

Properties of constant Acceleration

1/4

Let's consider a constant acceleration of

$$a = 12 \frac{\text{m}}{\text{s}^2} \leftarrow \text{that's a lot} - \text{I rounded up}$$

— the fastest drag racer is a
Porsche 919 Hybrid that can sustain

$$11.67 \frac{\text{m}}{\text{s}^2}$$

for 402m

The equations are

$$x_{i+1} = x_i + (t_{i+1} - t_i) v_i$$

$$v_{i+1} = v_i + (t_{i+1} - t_i) a$$

↑ the constant acceleration

I'm going to

make things a little trickier by doing 0.5s time steps instead of our usual 1s time steps.

Focusing just on the second equation,
 $V_{i+1} = V_i + \underbrace{(t_{i+1} - t_i)}_{\substack{\text{difference} \\ \text{is } 0.5s}} a$ and starting with
 $V_0 = 0$ $\nearrow 12m/s^2$

\nwarrow drag racer begins the race stopped

Fill in all empty table cells

| i | t_i | a | V_i |
|----|-------|--------------------|----------------------|
| 0 | 0s | 12m/s ² | 0m/s $\nwarrow V_0$ |
| 1 | 0.5s | 12m/s ² | 6m/s $\nwarrow V_1$ |
| 2 | 1.0s | 12m/s ² | 12m/s $\nwarrow V_2$ |
| 3 | 1.5s | 12m/s ² | |
| 4 | 2.0s | 12m/s ² | |
| 5 | 2.5s | 12m/s ² | |
| 6 | | 12m/s ² | |
| 7 | | 12m/s ² | |
| 8 | | 12m/s ² | |
| 9 | | 12m/s ² | |
| 10 | | 12m/s ² | |
| 11 | | 12m/s ² | |
| 12 | | 12m/s ² | |
| 13 | | 12m/s ² | |
| 14 | | 12m/s ² | |
| 15 | | 12m/s ² | |
| 16 | | 12m/s ² | |
| 17 | | 12m/s ² | |

what goes here is
 $V_2 + (t_3 - t_2) \cdot a$

here goes
 $V_3 + (t_4 - t_3) \cdot a$

etc.

Now that we have all the V_i let's expand the table to include all the x_i . We get the x_i from 3/4

$$x_{i+1} = x_i + \underbrace{(t_{i+1} - t_i)}_{\text{Still } 0.5s} V_i$$

$x_0 = 0$ ← drag racer starts at start line

| i | $t_i(s)$ | $a(m/s^2)$ | $V_i(m/s)$ | $x_i(m)$ | |
|-----|----------|------------|------------|----------|---------|
| 0 | 0 | 12 | 0 | 0 | ← x_0 |
| 1 | 0.5 | 12 | 6 | 0 | ← x_1 |
| 2 | 1.0 | 12 | 12 | 3 | ← x_2 |
| 3 | 1.5 | 12 | 18 | | ← |
| 4 | 2.0 | 12 | 24 | | ← |
| 5 | 2.5 | 12 | 30 | | ← |
| 6 | 3.0 | 12 | 36 | | ← |
| 7 | 3.5 | 12 | 42 | | ← |
| 8 | 4.0 | 12 | 48 | | ← |
| 9 | 4.5 | 12 | 54 | | ← |
| 10 | 5.0 | 12 | 60 | | ← |
| 11 | 5.5 | 12 | 66 | | ← |
| 12 | 6.0 | 12 | 72 | | ← |
| 13 | 6.5 | 12 | 78 | | ← |
| 14 | 7.0 | 12 | 84 | | ← |
| 15 | 7.5 | 12 | 90 | | ← |
| 16 | 8.0 | 12 | 96 | | ← |
| 17 | 8.5 | 12 | 102 | | ← |

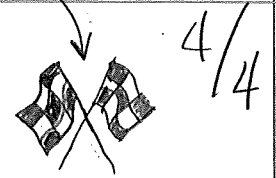
what goes here is $x_2 + (t_3 - t_2) \cdot V_2$

here goes $x_3 + (t_4 - t_3) \cdot V_3$

etc.

← HINT/CHECK LAST IS 408

finish at 402m



Two Ways of Graphing your Work

0 1 2 3 4

0m 50m 100m 150m 200m 250m 300m 350m 400m

I have plotted positions x_0, x_1, x_2, x_3 , and x_4 above.
You plot positions x_5, \dots, x_{17} . Do $t=2.5s$ to $8.5s$ below.

