**A Report for Assignment 1 of Machine Learning (UCS611)**

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**OBJECTIVES -**

1. Build an ML model for predicting the number of total infections in India till 31st of July 2020.
2. Build an ML model for predicting the number of deaths in India till 31st of July 2020.
3. Build an ML model and predict recovery rate and death rate in India for the period 15th June to 31st of July.

**DATA USED –**

The data used in the model is fetched from official government API namely <https://api.covid19india.org/data.json>

import requests

api = 'https://api.covid19india.org/data.json'

data = requests.get(api)

with open('data.json', 'wb') as f:

    f.write(data.content)

time\_series\_data = data.json()['cases\_time\_series']

print(time\_series\_data)

This code fetches the data from API in JSON format and reads it into Python Dictionary. From this we get data in the following format -

{

    "cases\_time\_series": [

        {

            "dailyconfirmed": "1",

            "dailydeceased": "0",

            "dailyrecovered": "0",

            "date": "30 January ",

            "totalconfirmed": "1",

            "totaldeceased": "0",

            "totalrecovered": "0"

        },

        {

            "dailyconfirmed": "0",

            "dailydeceased": "0",

            "dailyrecovered": "0",

            "date": "31 January ",

            "totalconfirmed": "1",

            "totaldeceased": "0",

            "totalrecovered": "0"

        },

        .

        .

        .

    ]

}

The following code converts the above depicted data to a more usable format -

def transpose(*list\_of\_dict*):

    dict\_of\_list = {}

    for key in list\_of\_dict[0]:

        if key == 'date':

            dict\_of\_list[key] = [dic[key] for dic in list\_of\_dict]

        else:

            dict\_of\_list[key] = [int(dic[key]) for dic in list\_of\_dict]

    return dict\_of\_list

time\_series\_list = transpose(time\_series\_data)

print(time\_series\_list)

def get\_data():

    return time\_series\_list

Output after data conversion –

{

    "dailyconfirmed": [. . . , 8, 10, 10, 11, 10, 14, 20, 25, 27, 58,

        78, 69, 94, 74, 86, 73, 153, 136, 120, 187, 309, . . .],

    "dailydeceased": [. . . , 0, 1, 0, 0, 1, 0, 1, 0, 0, 3, 2, 1, 1,

        5, 3, 5, 3, 14, 6, 6, 16, 14, 13, 22, 16, 27, 20, . . .],

    "dailyrecovered": [. . . , 3, 1, 1, 0, 5, 3, 0, 0, 2, 15, 3, 7,

        25, 10, 17, 35, 13, 19, 22, 39, 56, 43, 65, 75, 96, . . .],

    "date": [. . . , "13 February ", "14 February ", "15 February ",

        "16 February ", "17 February ", "18 February ", . . .],

    "totalconfirmed": [. . . , 5, 6, 28, 30, 31, 34, 39, 48, 63, 71,

        81, 91, 102, 112, 126, 146, 171, 198, 256, 334, . . .],

    "totaldeceased": [. . . , 2, 2, 3, 3, 4, 4, 4, 7, 9, 10, 11, 16,

        19, 24, 27, 41, 47, 53, 69, 83, 96, 118, 134, . . .],

    "totalrecovered": [. . . , 5, 15, 20, 23, 23, 23, 25, 40, 43, 50,

        75, 85, 102, 137, 150, 169, 191, 230, 286, 329, . . .]

}

Above given codes will be referred as dataloader.py after this.

**MODELS USED –**

MLPs (Multi Layered Perceptron(s)) of different sizes are used for prediction of the given time series data. There are five different sizes used.

*The MLPs (aka Vanilla NNs) are completely implemented from scratch without using any ML / DL Library.*

Each model is run for 400 Epochs spitting out a graph every 100 Epochs. So in total there are 80 (4 graphs per model x 5 models per task x 4 tasks) graphs. So only graphs depicting something useful or best performing are shown in the report.

All graphs can be seen in the zip file in high resolution.

For training the model the data is transformed into X (input), Y (output) pairs. X being a 1 x 10 sized vector and Y being a 1 x 1 vector. X is 10 consecutive days of input data and Y is the 1 following day output data.

**Following code does the stated transformation –**

import data\_loader as dtl

import numpy as np

def process\_data(*raw\_data*):

    max\_case = max(raw\_data)

    max\_case += max\_case / 3

    raw\_data = [case / max\_case for case in raw\_data]

    train\_data = [(np.array(raw\_data[i-11:i-1]).reshape(1, 10), np.array(raw\_data[i]).reshape(1, 1)) for i in range(11, len(raw\_data))]

    return train\_data, max\_case

data\_loader = dtl.get\_data()

raw\_train\_data = data\_loader['totalconfirmed']

train\_data, max\_case = process\_data(raw\_train\_data)

print(train\_data)

**Output Format –**

A list of (array (1 x 10), array (1 x 1)) tuples denoting X and Y respectively.

[

    (array([[3.93446751e-06, 3.93446751e-06, 3.93446751e-06, 7.86893502e-06,

    1.18034025e-05, 1.18034025e-05, 1.18034025e-05, 1.18034025e-05,

    1.18034025e-05, 1.18034025e-05]]), array([[1.18034025e-05]])),

    (array([[3.93446751e-06, 3.93446751e-06, 7.86893502e-06, 1.18034025e-05,

    1.18034025e-05, 1.18034025e-05, 1.18034025e-05, 1.18034025e-05,

    1.18034025e-05, 1.18034025e-05]]), array([[1.18034025e-05]])),

    .

    .

    .

]

Now we have our training data completely ready. The values were normalised by dividing the data by (max(data) \* 4 / 3) effectively giving values between 0 (min) to 0.75 (max).

**CODE –**

MLPs code is written from scratch in python using numpy & matplotlib is used to draw graphs.

It is as follows –

1. Importing all the required libraries for the MLP –

import numpy as np

import random

import math

import time

import os

import matplotlib.pyplot as plt

from matplotlib.ticker import MultipleLocator

1. The Layer class which makes a single layer of the perceptron. It takes Input Size, Output Size and Learning Rate as arguments and implements all the basic functions required by the model to train.

