CS711008Z Algorithm Design and Analysis

Lecture 7. UNION-FIND data structure ¹

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Outline

- Introduction to UNION-FIND data structure
- Various implementations of UNION-FIND data structure:
 - Array: store "set name" for each element separately. Easy to FIND set of any element, but hard to UNION two sets.
 - Tree: each set is organized as a tree with root as "set name".
 It is easy to Union two sets, but hard to Find set for an element.
 - Link-by-rank: maintain a balanced-tree to limit tree depth to $O(\log n)$, making FIND operations efficient.
 - \bullet Link-by-rank and path compression: compress path when performing ${\rm FIND},$ making subsequent ${\rm FIND}$ operations much quicker.

$U{\scriptsize \mbox{NION-FIND}}$ data structure

UNION-FIND: motivation

- Motivation: Suppose we have a collection of disjoint sets.
 The objective of Union-Find is to keep track of elements by using the following operations:
 - MakeSet(x): to create a new set {x}.
 - FIND(x): to find the set that contains the element x;
 - UNION(x, y): to union the two sets that contain elements x and y, respectively.
- Analysis: total running time of a sequence of m FIND and n UNION.

UNION-FIND is very useful

- Union-Find has extensive applications, such as:
 - Network connectivity
 - Kruskal's MST algorithm
 - Least common ancestor
 - Games (Go)
 -

An example: Kruskal's MST algorithm

Kruskal's algorithm [1956]

 Basic idea: during the execution, F is always an acyclic forest, and the safe edge added to F is always a least-weight edge connecting two distinct components.

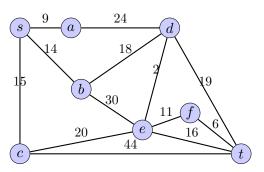


Figure 1: Joseph Kruskal

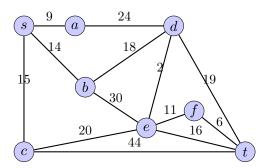
Kruskal's algorithm [1956]

```
MST-Kruskal(G, W)
 1: F = \{\};
 2: for all vertex v \in V do
 3: MakeSet(v);
 4: end for
 5: sort the edges of E into nondecreasing order by weight W;
 6: for each edge (u, v) \in E in the order do
     if FINDSet(u) \neq FINDSet(v) then
        F = F \cup \{(u, v)\};
 8:
        Union (u, v);
10: end if
11: end for
```

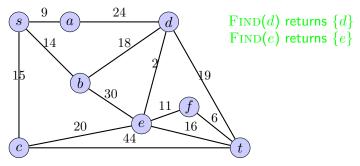
- Here. Union-Find structure is used to detect whether a set of edges form a cycle.
- Specifically, each set represents a connected component; thus, an edge connecting two nodes in the same set is "unsafe", as adding this edge will form a cycle. ◆□ → ◆□ → ◆ き → ◆ き → りへの



