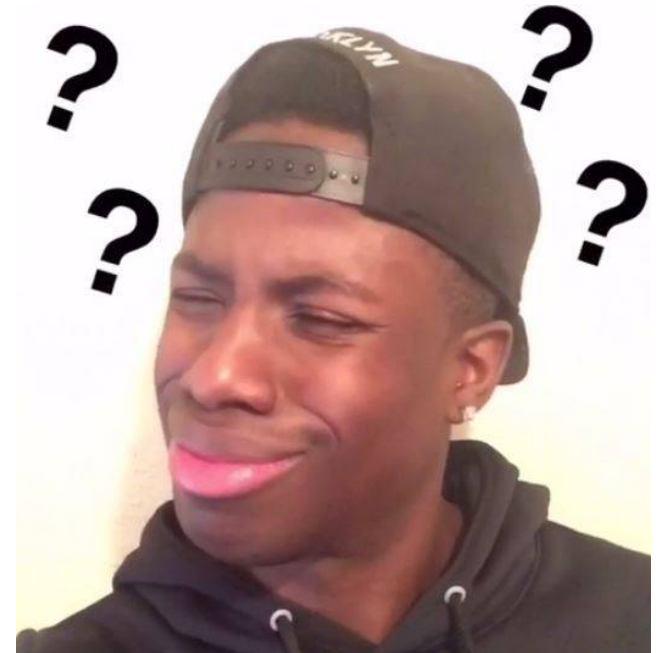
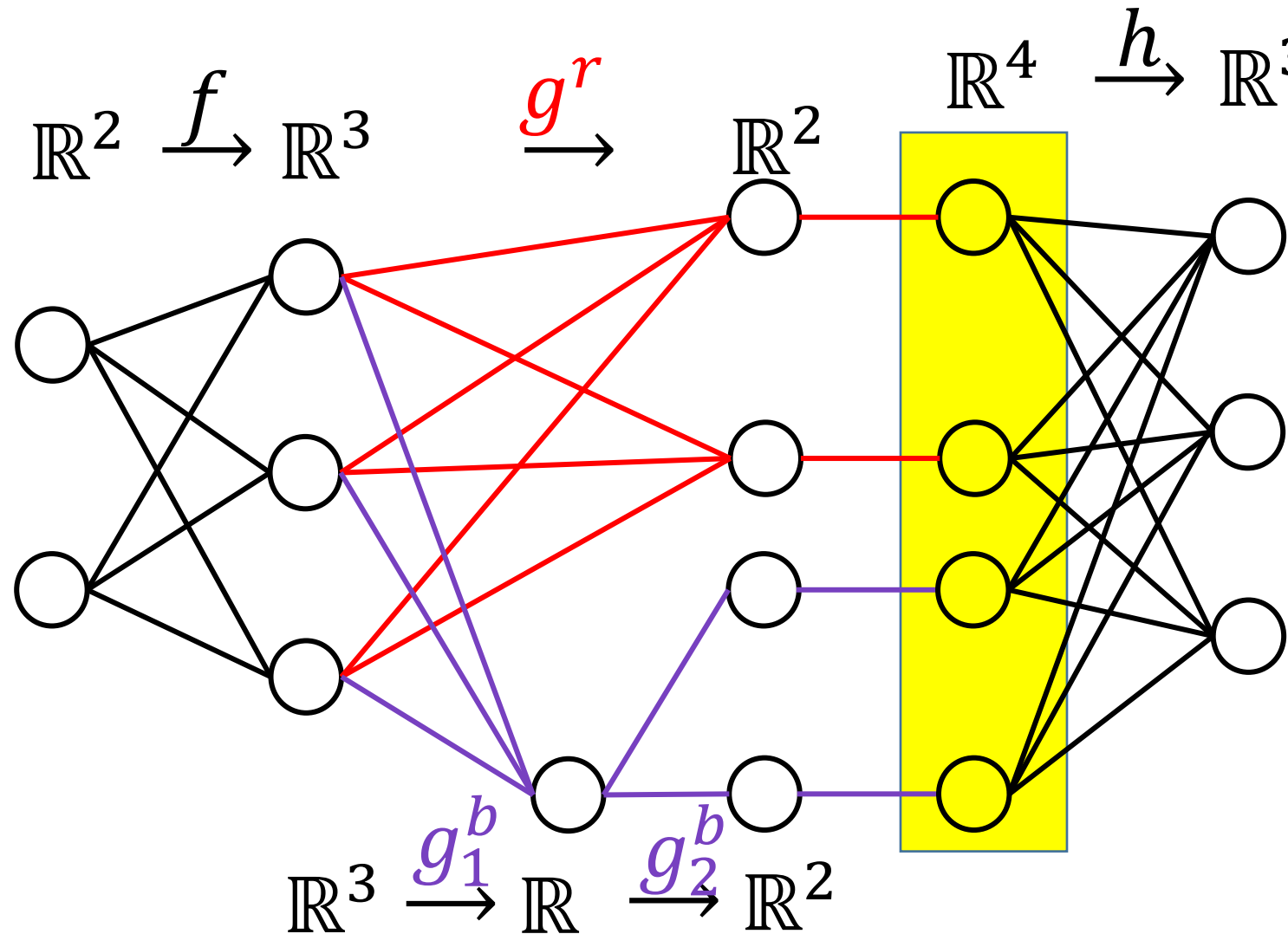
```
In [ ]: merged_v = concatenate([u_1, u_2])
```

```
In [ ]: h = Dense(1, activation='softmax')
```

```
In [ ]: y = h(merged_v)
```