def sigmoid(*z*):

    return 1.0/(1.0+np.exp(-z))

def sigmoid\_prime(*z*):

    return sigmoid(z)\*(1-sigmoid(z))

class layer:

    def \_\_init\_\_(*self*, *inp\_size*, *out\_size*, *ETA*):

        self.ETA = ETA

        self.b = np.random.randn(1, out\_size)

        self.w = np.random.randn(inp\_size, out\_size)

        self.bgrad = 0.0

        self.wgrad = 0.0

    def forward(*self*, *inp*):

        self.x = inp

        self.y = np.dot(self.x, self.w) + self.b

        self.a = sigmoid(self.y)

        return self.a

    def compgrad(*self*, *a\_grad*):

        y\_grad = sigmoid\_prime(self.y) \* a\_grad

        self.bgrad += y\_grad

        self.wgrad += np.dot(self.x.T, y\_grad)

        return np.dot(y\_grad, self.w.T)

    def backprop(*self*):

        self.w -= self.ETA \* self.wgrad

        self.b -= self.ETA \* self.bgrad

        self.bgrad = 0

        self.wgrad = 0

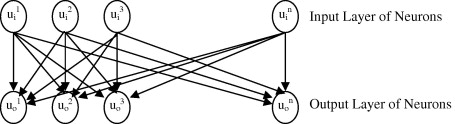
The ‘\_\_init\_\_’ function takes 3 arguments ‘inp\_size’, ‘out\_size’ & ‘ETA’ and creates a bias vector ‘b’ and weight vector ‘w’ of size (1 x ‘out\_size’) and (‘inp\_size’ x ‘out\_size’) respectively. Both of these are randomly initialised using normal distribution. Two variables ‘bgrad’ and ‘wgrad’ are also initialised which will be used later to accumulate the gradient.

The ‘forward’ function takes a ‘inp’ vector of size (1, ‘inp\_size) and stores it in ‘x’. It then computes sigmoid(wx + b) and returns it as the output ‘a’.

The ‘compgrad’ function takes an argument ‘a\_grad’ which is gradient vector of the loss function on ‘a’ with respect to loss . It than computes ‘y\_grad’ which is sigmoid\_prime(‘y’) \* ‘a\_gard’ . It than accumulates ‘bgrad’ which is same as ‘ygrad’. Than it accumulates ‘wgrad’ which is ‘x’ dot ‘y\_grad’ . Finally, it returns ‘xgrad’ which is ‘w’ dot ‘y\_grad’ and is to be used by previous layer as its ‘a\_grad’.

Note that actual weights weren’t updated in this function. They are only accumulated in two class variables. This will be useful in accumulating the gradient for a ‘batch’.

Finally, the ‘backprop’ function. It takes no argument and just uses internally stored gradients (‘wgrad’ and ‘bgrad’) to update weights ‘w’ and biases ‘b’. It subtracts learning rate \* gradient of vector from the vector (‘w’ -= ‘ETA’ \* ‘wgrad’ and ‘b’ -= ‘ETA’ \* ‘bgrad’) and sets ‘wgrad’ and ‘bgrad’ to 0.0.



1. The Model class makes it easier to define and train a multi-layered network. As we can see the above class only makes a 2-layered network with no hidden layer. We can make hidden layers by stacking input output layers. Doing the manually for every model will not be very convenient. That’s what the model class does.

class model:

    def \_\_init\_\_(*self*, *net\_size*, *ETA*):

        self.layers = []

        for i in range(len(net\_size) - 1):

            self.layers.append(layer(net\_size[i], net\_size[i + 1], ETA))

    def forward(*self*, *x*):

        for l in self.layers:

            x = l.forward(x)

        return x

    def compgrad(*self*, *a\_grad*):

        for l in reversed(self.layers):

            a\_grad = l.compgrad(a\_grad)

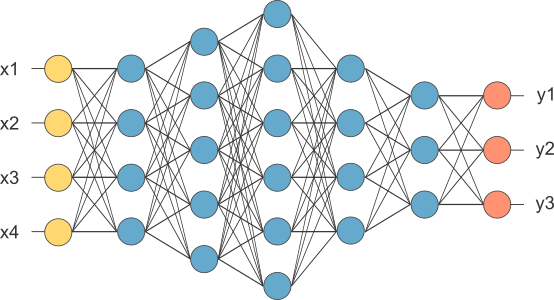
    def backprop(*self*):

        for l in reversed(self.layers):

            l.backprop()

It takes input a list called ‘net\_size’ and learning rate ‘ETA’. The input list contains a list of integers defining the size of layers in the network.

For example list[4, 4, 5, 6, 4, 3, 3] will make the following network-



All the blue neurons are hidden layers and yellow layer must be equal to input size and orange layer denotes the output size of our data.

1. The ‘train’ function takes input the training data and batch size called ‘data’ and ‘BATCH\_SIZE’ respectively.

def train(*data*, *BATCH\_SIZE*= 10):

    data\_size = len(data)

*# random.shuffle(data)*

    batches = (data[i : i + BATCH\_SIZE] for i in range(0, data\_size, BATCH\_SIZE))

    loss = 0.0

    for batch in batches:

        for x, y in batch:

            a = network.forward(x)

            loss += (a - y) \*\* 2 / BATCH\_SIZE

            a\_grad = 2 \* (a - y) / BATCH\_SIZE

            network.compgrad(a\_grad)

        network.backprop()

    return np.sum(loss) \* BATCH\_SIZE / data\_size

Train function divides the data into mini batches of size ‘BATCH\_SIZE’ and the for each batch it updates the model using ‘backprop’ function. The inner loop for each batch goes through every single training example accumulates the gradients for the batch using ‘compgrad’ function.

1. The test function called ‘predict’ takes quite a few variables.

def int\_round(*n*, *p*=0):

    return int(round(n / 10\*\*int(math.log10(n)), p) \* 10\*\*int(math.log10(n)))

def predict(*data*, *line*='-', *title*='', *file\_path*='./', *future*=10):

    fig = plt.figure(*figsize*=(13,5))

*fig = plt.figure(figsize=(16,4.5))*

    ax = plt.axes()

    ax.set\_title(title)

    ax.xaxis.set\_major\_locator(MultipleLocator(5))

    ax.xaxis.set\_minor\_locator(MultipleLocator(1))

    ax.yaxis.set\_major\_locator(MultipleLocator(int\_round(max\_case) // 10))

    ax.yaxis.set\_minor\_locator(MultipleLocator(int\_round(max\_case) // 50))

    ax.grid(*which*='major')

    ax.grid(*which*='minor', *alpha*=0.3)

    plt.plot(raw\_train\_data, line)

    size = len(raw\_train\_data)

    out = [network.forward(x).item() for x,\_ in data]

    plt.plot(list(range(11, size)), [c \* max\_case for c in out], line)

    pred = []

    for i in range(future):

        pred.append(network.forward(np.array(out[-10:]).reshape(1, 10)).item())

        out.append(pred[-1])

    plt.plot(list(range(size, size+future)), [c \* max\_case for c in pred], line)

    plt.legend(['Ground Truth', 'Testset Validation', 'Future Prediction'])

    os.makedirs(os.path.dirname(file\_path), *exist\_ok*=True)

    plt.savefig(file\_path, *bbox\_inches*='tight', *dpi*=600)

    plt.close()

It plots a graph using matplotlib. We can see 3 graphs are plotted on same figure in this function. The 3 graphs are 'Ground Truth', 'Testset Validation' and 'Future Prediction'. ‘Ground truth’ is the actual dataset plotted, ‘Testset Validation’ is the models output on training data and ‘Future Prediction’ is the models output on ‘future’ future days. Here future variable controls the number of days to predict. For this model we have use future equal to 30.