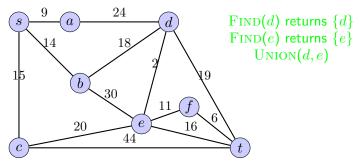
Step 1



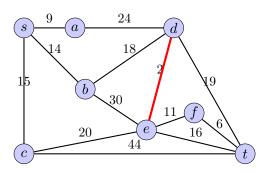
Step 1



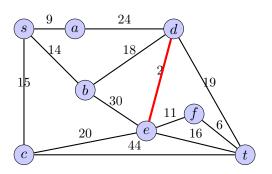
Step 1



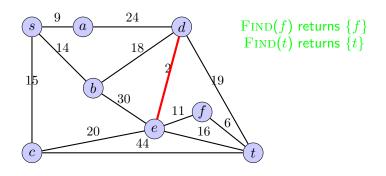
Step 1



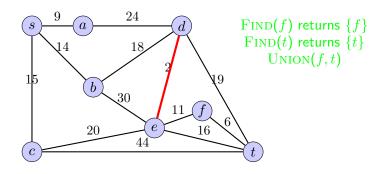
Step 2



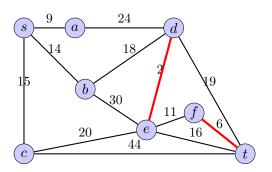
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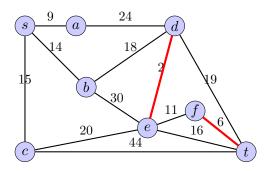
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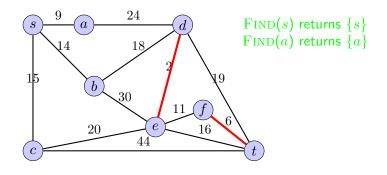
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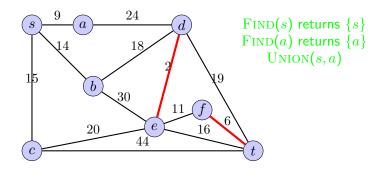
Step 3



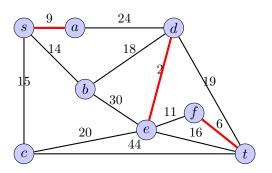
Step 3



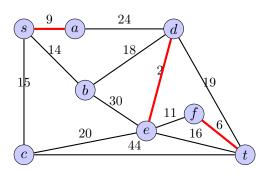
Step 3



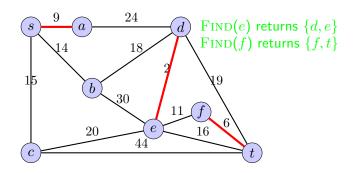
Step 3



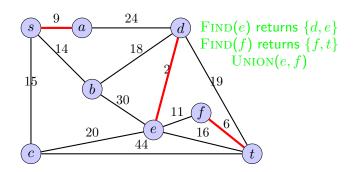
Step 4



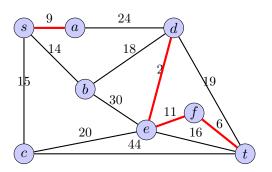
Step 4



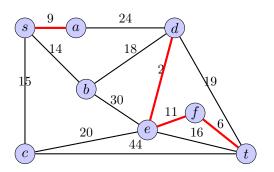
Step 4



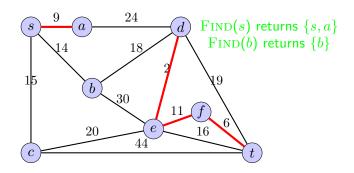
Step 4



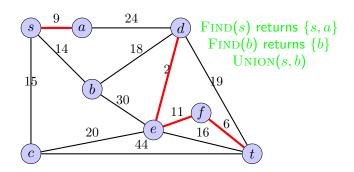
Step 5



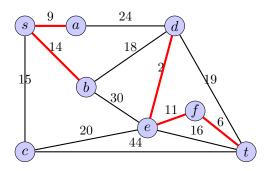
Step 5
Edge weight: 2,6,9,11,14,15,16,18,19,20,24,30,44
Disjoint sets: $\{a,s\},\{b\},\{c\},\{d,e,f,t\}$



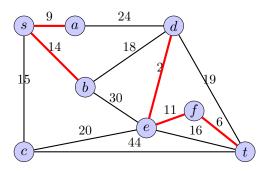
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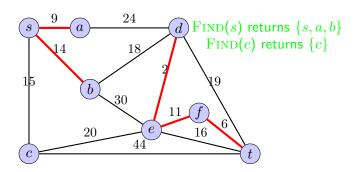
Step 5



