Task1: Design:

First fork the program

```
printf("Process start to fork\n");
pid = fork();
```

Check if error

```
if(pid==-1){
    perror("fork");
    exit(1);
}
```

Execute child

```
else{
    if(pid==0){
        int i;
        char *arg[argc];
        printf("I'm the Child Process, my pid = %d\n", getpid());
        printf("Child process start to execute test program:\n");
        for(i=0;i<argc-1;i++){
            arg[i] = argv[i+1];
        }
        arg[argc-1] = NULL;
        execve(arg[0],arg,NULL);
        perror("execve");
        exit(EXIT_FAILURE);
}</pre>
```

Wait for the child program

status

```
else{
    printf("I'm the Parent Process, my pid = %d\n", getpid());
    waitpid(pid,&status,WUNTRACED);
    printf("Parent process receives SIGCHLD signal\n");
```

Check the child's

```
if(WIFEXITED(status)){
    printf("Normal termination with EXIT STATUS = %d\n", WEXITSTATUS(status));
}
else if(WIFSIGNALED(status)){
    printf("CHILD EXECUTION FAILED: %d\n", WTERMSIG(status));
}
else if(WIFSTOPPED(status)){
    printf("CHILD PROCESS STOPPED: %d\n", WSTOPSIG(status));
}
else{
    printf("CHILD PROCESS CONTINUED\n");
}
exit(0);
}
return 0;
}
```

Output

## 转到(G) 运行(R) 终端(T) 帮助(H)

问题 輸出 调试控制台 终端 端口 vagrant@csc3150:~/csc3150\$ ./program1 ./abort Process start to fork I'm the Parent Process, my pid = 21638 I'm the Child Process, my pid = 21639 Child process start to execute test program: -----CHILD PROCESS START-----This is the SIGABRT program Parent process receives SIGCHLD signal CHILD EXECUTION FAILED: 6 vagrant@csc3150:~/csc3150\$ ./program1 ./alarm Process start to fork I'm the Parent Process, my pid = 21665 I'm the Child Process, my pid = 21666 Child process start to execute test program: -----CHILD PROCESS START------This is the SIGALRM program Parent process receives SIGCHLD signal CHILD EXECUTION FAILED: 14 vagrant@csc3150:~/csc3150\$ ./program1 ./bus Process start to fork I'm the Parent Process, my pid = 21707 I'm the Child Process, my pid = 21708 Child process start to execute test program: -----CHILD PROCESS START-----This is the SIGBUS program Parent process receives SIGCHLD signal CHILD EXECUTION FAILED: 7

vagrant@csc3150:~/csc3150\$ ./program1 ./floating

Process start to fork

```
-----CHILD PROCESS START------
This is the SIGHUP program
Parent process receives SIGCHLD signal
CHILD EXECUTION FAILED: 1
vagrant@csc3150:~/csc3150$ ./program1 ./illegal_instr
Process start to fork
I'm the Parent Process, my pid = 21809
I'm the Child Process, my pid = 21810
Child process start to execute test program:
 -----CHILD PROCESS START-----
This is the SIGILL program
Parent process receives SIGCHLD signal
CHILD EXECUTION FAILED: 4
vagrant@csc3150:~/csc3150$ ./program1 ./interrupt
Process start to fork
I'm the Parent Process, my pid = 21840
I'm the Child Process, my pid = 21841
Child process start to execute test program:
 -----CHILD PROCESS START-----
This is the SIGINT program
Parent process receives SIGCHLD signal
CHILD EXECUTION FAILED: 2
vagrant@csc3150:~/csc3150$ ./program1 ./kill
Process start to fork
I'm the Parent Process, my pid = 21879
I'm the Child Process, my pid = 21880
Child process start to execute test program:
 -----CHILD PROCESS START-----
This is the SIGKILL program
Parent process receives SIGCHLD signal
CHILD EXECUTION FAILED: 9
vagrant@csc3150:~/csc3150$ ./program1 ./normal
Process start to fork
I'm the Parent Process, my pid = 21905
I'm the Child Process, my pid = 21906
Child process start to execute test program:
-----CHILD PROCESS START-----
```

```
Normal termination with EXIT STATUS = 0
vagrant@csc3150:~/csc3150$ ./program1 ./pipe
 Process start to fork
 I'm the Parent Process, my pid = 21931
 I'm the Child Process, my pid = 21932
 Child process start to execute test program:
 -----CHILD PROCESS START-----
 This is the SIGPIPE program
 Parent process receives SIGCHLD signal
 CHILD EXECUTION FAILED: 13
vagrant@csc3150:~/csc3150$ ./program1 ./quit
 Process start to fork
 I'm the Parent Process, my pid = 21945
 I'm the Child Process, my pid = 21946
 Child process start to execute test program:
   -----CHILD PROCESS START-----
 This is the SIGQUIT program
 Parent process receives SIGCHLD signal
 CHILD EXECUTION FAILED: 3
vagrant@csc3150:~/csc3150$ ./program1 ./segment_fault
 Process start to fork
 I'm the Parent Process, my pid = 21984
 I'm the Child Process, my pid = 21985
 Child process start to execute test program:
  -----CHILD PROCESS START-----
 This is the SIGSEGV program
 Parent process receives SIGCHLD signal
 CHILD EXECUTION FAILED: 11
vagrant@csc3150:~/csc3150$ ./program1 ./stop
 Process start to fork
 I'm the Parent Process, my pid = 22008
 I'm the Child Process, my pid = 22009
 Child process start to execute test program:
 -----CHILD PROCESS START-----
 This is the SIGSTOP program
 Parent process receives SIGCHLD signal
 CHILD PROCESS STOPPED: 19
vagrant@csc3150:~/csc3150$ ./program1 ./terminate
 Process start to fork
 I'm the Parent Process, my pid = 22025
```

