# Seismic rock physics

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Rock physics studies the relation between physical and elastic properties of rocks and is the basis of quantitative seismic interpretation. It has arguably given exploration geophysicists a solid quantitative basis to their interpretation of seismic data.It can be tackled at different scales of investigation by people with various backgrounds — from geophysicists to civil engineers, from mathematicians to petrophysicists.

In this tutorial and the Python code in the accompanying Jupyter Notebook (https://github.com/seg/tutorials), I offer a practical introduction to rock physics, showing how to code simple models and apply them to analyse well log data and predict their seismic responses. Here's the workflow:

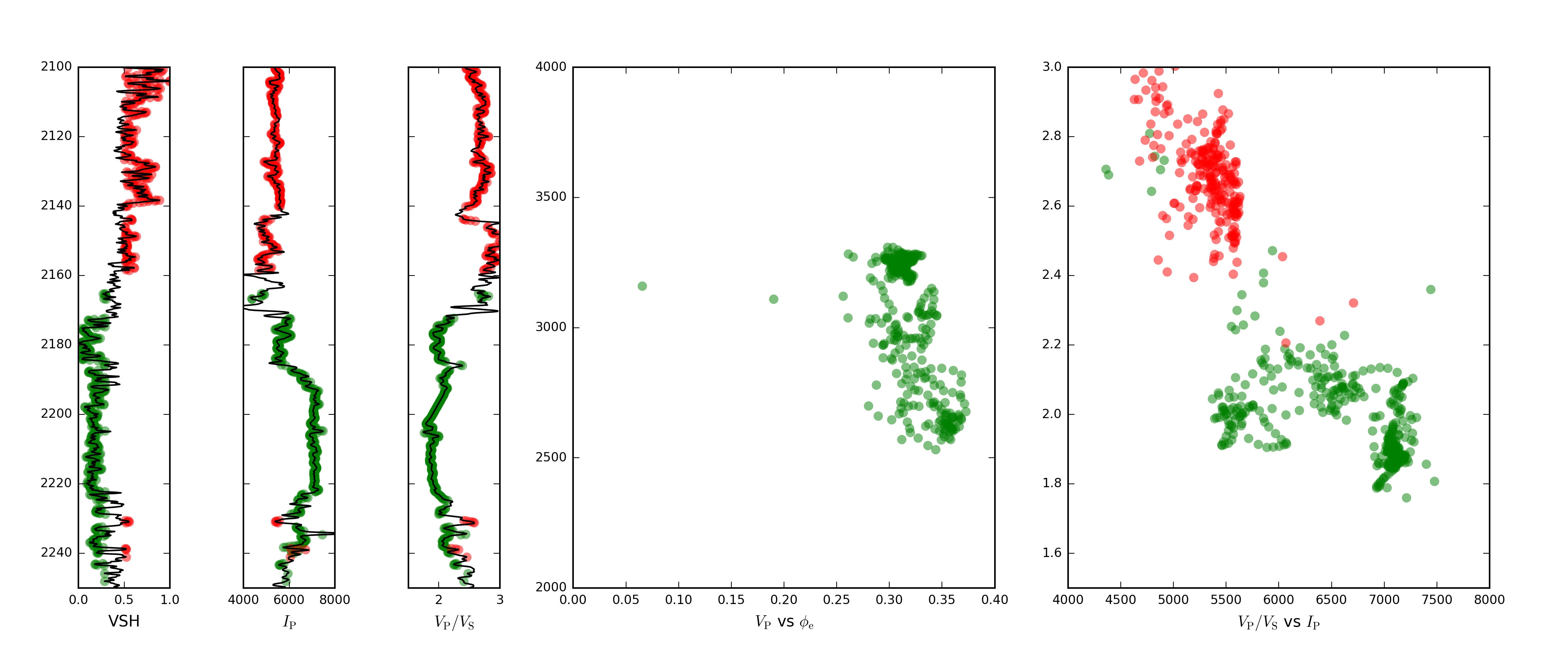
1. Data exploration — inspecting what we have.
2. Rock physics modeling — two simple models.
3. Rock physics templates — modeling more parameters.
4. Seismic response modeling — predicting seismic.

The well data used in this tutorial is one of the test datasets available on the *Quantitative Seismic Interpretation* book website (Avseth et al. 2005).

## Data exploration

We get our bearings by plotting the logs together. Figure 1 shows VSH (shale volume) and (water saturation) logs in the first track, (P-wave or acoustic impedance) in the second, and (the ratio of P-wave to S-wave velocities) in the third track. I highlight sands in yellow and shales in red. Next to these three tracks are crossplots of against (effective porosity), and of against .