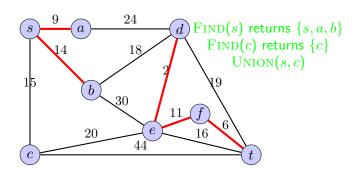
Step 6



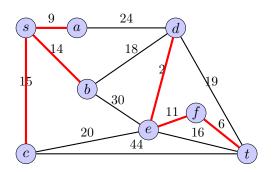
Step 6



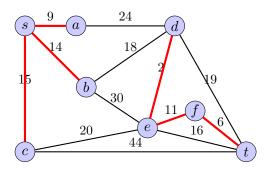
Step 6 Edge weight: 2,6,9,11,14,15,16,18,19,20,24,30,44 Disjoint sets: $\{a,s,b\},\{c\},\{d,e,f,t\}$



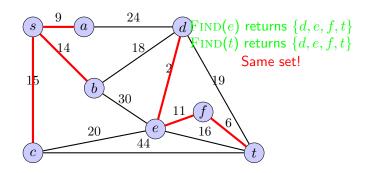
 $\begin{array}{c} {\bf Step~6}\\ {\bf Edge~weight:}~~2,6,9,11,14,15,16,18,19,20,24,30,44\\ {\bf Disjoint~sets:}~~\{a,s,b,c\},\{d,e,f,t\} \end{array}$



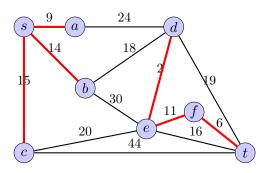
 $\begin{array}{c} {\rm Step~7} \\ {\rm Edge~weight:}~~2,6,9,11,14,15,16,18,19,20,24,30,44} \\ {\rm Disjoint~sets:}~~\{a,s,b,c\},\{d,e,f,t\} \end{array}$



Step 7
Edge weight: 2,6,9,11,14,15,16,18,19,20,24,30,44
Disjoint sets: $\{a,s,b,c\},\{d,e,f,t\}$

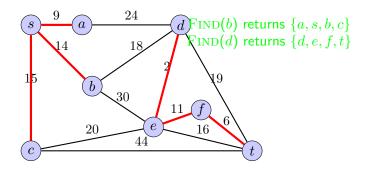


Step 8



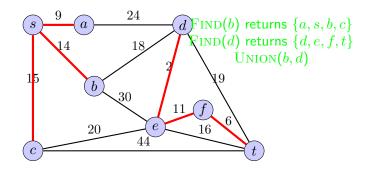
Kruskal's MST algorithm: an example

 $\begin{array}{c} {\bf Step~8}\\ {\bf Edge~weight:}~~2,6,9,11,14,15,16,18,19,20,24,30,44\\ {\bf Disjoint~sets:}~~\{a,s,b,c\},\{d,e,f,t\} \end{array}$



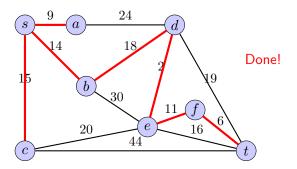
Kruskal's MST algorithm: an example

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Kruskal's MST algorithm: an example

Step 8



Time complexity of KRUSKAL'S MST algorithm

Operation	Array	Tree	Link-by-rank	Link-by-rank +
				path compression
MAKESET	1	1	1	1
FIND	1	n	$\log n$	$\log^* n$
Union	n	1	$\log n$	$\log^* n$
Kruskal's MST	$O(n^2)$	O(mn)	$O(m \log n)$	$O(m \log^* n)$

Kruskal's MST algorithm: n MakeSet, n-1 Union, and m Find operations.

Implementing $\operatorname{Union-Find}:$ array or linked list

Implementing Union-Find: array

 Basic idea: for each element, we record its "set name" individually.

