# Building riscv-openocd

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#### 1 About

OpenOCD is a free and open-source software distributed under the GPL-2.0 license. It provides on-chip programming and debugging support with a layered architecture of JTAG interface and TAP support.

A fork with RISC-V support has been developped and is available on GitHub at https://github.com/riscv/riscv-openocd

This guide aims to provide help about building OpenOCD for various plateforms. More details, guides and manuals about OpenOCD can be found in the repository's README.md

## 2 Dependencies

### 2.1 Compiler

GCC or Clang is currently required to build OpenOCD. On a Linux workstation, GCC should be available by default or in the distribution's repositories.

For other architectures, cross-compiling is possible. Linaro provides pre-built GNU cross-toolchain binary archives at https://releases.linaro.org/components/toolchain/binaries/

The uname command can help finding the architecture of a target:

\$ uname —m

### 2.2 Tools

Other tools are also needed:

- make
- libtool
- pkg-config  $\geq 0.23$
- autoconf  $\geq 2.64$
- automake  $\geq 1.14$
- texinfo

On Ubuntu, ensure that everything is installed with:

\$ sudo apt install make libtool pkg-config autoconf automake texinfo

#### 2.3 Libraries

Depending on the compilation options, some libraries might be needed.

#### 2.3.1 libusb

If the target is the workstation (i.e. not cross-compiling), it is likely that libusb is already installed or included in the distribution's repositories. For Ubuntu:

```
$ sudo apt install libusb -1.0-0-dev
```

To cross-compile, or to use the latest version from source:

- Obtain the source. The latest tarball is available on https://libusb.info
- Extract the source

```
$ tar -zxvf libusb-X.X.XX.tar.bz2
```

- Make a build directory somewhere, inside the libusb root directory for example
  - \$ cd libusb-X.X.XX
  - \$ mkdir build
- If cross-compiling, set the compiler. Ensure that the given compiler is in the \$PATH
  - \$ export CC=arm-linux-gnueabihf-gcc
- Use the *configure* script. You can see all the options with:
  - \$ ./configure —help
- For example, these options set the install directory, set the host for cross-compiling and disable udev:
  - $\$  ./configure —prefix=/home/abouvier/Documents/libusb -1.0.22/ build —execprefix=/home/abouvier/Documents/libusb -1.0.22/ build —host=arm-linux-gnueabihf —disable-udev
- Compile and install files
  - \$ make
  - \$ make install
- The produced library files are in the build directory. They needed to be added to the compiler to be used.

#### 2.3.2 libftdi

If the target is the workstation (i.e. not cross-compiling), it is likely that libusb is already installed or included in the distribution's repositories. For Ubuntu:

```
$ sudo apt install libftdi1-dev
```

To cross-compile or to get the latest version, the source is available at https://www.intra2net.com/en/developer/libftdi/download.php

- Some tools are needed. On Ubuntu:
  - \$ sudo apt install build-essential cmake
- Libusb is also required.
- Download and extract the tarball
- Inside the directory, make a build directory
  - \$ cd libftdiX -X.X
  - \$ mkdir build
  - \$ cd build
- Create a cmake toolchain file and fill it with the target informations

toolchain-arm-linux-gnueabihf.cmake

```
SET(CMAKE\_SYSTEM\_NAME\_arm-linux-gnueabihf)\\SET(CMAKE\_C\_COMPILER\_arm-linux-gnueabihf-gcc)\\SET(CMAKE\_CXX\_COMPILER\_arm-linux-gnueabihf-g++)\\SET(LIBUSB\_LIBRARIES\_/home/abouvier/Documents/gcc-linaro-7.4.1-2019.02-x86\_64\_arm-linux-gnueabihf/lib/libusb-1.0.so.0)\\SET(LIBUSB\_INCLUDE\_DIR\_/home/abouvier/Documents/gcc-linaro-7.4.1-2019.02-x86\_64\_arm-linux-gnueabihf/include/libusb-1.0)
```

- Make sure the compilers are in the \$PATH and use cmake. The install directory can be controlled with the prefix options.
  - \$ cmake -DCMAKE\_TOOLCHAIN\_FILE='/home/abouvier/Workspace/toolchain-arm-linux -gnueabihf.cmake' -DCMAKE\_INSTALL\_PREFIX=\$(pwd) -DLIBFTDI\_LIBRARY\_DIRS=\$(pwd) ...
- Compile and install the files
  - \$ make
  - \$ make install
- The produced library files are in the build directory. They needed to be added to the compiler to be used.

# 3 OpenOCD

• Download the sources

```
$ git clone https://github.com/riscv/riscv-openocd
$ cd riscv-openocd
```

- Prepare a build directory
  - \$ mkdir build
- If the aim is to use OpenOCD for PULP applications, a small patch is required. Find src/target/riscv/riscv.h and modify the following definition :

```
-#define RISCV_MAX_HARTS 32
+#define RISCV_MAX_HARTS 1024
```

- If cross-compiling, set the compiler. Ensure that the given compiler is in the \$PATH
  - \$ export CC=arm-linux-gnueabihf-gcc
- Launch the bbotstrap script
  - \$ ./bootstrap
- Review the possible configuration options
  - \$ ./configure --help
- In particular, -enable-sysfsgpio and -enable-remote-bitbang must be added to use the corresponding features.
- The -host= option must be provided to cross-compile
- The -prefix= and -exec-prefix= options control the installation directory
- Use configure with all the chosen options
  - \$ ./configure enable-sysfsgpio host=arm-linux-gnueabihf prefix=/home/abouvier/Documents/riscv-openocd/build exec-prefix=/home/abouvier/Documents/riscv-openocd/build

- Some problems may be encountered with an aarch64-linux-gnu host. Please review https://github.com/riscv/riscv-openocd/issues/17
- Compile and install files
  - \$ make
  - \$ make install

A single openocd binary should be available in build