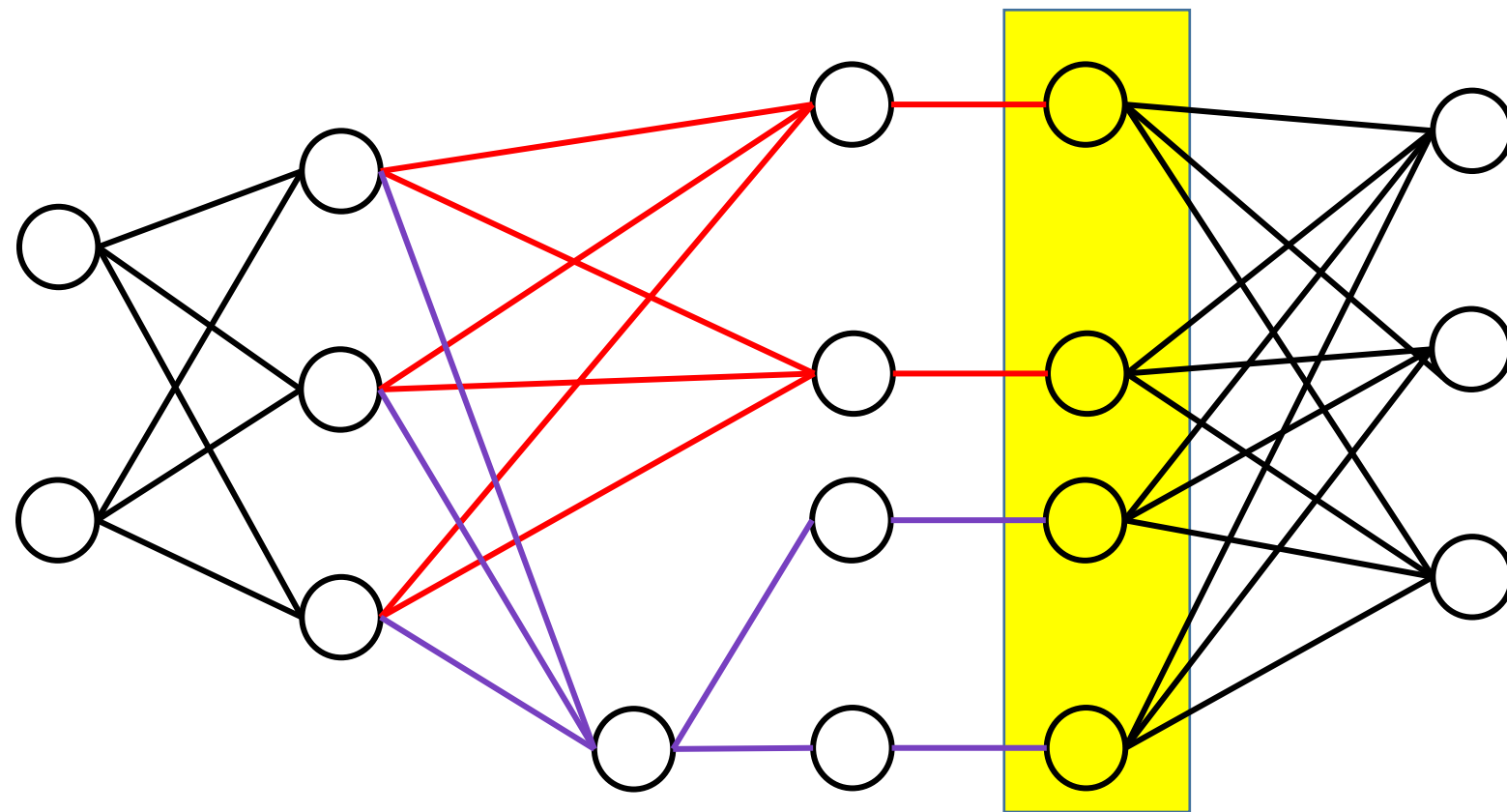
```
In [ ]: model = Model(x, y)
```

Black Magic Revisit – Challenge



Hint:

$$\begin{array}{ccccccc}
 & & & \xrightarrow{g^r} & \mathbb{R}^2 & & \\
 \mathbb{R}^2 & \xrightarrow{f} & \mathbb{R}^3 & & & & \\
 & \xrightarrow{g_1^b} & \mathbb{R} & \xrightarrow{g_2^b} & \mathbb{R}^2 & \boxed{=} & \mathbb{R}^4 \xrightarrow{h} \mathbb{R}^3
 \end{array}$$



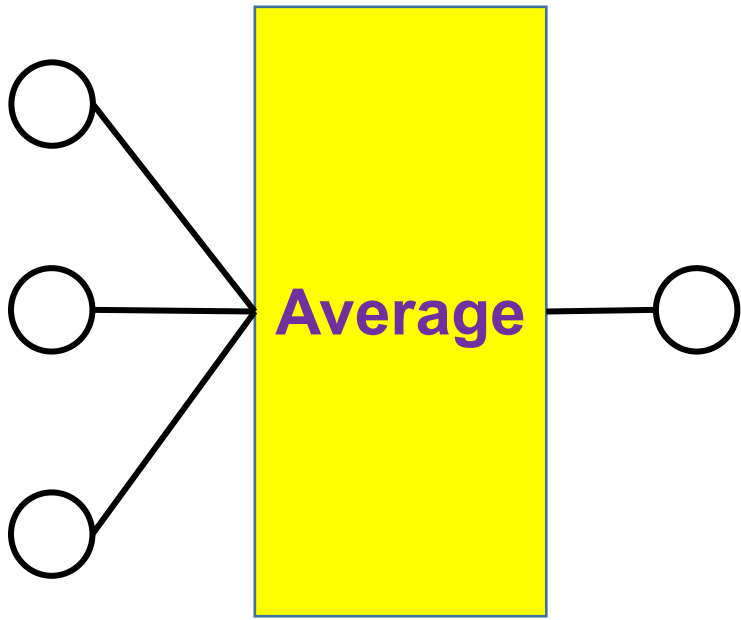
Black Magic Revisit – Conclusion

- A common application of Branch-and-Merge is to build Multi-input and multi-output models.

Ref: <https://keras.io/getting-started/functional-api-guide/#multi-input-and-multi-output-models>

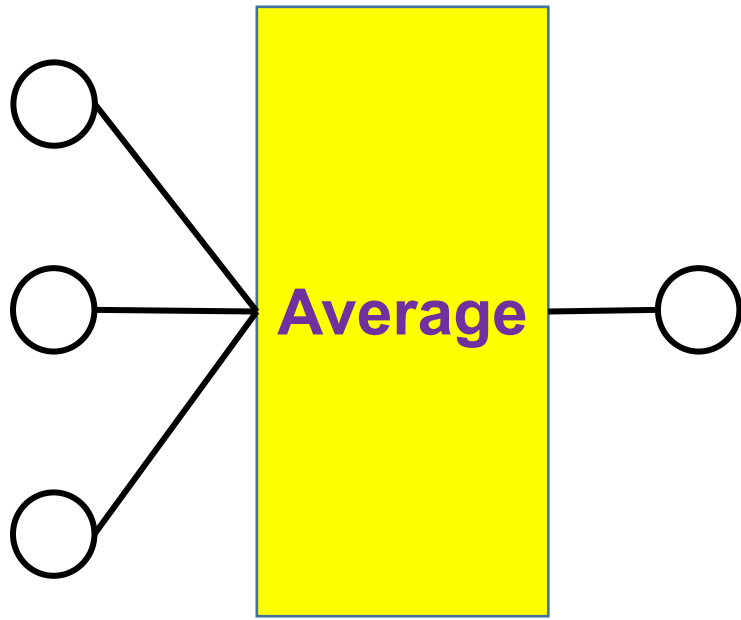
Customized Layer

- For example, we want a layer which output the average of the input neurons



Customized Layer

- Lambda layer transfers customized function as a layer.
- This could be also used when using **Sequential** API.



```
def my_avergae(args):  
    return K.mean(args)
```