• Operation: FIND(x)

1: **return** SetName[x];

• Complexity: O(1)

Implementing UNION-FIND: array

Operation:

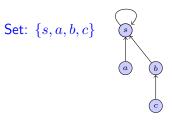
```
UNION(x, y)
 1: s_x = \text{FIND}(x);
 2: s_y = \text{FIND}(y);
 3: for all element i do
       if SetName[i]==s_u then
         SetName[i]=s_x
      end if
 6:
 7: end for
                     s \quad a \quad b \quad c \quad d \quad e \quad f \quad t
        Set name: 0 1 2 3 4 5 6
                                                 Union(d, e)
        Set name: |0|1|2|3|5
                                                 Union(f, e)
        Set name: | 0 | 1 | 2 | 3
```

• Complexity: O(n)

Tree implementation: organizing a set into a tree with its root as representative of the set

Tree implementation: FIND

 Basic idea: We use a tree to store elements of a set, and use root as "set name". Thus, only one representative should be maintained.



Operation:

```
FIND(x)
```

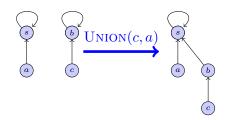
- 1: r = x;
- 2: while r! = parent(r) do
- 3: r = parent(r);
- 4: end while
- 5: **return** r;

Tree implementation: UNION

Operation:

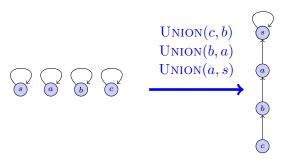
Union(x, y)

- 1: $r_x = \text{FIND}(x)$;
- 2: $r_y = \text{FIND}(y)$;
- 3: $parent(r_x) = r_y$;
- Example: UNION(c, a)



Tree implementation: worst case

• Worst case: the tree degenerates into a linked list. For example, UNION(c,b), UNION(b,a), UNION(a,s).



- \bullet Complexity: FIND takes O(n) time, and UNION takes O(n) time.
- Question: how to keep a "good" tree shape to limit path length?

Link-by-rank: shorten the path by maintaining a balanced tree

Tree implementation with link-by-size

- Basic idea: We shorten the path by maintaining a balanced-tree. In fact, this will limit path length to $O(\log n)$.
- How to maintain a balanced tree? Each node is associated with a rank, denoting its height. The tree has a balanced shape via linking smaller tree to larger tree; if tie, increase the rank of new root by 1.

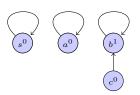
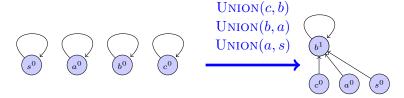


Figure 2: Three sets: $\{s\}$, $\{a\}$, $\{b,c\}$

Tree implementation with link-by-size: Union operation

```
\begin{array}{lll} \text{UNION}(x,y) \\ 1: & r_x = \text{FIND}(x); \\ 2: & r_y = \text{FIND}(y); \\ 3: & \text{if} & rank(r_x) > rank(r_y) \text{ then} \\ 4: & parent(r_y) = r_x; \\ 5: & \text{else} \\ 6: & parent(r_x) = r_y; \\ 7: & \text{if} & rank(r_x) == rank(r_y) \text{ then} \\ 8: & rank(r_y) = rank(r_y) + 1; \\ 9: & \text{end if} \\ 10: & \text{end if} \end{array}
```

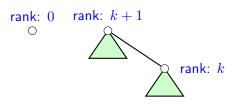
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Note: a node's rank will not change after it becomes an internal

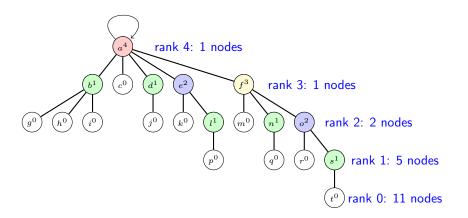
Properties of rank I

- **①** For any node x, rank(x) < rank(parent(x)).
- ② Any tree with root rank of k contains at least 2^k nodes. (Hint: by induction on k.)
- Once a root node was changed into internal node during a UNION operation, its rank will not change afterwards.



4 Suppose we have n elements. The number of rank k nodes is at most $\frac{n}{2^k}$. (Hint: Different nodes of rank k share no common descendants.)

