

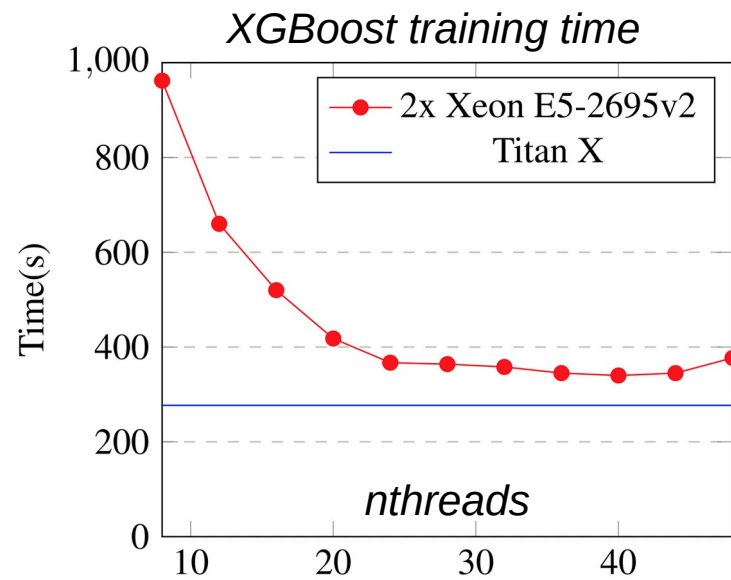
Distributed Machine Learning

Efficient DL'23, Episode II

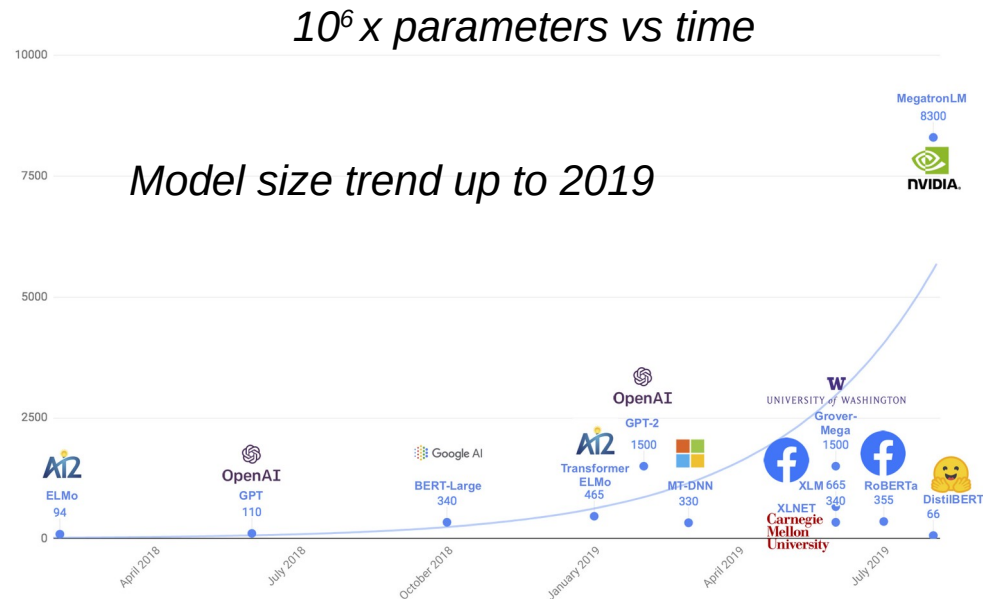
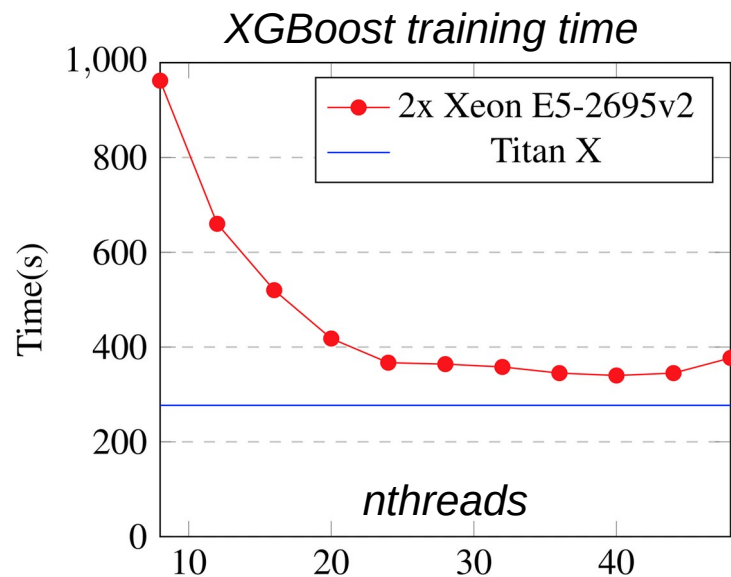
Yandex
Research



Зачем это всё?



Зачем это всё?

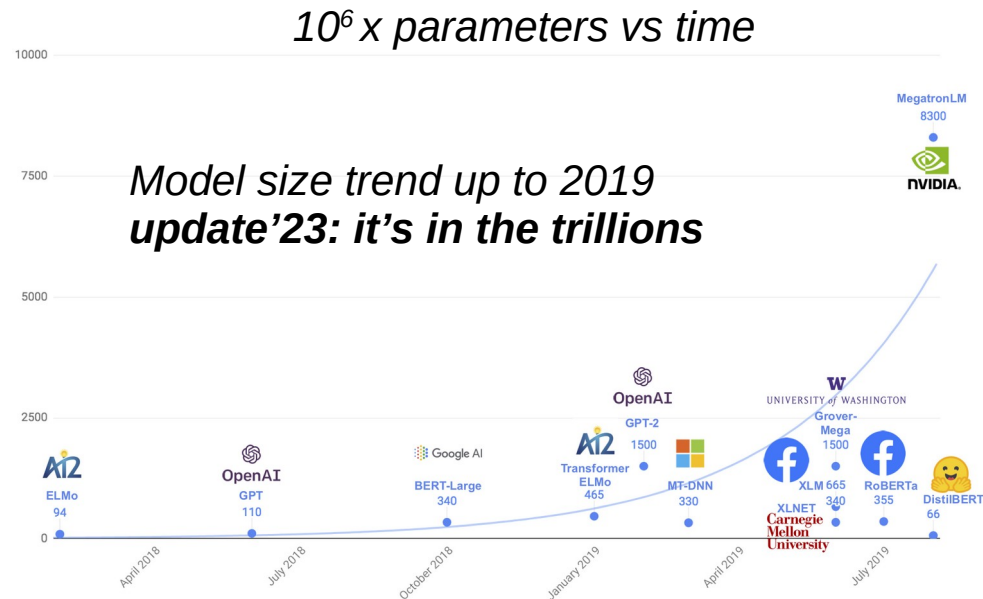
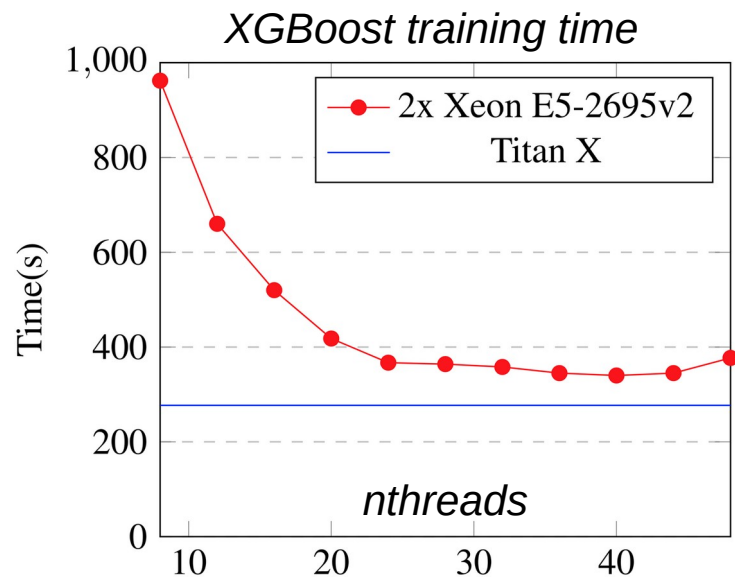


BERT-Large Training Times on GPUs

| Time | System | Number of Nodes | Number of V100 GPUs |
|---------|--------------|-----------------|---------------------|
| 47 min | DGX SuperPOD | 92 x DGX-2H | 1,472 |
| 67 min | DGX SuperPOD | 64 x DGX-2H | 1,024 |
| 236 min | DGX SuperPOD | 16 x DGX-2H | 256 |

(single V100 – over 2 weeks)

Зачем это всё?



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Зачем мы тут?

Заставить много железяк вместе учить одну модель



Зачем мы тут?

Заставить много железяк вместе учить одну модель

понять общие подходы

закодировать своими руками

на python / pytorch

TL;DR our plan

lectures 4,5,6

4) Distributed machine learning

Embeddings or log.regression with tons of training data

TL;DR our plan

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5) Data-parallel deep learning

Train BERT-base on wikipedia in 20 minutes or less

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Fine-tune and deploy models with 100B parameters

TL;DR our plan

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Fine-tune and deploy models with 100B parameters

like OPT-175B, BLOOM-176B, YALM, GLM, Galactica

TL;DR our plan

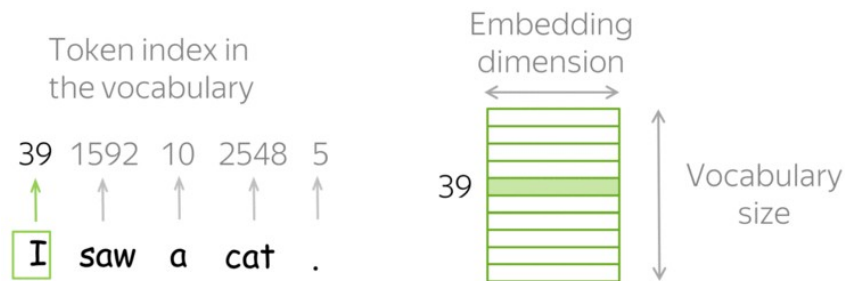
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4) Distributed machine learning

Embeddings or log.regression with tons of training data

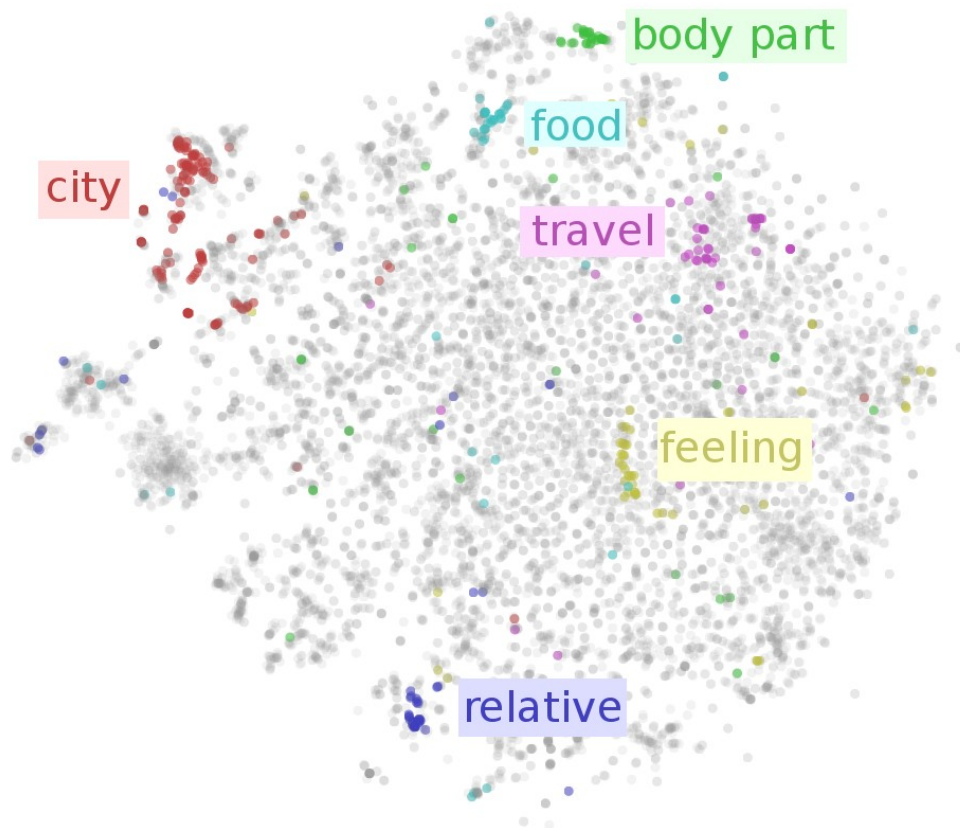
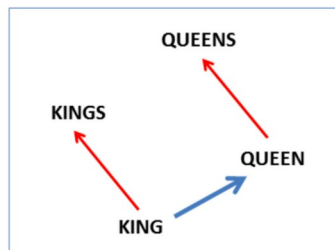
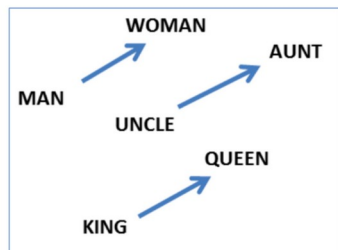
Today: learn the basics behind it all