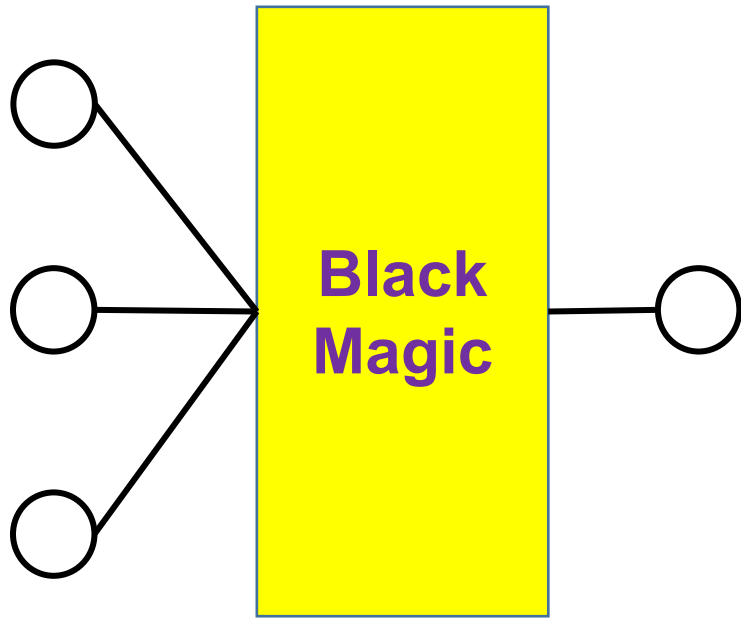
```
x = Input(shape=(3,), name='x_is_input')
```

```
f = Lambda(my_avergae, output_shape=(1,))
```

```
y = f(x)  
model = Model(x, y)
```

Customized Layer

- Lambda layer is used for customized function as layer behavior.
- This could be also used when using **Sequential** API.

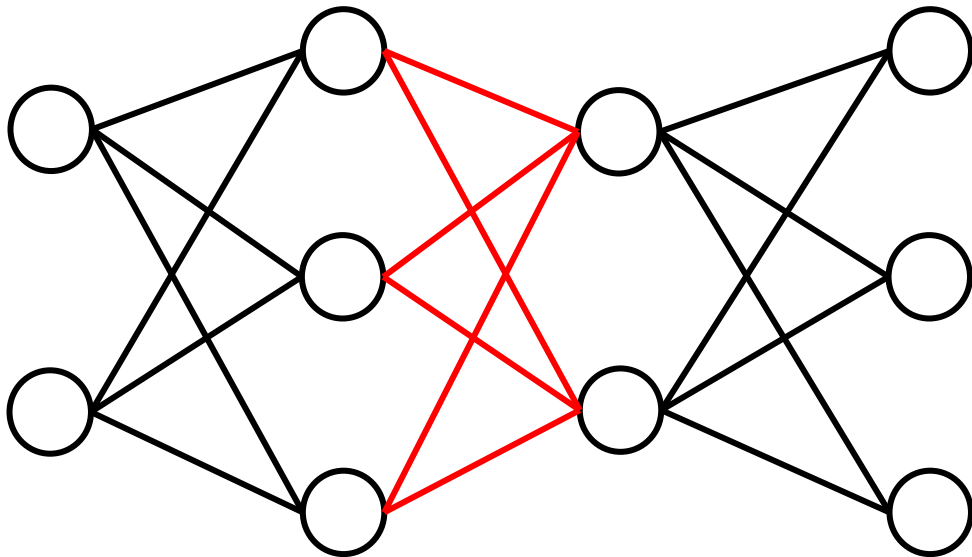


```
def my_spell(args):  
    xxx  
    return black_magic  
x = Input(shape=(3,), name='x_is_input')  
  
f = Lambda(my_spell, output_shape=(1,))  
  
y = f(x)  
model = Model(x, y)
```

Customized Loss Function

- Can we use user-defined loss function?

model

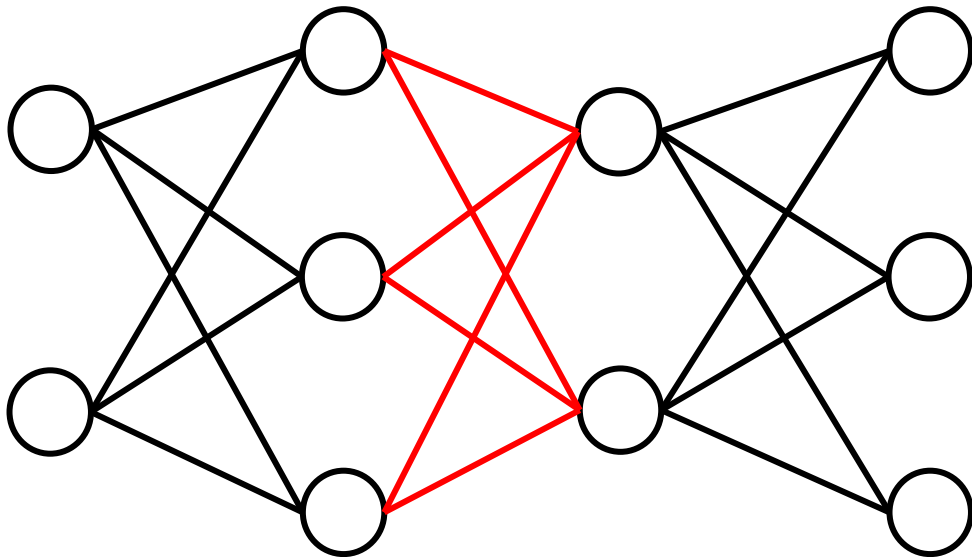


```
In [ ]: x = Input(shape=(2,))
In [ ]: f = Dense(3, activation='relu')
In [ ]: u = f(x)
In [ ]: g = Dense(2, activation='relu')
In [ ]: v = g(u)
In [ ]: h = Dense(3, activation='sigmoid')
In [ ]: y = h(v)
In [ ]: model = Model(x, y)
In [ ]: model.compile(loss='mse')
```

Customized Loss Function

- Can we use user-defined loss function?
- Yes, as shown below. Another example is VAE.

model



```
In [ ]: x = Input(shape=(2,))
In [ ]: f = Dense(3, activation='relu')
In [ ]: u = f(x)
In [ ]: g = Dense(2, activation='relu')
In [ ]: v = g(u)
In [ ]: h = Dense(3, activation='sigmoid')
In [ ]: y = h(v)
In [ ]: model = Model(x, y)
```

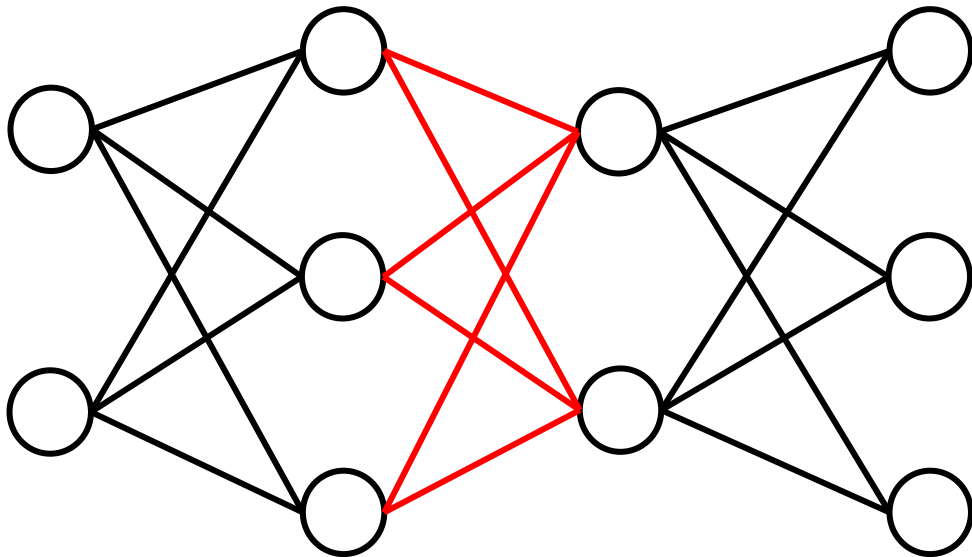
```
In [ ]: def my_loss(y_true, y_pred):
        return K.mean(y_true - y_pred)
```

```
In [ ]: model.compile(loss=my_loss)
```

