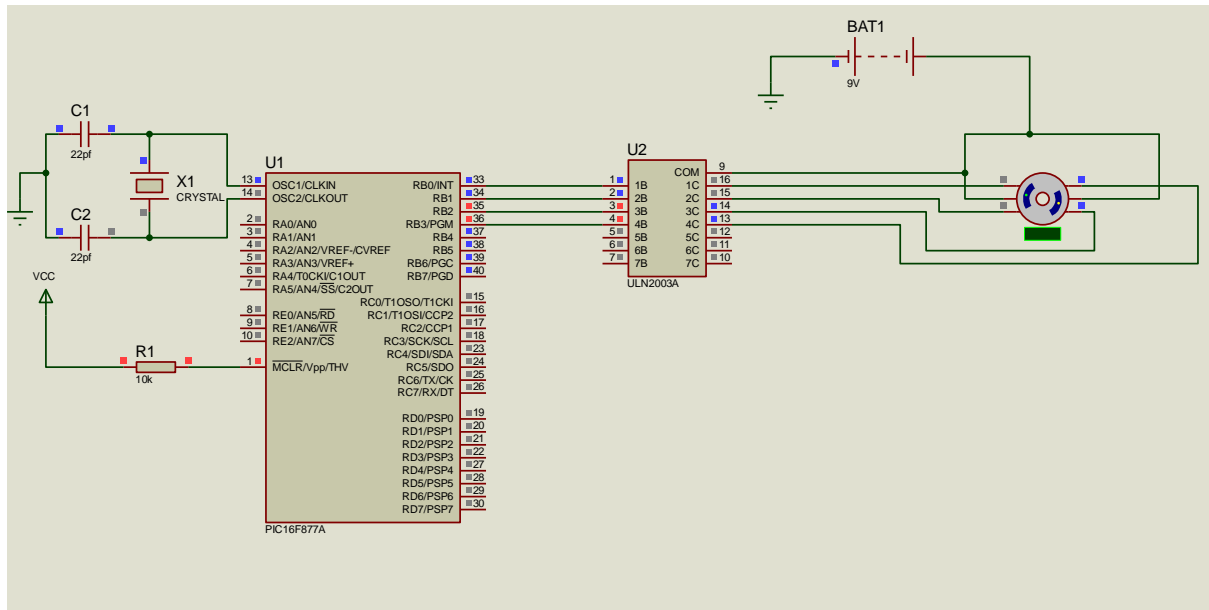Stepper motor

Code:
```
void main(){
 TrisB=0x00;
 portb=1;
 do{
 Portb=0b00000011;
 delay_ms(500);
 portb=0b00000110;
 delay_ms(500);
 portb=0b00001100;
 delay_ms(500);
 portb=0b00011000;
 delay_ms(500);
 }
 while(1);
}
```