In the – crossplot I have decided to avoid plotting shales since effective porosity is effectively zero for pure shales so this plot will not help in the analysis of non-reservoir rocks.

 **Figure 1.** (a) VSH, (in units of ), and for the interval 2100 m to 2250 m. (b) vs . (c) vs .

## Rock physics modeling

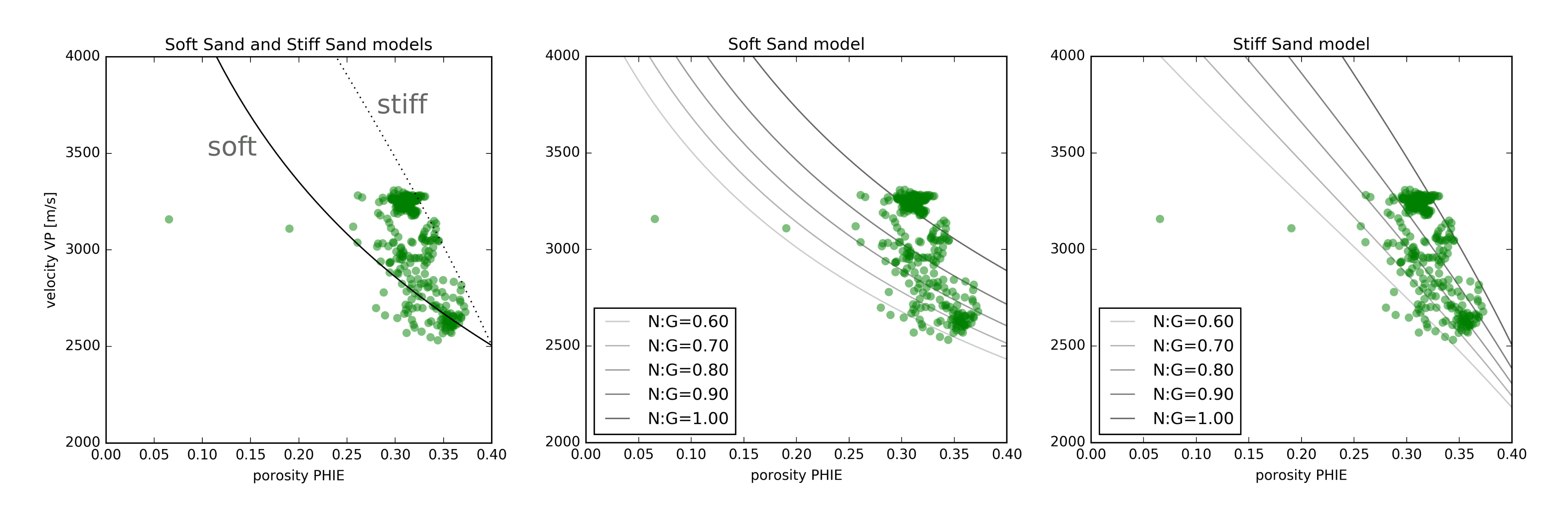
Rock physics models output dry-rock frame moduli: bulk modulus and shear modulus . These moduli represent the resistance of the rock's dry frame to normal and tangential stress respectively. They are used together with Gassmann's equation to calculate the saturated rock moduli ( and ) which are, together with density, the building blocks for P-wave and S-wave velocities, and :

The product of velocity by density is called acoustic impedance. Impedance contrasts are ultimately what generate seismic reflections; this is why rock physics, by linking rock and fluid properties to velocities, allows us to understand and explain seismic reflections.

In many cases, we know the velocity and density of a non-reservoir sandstone, and would like to know how these quantities will change if the porosity were only higher, the net:gross more favourable, or the fluid more valuable. We need a model!

In the notebook, I introduce two simple but useful models, the Soft Sand model and the Stiff Sand model. The notebook provides the theory and the code to help you understand these models. Here I only show what they produce.

We'd like to know how well our data fit the models we make. The easiest way is to look at them both in one plot. Figure 2(a) shows the same interval as before — the reservoir sand from 2100 m to 2250 m — with the Soft Sand model and the Stiff Sand model superimposed. At first sight, both models may offer a good starting point to investigate these sands.

 **Figure 2.** vs porosity for the reservoir interval shown in Figure 1. (a) The Soft Sand model is shown as a black line; the Stiff Sand model is a discontinuous line. (b) The Soft Sand model and (c) the Stiff Sand model with varying net:gross.