Example problem: word embeddings

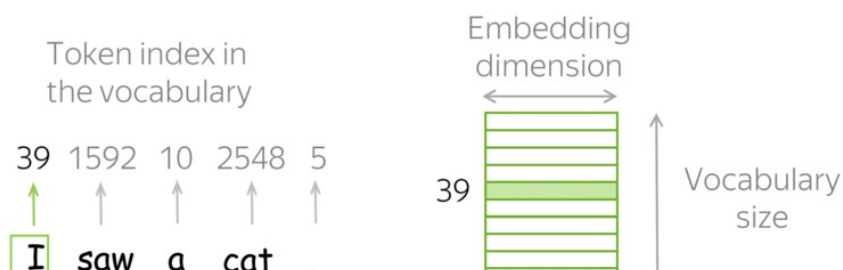


semantic: $v(\text{king}) - v(\text{man}) + v(\text{woman}) \approx v(\text{queen})$

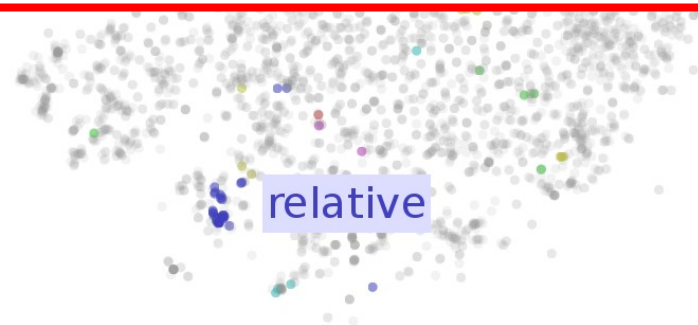
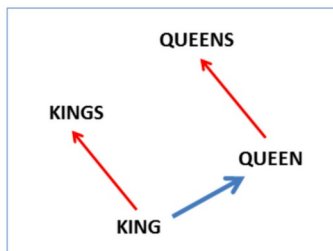
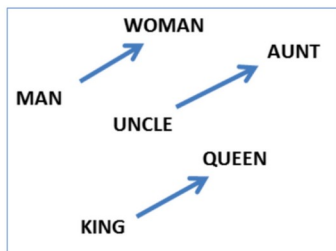
syntactic: $v(\text{kings}) - v(\text{king}) + v(\text{queen}) \approx v(\text{queens})$



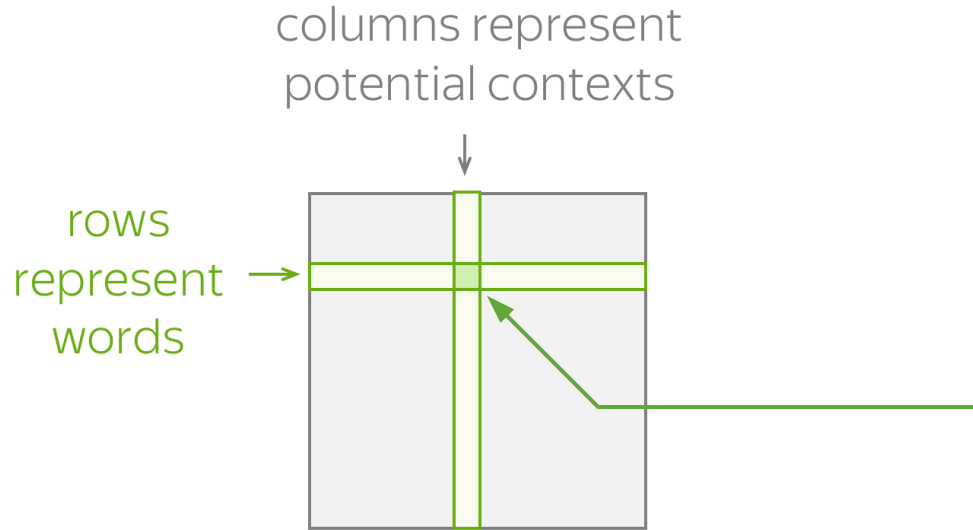
Example problem: word embeddings



This is an example problem, don't focus on NLP too much
computationally similar: large-scale LogReg, SVD, GBDT



Co-occurrence matrix

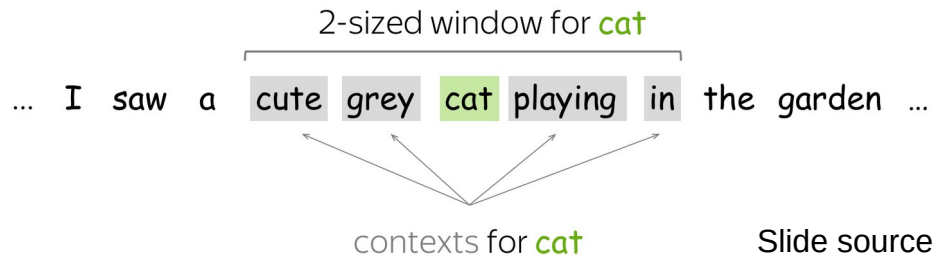


Context:

- surrounding words in a L-sized window

Matrix element:


- $N(w, c)$ – number of times word w appears in context c



Note: in our case, N is symmetric!

GloVe

context vector word vector bias terms (also learned)


$$L = \sum_{i \neq j} w(N(i, j)) \cdot (\langle \vec{v}_i, \vec{v}_j \rangle + b_i + b_j - \log N(i, j))^2$$

GloVe

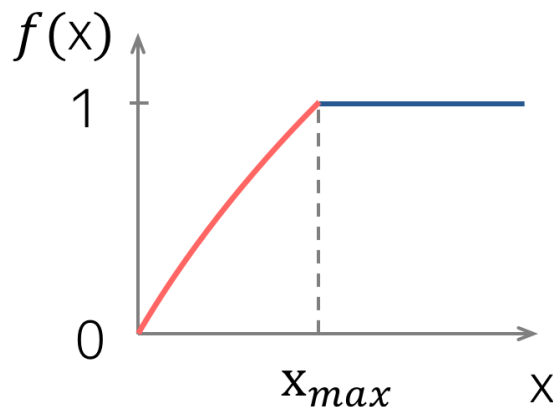
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↓

Weighting function to:


- penalize rare events
- not to over-weight frequent events



$$\begin{cases} (x/x_{max})^\alpha & \text{if } x < x_{max}, \\ 1 & \text{otherwise.} \end{cases}$$

$$\alpha = 0.75, x_{max} = 100$$

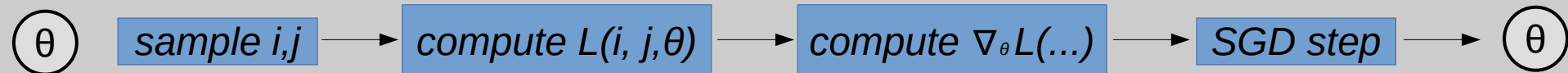
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Learn more: lena-voita.github.io/nlp_course/word_embeddings.html

So how do we train 'em?

Training Step

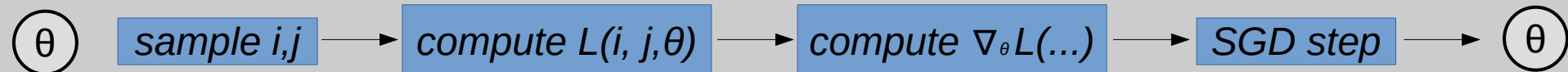


current
params
 $\theta: \{v, b\}$

$$L = \sum_{i \neq j} w(N(i, j)) \cdot (\langle \vec{v}_i, \vec{v}_j \rangle + b_i + b_j - \log N(i, j))^2$$

updated
params

Training Step

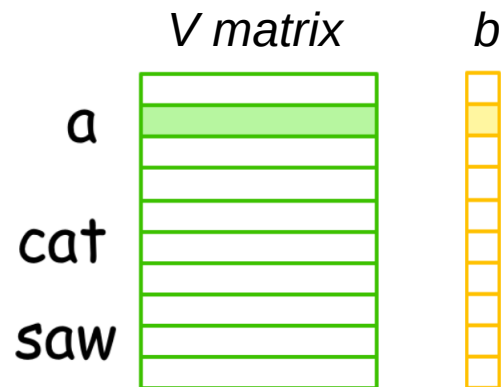


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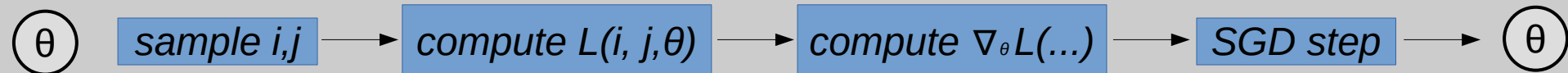
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updated
params

Trainable parameters:



Training Step

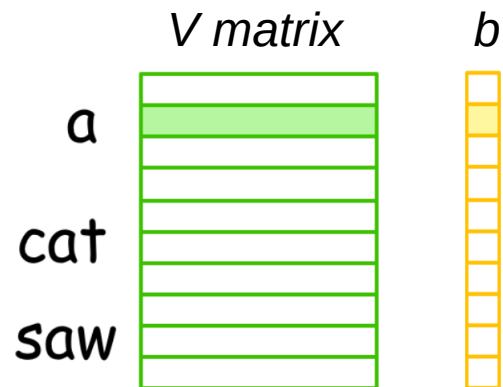


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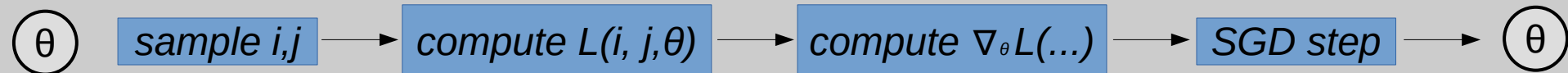
updated
params

Trainable parameters:



***How do we go faster
with 8 CPU cores?***

Training Step



current
params
 $\theta: \{v, b\}$

$$L = \sum_{i \neq j} w(N(i, j)) \cdot (\langle \vec{v}_i, \vec{v}_j \rangle + b_i + b_j - \log N(i, j))^2$$

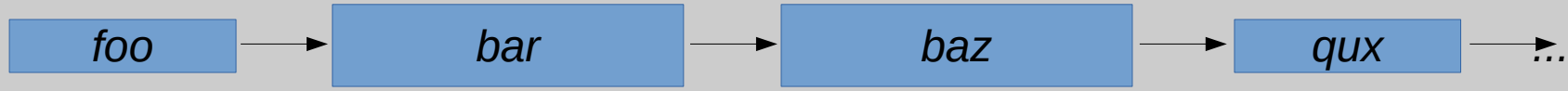
updated
params

Trainable parameters:

| | V matrix | b |
|-----|----------|---|
| a | | |
| | | |
| | | |
| cat | | |
| | | |
| saw | | |
| | | |
| | | |

[let's formalize your ideas]

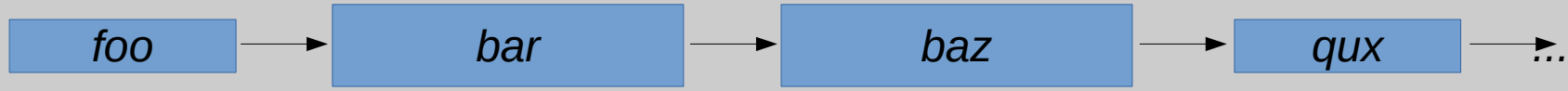
Rules: Process



Process:

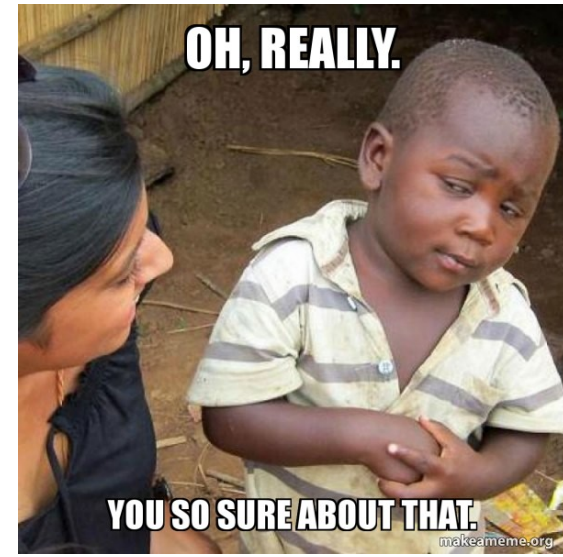
- Runs some code
- Has some memory
- No one else can access your memory

Rules: Process



Process:

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Rules: Process



Process:

- Runs some code
- Has some memory
- No one else can access your memory*

* – not if you use shared memory

Rules: Process



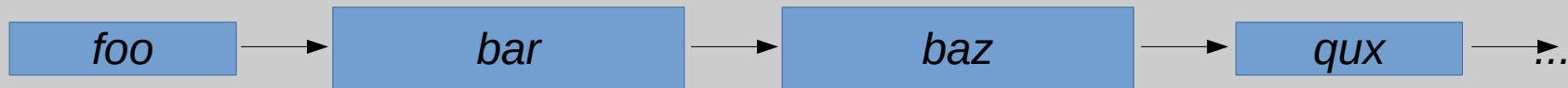
Process:

- Runs some code
- Has some memory
- No one else can access your memory^{*†}

^{*} – not if you use shared memory

[†] – superuser can still do that (os-dependent)

Rules: Process



Process:

- Runs some code
- Has some memory
- No one else can access your memory^{*†‡}

* – not if you use shared memory

† – superuser can still do that (os-dependent)

‡ – attacker can do that through spectre/meltdown/etc

Rules: Process

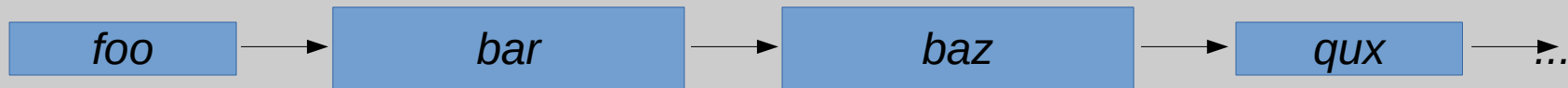


Process:

- Runs some code
- Has some memory
- No one else **should** access your memory^{*†‡}

^{*†‡} – not relevant for this course

Rules: Process



Process:

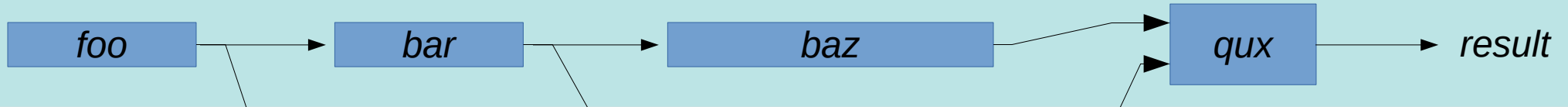
- Runs some code
- Has some memory
- No one else **should** access your memory^{*†‡}

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Q: How do we make processes work together?