I'm the Child Drocess my mid - 22026

Task2

Design

Execute program

```
int my_exec(void){
    int c = 0;
    if(c==0);
    int output;
    char TestPath[] = "/tmp/test";
    struct filename *FileName = getname_kernel(TestPath);
    int a = 1;
    if(a==0);
    output = do_execve(FileName, NULL, NULL);
    int b = 2;
    if(b==0);
    if(output){
        do_exit(output);
    }
    else{
        return 0;
    }
}
```

Wait and get the child status

```
void my_wait(pid_t pid, int status){
   int wat;
   struct wait_opts wo;
   struct pid * wo_pid = NULL;
   enum pid type type = PIDTYPE PID;
   wo_pid = find_get_pid(pid);
   wo.wo_type = type;
   wo.wo_pid = wo_pid;
   wo.wo_flags = WEXITED | WUNTRACED;
   wo.wo_info = NULL;
   wo.wo_rusage = NULL;
   wat = do_wait(&wo);
   if (wo.wo_stat == 0){
       printk("[program2] : This is a normal child process\n");
   else if (wo.wo_stat == 1){
       printk("[program2] : get SIGHUP signal\n");
   else if (wo.wo_stat == 2){
       printk("[program2] : get SIGINT signal\n");
   else if (wo.wo stat == 9){
       printk("[program2] : get SIGKILL signal\n");
   else if (wo.wo_stat == 13){
       printk("[program2] : get SIGPIPE signal\n");
   else if ( wo.wo_stat == 14){
       printk("[program2] : get SIGALRM signal\n");
```

```
printk("[program2] : get SIGTERM signal\n");
else if (wo.wo_stat == 131){
    printk("[program2] : get SIGQUIT signal\n");
else if (wo.wo_stat == 132){
    printk("[program2] : get SIGILL signal\n");
else if (wo.wo_stat == 133){
    printk("[program2] : get SIGTRAP signal\n");
else if (wo.wo stat == 134){
    printk("[program2] : get SIGABRT signal\n");
else if (wo.wo_stat == 135){
    printk("[program2] : get SIGBUS signal\n");
else if (wo.wo_stat == 136){
    printk("[program2] : get SIGFPE signal\n");
else if (wo.wo_stat == 139){
    printk("[program2] : get SIGSEGV signal\n");
else if (wo.wo stat == 4991){
    printk("[program2] : get SIGSTOP signal\n");
else{
    printk("[program2] : something other wrong\n");
printk("[program2] : child process terminates\n");
printk("[program2] : The return signal is %d\n", wo.wo_stat );
put_pid(wo_pid);
return;
```

Clone

```
/* fork a process using kernel_clone or kernel_thread */
pid = kernel_clone(&c_args);
int ppid = (int)current->pid;
if(pid==-1){
    //perror("kernal_clone");
    //exit(1);
}

/* execute a test program in child process */
else{
    if(pid==0){
        printk("[program2] : This is the parent process, pid = %d\n",pid);
        my_exec();
}

/* wait until child process terminates */
else{
        printk("[program2] : This is the parent process, pid = %d\n", ppid);
        my_wait(pid,status);
}

return 0;
```

## About kernel

```
struct wait_opts {
    enum pid_type wo_type;
    int wo_flags;
    struct pid *wo_pid;
    struct siginfo *wo_info;
    int wo_stat;
    struct rusage *wo_rusage;
    wait_queue_entry_t child_wait;
    int notask_error;
};

extern pid_t kernel_clone(struct kernel_clone_args *args);
    extern struct filename *getname_kernel(const char * filename);
    extern int do_execve(struct filename *filename,const char __user *const __user *_argv,const char __user *const __user *_envp);
    static struct task_struct *task;
    extern long do_wait(struct wait_opts *wo);
    extern signed char my_WIFSIGNALED(int status);
```