The sands are not hydrocarbon-bearing so I can dismiss fluid effects and start leveraging the rock physics model by displaying how mineralogy affects the velocities. To do that, I will simplify the problem assuming variations in net:gross. When net:gross is 1, then the mineral moduli will be equal to those of quartz, when it is lower than 1 than I will use composite mineral moduli given by the Voigt–Reuss–Hill average of quartz and a generic shale. So to compute the bulk modulus given the constituent volume fractions *f*:

Now let's put it all together and create show how the models change for different mineralogies. There's just one catch: to have the models spread out to cover the entire range of the well data, I had to code them with different parameters. In the notebook, these are the lines that call the two models:

Kdry, MUdry = softsand(K0, MU0, phi, phic=0.5, Cn=12, P=45)  
Kdry, MUdry = stiffsand(K0, MU0, phi, phic=0.4, Cn=8, P=45)

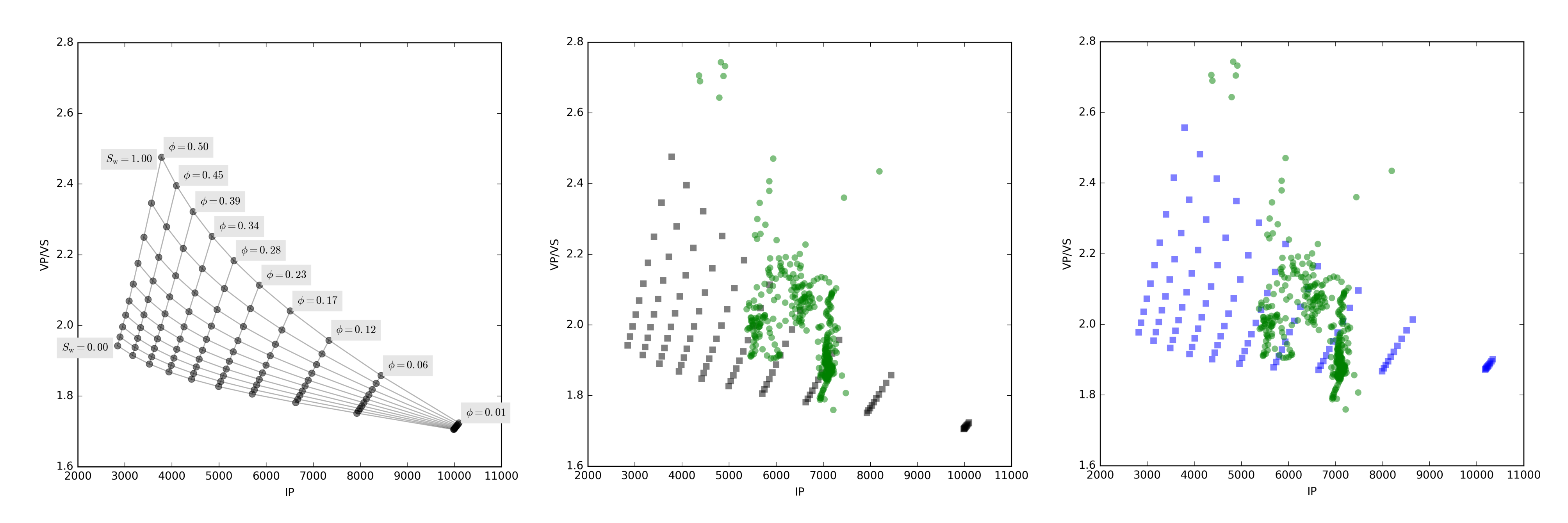
The Soft Sand model uses higher critical porosity and coordination number than the Stiff Sand model, which means that the reservoir sands can be described by either a stiffer 'soft' sand or a softer 'stiff' sand (the coordination number Cn suggests a closer packing of the individual grains that make up our sand, which in turn means a more compact and harder material).

Figures 2(b) and 2(c) show the result of plotting the data against the two models. So far, both models fit the datapoints. It is up to the interpreter to decide which model is more appropriate. Adding the effect of hydrocarbons, and changing other parameters — especially porosity — might help us figure it out.

## Rock physics templates

The set of models for varying degrees of net:gross shown above are a basic example of rock physics templates (RPTs), as promoted by Avseth et al. (2005). From that starting point, it is fairly easy to build a function to create RPTs which show not only variations in porosity and mineralogy but also fluid content.