Rules: Channel / Pipe

Process A:



Process B:



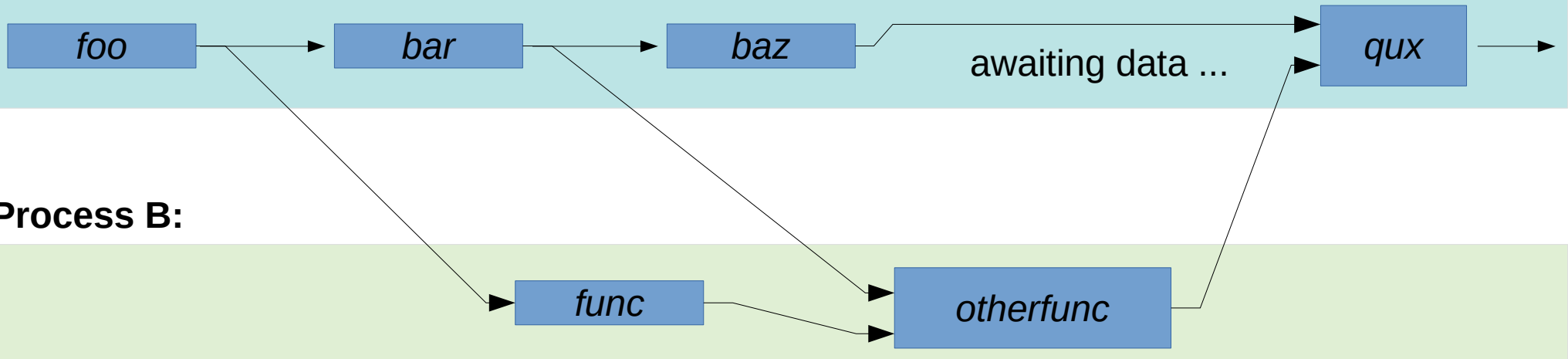
Channel (pipe):

- Communication in $O(\text{message size})$
- Asynchronous read/write

MP Rules

Process A:

not waiting on write

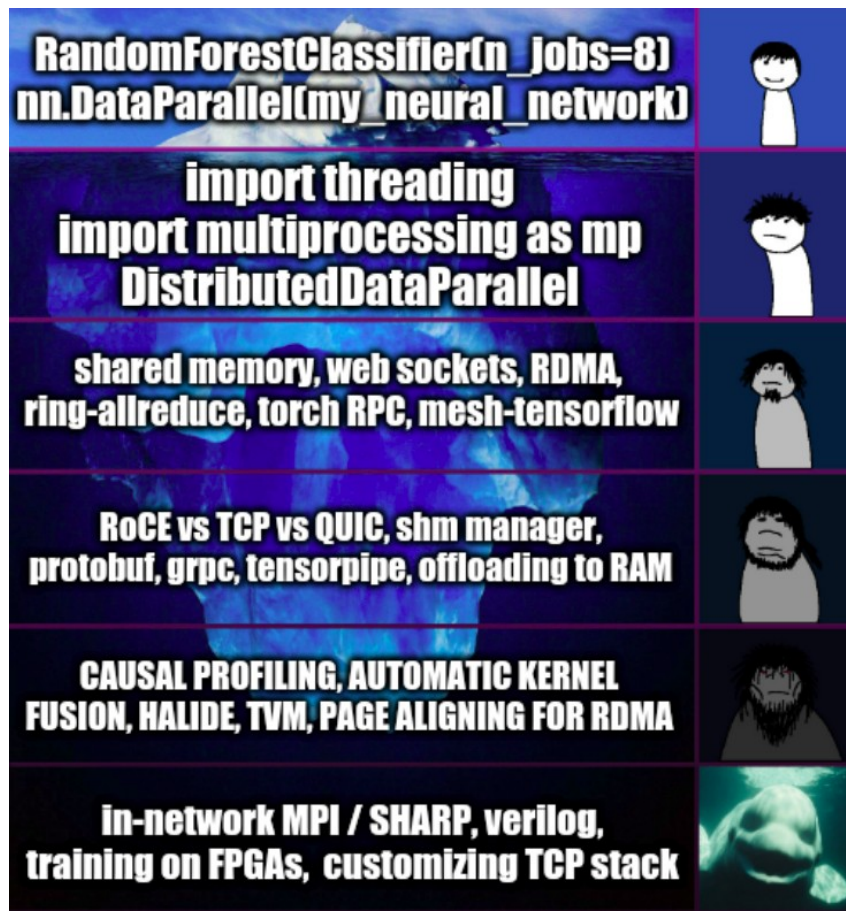


Process B:

Channel (pipe):

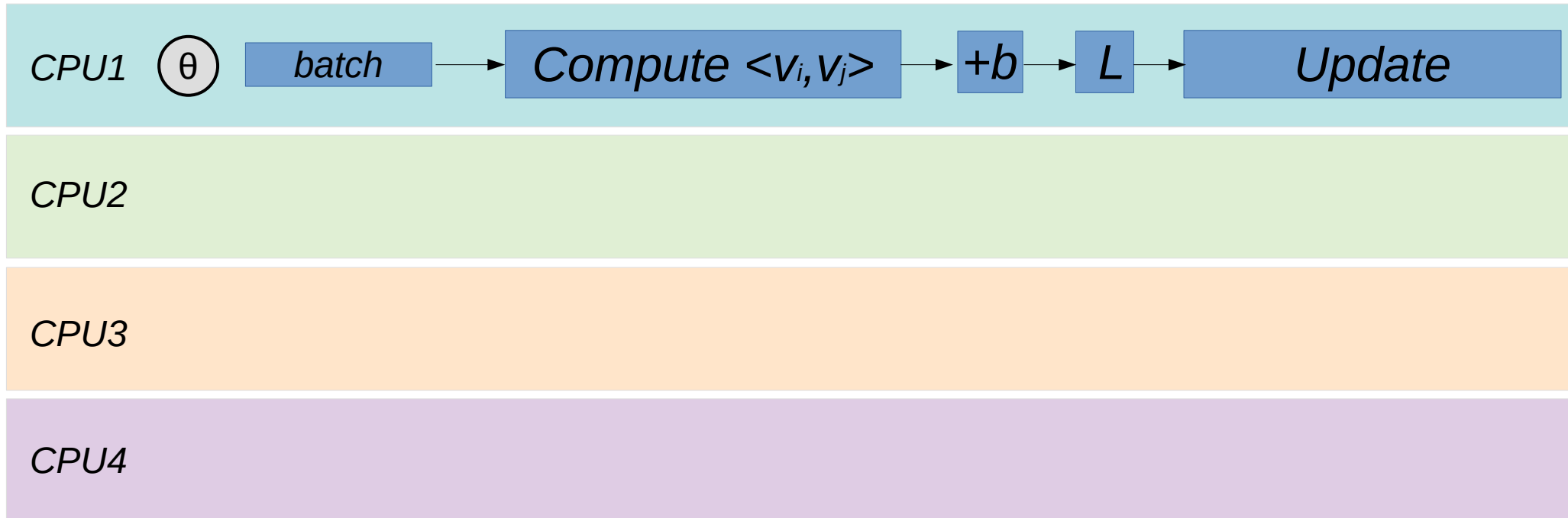
- Communication in $O(\text{message size})$
- **Asynchronous** read/write

Details are (not) important



Operation parallelism

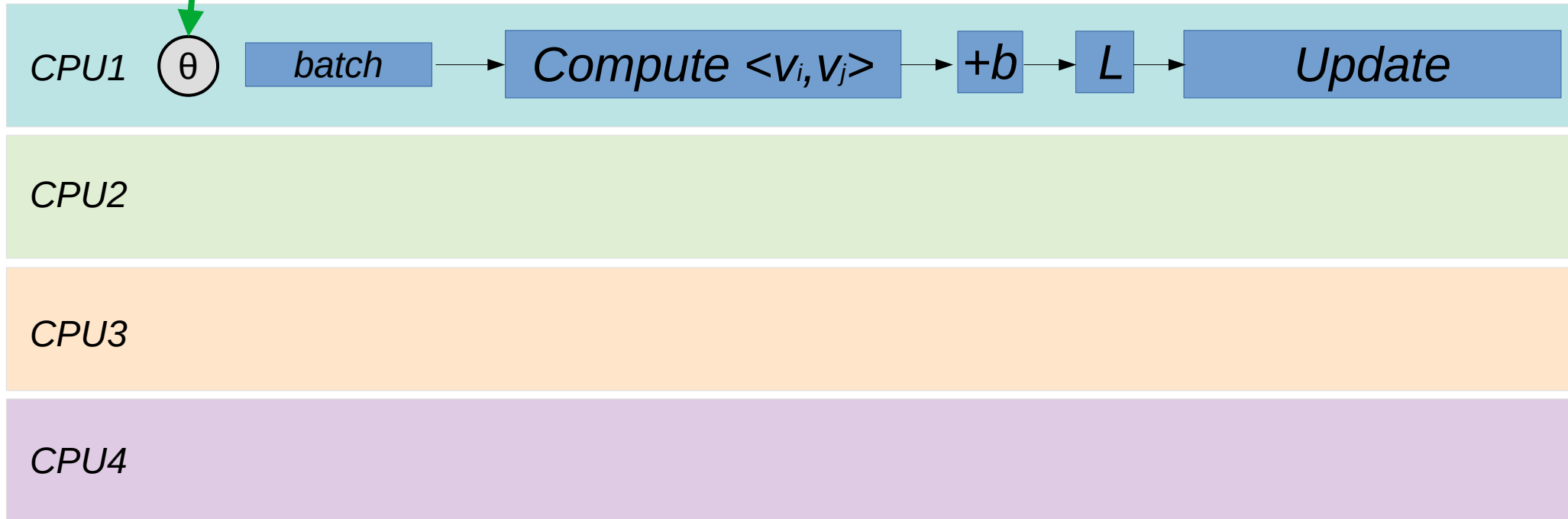
run algorithm in parallel without changing the math



Operation parallelism

*model
weights*

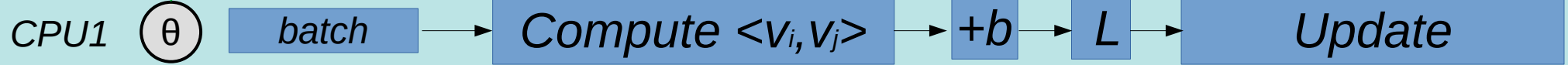
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Operation parallelism