Customized Loss Function

- In most case, the order of `y_true` and `y_pred` is not important
- However, for cross-entropy-like loss function, it's **IMPORTANT**

model



```
In [ ]: x = Input(shape=(2,))
In [ ]: f = Dense(3, activation='relu')
In [ ]: u = f(x)
In [ ]: g = Dense(2, activation='relu')
In [ ]: v = g(u)
In [ ]: h = Dense(3, activation='sigmoid')
In [ ]: y = h(v)
In [ ]: model = Model(x, y)
```

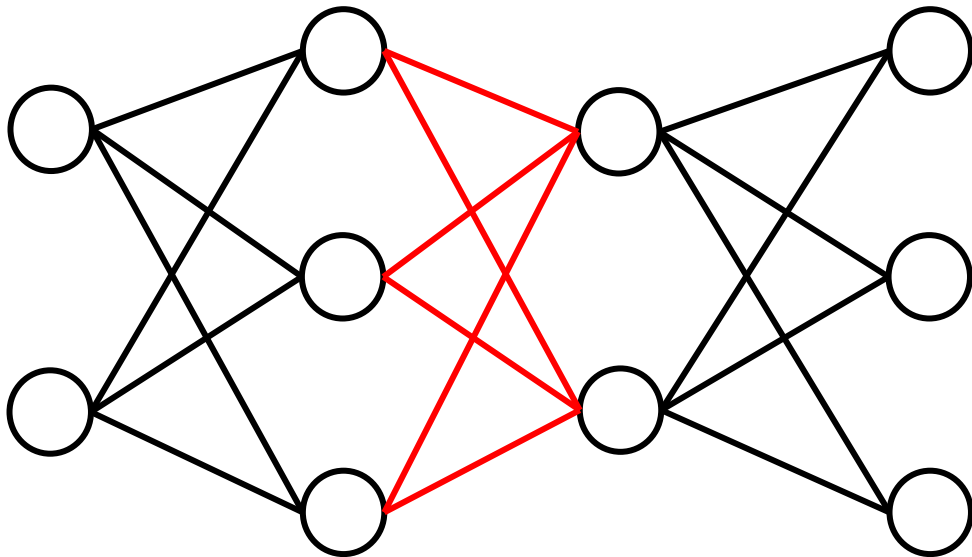
```
In [ ]: def my_loss(y_true, y_pred):
        return K.mean(y_true - y_pred)
```

```
In [ ]: model.compile(loss=my_loss)
```


Customized Loss Function

- Now, try to define some loss function using functions provided from backend.

model



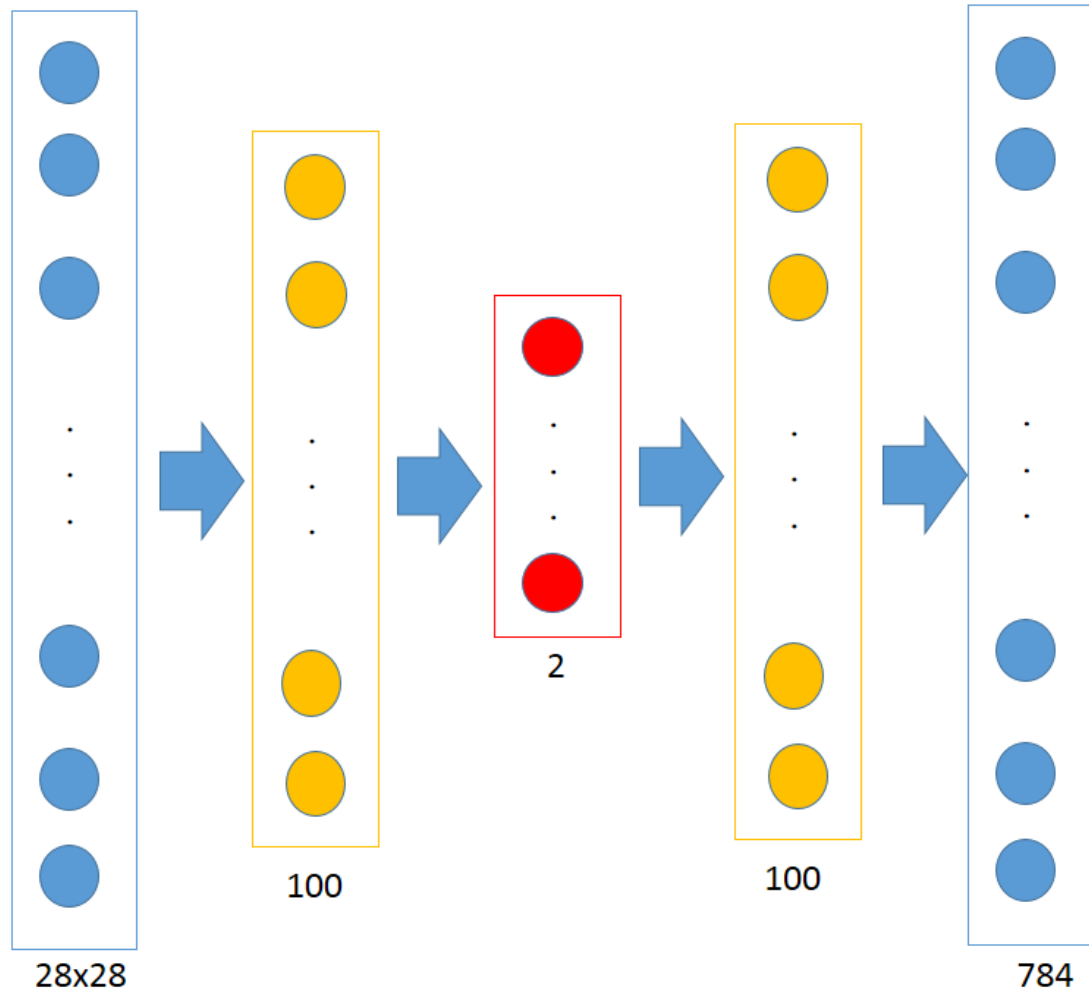
```
In [ ]: x = Input(shape=(2,))
In [ ]: f = Dense(3, activation='relu')
In [ ]: u = f(x)
In [ ]: g = Dense(2, activation='relu')
In [ ]: v = g(u)
In [ ]: h = Dense(3, activation='sigmoid')
In [ ]: y = h(v)
In [ ]: model = Model(x, y)
```

```
In [ ]: def my_loss(y_true, y_pred):
        xxx
        return ooo
In [ ]: model.compile(loss=my_loss)
```