1. Finally, the main code which calls and runs all these functions and classes together.

data\_loader = dtl.get\_data()

tasks = list(data\_loader.keys())

tasks.remove('date')

network\_list = [

    [10, 100, 32, 10, 1],

    [10, 100, 100, 1],

    [10, 100, 32, 100, 1],

    [10, 200, 130, 200, 150, 200, 130, 200, 150, 1],

    [10, 80, 100, 100, 120, 140, 140, 120, 100, 100, 25, 1]

]

for task in tasks:

    EPOCHS = 500

    BATCH\_SIZE = 1

    ETA = 0.06

    raw\_train\_data = data\_loader[task]

    train\_data, max\_case = process\_data(raw\_train\_data)

    line = 'x' if task.find('total') != -1 else '-'

    for i in range(len(network\_list)):

        network = model(network\_list[i], ETA)

        network\_str = ' x '.join(map(str, network\_list[i]))

        for itr in range(EPOCHS):

            if itr % 100 == 0:

                title = f'Task: {task}    Model: {network\_str}    Epochs: {itr}'

                file\_path = f'./graphs/{task}/{i+1}/MLP\_predction{itr}.png'

                predict(train\_data, *line*=line, *title*=title, *file\_path*=file\_path, *future*=30)

            loss = train(train\_data, BATCH\_SIZE)

            print(f'Loss: {loss}\tTask: {task}\tModel: {i+1}\tEpoch: {itr}')

First the ‘data\_loader’ get all the data from the data\_loader.py.

Then ‘tasks’ extract the keys from the dictionary and removes the ‘date’ key.

‘tasks’ now have the following keys [‘dailyconfirmed’, ’dailydeceased’, ‘dailyrecovered’, ‘totalconfirmed’, ‘totaldeceased’, ‘totalrecovered’]. This is from the data provided by the government. This was explained before in the document in data\_loader.py. The data with ‘daily’ in key corresponds to its rate (per day) and the data with ‘total’ in key corresponds to total cumulative infections till that date.

Network list defines the sizes of the models used, these are –

10 x 100 x 32 x 10 x 1

10 x 100 x 100 x 1

10 x 100 x 32 x 100 x 1

10 x 200 x 130 x 200 x 150 x 200 x 130 x 200 x 150 x 1

10 x 80 x 100 x 100 x 120 x 140 x 140 x 120 x 100 x 100 x 25 x 1

Then a loop runs for all the 6 tasks taking 1 of them as training data.

Inside the loop we have variables defining the epochs = 500, batch size = 1, learning rate ‘ETA’ = 0.06.

‘raw\_train\_data’ gets the data from ‘data\_loader’ in time-series list format.

‘train\_data’, ‘max\_case’ gets data in list of (input, output) tuples where input and output are numpy arrays of size (1, 10) and (1, 1) respectively. This was also explained above in the document.

Then I set the line variable which controls the design of line on the graph.

Then a loop runs for ‘network\_list’ to choose a model and fit the given tasks on it.

Inside it is the usual loop for ‘EPOCHS’ and calls to ‘train’ and ‘predict’ functions and a few variables to set title and save directory of the graphs.

**RESULTING GRAPHS –**

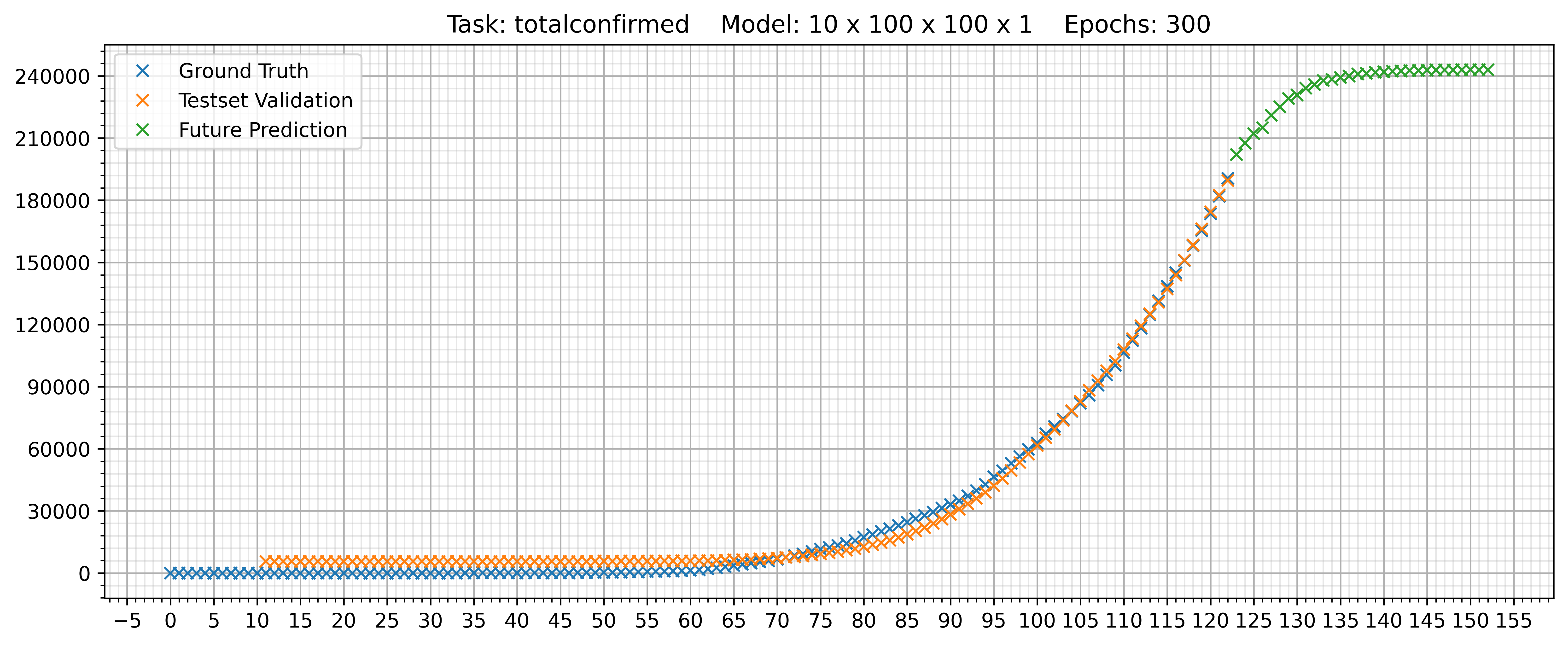
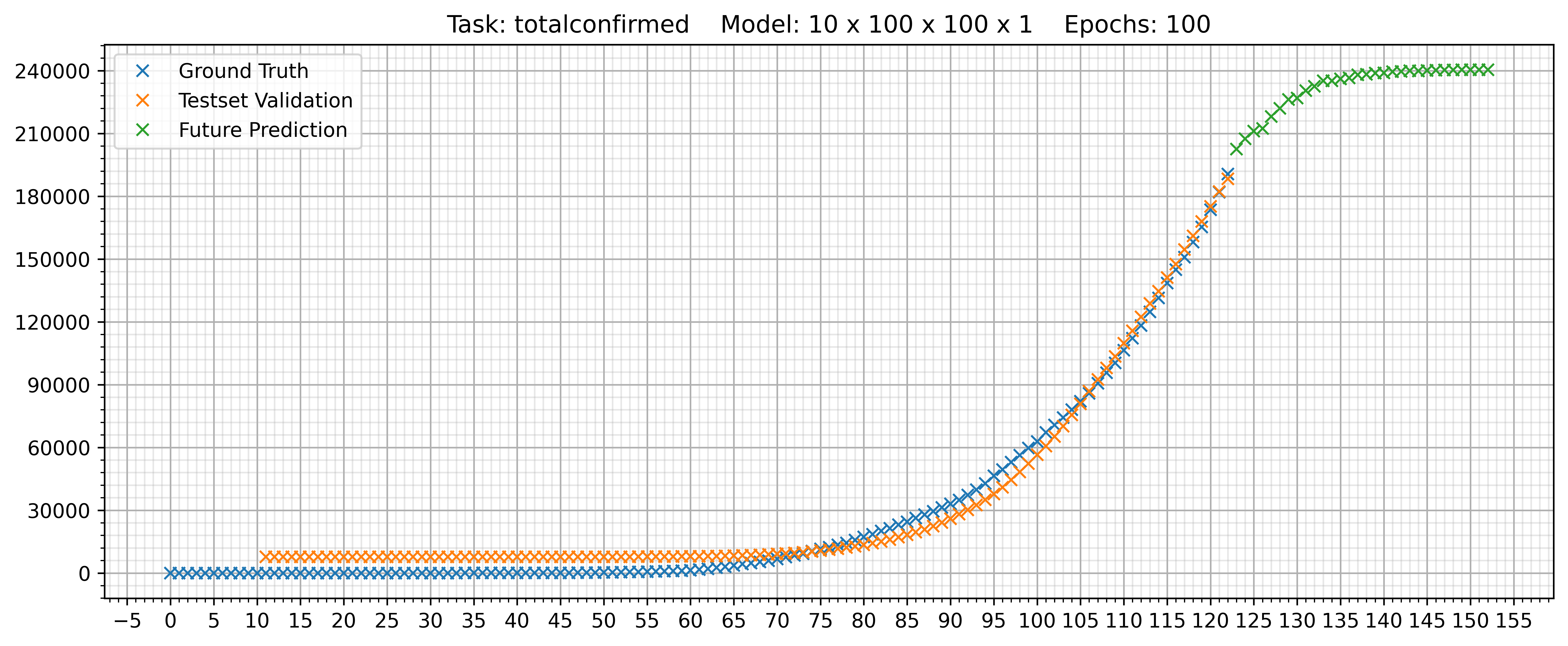
Following shown are some of the graphs which showed a good predict. Other graphs can be seen in the zip file in high res.