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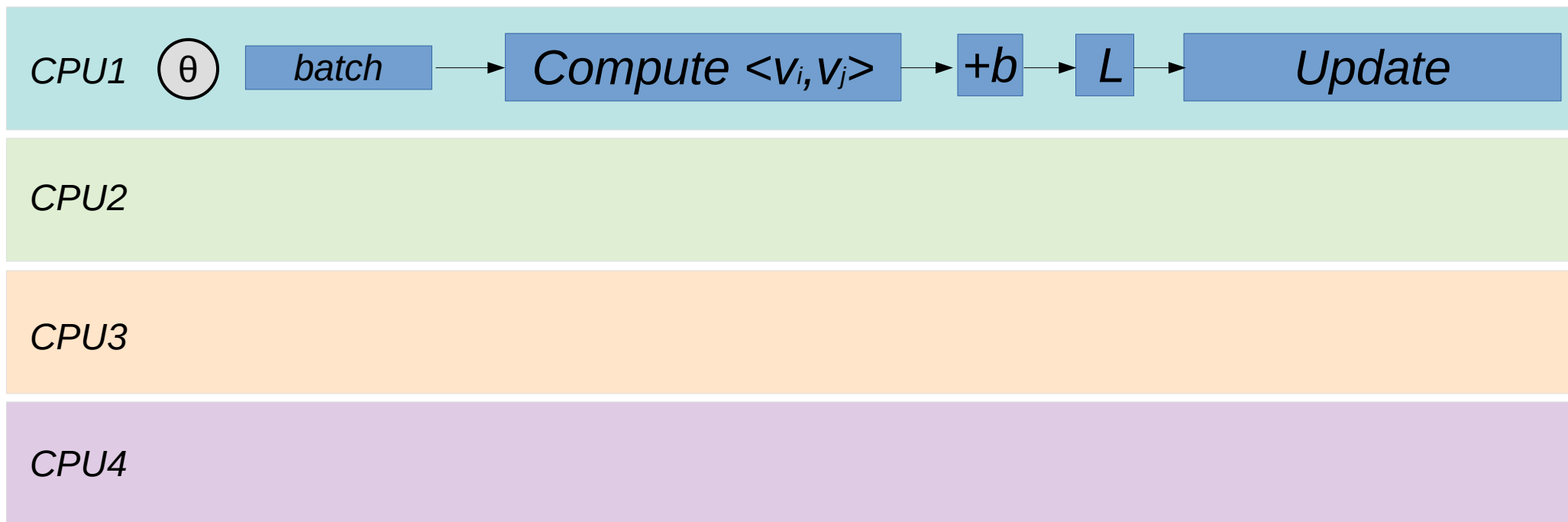
CPU2

CPU3

CPU4

“Data parallelism”

*Each process runs **full** model on **some** samples*



“Data parallelism”

*Each process runs **full** model on **some** samples*

CPU1 θ

batch

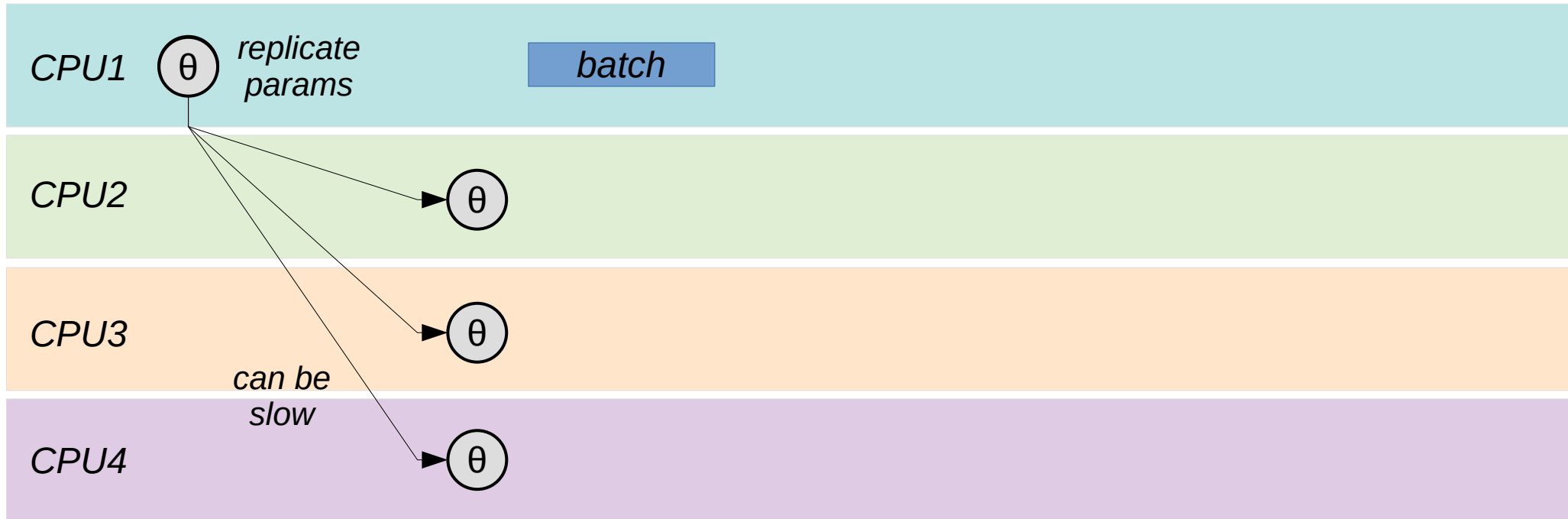
CPU2

CPU3

CPU4

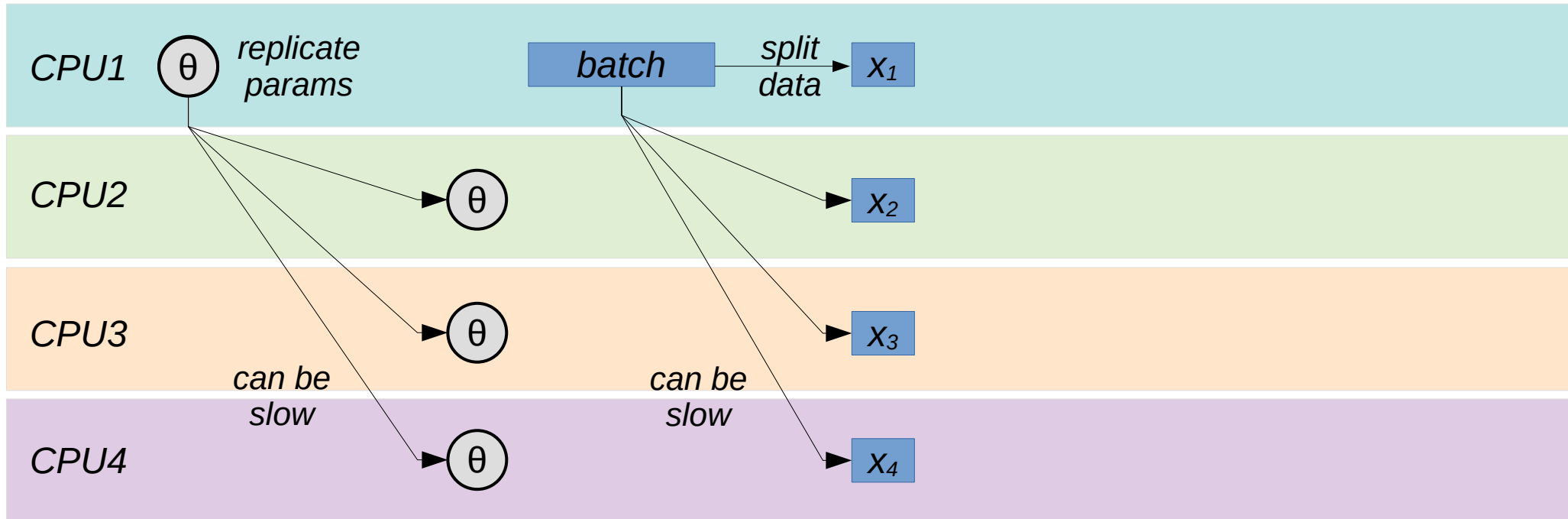
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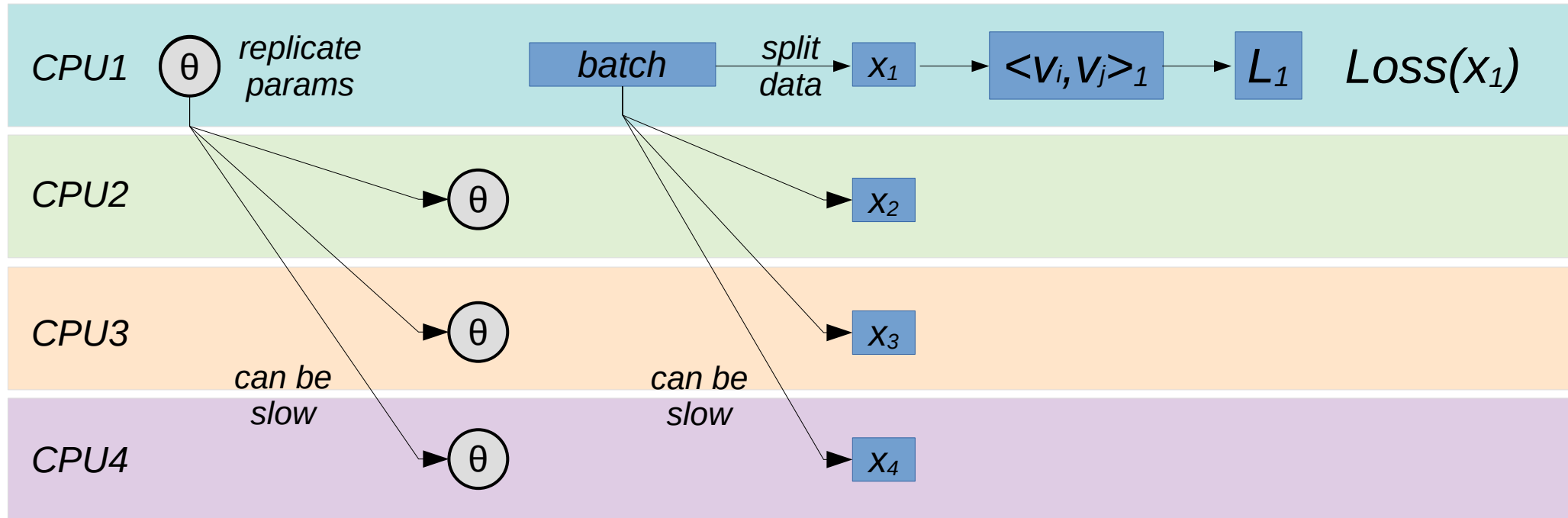
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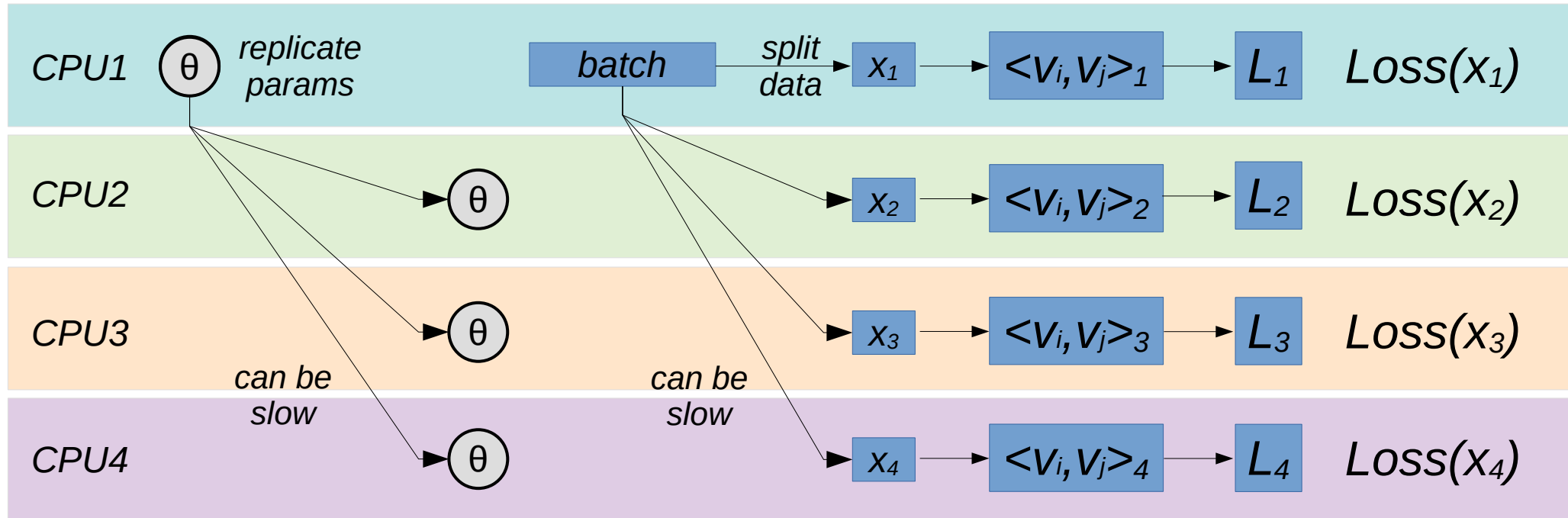
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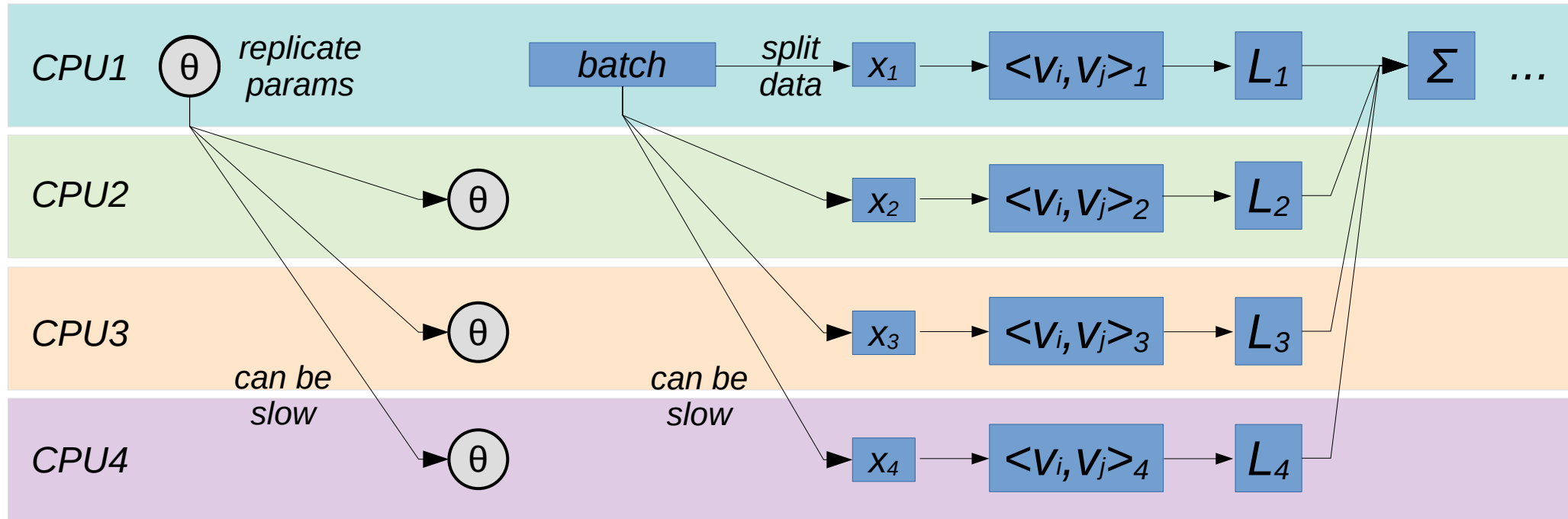
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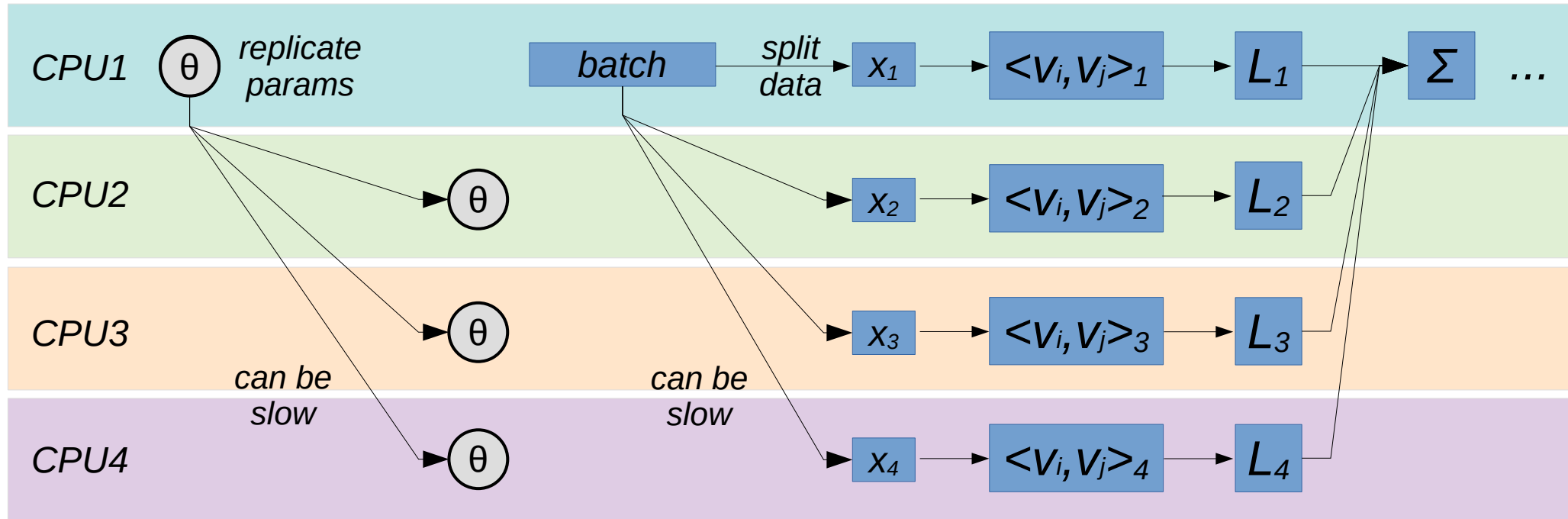
“Data parallelism”

