Table A5. Steps to deploy a remote camera.

| Task | Instructions |
|----------------------------|---|
| Select camera locations | Locate the predetermined <u>camera locations</u> (e.g. based on study design and determined before camera set up; <u>Appendix A - Table A2</u>). |
| | Select a <u>FOV Target Feature</u> (if applicable) to maximize <u>detection probability</u> (e.g., wildlife trail). |
| | 3) Identify a suitable attachment point in the vicinity of the target area (e.g., tree, fence post) that supports: |
| | a detection zone ~3–5 m from the camera (~3–5 m from the FOV Target Feature), a Field of View (FOV) at least 5 m wide and 10 m long (unobstructed by objects, shrubs or trees), and the camera aimed perpendicular to the expected movement path of the Target Species. |
| | 4) Trim vegetation as needed. |
| | Note: It may be necessary to bring a man-made attachment point (e.g., stake). The most suitable attachment point will depend on the <u>camera height</u> , <u>angle</u> , and <u>direction</u> because these choices will impact the <u>Field of View (FOV)</u> . |
| Set camera | 5) Before setting up the camera, record the <u>Camera Make</u> and <u>Camera Model</u> , <u>Camera Serial Number</u> , and optionally the <u>Camera ID</u> , SD Card ID, key ID (for python or cable lock), attachment and the equipment that will be used to secure the camera. |
| | 6) Ensure the SD card is inserted, the batteries are fresh and turn the camera on. |
| | 7) Check (and record) the camera settings (e.g., <u>Trigger Mode(s)</u> , <u>Video Length (seconds)</u> , <u>Trigger Sensitivity</u> , # of <u>Photos Per Trigger</u> , <u>Motion Image Interval (seconds)</u> , <u>Quiet Period (seconds)</u> , etc.) to ensure they match the predetermined choices and that the date time is correct. Record the <u>Deployment Start Date Time</u> (in the format: "DD-MMM-YY HH:MM:SS") |
| Walktest | Perform a <u>walktest</u> to confirm that the <u>Field of View (FOV)</u> is satisfactory (see <u>section 7.4.5</u>). See the camera's user manual for instructions on how to perform the <u>walktest</u> for your particular <u>Camera Make</u> and <u>Camera Model</u> . |
| | 8) Ensure the camera detects motion 5 m in front of the camera, at both 0 m and 0.5–1 m height. Trim vegetation as needed. |
| | 9) Activate the walktest mode. |
| | 10) Attach the camera at the desired <u>camera height</u> , <u>angle</u> , and <u>direction</u> . |
| | 11) Walk in front of the camera to a specified distance (i.e., the "Walktest Distance," e.g., 5 m). |
| | 12) Wave your hand in front of the camera (usually at ground level and at a chosen height [i.e., the "Walktest Height," e.g., 0.8 m]) to determine if the camera is activating. |
| | 13) If the camera is set correctly (based on the user's criteria), an indicator light will flash to signal that the sensor is detecting heat and motion (thus indicating the camera's detection zone). |
| | 14) Arm the camera or wait for the camera to arm itself (~2 minutes of inactivity). |

| Task | Instructions |
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| | 15) Note whether a <u>walktest</u> was performed on the field datasheets and if so, optionally record the <u>Walktest Distance (m)</u> and <u>Walktest Height (m)</u> . |
| Attach and secure the camera | 16) Attach and secure the camera to the tree/post (e.g., security box or bracket, cable lock and lock box, as needed). Security / lock boxes are recommended to avoid theft. Cameras should be angled slightly downward. |
| | 17) Record the camera height (m). |
| | In general, cameras should be ~0.5–1 m from the base of the tree to the bottom of the camera lens. |
| | 18) Record the Camera Direction (degrees). |
| | Cameras should ideally face north (if not, south). |
| Test images | 19) Write the <u>deployment metadata</u> (specifically, <u>Sample Station ID</u> , <u>Camera Location ID</u> , <u>Deployment ID</u> , <u>Deployment Crew</u> , and <u>Deployment Start Date Time</u> (in the format "DD-MMM-YYYY HH:MM:SS") on either a <u>Test Image Sheet</u> or a dry-erase board with a marker. This is important in case of the situation that the camera does not properly record the <u>user label</u> . |
| | 20) Walk ~5 m in front of the camera. |
| | 21) Face the <u>Test Image Sheet</u> /dry-erase board towards the camera, and slowly walk towards the camera. If the <u>Test Image Sheet</u> is laminated, tilt it slightly downward to avoid sun glare on the shiny surface. |
| | 22) Allow the camera to take a series of images. |
| Document deployment metadata | Relevant <u>deployment metadata</u> should be documented each time a camera is deployed (see full list below). Each event should have its own <u>Camera Deployment Field Datasheet</u> . |
| | Note: If a camera is deployed for more than one <u>survey</u> , the field <u>crews</u> will need to revisit the <u>camera location</u> to " service " the camera and/or equipment (e.g., to refresh batteries or swap out SD cards. If the field <u>crew</u> visits the <u>camera location</u> to collect the camera and other equipment (" <u>Service/Retrieval Crew</u> "; i.e., the <u>camera location</u> will no longer be used and cameras, SD cards, and batteries are not replaced), this is referred to as a " retrieval ." Whether the <u>Service/Retrieval Crew</u> services or retrieves a camera, additional <u>metadata</u> should be collected that is not included in the <u>deployment metadata</u> (see " <u>service/retrieval metadata</u> " below). |
| | Pertinent <u>deployment metadata</u> collection fields include [Camera Deployment Field <u>Datasheet</u>]: |
| | Project ID Sample Station ID Camera Location ID Latitude Camera Location OR Northing Camera Location Longitude Camera Location OR Easting Camera Location UTM Zone Camera Location (if applicable) GPS Unit Accuracy (m) *Access Method Deployment Crew |

