$$[M]\ddot{u}_{n+1} + [\int_{B}^{T}\sigma''d\Omega] - [Q]p_{n+1} - f_{n+1}^{(1)} = 0$$

$$[Q]\dot{u}_{n+1} + [H]p_{n+1} + [S]\dot{p}_{n+1} - f^{(1)} = 0$$

Extend B method

$$\ddot{\vec{u}}_{n+1} = \ddot{\vec{u}}_n + \Delta \ddot{\vec{u}}_{n+1}$$

$$R^{(i)} = M_{n+1} \Delta \ddot{u}_{n+1} + P(\ddot{u}_{n+1}) - Q_{n+1} \Delta \Delta t \Delta \dot{p}_{n+1} - F_{n+1}^{(i)}$$

$$R^{(2)} = Q_{n+1}^{T} \beta_{1} \Delta t \Delta \dot{u}_{n+2} + H_{n+1} \Delta \Delta t \Delta \dot{p}_{n} + S_{n+1} \Delta \dot{p}_{n+1} - F_{n+1}^{(i)}$$

$$P(\ddot{u}_{n+1}) = \int_{B^{T}} \sigma_{n+1}^{T} d\Omega = \int_{\Omega} B^{T} \Delta \sigma_{n+2}^{T} d\Omega + P(\ddot{u}_{n})$$

$$R^{T} = \begin{bmatrix} \frac{\partial R^{(i)}}{\partial D \ddot{u}_{n}} & \frac{\partial R^{(i)}}{\partial \Delta \dot{p}} \\ \frac{\partial R^{(2)}}{\partial \Delta \ddot{u}_{n}} & \frac{\partial R^{(2)}}{\partial \Delta \dot{p}} \end{bmatrix} \qquad \text{use Newtons nethod to Solw}$$

$$K^{T} = \begin{bmatrix} \frac{\partial R^{(i)}}{\partial \Delta \ddot{u}_{n}} & \frac{\partial R^{(i)}}{\partial \Delta \dot{p}} \\ \frac{\partial R^{(i)}}{\partial \Delta \ddot{u}_{n}} & \frac{\partial R^{(i)}}{\partial \Delta \dot{p}} \end{bmatrix} \qquad \text{for } \Delta \ddot{u}_{n+2} + \frac{1}{2} \int_{\Omega} \dot{p}_{n+2} d\Omega$$