BatLab Basic Project Kit – Servo Motor



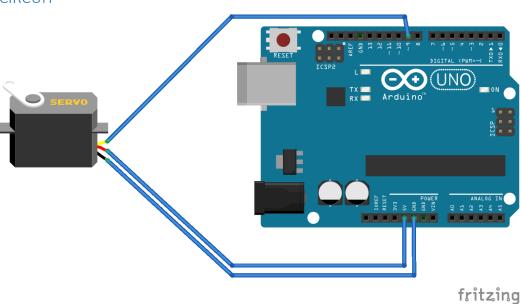
HOW IT WORKS

Servo motors are useful when you need a part to turn in precise increments. The servo motor in this kit rotates through 180°, or half a full circle. It has three leads. The red lead goes to a 5 volt power supply, the brown lead goes to ground, and oranges goes to a control signal provided by the Arduino.

PARTS

- Arduino Uno
- Servo Motor
- Breadboard & jumper wires

CIRCUIT



CODE

```
/* Sweep
by BARRAGAN <http://barraganstudio.com>
This example code is in the public domain.
modified 8 Nov 2013
by Scott Fitzgerald
http://www.arduino.cc/en/Tutorial/Sweep
This program uses a library called "Servo" but because it is automatically
included with the Arduino IDE download, you don't need to download and
install it - it's already there.
*/
#include <Servo.h> // Include the Servo library
Servo myservo; // create servo object to control a servo
                      // twelve servo objects can be created on most
                      // boards
int pos = 0; // variable to store the servo position
void setup()
 myservo.attach(9); // attaches the servo on pin 9 to the servo object
}
void loop()
 for(pos = 0; pos <= 180; pos += 1) // goes from 0 degrees to 180 degrees
                                    // in steps of 1 degree
   myservo.write(pos);
                                    // tell servo to go to position in
                                    // variable 'pos'
   delay(15);
                                    // waits 15ms for the servo to reach
                                    // the position
 for(pos = 180; pos>=0; pos-=1) // goes from 180 degrees to 0 degrees
   myservo.write(pos);
                                    // tell servo to go to position in
                                    // variable 'pos'
   delay(15);
                                    // waits 15ms for the servo to reach
                                    // the position
 }
}
```