The first 3 models defined in the code are shallow models and the last two are deep models.

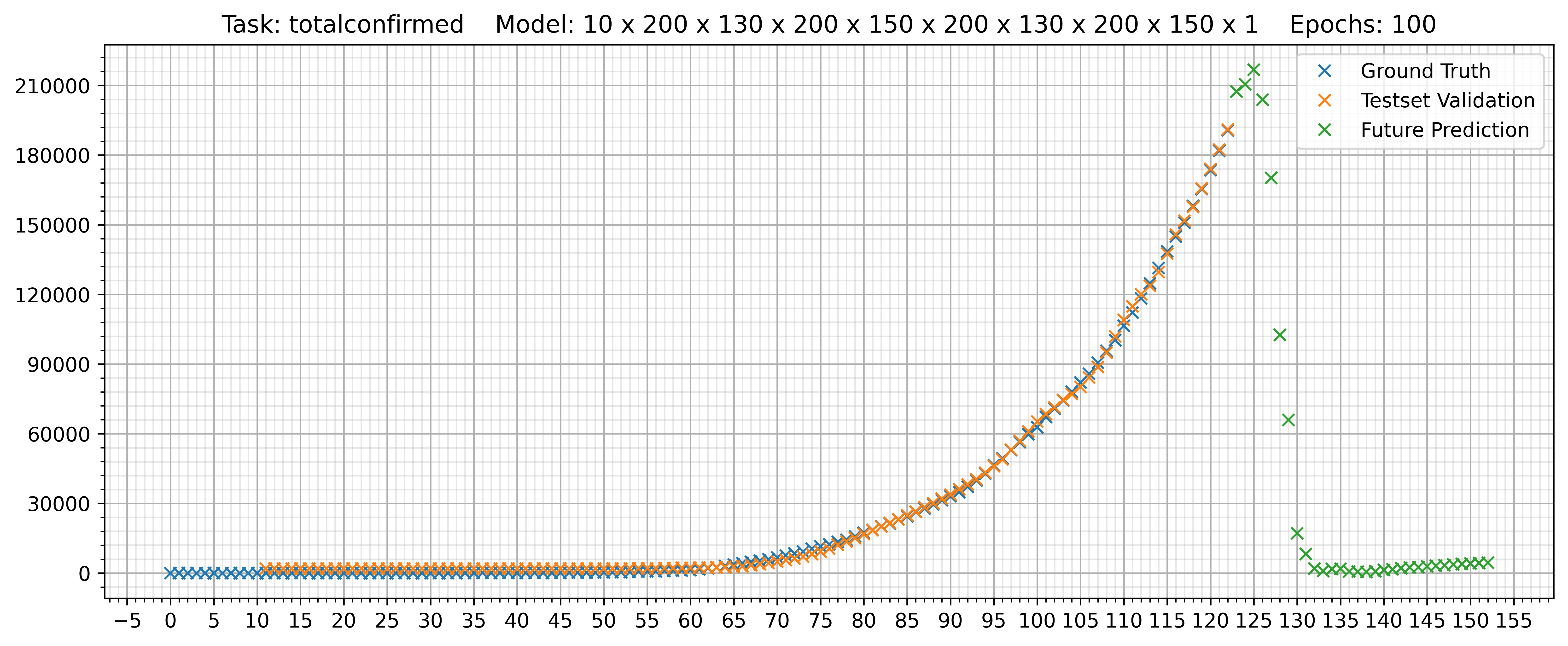
Generally, the shallow models performed well on the cumulative data (as it is smooth) while the deep models performed well on the daily data (rate per day) as the data changes frequently.

