## **Linear Transformations**

So far we've been treating the matrix equation

$$A\mathbf{x} = \mathbf{b}$$

as simply another way of writing the vector equation

$$x_1\mathbf{a_1} + \dots + x_n\mathbf{a_n} = \mathbf{b}.$$

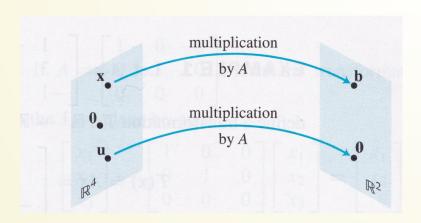
However, we'll now think of the matrix equation in a new way: we will think of A as "acting on" the vector  $\mathbf{x}$  to form a new vector  $\mathbf{b}$ .

For example, let's let 
$$A = \begin{bmatrix} 4 & -3 & 1 & 3 \\ 2 & 0 & 5 & 1 \end{bmatrix}$$
. Then we find:

$$A \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \end{bmatrix} \quad \text{and} \quad A \begin{bmatrix} 1 \\ 4 \\ -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

In other words, if 
$$\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$
 and  $\mathbf{b} = \begin{bmatrix} 5 \\ 8 \end{bmatrix}$ , then  $A$  transforms  $\mathbf{x}$  into  $\mathbf{b}$ .

Likewise, if 
$$\mathbf{u} = \begin{bmatrix} 1 \\ 4 \\ -1 \\ 3 \end{bmatrix}$$
, then  $A$  transforms  $\mathbf{u}$  into the  $\mathbf{0}$  vector.



This gives a **new** way of thinking about solving  $A\mathbf{x} = \mathbf{b}$ . We are "searching" for the vectors  $\mathbf{x}$  in  $\mathbb{R}^4$  that are transformed into  $\mathbf{b}$  in  $\mathbb{R}^2$  under the "action" of A.

We have moved out of the familiar world of functions of one variable: we are now thinking about functions that transform a vector into a vector.

Or, put another way, functions that transform multiple variables into multiple variables.

## Some terminology:

A transformation (or function or mapping) T from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  is a rule that assigns to each vector  $\mathbf{x}$  in  $\mathbb{R}^n$  a vector  $T(\mathbf{x})$  in  $\mathbb{R}^m$ .

The set  $\mathbb{R}^n$  is called the **domain** of T, and  $\mathbb{R}^m$  is called the **codomain** of T.

The notation:

$$T:\mathbb{R}^n\to\mathbb{R}^m$$

indicates that the domain of T is  $\mathbb{R}^n$  and the codomain is  $\mathbb{R}^m$ .

For **x** in  $\mathbb{R}^n$ , the vector  $T(\mathbf{x})$  is called the **image** of **x** (under T). The set of all images  $T(\mathbf{x})$  is called the **range** of T.