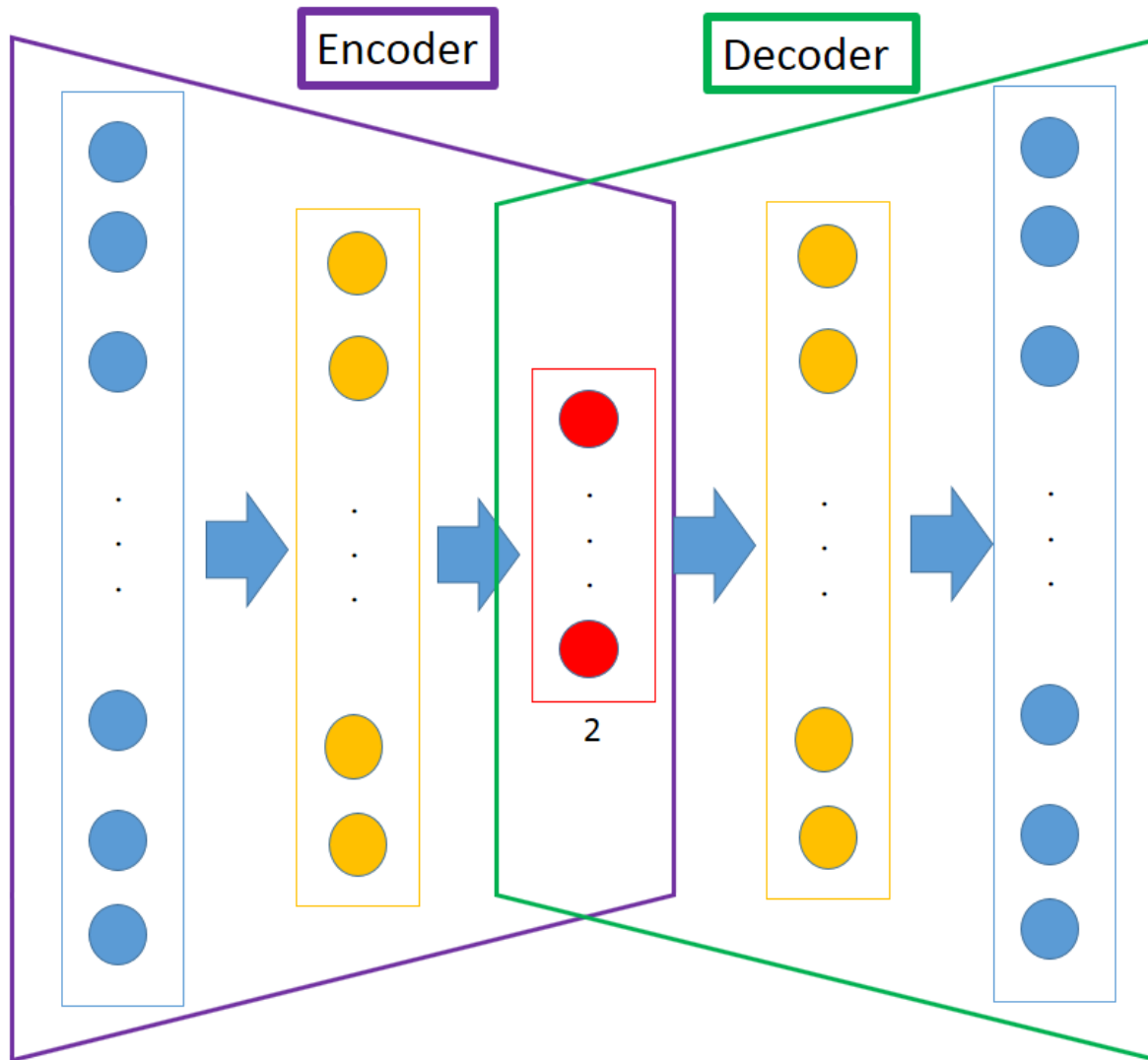
Submodels

- When we define a NN model, sometimes, we don't care about output value or class.
- Usually, neurons in the hidden layers are of interesting.