Deep models failed miserably on the cumulative data as the just over-fitted the training data predicting random values for future.

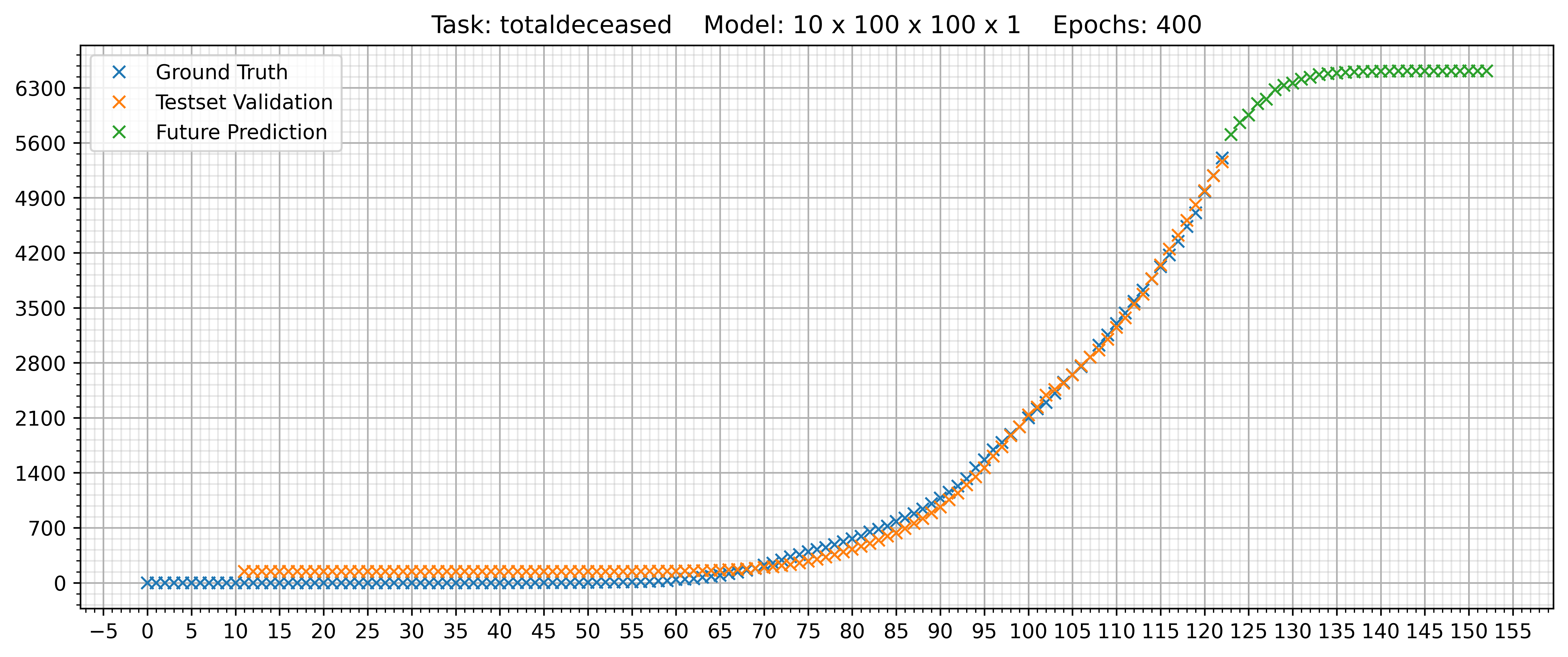
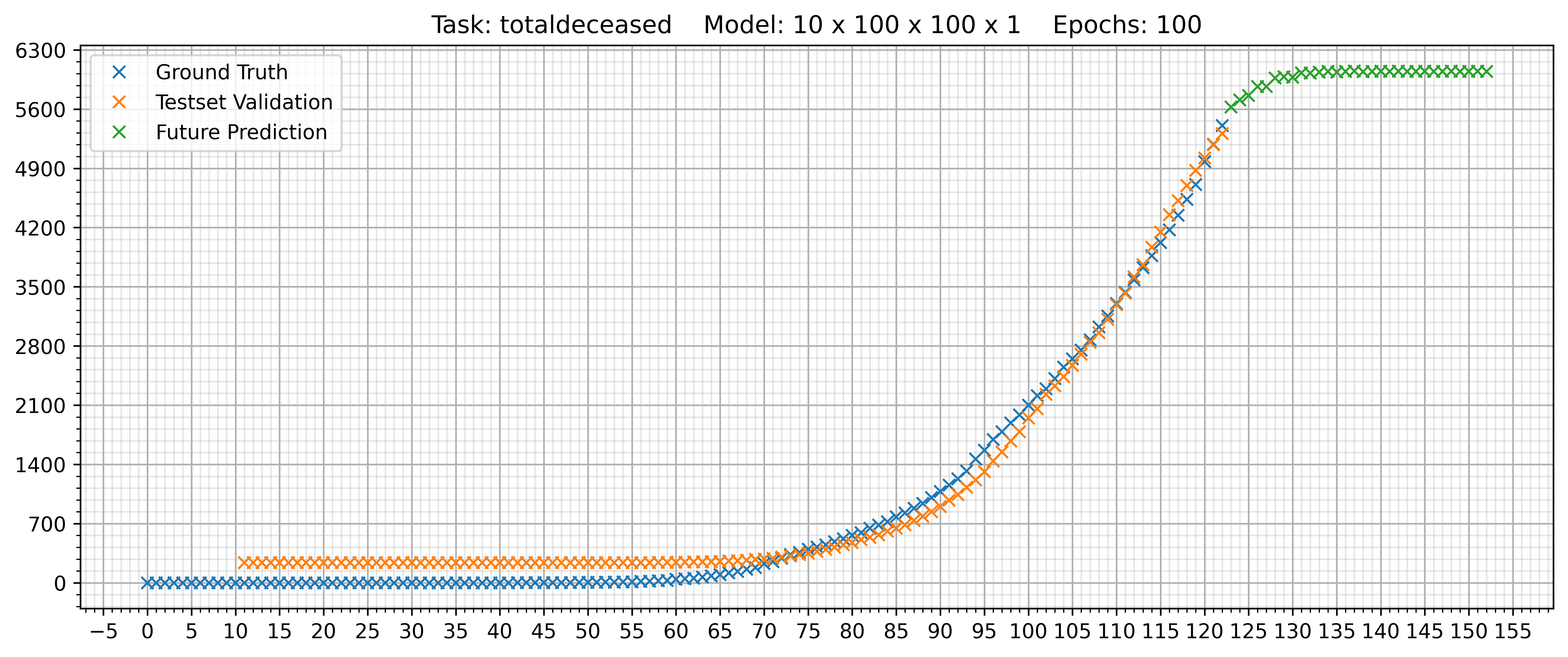
**Graphs of ML model for predicting the number of total infections in India till 31st of July 2020 -**