Each process runs **full** model on **some** samples



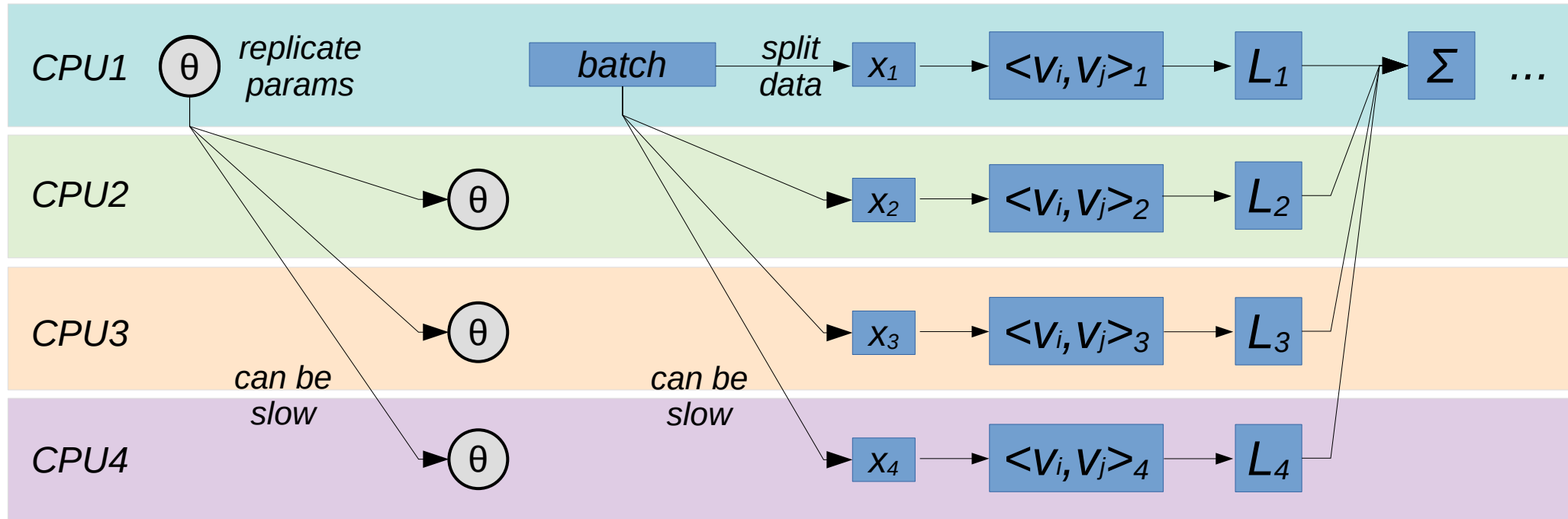
“Data parallelism”

Q: Is it guaranteed to be faster?



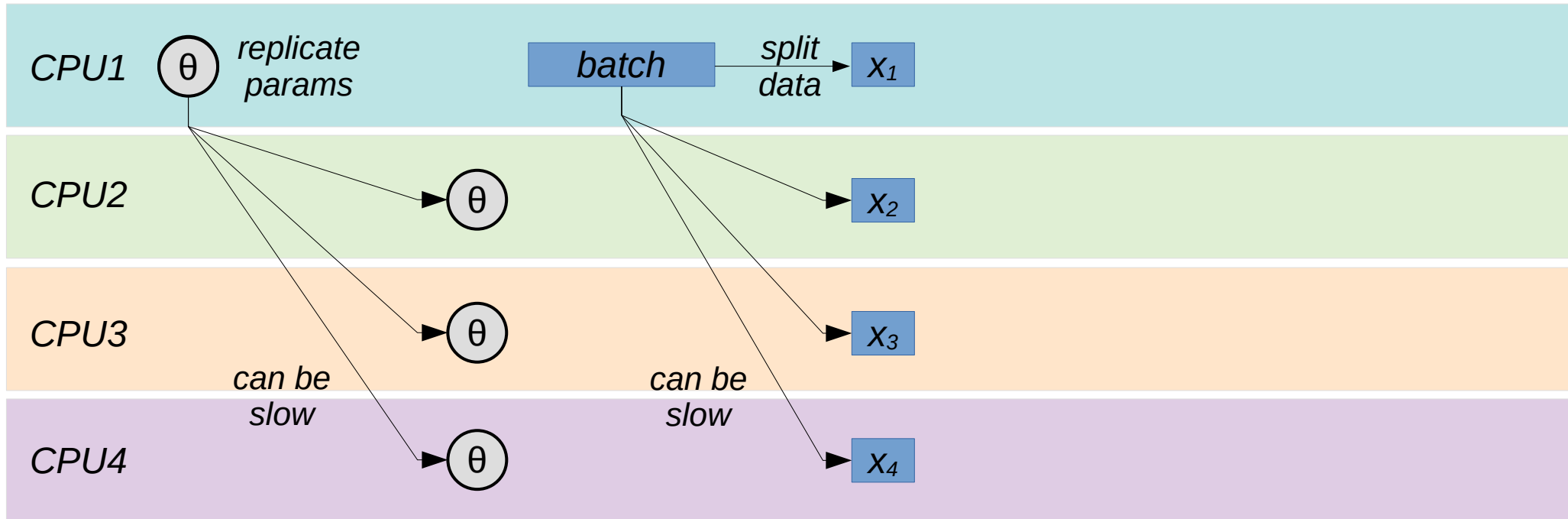
“Data parallelism”

Q: Is it guaranteed to be faster? **No, sending data may take longer than computing**



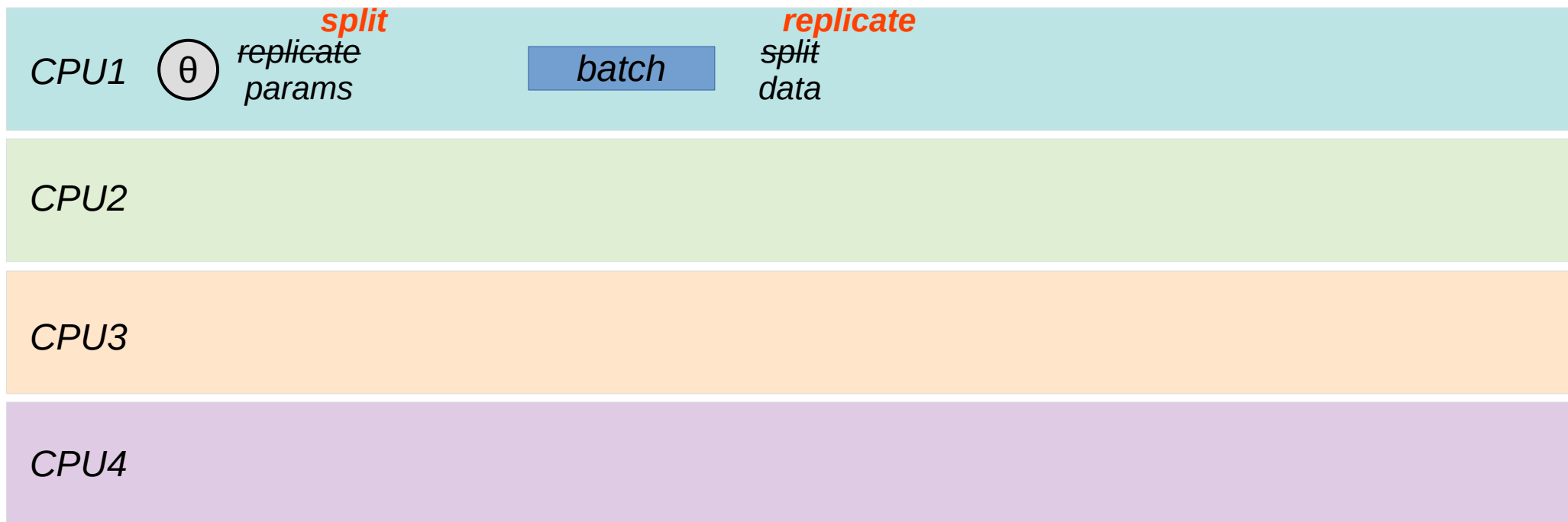
“Data parallelism”

Q: any other way to compute $\langle v_i, v_j \rangle$ in parallel?