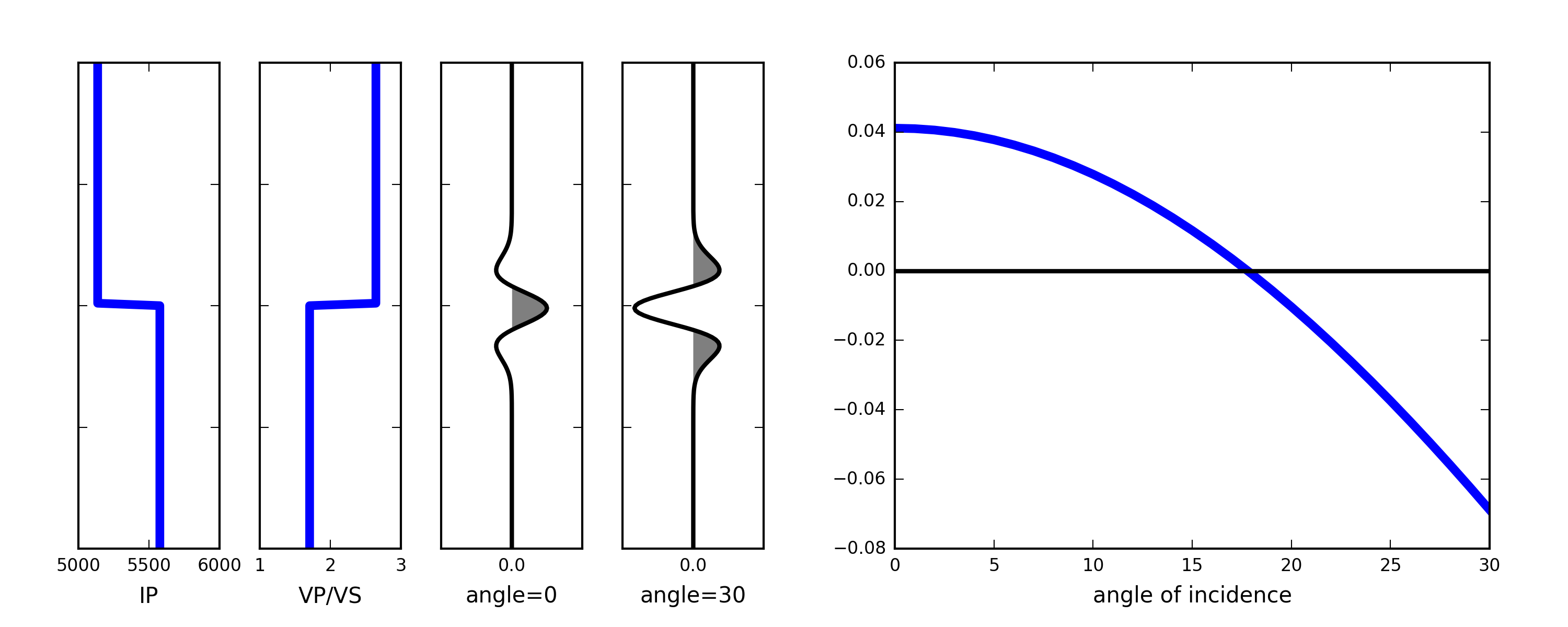
In the notebook, I show how to combine the functions to compute and for the Soft Sand and Stiff Sand models with the velocities given by Gassmann's equation, to produce arrays of P-wave impedance and that we can study individually — as in Figure 3(a) — or overlay on top of well data as an aid to interpretation — as in Figures 3(b) and 3(c).

 **Figure 3.** Rock physics templates for the Soft Sand model. (a) The template by itself, showing how we expect and to vary with water saturation and porosity . (b) The template (gray) plotted with the data (green). (c) The template (blue) has been recalculated with new elastic moduli for the 'shale'.

We can go further, for example one can check the validity of the elastic moduli assigned to the second mineral (the one I have referred to as 'shale') by varying them and displaying different RPTs. In Figure 3(c) I have changed the bulk and shear modulus values to get a better fit against the data. In the absence of other information, this is perfectly reasonable — and valuable — knowledge to add to the exploration puzzle.

## Seismic response modeling

Once I have a good grasp of the RPM and the way it reacts to different input parameters, I can start using it to explore seismic data too. It is very easy to use the velocities and densities output by our rock physics model to build simple two-layer models and analyse seismic and AVO signatures of the modeled top reservoir. One example is shown in Figure 4; the idea is fully developed in the accompanying Jupyter Notebook.

 **Figure 4.** The expected seismic response of a gas-saturated sand with 15% porosity. From left to right: acoustic impedance, , the response at 0 degrees and 30 degrees of offset, and the amplitude-vs-angle curve.

## Conclusions

I have shown here how I implement rock physics models and templates using standard Python libraries. The functions introduced here can be extended fairly easily for additional rock physics models, some of which are shown in the accompanying notebook (https://github.com/seg/tutorials). The workflow can be used to study real datasets, analyse the elastic behaviour of individual reservoirs, and build a collection of seismic and AVO signatures to be associated to particular combinations of caprocks and reservoirs.

## References

Avseth, P., Mukerji, T. & Mavko, G. (2005). *Quantitative Seismic Interpretation.* Cambridge University Press. Data repository: http://ageo.co/QSIdata