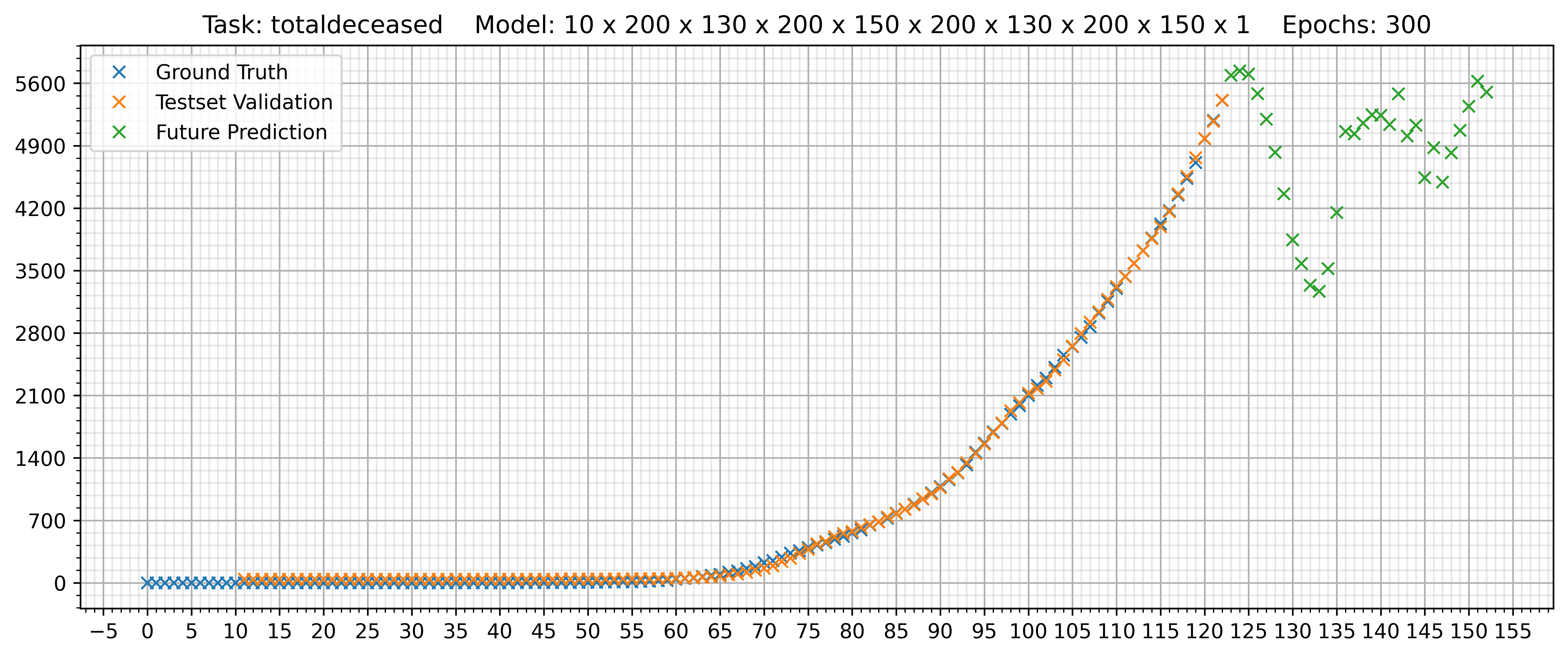
Failed deep model -



**Graphs of ML model for predicting the number of deaths in India till 31st of July 2020.**

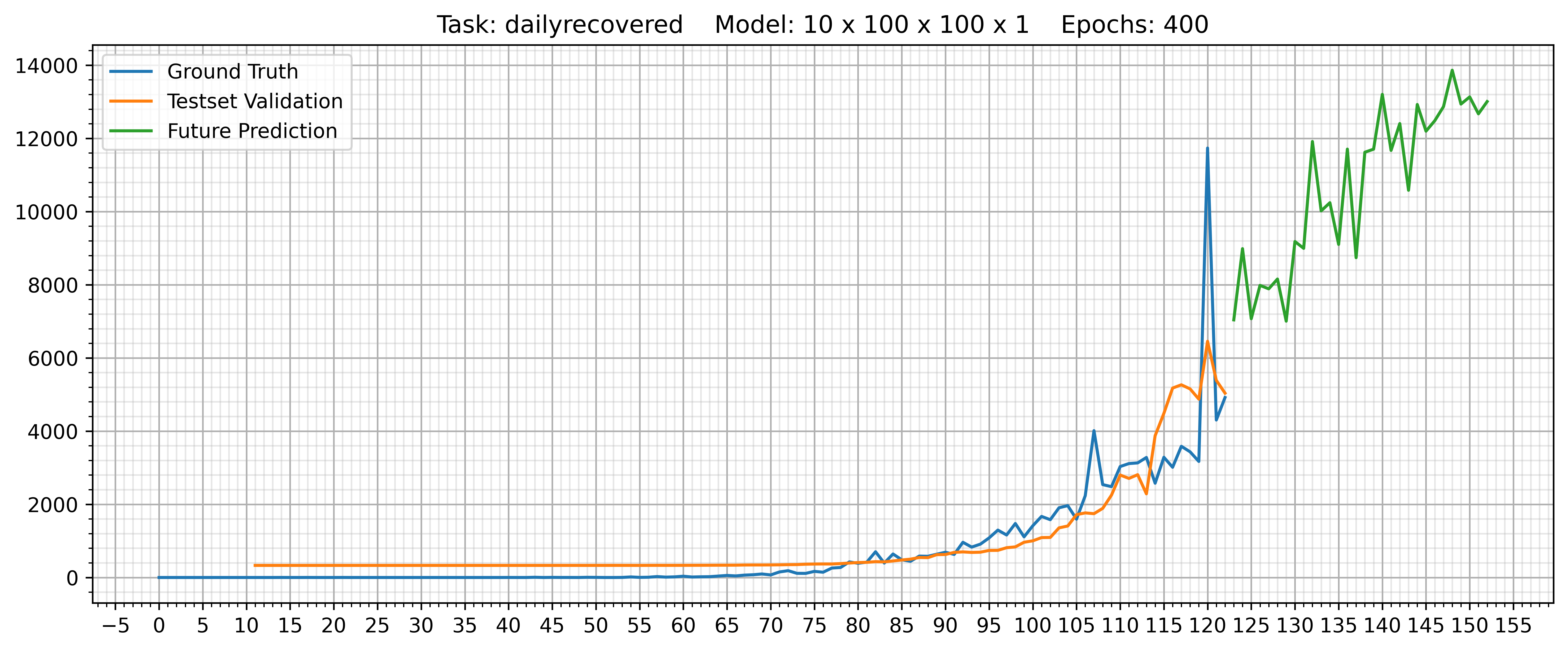
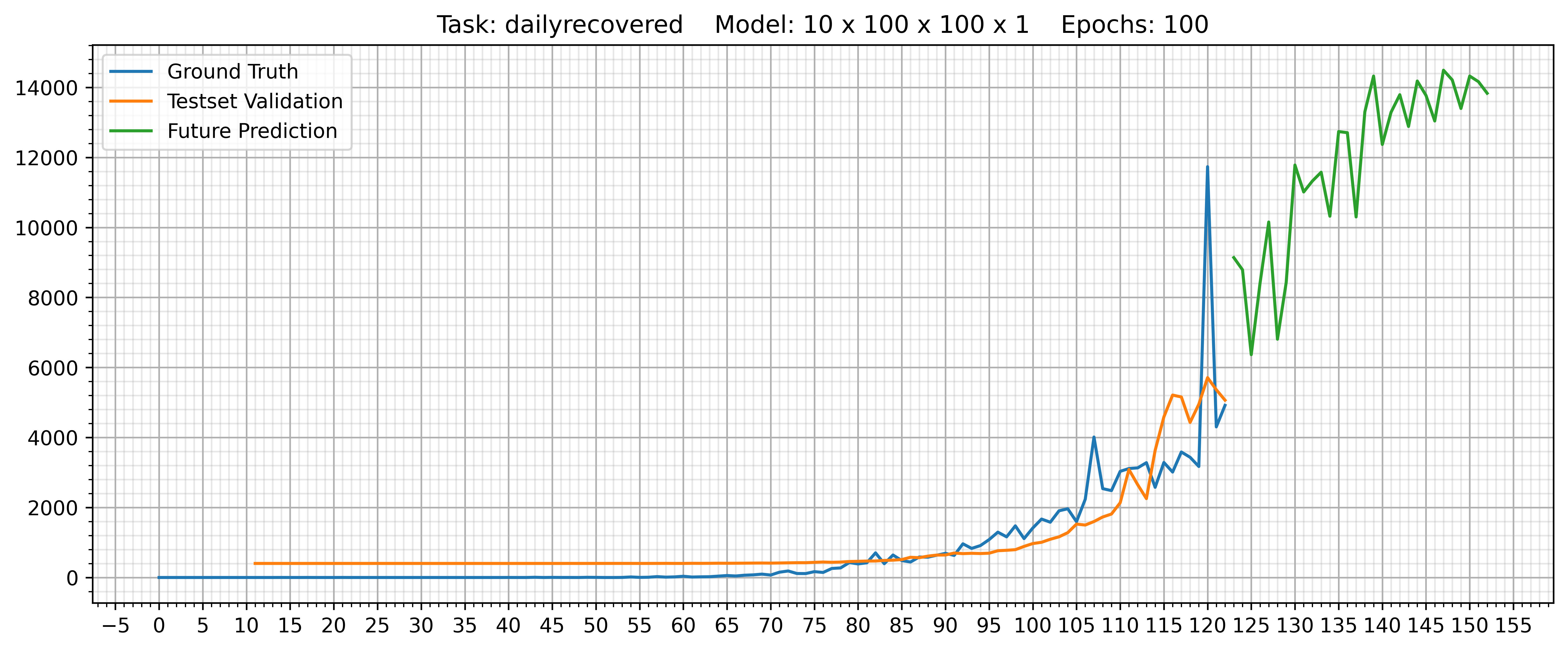


