

Pozyx  
UWB

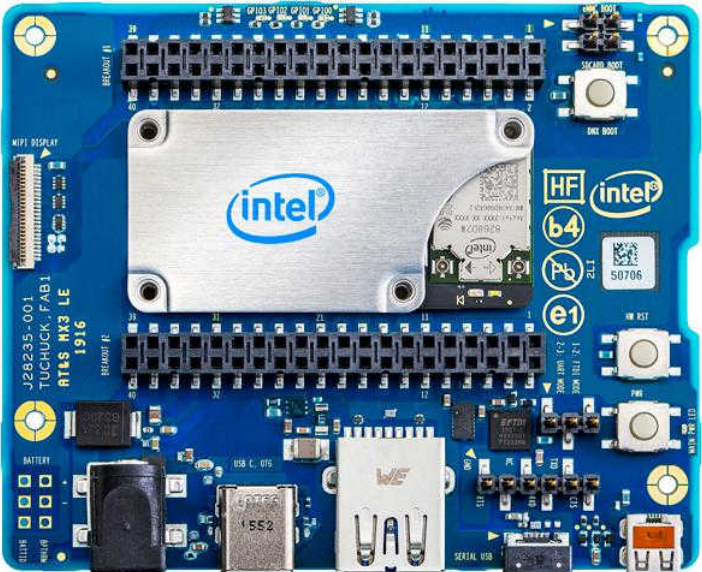


RpLidar A3

*posa UWB*

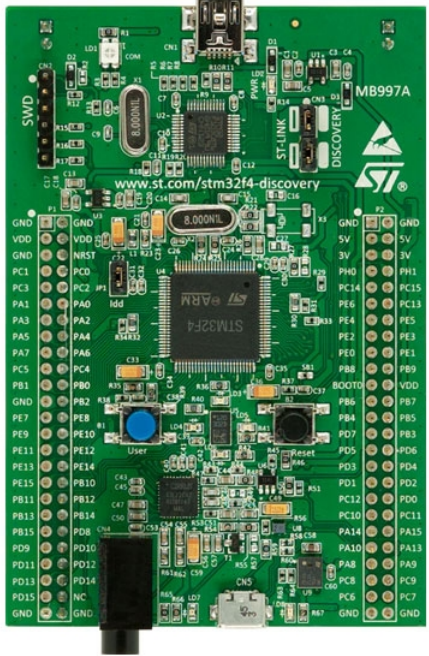
*Laser scan*

IntelJoule



*Stima posa*

STM32 F407



*Controllo motori*

Crawler