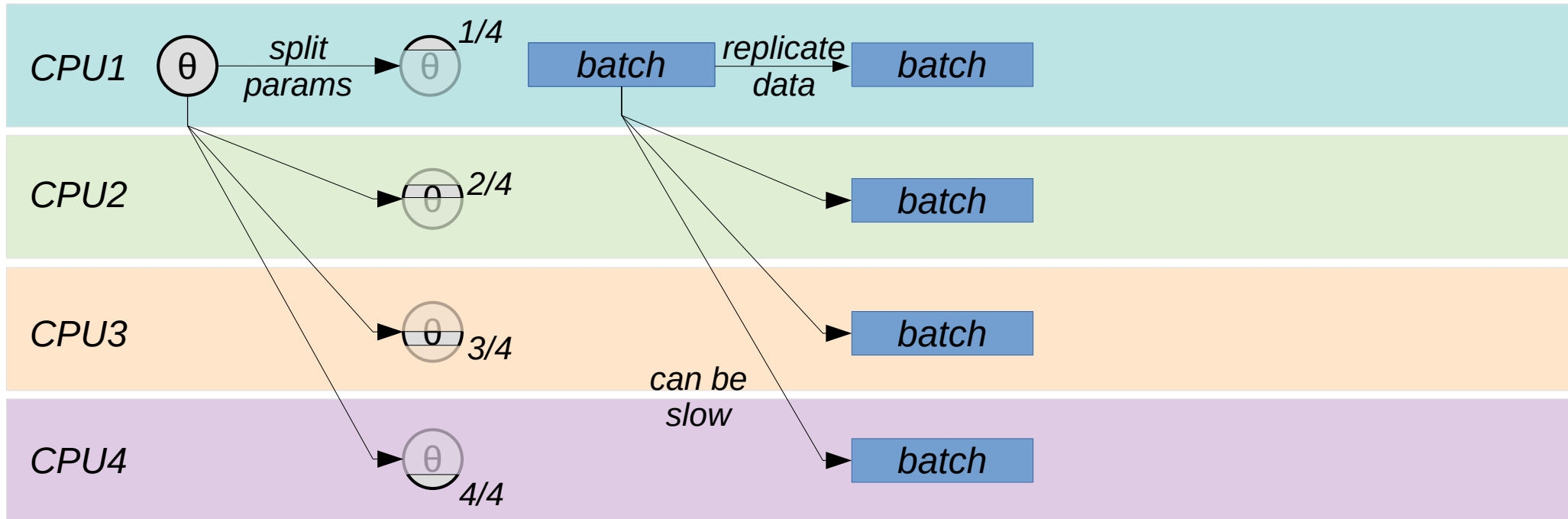
“Model parallelism”

Each process runs *partial* model on *all* samples



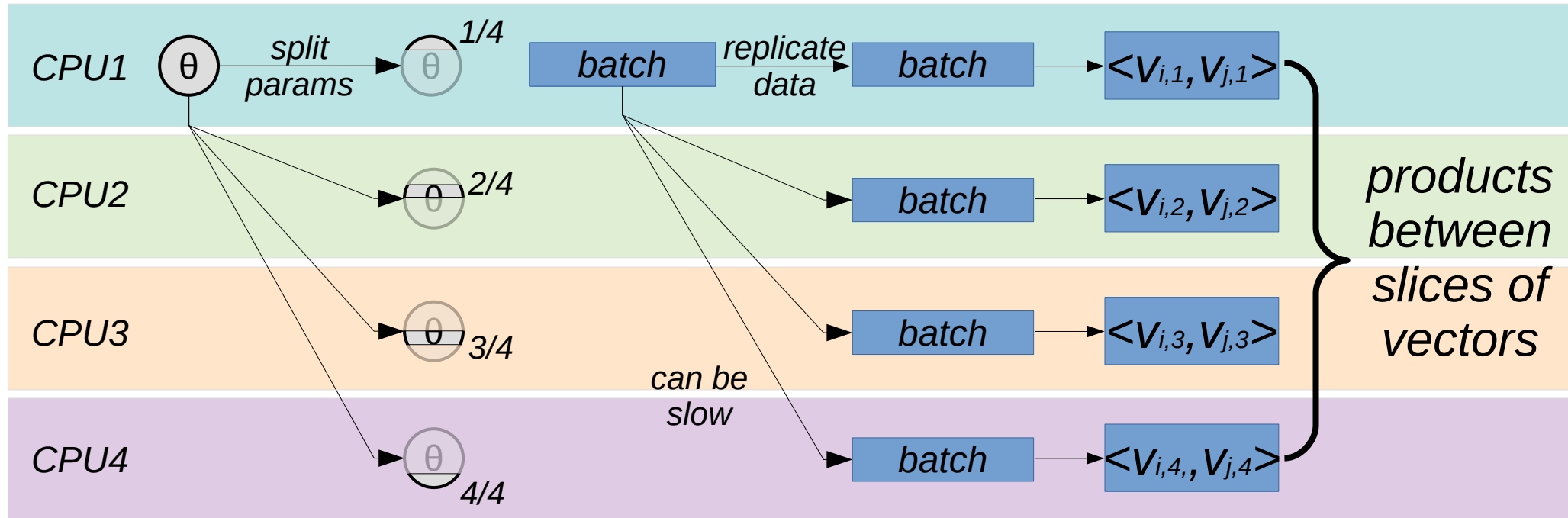
“Model parallelism”

Each process runs **partial** model on **all** samples



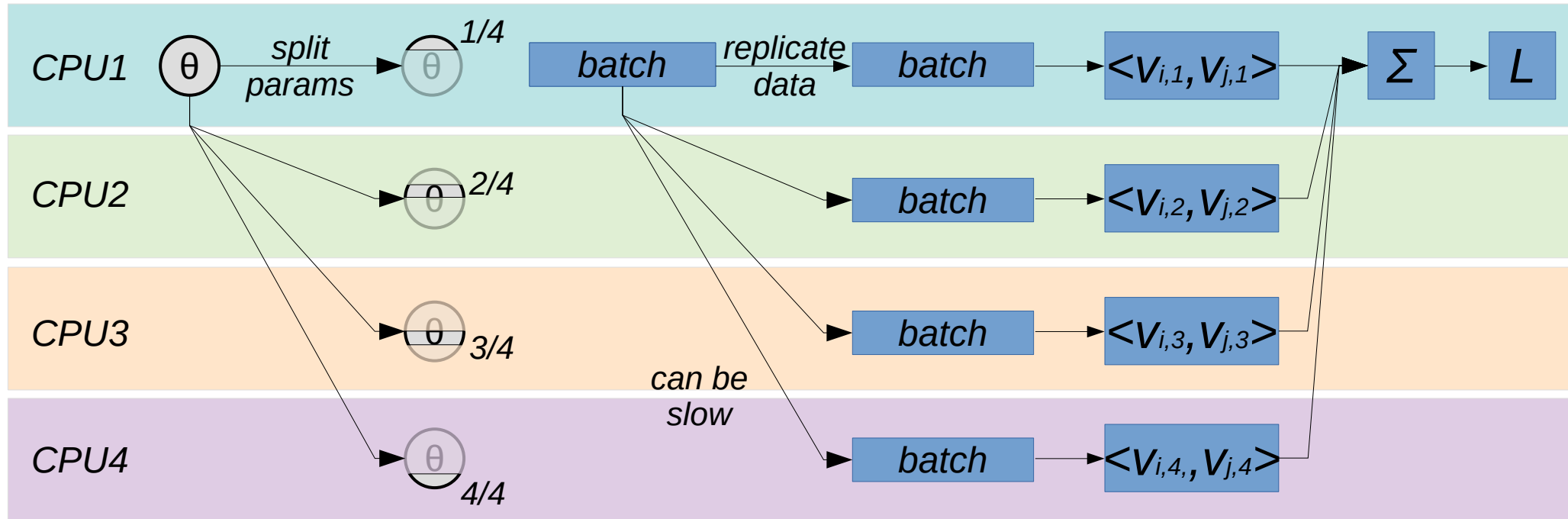
“Model parallelism”

Each process runs *partial* model on *all* samples



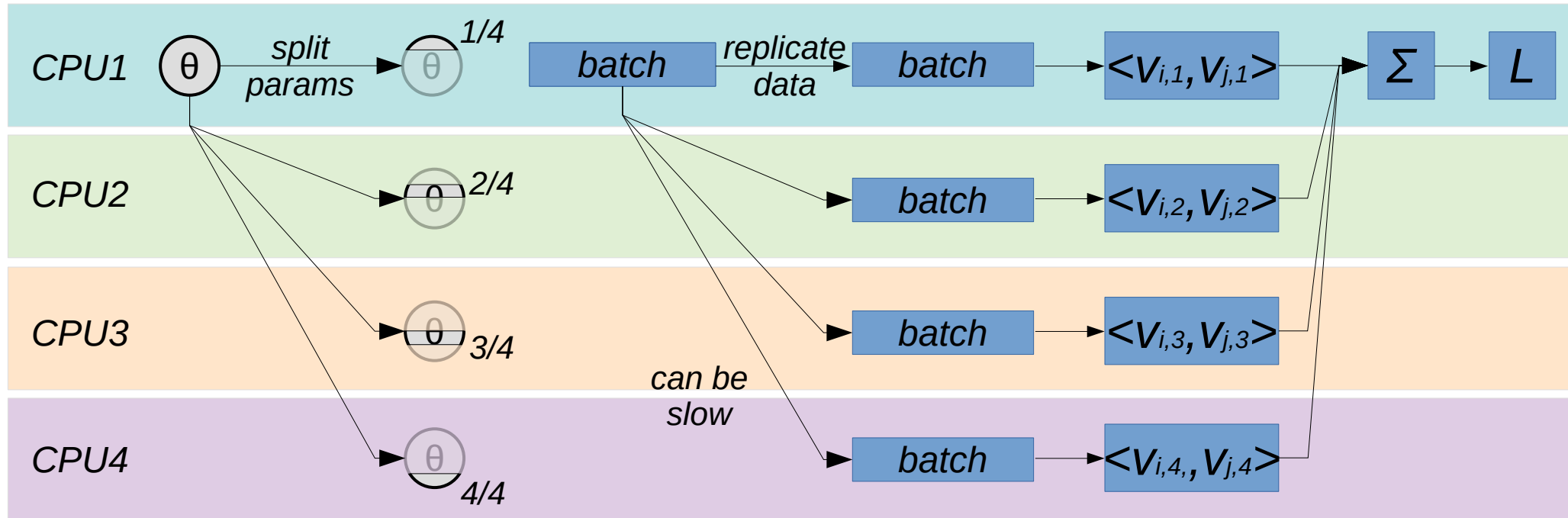
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Each process runs *partial* model on *all* samples



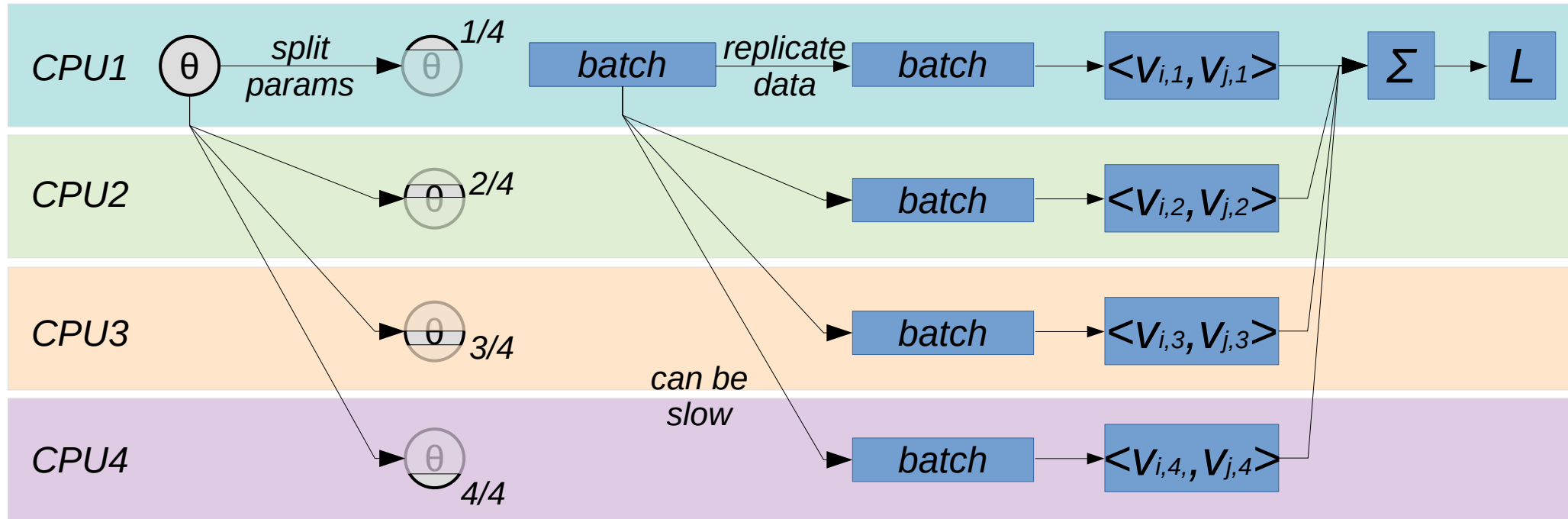
“Model parallelism”

Q: do we have to send params from P1 each time?