Submodels – Autoencoder as Example



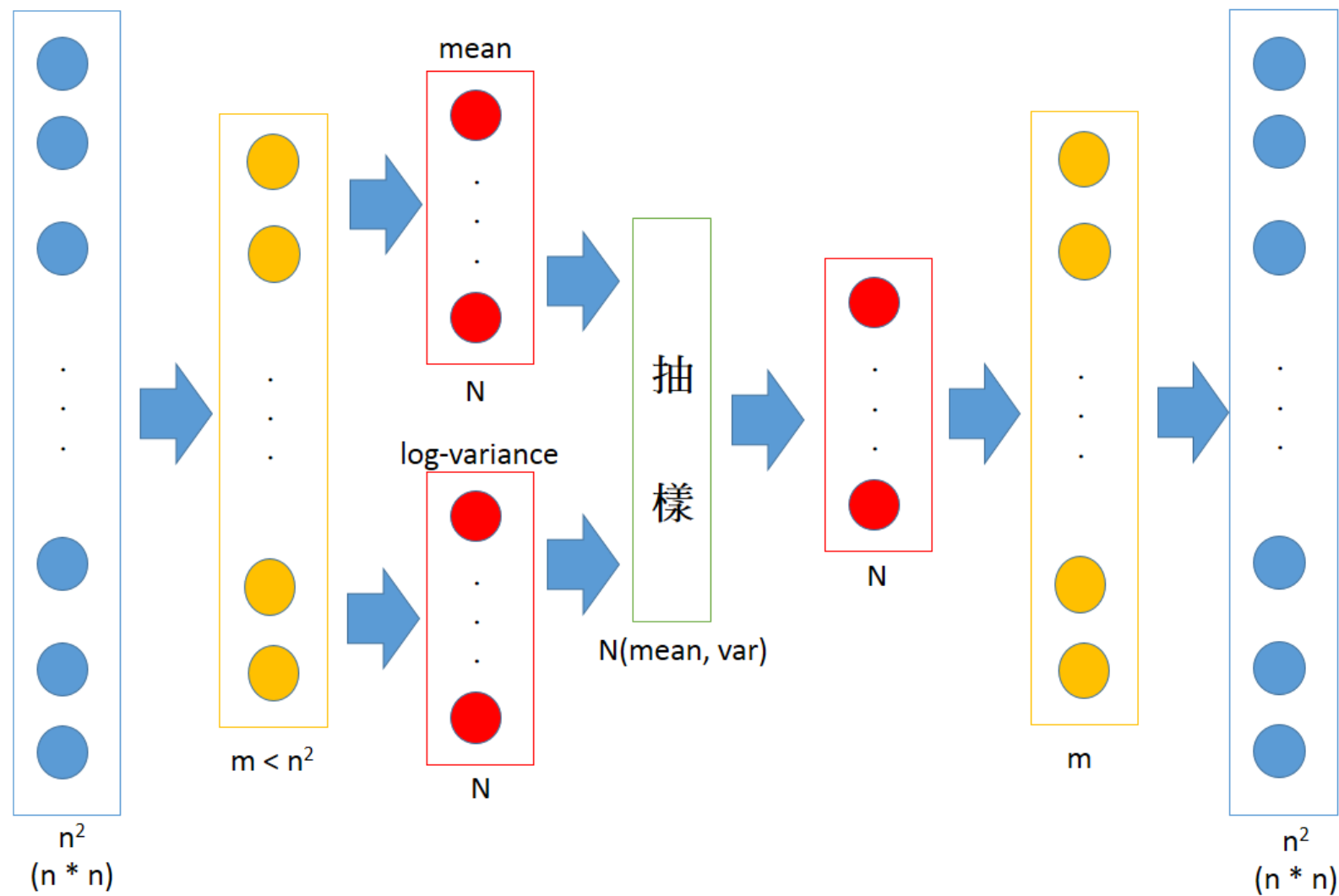
Submodels – Autoencoder as Example

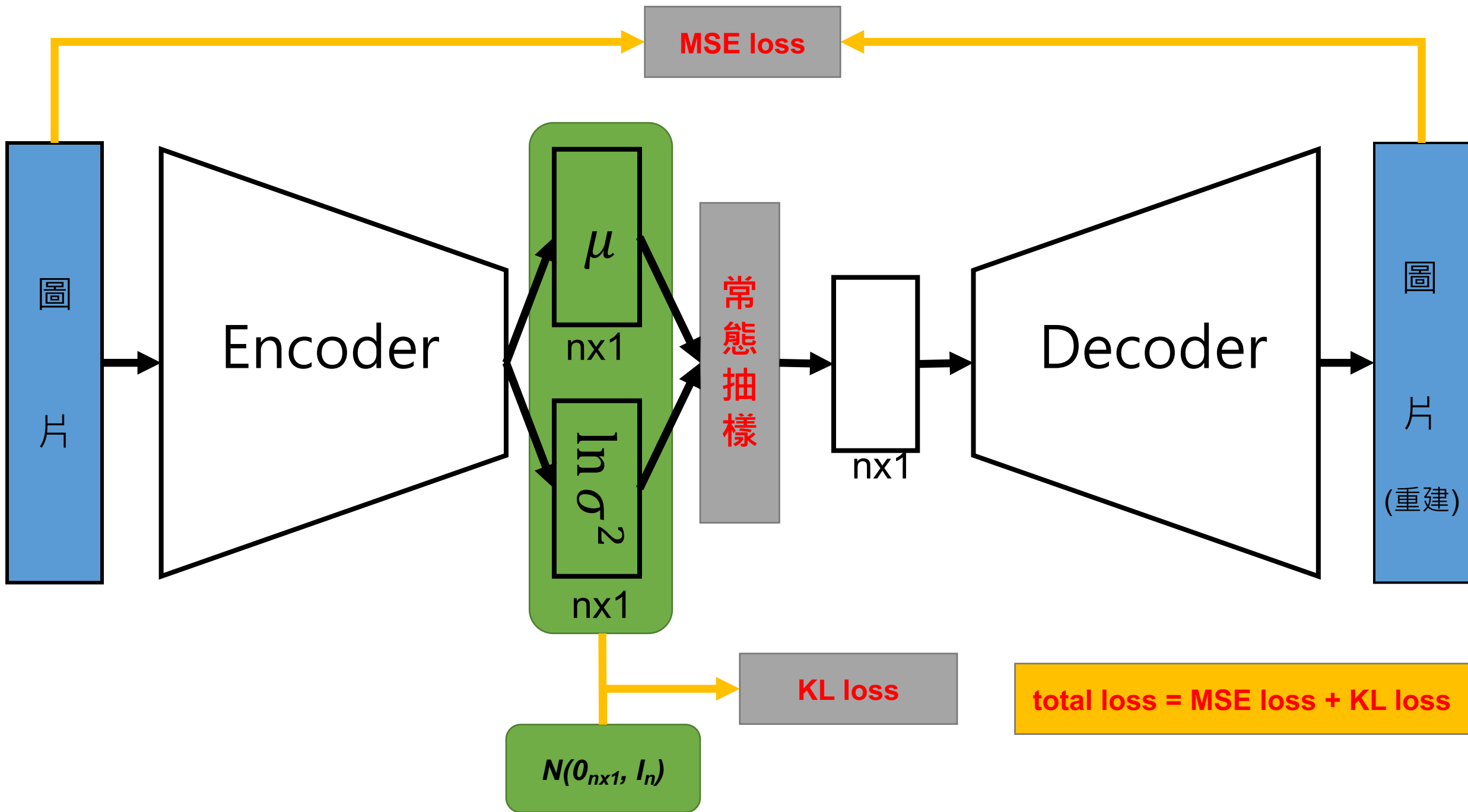


Assignment Revisit – VAE

- Variational Autoencoder (VAE) is a variant of AE which randomize latent vector from deterministic one. (Don't worry, I will explain what it means)
- VAE can be constructed using all tips we learned above: Model, Branch-and-Merge, Customized Layers, Customized Loss Function.

Assignment Revisit – VAE





Assignment Revisit – VAE

- So, we need to define two things:
 - Sampling from Normal distribution where mean and covariance are given by previous two layers.
 - Loss function defined by sum of MSE between I/O and KL-divergence between $N(\mu, \sigma^2)$ and $N(0, I_n)$.

Assignment Revisit – VAE

- So, we need to define two things:
 - **Sampling from Normal distribution where mean and covariance are given by previous two layers.**
 - Loss function defined by sum of MSE between I/O and KL-divergence between $N(\mu, \sigma^2)$ and $N(0, I_n)$.
- Recall in probability, if $X \sim N(0, 1)$, then $\mu + \sigma X \sim N(\mu, \sigma^2)$.
- For higher dimensional Normal distribution, we have similar result.

Assignment Revisit – VAE

- So, we need to define two things:
 - **Sampling from Normal distribution where mean and covariance are given by previous two layers.**
 - Loss function defined by sum of MSE between I/O and KL-divergence between $N(\mu, \sigma^2)$ and $N(0, I_n)$.

```
def sampling(args):  
    z_mean, z_log_var = args  
    epsilon = K.random_normal(shape=(batch_size, latent_dim), mean=0., stddev=epsilon_std)  
    return z_mean + K.exp(z_log_var / 2) * epsilon
```

Assignment Revisit – VAE

- So, we need to define two things:
 - Sampling from Normal distribution where mean and covariance are given by previous two layers.
 - **Loss function defined by sum of MSE between I/O and KL-divergence between $N(\mu, \sigma^2)$ and $N(0, I_n)$.**

```
def vae_loss(y_true, y_pred):  
    mse_loss = K.square(y_true - y_pred)  
    kl_loss = - 0.5 * K.sum(1 + z_log_var - K.square(z_mean) - K.exp(z_log_var), axis=-1)  
    return K.mean(xent_loss + kl_loss)
```