Properties of rank II

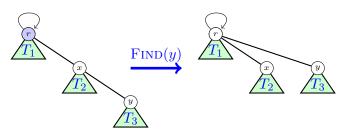


• Thus, all of the trees have height less than $\log n$, which means both FIND and UNION take $O(\log n)$ time.

Path compression: compress paths to make further $\ensuremath{\mathrm{FIND}}$ efficient

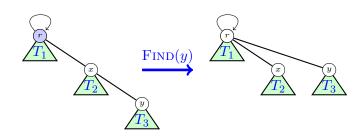
Path compression

• Basic idea: After finding the root r of the tree containing x, we change the parent of the nodes along the path to point directly to r. Thus, the subsequent $\operatorname{FIND}(x)$ operations will be efficient.



• Note: Path compression changes height of nodes but does not change rank of nodes. We always have $height(x) \leq rank(x)$; thus, the three properties still hold.

Path compression: FIND operation



FIND(x)

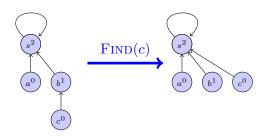
- 1: if x! = parent(x) then
- 2: parent(x) = FIND(parent(x));
- 3: **else**
- 4: **return** x;
- 5: end if

Some properties of FIND and UNION

- FIND operations change internal nodes only while UNION operations change root node only.
- Path compression changes parent node of certain internal nodes. However, it will not change the root nodes, rank of any node, and thus will not affect UNION operations.

Path compression: complexity

• Example: FIND(c)



• A $\operatorname{FIND}(c)$ operation might takes long time; however, the path compression makes subsequent $\operatorname{FIND}(c)$ (and other middle nodes in the path) efficient.

Theorem

Starting from each item forming an individual set, any sequence of m operations (including FIND and UNION) over n elements takes $O(m\log^* n)$ time.

Analysis of path compression: a brief history

- In 1972, Fischer proved a bound of $O(m \log \log n)$.
- In 1973, Hopcroft and Ullman proved a bound of $O(m \log^* n)$.
- In 1975, R. Tarjan et al. proved a bound using "inverse Ackerman function".
- Later, R. Tarjan, et. al. and Harfst and Reingold proved the bound using the potential function technique.

Here, we present the proof in *Algorithms* by S. Dasgupta, C. H. Papadimitriou, and U. V. Vazirani.

$\log^* n$: Iterated logarithm function

• Intuition: the number of logarithm operations to make n to be 1.

•
$$\log^* n = \begin{cases} 0 & \text{if } n = 1 \\ 1 + \log^*(\log n) & \text{otherwise} \end{cases}$$

\overline{n}	$\log^* n$
1	0
2	1
$[3, 2^2]$	2
$[5, 2^4]$	3
$[17, 2^{16}]$	4
$[65537, 2^{65536}]$	5

• Note: $\log^* n$ increases very slowly, and we have $\log^* n < 5$ unless n exceeds the number of atoms in the universe.

Analysis of rank

Let's divide the nonzero ranks into groups as below.

Group	Rank	Upper bound of #elements
0	1	$\frac{n}{2}$
1	2	$\frac{ ilde{n}}{2^2}$
2	$[3, 2^2]$	$\frac{\overline{n}}{2^2}$
3	$[5, 2^4]$	$egin{array}{c} rac{n}{2} \\ rac{n}{2^2} \\ rac{n}{2^2} \\ rac{n}{2^4} \end{array}$
4	$[17, 2^{16}]$	$\frac{n}{2^{16}}$
5	$[65537, 2^{65536}]$	$\frac{\frac{2n}{265536}}{\frac{265536}{2}}$

Note:

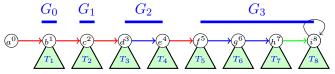
- Group number is $\log^* rank$ and the number of groups is at most $\log^* n$.
- The number of elements in the rank group G_k $(k \ge 2)$ is at most $\frac{n}{2^{2}}$ as the number of nodes with rank r is at most $\frac{n}{2^r}$.