“Model parallelism”

Optimization: each process can update it's own params locally instead of receiving them from P1



Summary: operation parallelism

Data-parallel: one process applies all model on ***partial data***

Model-parallel: one process applies ***partial model*** on all data

*Which one is better..
for word2vec?
In general?*

Summary: operation parallelism

Data-parallel: *one process applies all model on **partial data**
best for smaller model, more computations*

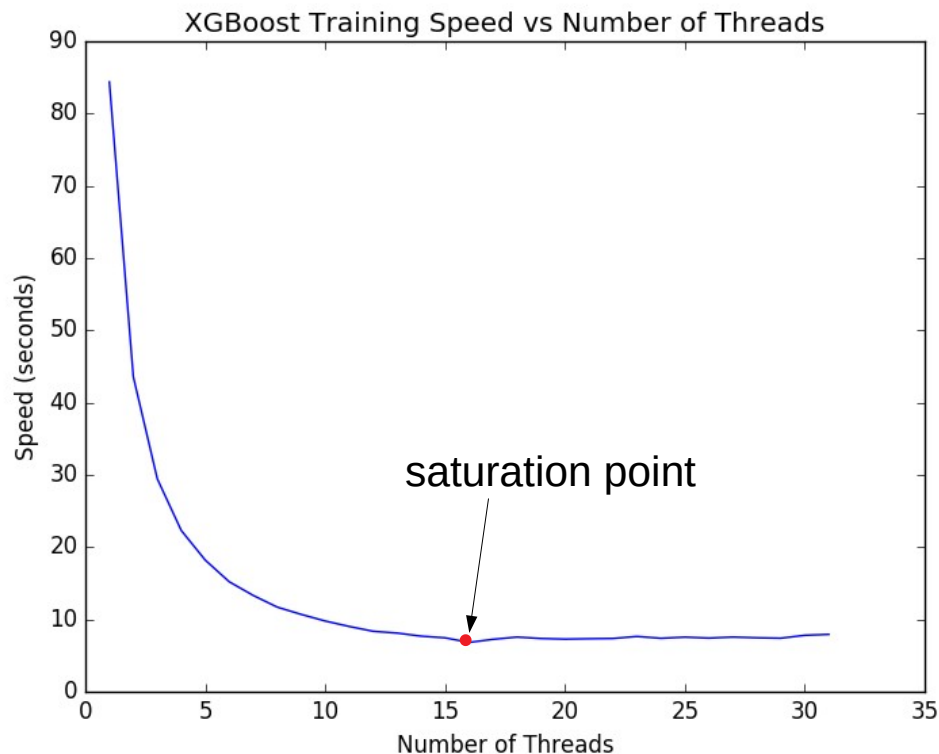
Model-parallel: *one process applies **partial model** on all data
best for larger model, fewer computations*

*Which one is better..
for word2vec?
In general?*

Summary: operation parallelism

*Если $time() < 19:00$, тут можно поговорить про бустинг.
и-или сделать перерыв*

Operation parallelism

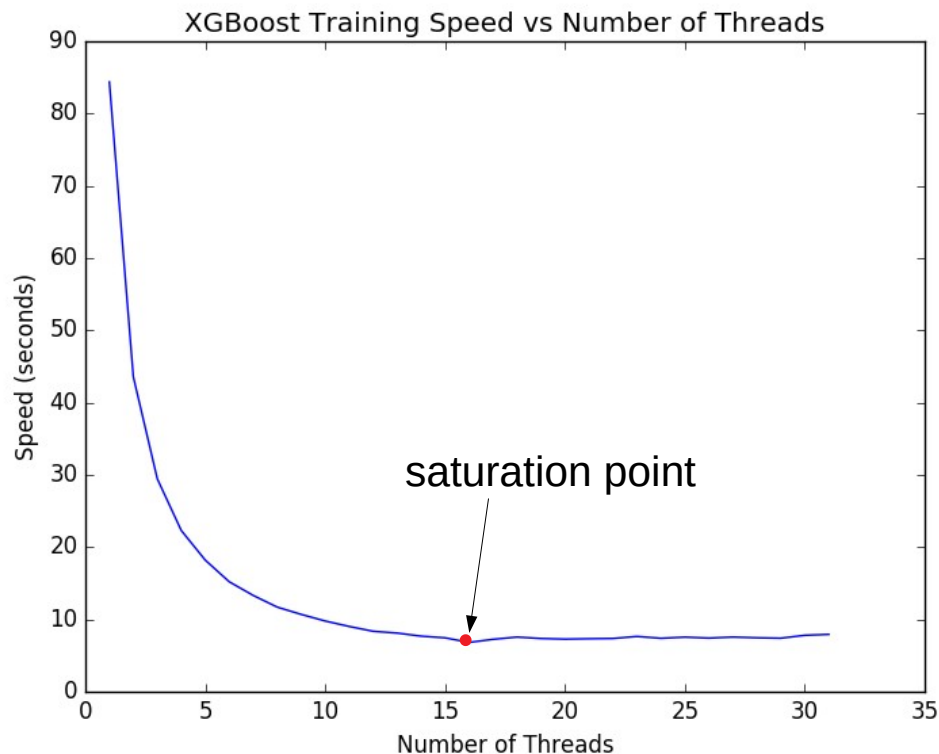


More processes = more overhead

- *waiting for each other*
- *sending data over the network*
- *performance fluctuations*

Eventually adding more threads will no longer boost performance

Operation parallelism



More processes = more overhead

- *waiting for each other*
- *sending data over the network*
- *performance fluctuations*

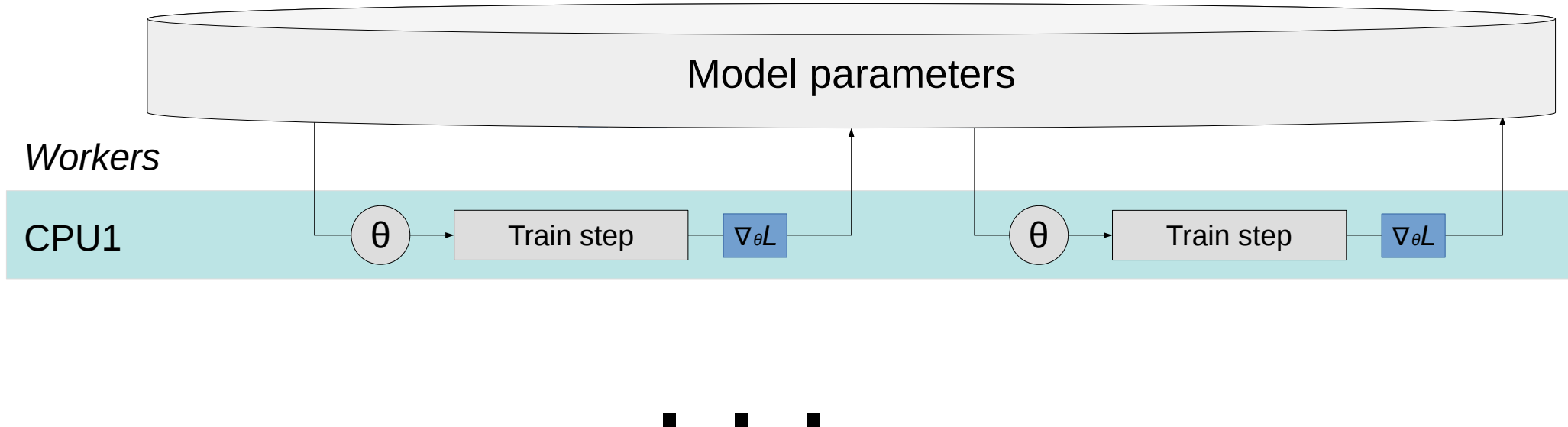
Eventually adding more threads will no longer boost performance

How do we push this point further?

Parameter Server

Paper: [Smola et al. \(2010\)](#)

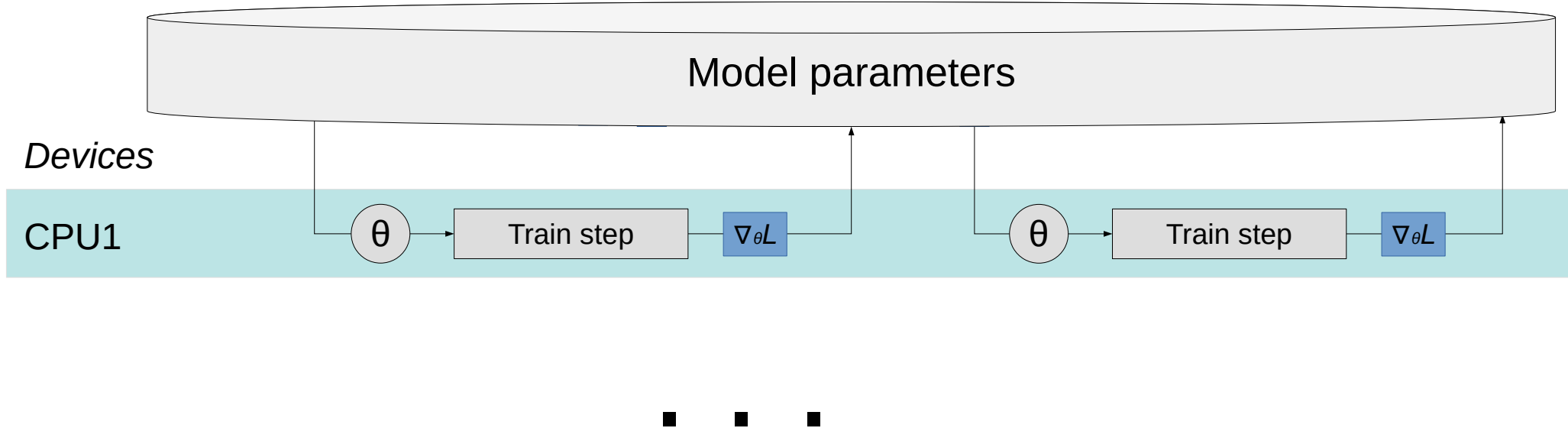
Make a dedicated process for parameters & optimizer



Asynchronous training

HOGWILD! arxiv.org/abs/1106.5730

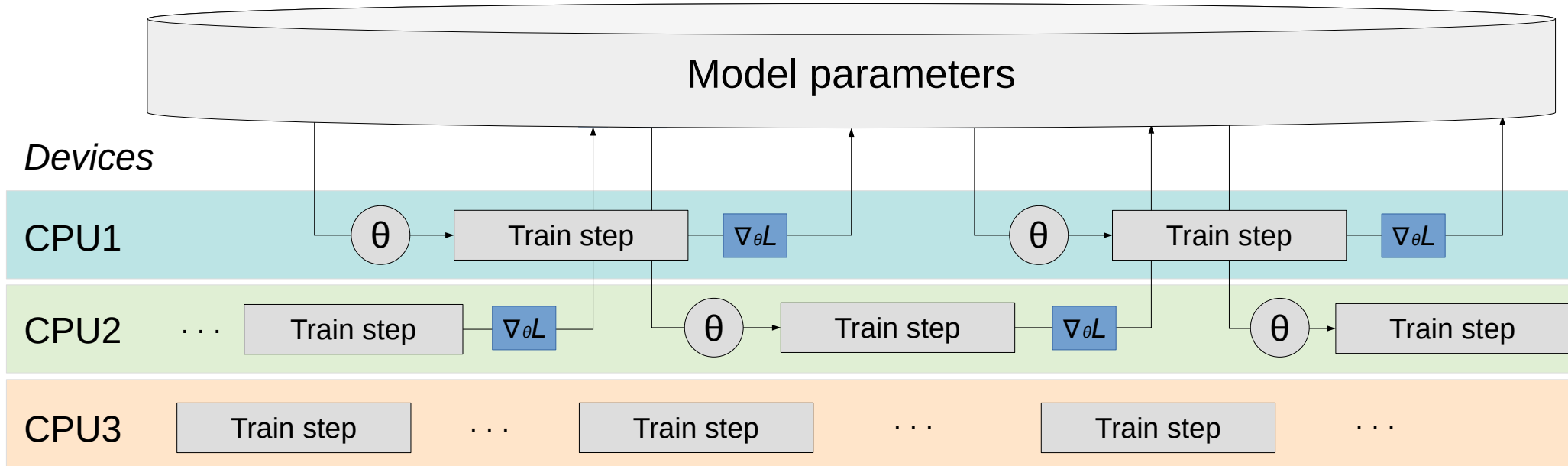
Idea: remove synchronization step altogether, use parameter server



