FEDERAL STATE AUTONOMOUS EDUCATIONAL INSTITUTION OF HIGHER EDUCATION

ITMO UNIVERSITY

Report on the practical task No. 2

"Algorithms for unconstrained nonlinear optimization. Direct methods"

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Goal

The use of direct methods (one-dimensional methods of exhaustive search, dichotomy, golden section search; multidimensional methods of exhaustive search, Gauss (coordinate descent), Nelder-Mead) in the tasks of unconstrained nonlinear optimization

Formulation of the problem

I. Use the one-dimensional methods of exhaustive search, dichotomy and golden section search to find an approximate (with precision $\Box = 0.001$) solution \Box : $\Box(\Box) \rightarrow \Box\Box$ for the following functions and domains:

$$f(x) = x^3, x \in [0, 1];$$

$$f(x) = |x - 0.2|, x \in [0, 1];$$

$$f(x) = x \sin \frac{1}{x}, x \in [0.01, 1].$$

Calculate the number of 1-calculations and the number of iterations performed in each method and analyze the results. Explain differences (if any) in the results obtained.

II. Generate random numbers $\square \in (0,1)$ and $\square \in (0,1)$. Furthermore, generate the noisy data $\{x_k, y_k\}$, where $\square = 0, ..., 100$, according to the following rule:

$$y_k = \alpha x_k + \beta + \delta_k$$
, $x_k = \frac{k}{100}$

where $\delta_k \sim N(0,1)$ are values of a random variable with standard normal distribution. Approximate the data by the following linear and rational functions:

- 1. F(x,a,b) = ax + b (linear approximant),
- 2. $F(x,a,b) = \frac{a}{1+bx}$ (rational approximant),

by means of least squares through the numerical minimization (with precision $\square = 0.001$) of the following function:

$$D(a,b) = \sum_{k=0}^{100} (F(x_k, a, b) - y_k)^2.$$

To solve the minimization problem, use the methods of exhaustive search, Gauss and Nelder-Mead. If necessary, set the initial approximations and other parameters of the methods. Visualize the data and the approximants obtained in a plot separately for each type of approximant so that one can compare the results for the numerical methods used. Analyze

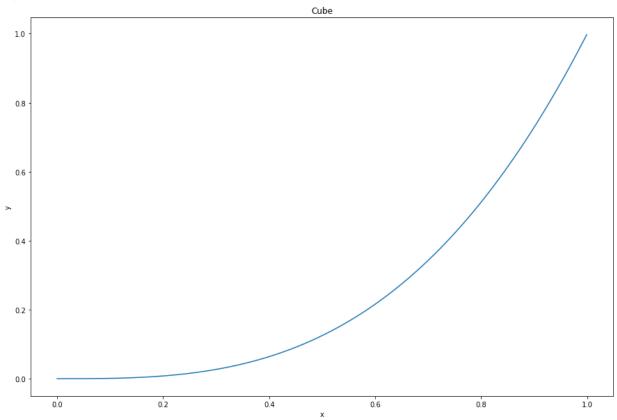
the results obtained (in terms of number of iterations, precision, number of function evaluations, etc.).

Results

Subtask 1

Cube function

$$f(x) = x^3, x \in [0, 1];$$

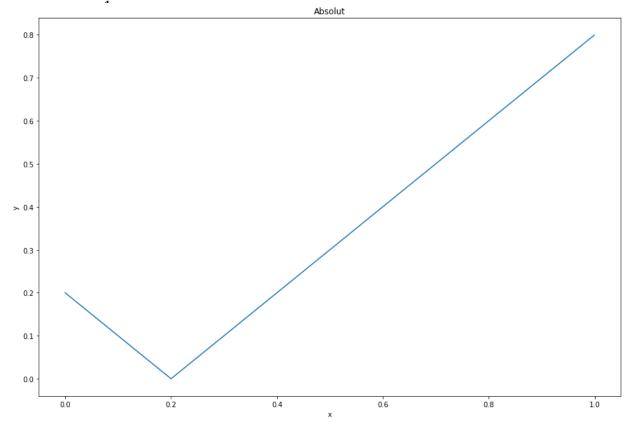


Results table:

Method	f(x)	x	Number of function calls	Number of iterations
Brute force	0.0	0.0	1000	1000
Dichotomy method	0.0	0.0	21	10
Golden ratio method	4.9e-11	0.00037	31	15

Absolut function

$$f(x) = |x - 0.2|, x \in [0, 1];$$

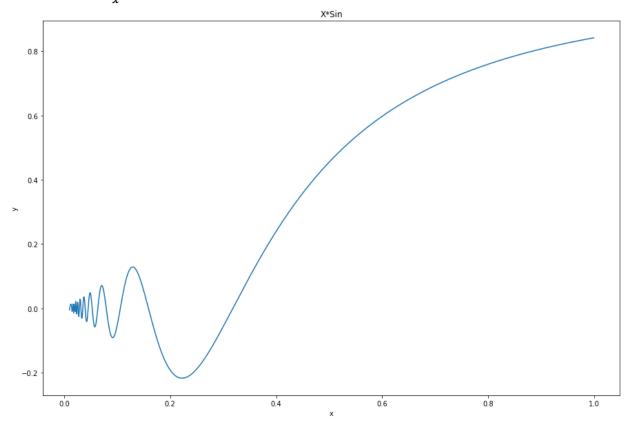


Results table:

Method	f(x)	х	Number of function calls	Number of iterations
Brute force	0.0	0.2	1000	1000
Dichotomy method	0.001	0.1989	21	10
Golden ratio method	0.0001	0.1999	31	15

Trigonometry function

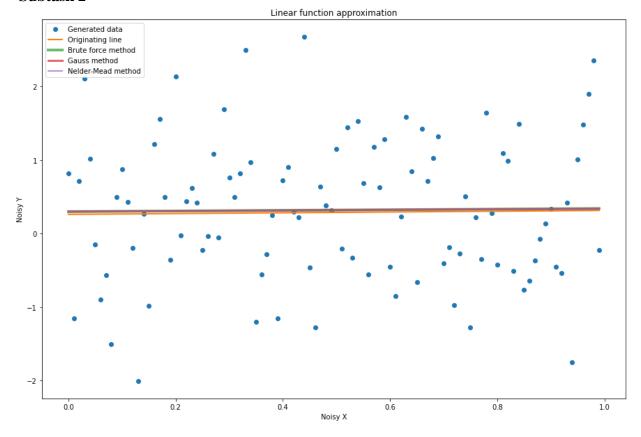
$$f(x) = x \sin \frac{1}{x}, x \in [0.01, 1].$$

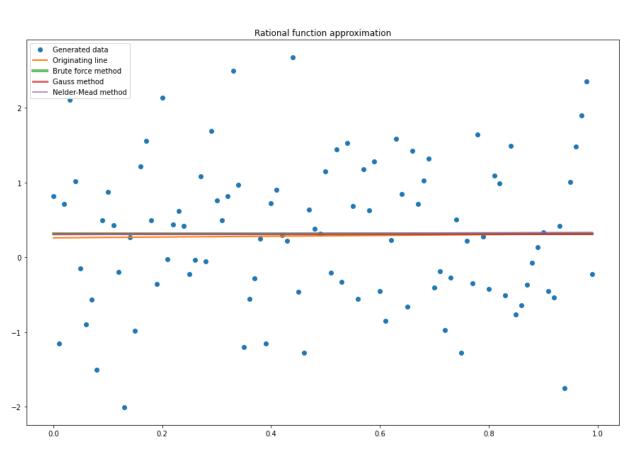


Results table:

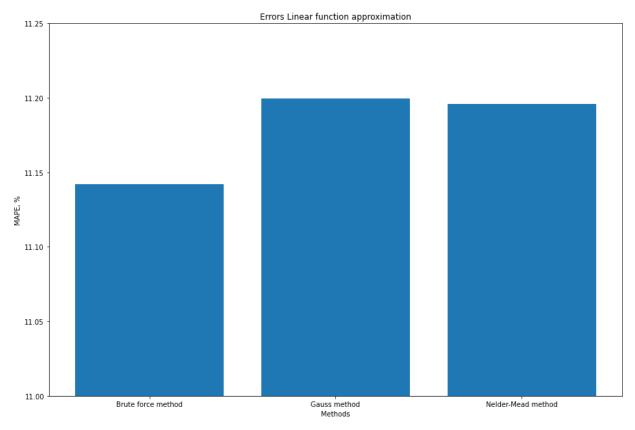
Method	f(x)	x	Number of functions call	Number of iterations
Brute force	-0.21722	0.223	990	990
Dichotomy method	-0.21717	0.2214	21	10
Golden ratio method	-0.21723	0.2225	31	15

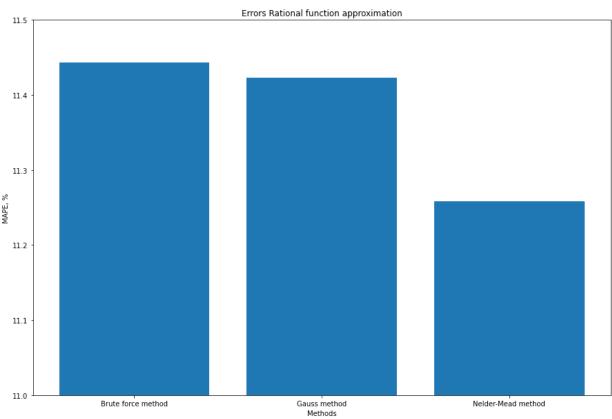
Subtask 2





Comparing MAPE for each type of approximation





Method	MAPE for linear app, %	MAPE for rational app, %	What's the better?
Brute Force	11.14	11.44	Linear
Gauss	11.20	11.42	Linear
Nelder-Mead	11.20	11.25	Linear

Conclusions

Subtask 1

From the results we see that all 3 methods find the minimum of the function within the margin of error. As expected, the brute-force method has the most iterations and calculations of the function. The number of iterations and calculations of the function for the dichotomy method and the brute force method are approximately equal.

Subtask 2

The results show that all three approximation methods give approximately the same result. But in comparing between the methods of approximation we can define that Linear approximation a little bit better than rational approximation. It is completely the same of our theoretical expectations because we generate our random data using mostly linear part of function (y = ax+b+Noize(N(0,1))).

Appendix

https://github.com/AAYamoldin/TrainingPrograms/blob/master/Python/ITMO_algorithms_lab/task2_Algorithms_for_unconstrained_nonlinear_optimization_direct_methods.ipynb