We will see why the group was set to take the form

$$[2^{2^{\dots 2}}_{k-1} + 1, 2^{2^{\dots 2}}]$$
 soon.

Amortized analysis: total time of m FIND operations

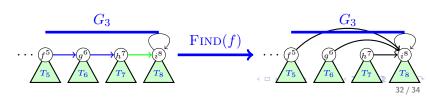
- Basic idea: a FIND operation might take long time; however, path compression makes subsequent FIND operations efficient.
- ullet Let's consider a sequence of m FIND operations, and divide the traversed links into the following three types:
 - Type 1: links to root
 - Type 2: links traversed between different rank groups
 - Type 3: links traversed within the same rank groups
- For example, the links that FIND(a) travels:



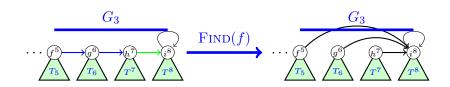
- The total time is $T = T_1 + T_2 + T_3$, where T_i denotes the number of links of type i. We have:
 - $T_1 = O(m)$.
 - $T_2 = O(m \log^* n)$. (Hint: there are at most $\log^* n$ groups.)
 - $T_3 = O(n \log^* n)$. (To be shown later.)
- Thus, $T = O(m \log^* n)$.

Amortized analysis: why $T_3 = O(n \log^* n)$?

- Note that the $\operatorname{FIND}(f)$ operation of type 3 will change $\operatorname{parent}(f)$: the rank of $\operatorname{parent}(f)$ increases by at least 1. In the example shown below, $\operatorname{parent}(f)$ changes from g^6 to i^8 . Let's consider the next $\operatorname{FIND}(f)$ operation.
 - ① If a UNION operation linked i^8 to another root node before the next FIND(f) operation, then this FIND(f) operation will again lead to the increase of the rank of parent(f).
 - ② Otherwise, parent(f) is itself a root, and the next FIND(f) operation will be accounted into T_1 .
- Hence, after at most 2^4 $\mathrm{FIND}(f)$ operations of type 3, parent(f) is itself a root, or the rank of parent(f) increase to make it lie in another group different from f, leading subsequent $\mathrm{FIND}(f)$ operations to be accounted into T_2 or T_1 .



Why $T_3 = O(n \log^* n)$? continued



Formally we have

$$T_3 \leq \sum_{k=2}^{\log^* n} \sum_{f \in G_k} \underbrace{2^{2^{\dots^2}}}_{\mathbf{k}} \qquad \text{(the largest rank in group } G_k \text{ is } \underbrace{2^{2^{\dots^2}}}_{\mathbf{k}})$$

$$\leq \sum_{k=2}^{\log^* n} \frac{n}{\underbrace{2^{2^{\dots^2}}}_{\mathbf{k}}} \underbrace{2^{2^{\dots^2}}}_{\mathbf{k}} \qquad (\# \text{nodes in group } G_k \leq \underbrace{\frac{n}{2^{2^{\dots^2}}}}_{\mathbf{k}})$$

$$= O(n \log^* n)$$

$T_3 = O(n \log^* n)$: another explanation using "credit"

- Let's give each node credits as soon as it ceases to be a root. If its rank is in the group $[k+1, 2^k]$, we give it 2^k credits.
- The total credits given to all nodes is $n \log^* n$. (Hint: each group of nodes receive n credits.)
- If rank(f) and rank(parent(f)) are in the same group, we will charge f 1 credit.
- In this case, rank(parent(f)) increases by at least 1.
- Thus, after at most 2^k FIND operations, rank(parent(f)) will be in a higher group.
- Thus, f has enough credits until rank(f) and rank(parent(f)) are in different group, which will be accounted into T_2 .