Failed deep model –

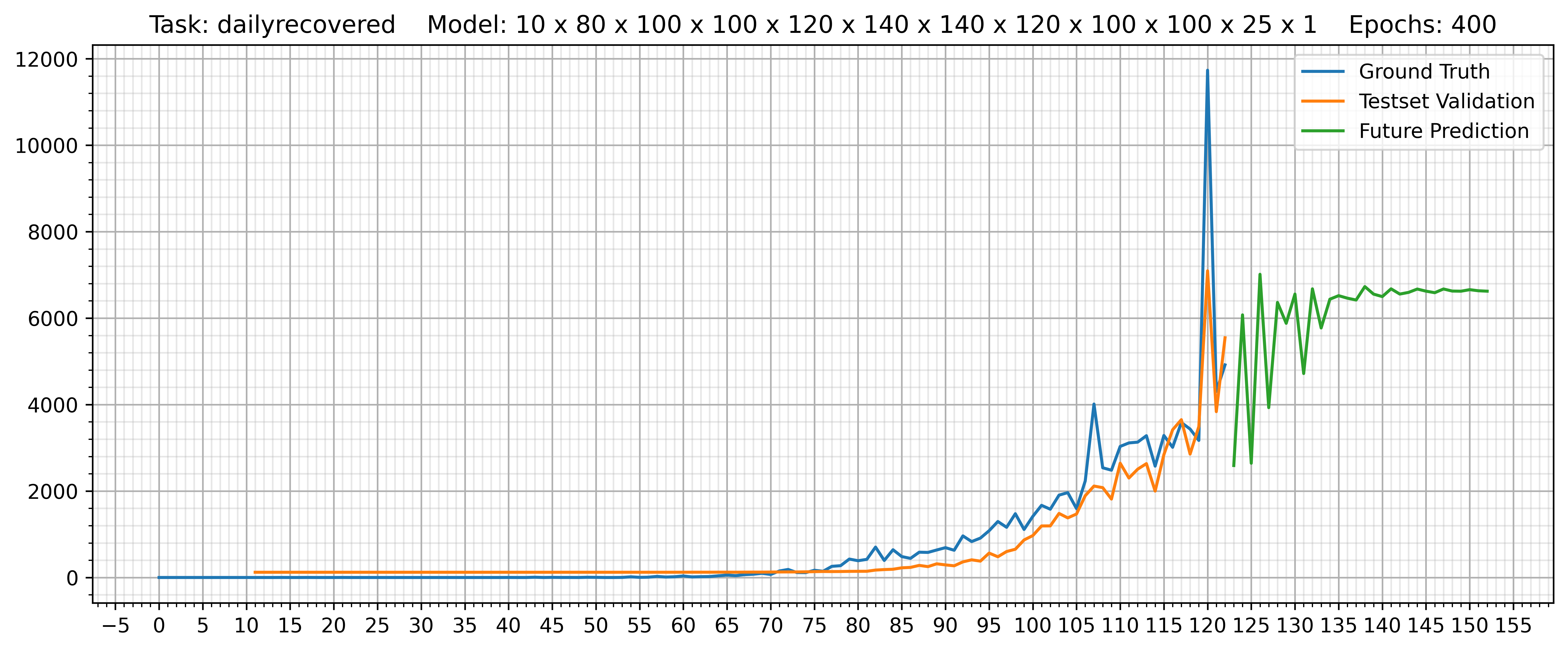


**Graphs of ML model for predicting recovery rate and death rate in India till 31st of July 2020.