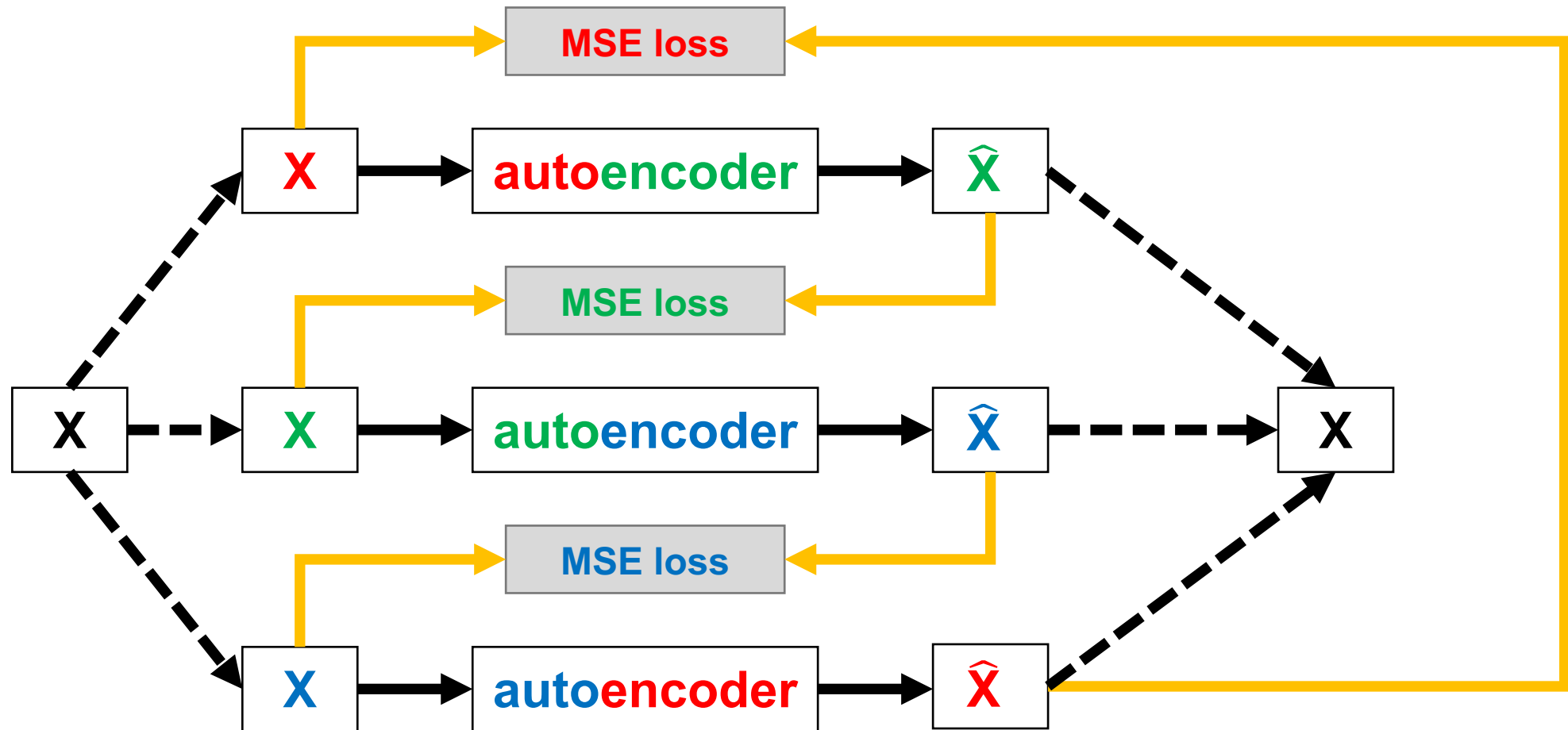
Assignment Revisit – VAE

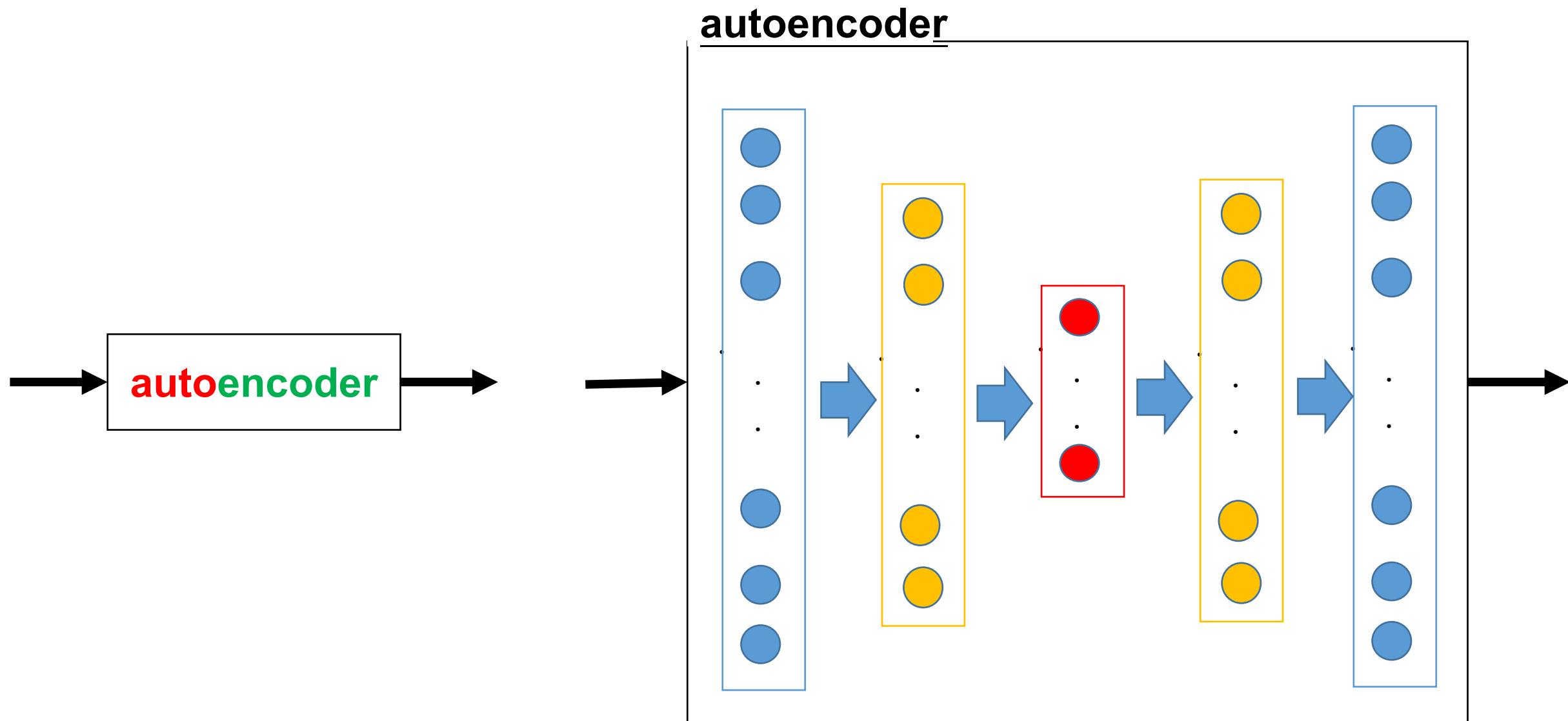
- Review the code of VAE!

