Report

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1. How did I design my program?

(1) Program 1

(a) basic ideas of the program

The program is to run a process under user mode. The main process will fork a child process to execute a test program and wait for its returning signal. After receiving the terminated signal, the parent process will print out the related information of the signal.

(b) implementation

Firstly, the program will use fork() function to fork a child process at the beginning. Then, the program will check the pid of the process and do the corresponding operations. If pid equals to 0, which means the process is the child process, then the program will let it execute the test program. If pid not equals to 0 or -1, then it is the parent process and it will wait for the terminated signal of the child process (using waitpid()) and print out the information of the signal.

(2) Program 2

(a) basic ideas of the program

This program will create a kernel thread. In the thread, the program will fork a child process and make it to execute another program. The parent process will wait for the child's terminated signal and print out related information.

(b) implementation

- 1. Firstly, since we need to use these 4 functions: "_do_fork" (/kernel/fork.c), "do_execve" (/fs/exec.c), "getname" (/fs/namei.c) and "do_wait" (/kernel/exit.c), we need to find their corresponding files in kernel and export them using EXPORT_SYMBOL. After modifications, we need to recompile the kernel. Then we just need to use extern to import them in program2.c.
- 2. Then, when initiating the module, we need to create a kernel thread using kthread_create() to run my_fork() function, where the program will fork a child process to execute another program.
- 3.To implement my_fork(), several functions need to be implemented in advance.

my_exec():This function will first get the information (using getname()) of
the test program using the address set inside it. After that, it will use
do_execve() to execute the file.

my wait():this function will get the terminated signal of the child process usin

g.

do_wait():With these 2 functions, my_fork() is implemented in the following:

First, my_fork() will use _do_fork to generate a child process to run

my_exec() function. Then it will use my_wait() to get the terminated

signal of the child process and print out corresponding information.

- 4. After creating the kernel thread, the program will wake up the program if there kthread create() create a thread successfully.
- 2. How to set up your development environment.
 - 1. Set visual machine: https://csc3150.cyzhu.dev/vm-configuration/windows-amd-intel-x86

Install vitrualbox and vagrant.

cd to new folder csc3150, and Execute vagrant init cyzhu/csc3150

Then execute vagrant up.

Then goto VScode to create terminal, and excute sudo apt update && sudo apt install -y build-essential

2. Compile Kernel

Download source code from

http://www.kernel.org

mirro: https://mirror.tuna.tsinghua.edu.cn/kernel/v5.x/

Install Dependency and development tools

sudo apt-get install libncurses-dev gawk flex bison openssl libssldev dkms libelf-devlibudev-dev libpci-dev libiberty-dev autoconf llvm dwarves

Extract the source file to /home/seed/work

cp KERNEL FILE.tar.xz /home/seed/work

cd /home/seed/work

\$sudo tar xvf KERNEL FILE.tar.xz

Copy config from /boot to /home/seed/work/KERNEL FILE

Login root account and go to kernel source directory

\$sudo su

\$cd /home/seed/work /KERNEL FILE

Clean previous setting and start configuration

\$make mrproper

\$make clean

\$make menuconfig

save the config and exit

```
Build kernel Image and modules

$make bzImage -j$(nproc)

$make modules -j$(nproc)

$make -j$(nproc)

Install kernel modules

$make modules_install

Install kernel

$make install

Reboot to load new kernel

$reboot
```

Then check the version:

```
vagrant@csc3150:~/csc3150/ASS_1/source/program1$ uname -r
5.10.5
```

- 3. Screenshot of my program output.
- (1) Program 1:

Normal:

Abort:

```
vagrant@csc3150:~/csc3150/ASS_1/source/program1$ ./program1 ./normal
Process start to fork
I'm the Parent Process, my pid = 8181
I'm the Child Process, my pid = 8182
Child process start to execute the program
------CHILD PROCESS START-----
This is the normal program
-------Parent process receiving the SIGCHLD signal
Normal termination with EXIT STATUS = 0
```

Alarm:

Rus

vagrant@csc3150:~/csc3150/ASS_1/source/program1\$./program1 ./bus
Process start to fork
I'm the Parent Process, my pid = 8266
I'm the Child Process, my pid = 8267
Child process start to execute the program
------CHILD PROCESS START----This is the SIGBUS program

Parent process receiving the SIGCHLD signal
child process get SIGBUS signal

Floating:

Hangup:

illegal instr:

Interrupt:

```
vagrant@csc3150:~/csc3150/ASS_1/source/program1$ ./program1 ./interrupt
Process start to fork
I'm the Parent Process, my pid = 8414
I'm the Child Process, my pid = 8415
Child process start to execute the program
------CHILD PROCESS START-----
This is the SIGINT program
Parent process receiving the SIGCHLD signal
child process get SIGINT signal
```

Kill:

```
• vagrant@csc3150:~/csc3150/ASS_1/source/program1$ ./program1 ./kill Process start to fork
I'm the Parent Process, my pid = 8431
I'm the Child Process, my pid = 8432
Child process start to execute the program
------CHILD PROCESS START-----
This is the SIGKILL program

Parent process receiving the SIGCHLD signal child process get SIGKILL signal
```

Pipe:

```
vagrant@csc3150:~/csc3150/ASS_1/source/program1$ ./program1 ./pipe
Process start to fork
I'm the Parent Process, my pid = 8457
I'm the Child Process, my pid = 8458
Child process start to execute the program
------CHILD PROCESS START-----
This is the SIGPIPE program
Parent process receiving the SIGCHLD signal
child process get SIGPIPE signal
```

Quit:

Stop:

```
vagrant@csc3150:~/csc3150/ASS_1/source/program1$ ./program1 ./stop
Process start to fork
I'm the Parent Process, my pid = 8510
I'm the Child Process, my pid = 8511
Child process start to execute the program
------CHILD PROCESS START-----
This is the SIGSTOP program
Parent process receiving the SIGCHLD signal
child process get SIGSTOP signal
```

Terminate:

Trap:

(2) Program 2:

1. test.c

```
[20529.800497] [program2] : module_init Wu Jingqi 120090357
[20529.800499] [program2] : module_init create kthread start
[20529.804759] [program2] : module_init Kthread starts
[20529.808581] [program2] : The Child process has pid = 7101
[20529.808582] [program2] : This is the parent process, pid = 7099
[20529.808584] [program2] : child process
[20529.809001] [program2] : CHILD EXECUTION FAILED!!
[20529.809003] [program2] : child process get SIGBUS signal
[20529.809003] [program2] : The return signal is 7
[20537.624459] [program2] : module_exit
```

2. normal

```
[20772.274390] [program2] : module_init Wu Jingqi 120090357
[20772.274391] [program2] : module_init create kthread start
[20772.274411] [program2] : module_init Kthread starts
[20772.279998] [program2] : The Child process has pid = 7876
[20772.280000] [program2] : This is the parent process, pid = 7874
[20772.280497] [program2] : child process
[20772.283174] [program2] : child process gets normal termination
[20772.283175] [program2] : The return signal is 0
[20780.359328] [program2] : module_exit
```

3. stop

```
20910.1066051
                            module_init Wu Jingqi 120090357
20910.106606]
               [program2]
                            module init create kthread start
20910.1066241
               [program2]
                            module init Kthread starts
               [program2]
                            The Child process has pid = 8304
               [program2
                            This is the parent process, pid = 8302
               [program2
                            child process
                            CHILD PROCESS STOPPED
                            child process get SIGSTOP signal
                            The return signal is 19
               [program2
                            module exit
```

4. What did I learn from the tasks?

(1) Program1

First, I learnt how to create child processes and how to use them to do some task. I also learnt how to execute other programs in the process using execve() function. Then, I also got some feelings about the terminated signals and know some basic knowledge of them.

(2) Program2

In this project, I learnt how to modify the kernel files and recompile the kernel to use it. I also learnt how to insert and remove modules to kernels.