Asynchronous training

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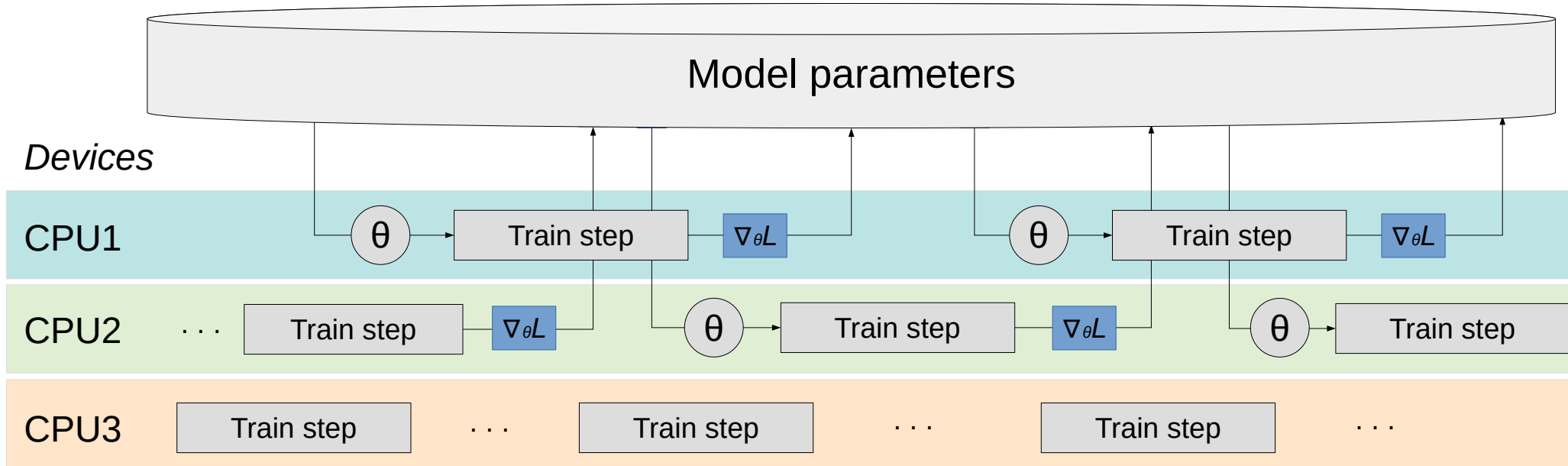
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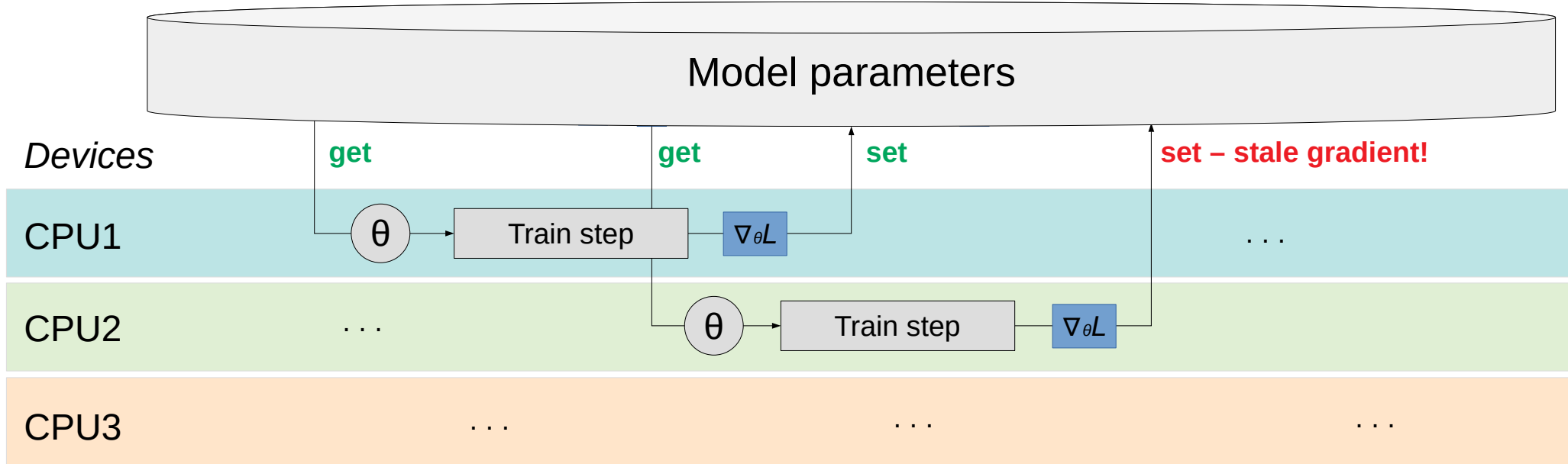


Q: have we lost anything by going asynchronous?

Asynchronous training

HOGWILD! arxiv.org/abs/1106.5730

Idea: remove synchronization step altogether, use parameter server



Staleness-aware SGD

Paper: arxiv.org/abs/1511.05950 & others

Updates accumulated: $c = \lfloor (\lambda/n) \rfloor$

Average gradient: $g_i = \frac{1}{c} \sum_{l=1}^c \alpha(\tau_{i,l}) \Delta \theta_l, \quad l \in \{1, 2, \dots, \lambda\}$

New parameters: $\theta_{i+1} = \theta_i - g_i,$

Staleness-aware SGD

Paper: arxiv.org/abs/1511.05950 & others

Updates accumulated: $c = \lfloor (\lambda/n) \rfloor$ **n = total workers**
 λ = “accumulation factor”

Average gradient:
$$g_i = \frac{1}{c} \sum_{l=1}^c \alpha(\tau_{i,l}) \Delta \theta_l, \quad l \in \{1, 2, \dots, \lambda\}$$

New parameters:
$$\theta_{i+1} = \theta_i - g_i,$$

Staleness-aware SGD

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Updates accumulated: $c = \lfloor (\lambda/n) \rfloor$

Average gradient: $g_i = \frac{1}{c} \sum_{l=1}^c \underbrace{\alpha(\tau_{i,l})}_{\text{staleness-dependent}} \Delta\theta_l, \quad l \in \{1, 2, \dots, \lambda\}$

New parameters: $\theta_{i+1} = \theta_i - g_i,$ “learning rate”

Staleness-aware SGD

Paper: arxiv.org/abs/1511.05950 & others

Updates accumulated: $c = \lfloor (\lambda/n) \rfloor$

Average gradient: $g_i = \frac{1}{c} \sum_{l=1}^c \alpha(\tau_{i,l}) \Delta\theta_l, \quad l \in \{1, 2, \dots, \lambda\}$

New parameters: $\theta_{i+1} = \theta_i - g_i,$

$$\alpha_{i,l} = \frac{\alpha_0}{\tau_{i,l}}$$

base learning rate

staleness (≥ 1)

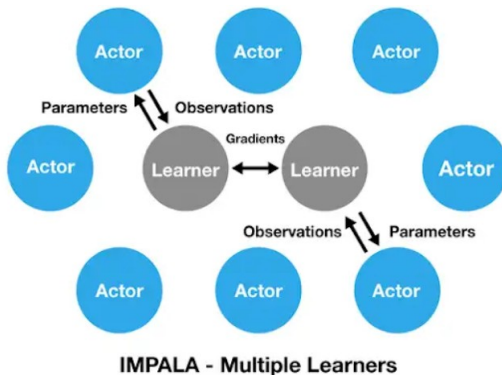
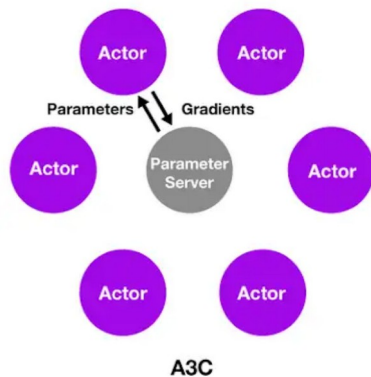
aka number of skipped updates

Parameter Server Applications

Conventional ML: *e.g. (Logistic Regression, CNN classifiers)*

Paper (sharded PS): <https://www.cs.cmu.edu/~muli/file/ps.pdf>
Another paper (optimization tricks): [parameter_server_nips14.pdf](#)
[PyTorch tutorial \(hogwild\)](#), [TF tutorial \(parameter server\)](#)

Reinforcement learning:



Async. RL: arxiv.org/abs/1602.01783

IMPALA: arxiv.org/abs/1802.01561

SEED RL: arxiv.org/abs/1910.06591

More:

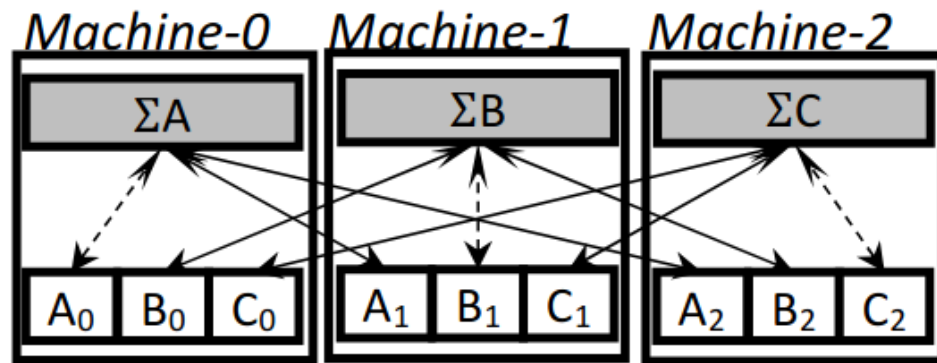
(english) <https://youtu.be/kOy49NqZeqI>

(russian) <https://youtu.be/wswbMkT55ml>

Modern Parameter Server Systems

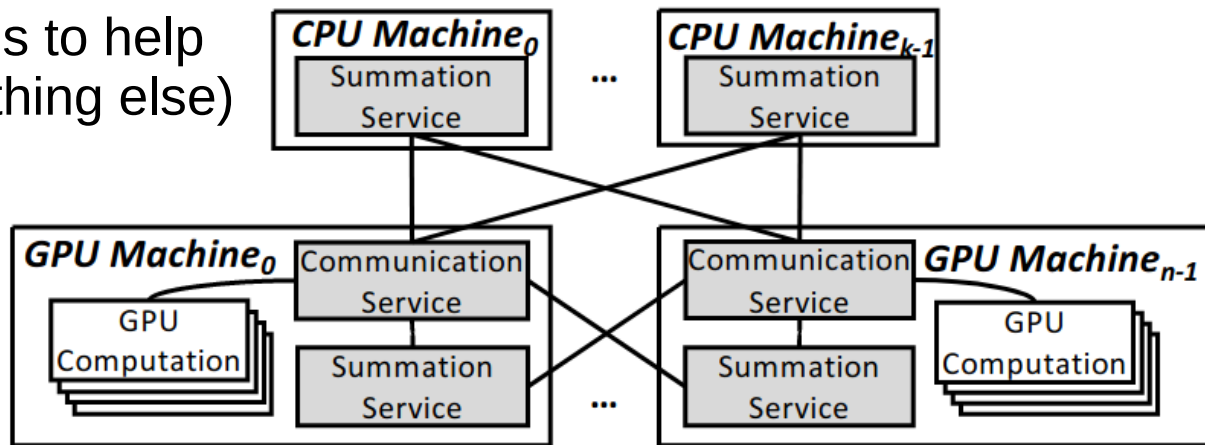
Read more: <https://www.usenix.org/system/files/osdi20-jiang.pdf>

Baseline: sharded PS on every node
Each server runs a subset of weights



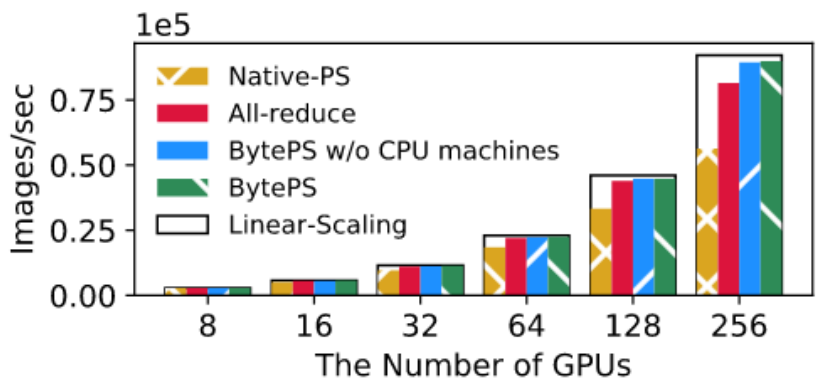
BytePS: add non-GPU nodes to help averaging gradients (and nothing else)

CPU nodes are ~10x cheaper to deploy / rent

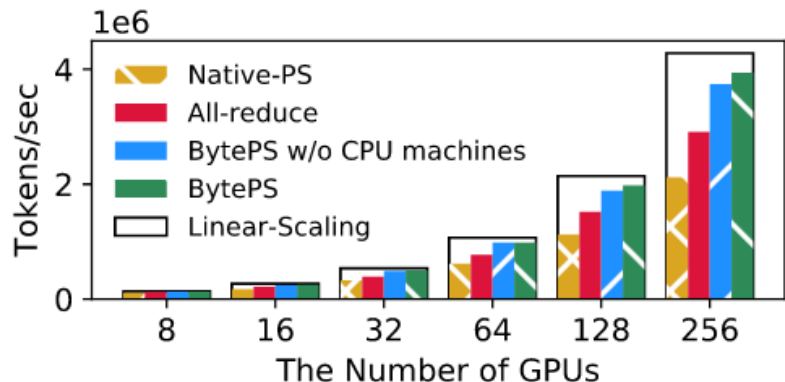


Modern Parameter Server Systems

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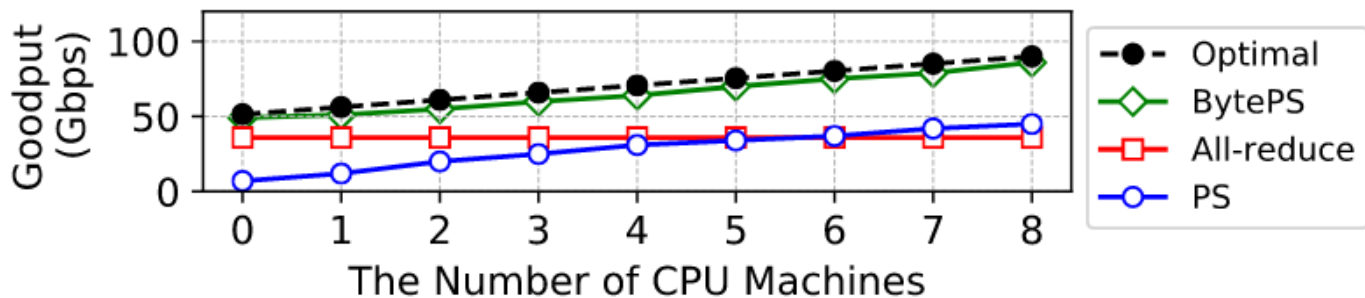


(a) TensorFlow, ResNet-50, batch=256 images



(b) MXNet, BERT-Large, batch=8192 tokens

The effect of auxiliary CPU nodes





"That's all Folks!"

l s b e r g[®]