

# Poker Zero Final Presentation

# Problem Definition

- **What are we solving?**
  - We aim to build a **reasoning model** for No-Limit Hold'em poker capable of decision-making under **incomplete information** and **adversarial conditions**.
- **Importance:**
  - Real-time strategic thinking, risk assessment, and adaptation.
  - Decision-making under uncertainty
- **Success Criteria**
  - **Win rate** (hands won, stack size, profit over time)
  - **Performance against GTO (Game Theory Optimal) strategies**

# Prior Work

- Poker solvers play game theory optimal poker, which is limited
  - Nash equilibria is hard to compute for multi-way zero sum games
  - Only able to calculate on a limited set of scenarios, but poker has a very large game tree
  - Won't take advantage of imperfect opponent
- State of the art poker bot: **Pluribus**
  - Uses self-play to iteratively converge at the equilibrium
  - Leverages Monte Carlo Counterfactual Regret Minimization

## Using LLMs

- Transformer models like ChatGPT / GPT-4 don't play GTO
- LLMs use less compute/resource consumption than CFR
- Can receive more information in the game tree

# Modeling the Problem

- **Stochastic Nature of Poker:**

- Poker is inherently random, with incomplete information and unpredictable outcomes.
- an\*Expected  $h$ (EV)  $R(h)$ :\*\*

$$EV = \sum_{h \in H} P(h) \times R(h)$$

- $P(h)$  is the probability of a hand outcome  $R(h)$  is the corresponding reward.

- **Goal:** maximize total expected winnings over all rounds  $r$ 
  - **Actions:** Possible moves (bet, raise, fold, call)

# Modeling the Problem

- Reinforcement Learning (RL) naturally suited for sequential decision making problems and long term problems
- **Setting up a basic framework**
  - **States:** Game configurations, including hole cards, community cards, betting history, stack sizes
  - **Actions:** Possible moves (bet, raise, fold, call) & associated amounts
  - **Rewards:** Based on how good the actions are

# Optimization Methods

- **Policy Gradient Methods:**

Directly optimize the policy by maximizing the expected reward.

- **PPO (Proximal Policy Optimization):**

Balances exploration and exploitation with clipping or penalty methods to ensure stable updates.

- **GRPO (Guaranteed Reward Policy Optimization):**
  - **Monotonic Improvement:**  
Provides theoretical guarantees for steady policy improvement.
  - **Reward-Centric Updates:**  
Focuses on adjusting policies based on long-term reward estimates.
  - **Empirical Advantages:**  
Demonstrates superior performance compared to PPO and TRPO in several benchmarks.
- **Relevance to Poker:**  
Enables strategic adaptation and robust performance in complex, adversarial settings.



# Unslloth

- **Purpose:**

An open-source Python framework optimized for fast fine-tuning and deployment of large language models.

- **Key Features:**

- High-performance PyTorch code with haT4 or A100written GPU kernels.
- Improved memory utilization through typecasting.
- Scalability: Fine-tuning 8B parameter models on modest GPU setups (e.g., Colab T4).

## LoRA (Low Rank Adaptation)

- **Concept:**

Introduces low-rank matrices into pretrained model layers to achieve efficient fine-tuning.

- **Benefit:**

Significant performance gains with a minimal increase in parameters—ideal for adapting large models in resource-constrained environments.

# Mathematical Formulation of LoRA

- **Pretrained Weight Matrix:**

Let  $W \in \mathbb{R}^{d \times k}$  be a pretrained weight matrix.

- **Low-Rank Update:**

Approximate the weight update as:

$$\Delta W = BA$$

where:

- $B \in \mathbb{R}^{d \times r}, A \in \mathbb{R}^{r \times k}, r \ll \min(d, k)$

- **Adapted Weights:**

The new weight matrix is given by:

$$W' = W + BA$$

# Optimization & Reward Functions

- **Reward Function Design:**
  - **For Initial Training:**
    - **Negative Reward:** Apply penalties for outputs that violate constraints.
    - **Zero Reward:** No reward for clearly incorrect moves.
  - **Partial Rewards:**
    - Reward for executing a correct action.
    - Additional reward for an almost correct action (e.g., bet size within  $\pm 20\%$  of the optimal).
  - **Maximum Reward:**
    - Full reward for both the correct action and optimal bet sizing.

- **Why This Approach?**

- Allows gradual, nuanced learning instead of an all-or-nothing reward.
- Helps the model learn the subtleties of decision-making in an environment where perfect play is rare.

## Selecting GRPO & Refining the Model

- **Algorithm Choice: Guaranteed Reward Policy Optimization (GRPO)**
  - **Justification:**
    - GRPO provides theoretical guarantees for steady policy improvement.
    - Suitable for poker's continuous and complex environment where isolated wins do not ensure overall success.

- **Tuning Procedure & Hyperparameters:**
  - **Reward Function Tuning:**
    - Began with rewards only for exact matches, but feedback was sparse.
    - Introduced partial credit for near-miss outputs (e.g., valid poker moves, near-optimal bet amounts).
  - **Hyperparameter Exploration:**
    - Systematic grid search over reward thresholds and learning rates.
    - Iterative refinement based on model performance and stability.

- **Implementation Choices:**

- Leveraged the **Unslloth** framework to optimize GRPO training.
- Utilized PyTorch for model development and integration, taking advantage of its efficient computation and GPU support.



## **\*\*Limits Encountered & Adaptations&**

- **Computational Resources:**

- Initially limited to a T4 GPU on Colab, leading to frequent disconnections and slow iteration.
- Challenges in accessing scalable GPU resources on platforms like Google Cloud.

- **Impact on Model Training:**

- Slow training and iteration speeds forced us to adjust our training framework.
- Required tuning reward functions to provide a denser, more continuous feedback signal.

- **Adaptation Strategies:**

- **Unslloth** played a critical role in speeding up our training cycles.
- Optimization of training loops and hyperparameter searches to work within computational constraints.
- Adoption of incremental learning strategies to mitigate resource limitations while still aiming for optimal performance.

# Results









## Results Overall

- **Profit Rate:** Consistent improvement in win rates against older iterations of the models

How do your results compare to baseline methods or the literature?

- **Performance Metrics:**
  - **Reward Rate:** Upward trend of rewards over time

# Demo

Showcase a demo or compelling visualization if applicable.

Compare expected progress with actual progress. Explain discrepancies.



# Project Reflection

## Technical/Conceptual difficulties

- Understanding the complexity of poker strategies and how to model them effectively.
- Implementing reinforcement learning algorithms, especially in the context of self-play.

# What part of the project workflow was easier than expected? Harder?

## Easier

- Implementing basic reinforcement learning algorithms using **unsloth** directly within Colab.

## Harder

- Debugging and tuning reinforcement learning models to converge effectively in self-play scenarios.

## How the project evolved

- Trained initial model using **GRPO** and attempted self-play reinforcement learning with **PPO** to generate initial neural layers.
- **Challenge:** Model wasn't converging.
  - Shifted to using the self-play environment to generate additional training data for **GRPO**.
- Focused more on **self-play**, with multiple iterations of PokerZero playing each other to measure performance improvements.

## How did AI tools assist your project?

### Specific Examples:

- **Literature Review:** Helped in understanding initial concepts and strategies for reinforcement learning.
- **Debugging:** Assisted in understanding complex algorithms and generating code snippets for reinforcement learning tasks.