**

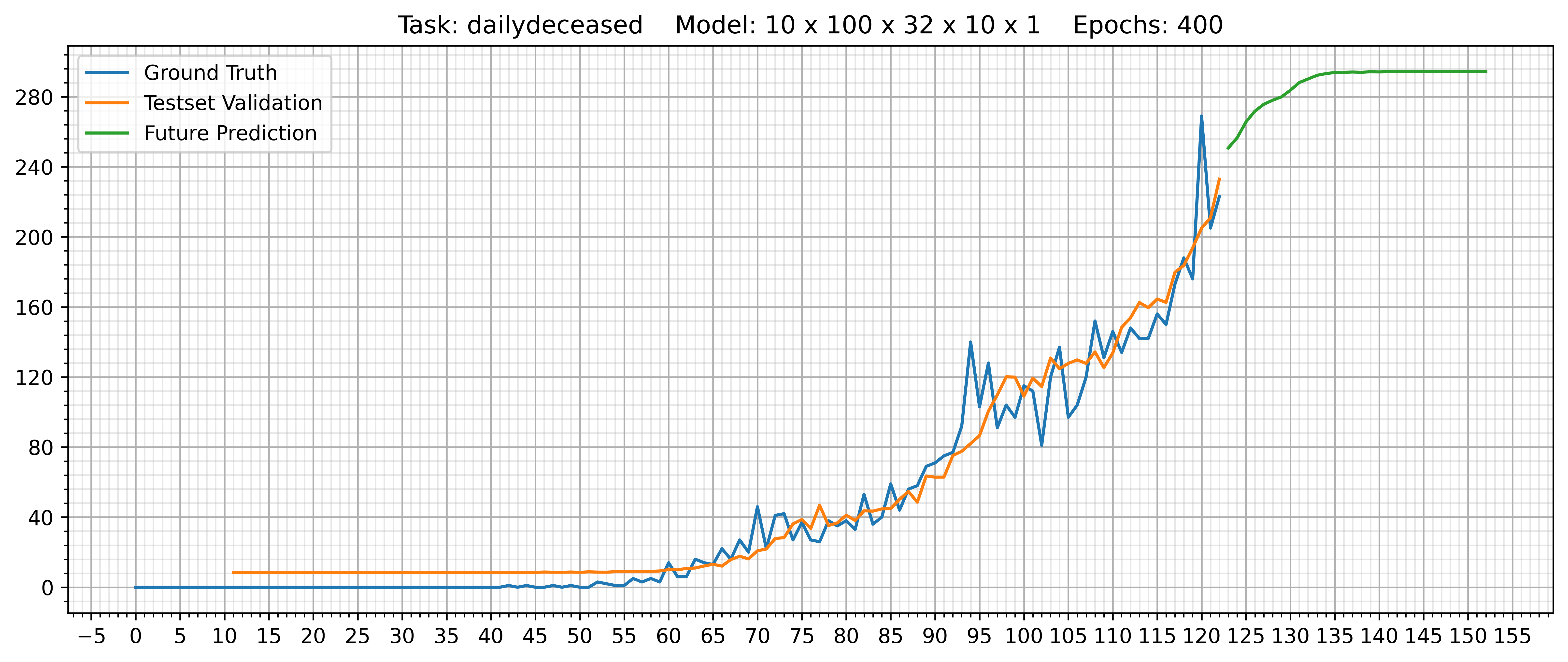
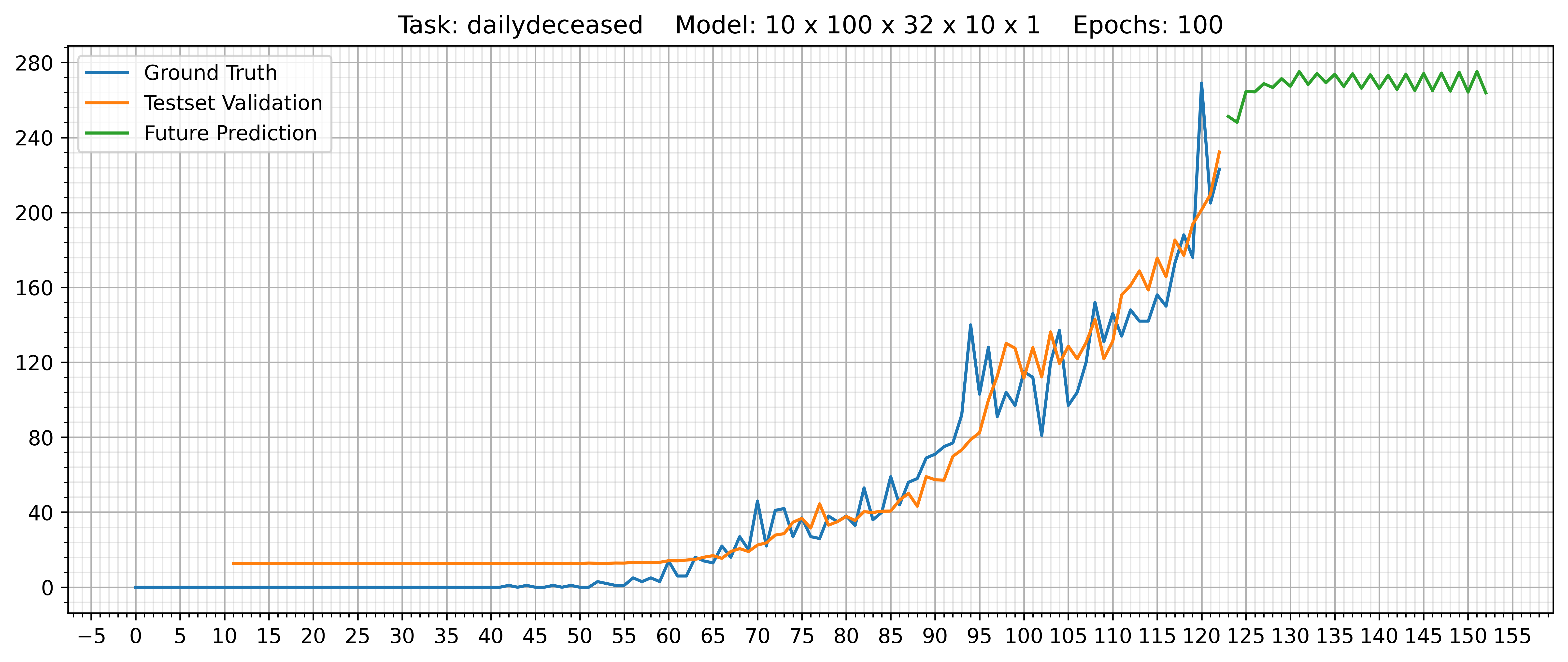
Recovery Rate –



Deep model prediction –



Death rate –



Deep models prediction –