Final Challenge

- For the remaining time, I want you all to build up a model which is a combination of what we learned today.
- You might use Model, Branch-and-Merge, Customized Loss Function in this model.

Final Challenge - Structure





Congratulations!

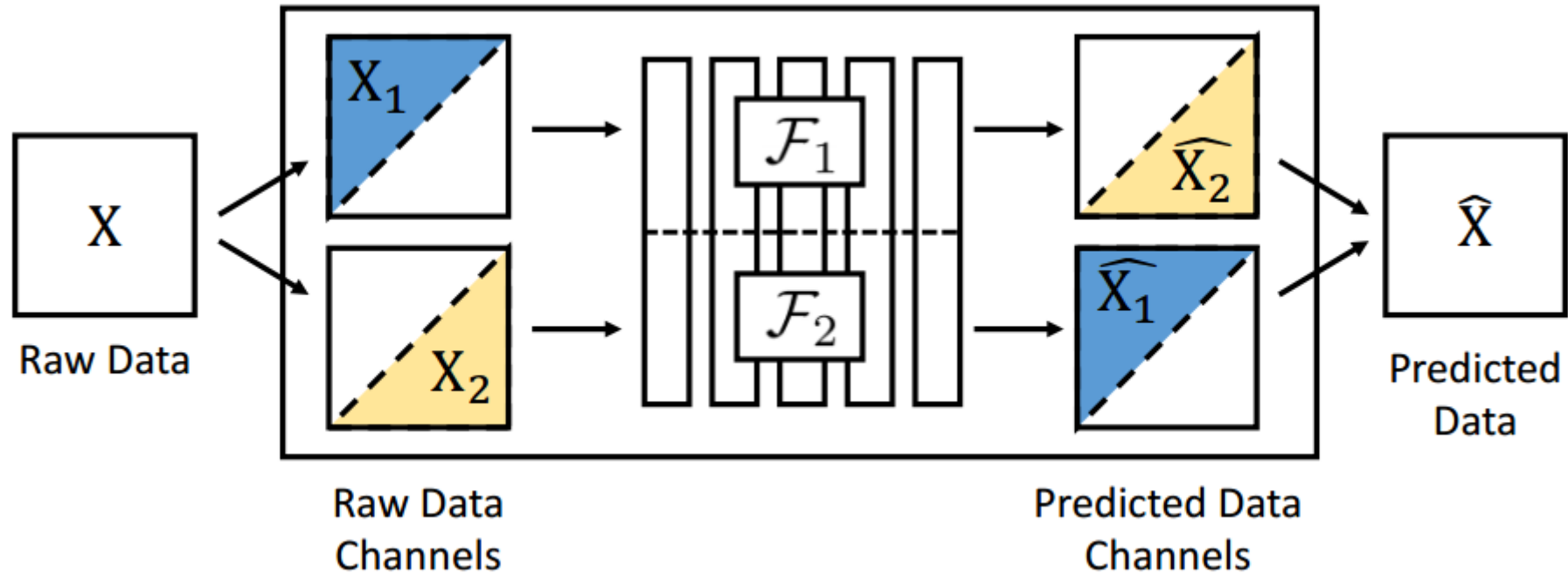
- If you can finish this final challenge, then you are one step closer to ...

Congratulations!

- If you can finish this final challenge, then you are one step closer to ...

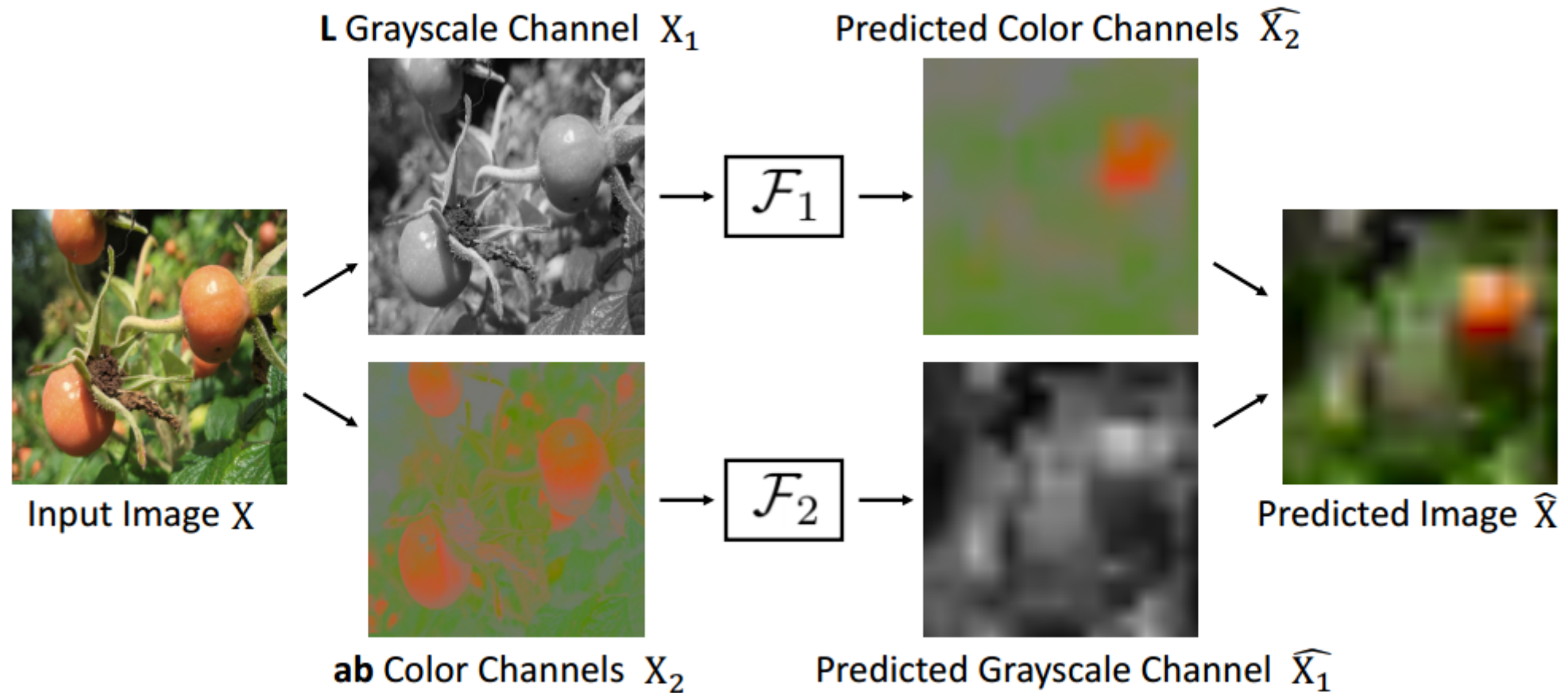
Berkeley AI Research (BAIR) Laboratory !

Real World Implementation



Ref: R. Zhang, P. Isola, and A. A. Efros. Split-brain autoencoders: Unsupervised learning by cross-channel prediction. CoRR, abs/1611.09842, 2016.

Real World Implementation



Acknowledgement

- Special thanks to Yen Jan who provides me some suggestion about this talk.

BCë