| Task | Instructions |
|---|--|
| | Deployment Start Date Time (DD-MMM-YYYY HH:MM:SS) Camera ID Camera Make Camera Model Camera Serial Number *SD Card ID *Key ID *Security Trigger Mode(s) *Yideo Length (seconds) Trigger Sensitivity Photos Per Trigger Motion Image Interval (seconds) Quiet Period (seconds) Camera Height (m) *Camera Direction (degrees) *Camera Attachment *Stake Distance (m) FOV Target Feature FOV Target Feature Distance (m) Bait/lure Type *Camera Location Characteristics *Deployment Area Photos Taken *Deployment Area Photos Numbers *Test Image Taken *Walktest Distance (m) *Walktest Complete *Walktest Distance (m) *Walktest Height (m) *Camera Active On Departure *Camera Location Comments *Deployment Comments *Deployment Comments |
| Camera service or retrieval | 23) Approach the camera from the front so that the camera will collect images of the field crew , thus serving as backup documentation of the Deployment End Date Time (in the format "DD-MMM-YYYY HH:MM:SS") in case that field sheets are lost, destroyed, etc. |
| Document service/retrieval metadata | Relevant <u>Service/Retrieval metadata</u> should be collected each time a camera is serviced (e.g., revisited to refresh batteries or swap out SD cards) or retrieved (e.g., revisited to collect the camera and other equipment, i.e., the <u>camera location</u> will no longer be used and the camera, SD card, and batteries are not being replaced) if there have been any changes to <u>camera location</u> , sampling period, and/or setting type (e.g., not <u>baited</u> and then <u>baited</u> later) (see below for a full list). Whether the <u>crew</u> services or retrieves a camera, additional <u>metadata</u> fields should be collected that are not included in the <u>deployment metadata</u> . Each event should have its own <u>Camera Service/Retrieval Field Datasheet</u> . |

| Task | Instructions |
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| | Be sure to record the "purpose of visit" (i.e., to service or retrieve the camera) as well as whether the camera was active or incurred damage, as this can provide context if there are no photos taken after a certain date. |
| | If the camera was damaged/is not functioning - before setting up the camera, record the new <u>Camera Make</u> and <u>Camera Model</u>, new <u>Camera Serial Number</u>, and optionally the New <u>Camera ID</u>, Key ID, and/or SD Card ID (if applicable; if python or cable lock damaged). |
| | Be sure to record whether the batteries were replaced (under "batteries replaced"). If using lithium batteries, the camera's battery level indicator may not decline evenly (but rather indicate full battery until a sudden drop-off). If you expect to leave your camera for a long period of time before checking it again, it is best to refresh the batteries. |
| | Record other relevant <u>metadata</u> below. |
| | Ensure you collect whatever material you used to attach the camera to the tree, post, etc. and any other equipment you brought with you. |
| | Pertinent <u>service/retrieval metadata</u> collection fields include [Camera Service/Retrieval <u>Field Datasheet</u>]: |
| | Project ID |
| | Sample Station ID |
| | <u>Camera Location ID</u> |
| | Purpose Of Visit (Service or Retrieve) |
| | Service/Retrieval Crew or Deployment Crew |
| | Deployment Start Date Time (DD-MMM-YYYY HH:MM:SS) (may also be the |
| | <u>Deployment End Date Time (DD-MMM-YYYY HH:MM:SS)</u> for a previous <u>deployment</u>) |
| | *Camera Active On Arrival |
| | *Camera Damaged |
| | *Card Status (% full) |
| | *# Of Images |
| | *SD Card Replaced |
| | *Remaining Battery (%) |
| | *Batteries Replaced |
| | New <u>Camera ID</u> |
| | New <u>Camera Make</u> |
| | New <u>Camera Model</u> |
| | New <u>Camera Serial Number</u> |
| | New SD Card ID |
| | Bait/lure Type |
| | *Deployment Area Photos Taken |
| | *Deployment Area Photos Numbers |
| | • * <u>Test Image Taken</u> |
| | *Walktest Complete |

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| Task | Instructions |
|------|--|
| | *Walktest Distance (m) |
| | • *Walktest Height (m) |
| | *Camera Active On Departure |
| | *Camera Location Comments |
| | *Service/Retrieval Comments |
| | Additional information may be collected as needed |
| | Data can be input into a tablet interface or recorded on a paper <u>Camera Service/Retrieval Field Datasheet</u> . |

Notes: An asterisk (*) indicates the field is optional and not required by the AB Metadata Standards (RCSC, 2023) and <u>B.C. Metadata Standards (RISC, 2019).</u>