Recorded at time: 1624011040.68 vicon\_frame Broadcaster: /charlie\_vicon2map Broadcaster: /vrpn\_client\_node Broadcaster: /vrpn\_client\_node Average rate: 100.004 Average rate: 100.002 Average rate: 49.51 Buffer length: 9.99 Buffer length: 3.959 Buffer length: 9.99 Most recent transform: 1624011040.54 Most recent transform: 1624011040.52 Most recent transform: 1624011040.54 Oldest transform: 1624011036.56 Oldest transform: 1624011030.55 Oldest transform: 1624011030.55 Charlie ActiveWandv2OriginTracking UWB Broadcaster: /tag\_1\_filter Broadcaster: /tag\_in\_map Broadcaster: /tag\_0\_filter Broadcaster: /pose\_pub\_2\_tag Broadcaster: /pose\_pub\_2\_tag Average rate: 94.954 Average rate: 96.686 Average rate: 6.623 Average rate: 50.1 Average rate: 6.128 Buffer length: 9.955 Buffer length: 9.994 Buffer length: 9.991 Buffer length: 9.965 Buffer length: 9.98 Most recent transform: 1624011037.78 Most recent transform: 1624011040.62 Most recent transform: 1624011040.61 Most recent transform: 1624011037.68 Most recent transform: 1624011040.61 Oldest transform: 1624011030.62 Oldest transform: 1624011030.62 Oldest transform: 1624011027.73 Oldest transform: 1624011027.82 Oldest transform: 1624011030.61 tag1\_frame\_f tag0\_frame tag1\_frame tag0\_frame\_f map Broadcaster: /amcl Broadcaster: /amcl2robot\_pose\_PY Broadcaster: /tag\_in\_map Average rate: 50.097 Average rate: 12.012 Average rate: 89.043 Buffer length: 9.981 Buffer length: 9.984 Buffer length: 9.99 Most recent transform: 1624011040.44 Most recent transform: 1624011040.61 Most recent transform: 1624011040.61 Oldest transform: 1624011030.45 Oldest transform: 1624011030.63 Oldest transform: 1624011030.63 tag\_center\_frame laser\_odom robot\_pose Broadcaster: /scan\_matcher Average rate: 5.651 Buffer length: 9.91 Most recent transform: 1624011040.24 Oldest transform: 1624011030.33 base\_link Broadcaster: /base\_link2laser Average rate: 10.067 Buffer length: 9.933 Most recent transform: 1624011040.68 Oldest transform: 1624011030.75

laser