

**Homework (*required*):**

Prepare for the midterm:

- Reread the assigned sections of Artin.

- Review assigned homework problems and solutions.

- Try the practice midterm included in this document  
(and check your answers against the solutions  
also included in this document).

- Try other problems from the relevant sections of Artin.

Do exercises 4.3.5, 4.3.10, 4.4.2, 4.4.7.

Read §4.5 for next lecture.

## Practice Midterm 1

Math 122/E222

- (1) Define a *normal subgroup*. Show that any normal subgroup is the kernel of a homomorphism.
- (2) Enumerate the 6 subgroups of  $S_3$  and identify which are normal.
- (3) Let  $Z$  be the center of a group  $G$ . Show that  $Z$  is a normal subgroup. Suppose  $G/Z$  is cyclic. Show that  $G$  is abelian.
- (4) Let  $G$  be the group  $(\mathbb{Z}/p\mathbb{Z})^2$  under addition. Calculate the automorphism group of  $G$ .
- (5) Let  $F$  be a field and let  $E = \{e_1, e_2\}$  be the standard basis of  $F^2$ . When is  $S = \{e_1 + e_2, e_1 - e_2\}$  a basis?  
Let  $T$  be the linear operator  $F^2 \rightarrow F^2$  whose matrix with respect to  $E$  is

$$\begin{pmatrix} 5 & 2 \\ 1 & 8 \end{pmatrix}.$$

If  $S$  is a basis, write the matrix of  $T$  with respect to it.

- (6) Let  $V$  be the vectorspace of polynomials of degree  $\leq 2$  over  $\mathbb{Z}/3\mathbb{Z}$  with indeterminate  $X$ . Show that  $B = \{1 + X, X + X^2, 1 + X^2\}$  is a basis for  $V$ . Let  $T : V \rightarrow V$  be the linear map  $T(f(X)) = \frac{d}{dx}f(X)$ . Write  $T$  with respect to the basis  $B$  and calculate the image of  $T$ .

## Solutions

- (1) A normal subgroup  $H$  of a group  $G$  is a subgroup such that for every  $g \in G$  and  $h \in H$ ,  $ghg^{-1} \in H$ . Given a normal subgroup  $H \trianglelefteq G$ , we know that the set of left cosets  $G/H$  forms a group under  $(xH)(yH) = (xy)H$ . The map  $f : G \rightarrow G/H$  taking  $x \mapsto xH$  is a well-defined homomorphism with kernel  $H$ .
- (2) Let  $e$  denote the identity in  $S_3$ , let  $\tau_{ij}$  be the transposition exchanging  $i$  and  $j$ , and let  $\sigma_{ijk}$  be the permutation taking  $i \mapsto j$ ,  $j \mapsto k$ ,  $k \mapsto i$ . Then

$$S_3 = \{e, \tau_{12}, \tau_{23}, \tau_{13}, \sigma_{123}, \sigma_{321}\}$$

and the six subgroups are:

$$\{e\}, \{e, \tau_{12}\}, \{e, \tau_{23}\}, \{e, \tau_{13}\}, \{e, \sigma_{123}, \sigma_{321}\}, S_3.$$

Only three of them are normal:

$$\{e\}, \{e, \sigma_{123}, \sigma_{321}\}, S_3.$$

since the transpositions get taken to different transpositions by conjugation, and the cycles  $\sigma$  get permuted by conjugation.

- (3) By definition, every element of  $Z$  commutes with every element of  $G$  so  $gzg^{-1} = z \in Z$  for every  $g \in G$ ,  $z \in Z$ . Assume now  $G/Z$  is cyclic. Then there is  $x \in G$  such that every element of  $G/Z$  is of the form  $x^n Z$  ( $n \in \mathbb{Z}$ ), and hence every element of  $G$  can be written in the form  $x^n z$  with  $n \in \mathbb{Z}$  and  $z \in Z$ . Since  $(x^n z)(x^m z') = x^{n+m} z z' = (x^m z')(x^n z)$  for all  $n, m \in \mathbb{Z}$  and  $z, z' \in Z$ , we conclude that  $G$  is abelian.
- (4) Suppose  $f : (\mathbb{Z}/p\mathbb{Z})^2 \rightarrow (\mathbb{Z}/p\mathbb{Z})^2$  is a group isomorphism. Then for every  $\bar{c} \in \mathbb{Z}/p\mathbb{Z}$ ,

$$\begin{aligned} f(\bar{c}(\bar{x}, \bar{y})) &= f((\bar{x}, \bar{y}) + \cdots + (\bar{x}, \bar{y})) \\ &= f((\bar{x}, \bar{y})) + \cdots + f((\bar{x}, \bar{y})) = \bar{c}f((\bar{x}, \bar{y})) \end{aligned}$$

(where each sum is taken to be  $c$ -fold,  $c \in \mathbb{Z}$ ). Thus  $f$  is in fact a linear map, and so  $f \in GL((\mathbb{Z}/p\mathbb{Z})^2)$ . We conclude that

$$\begin{aligned} \text{Aut}(G) &= GL_2(\mathbb{Z}/p\mathbb{Z}) \\ &= \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : a, b, c, d \in \mathbb{Z}/p\mathbb{Z}, ad - bc \neq 0 \right\}. \end{aligned}$$

- (5) Let  $v_1 = e_1 + e_2$  and  $v_2 = e_1 - e_2$ . Note that if  $2 = 0$  in  $F$  then  $v_1 + v_2 = 0$  so  $S$  is not linearly independent. However, if  $2 \neq 0$  in  $F$ , then  $2$  is invertible so  $e_1 = 2^{-1}(v_1 + v_2)$  and  $e_2 = 2^{-1}(v_1 - v_2)$ . Hence  $S$  spans, and since  $V$  is 2-dimensional, the dimension formula implies that  $S$  must in fact be a basis.

By the theory of change of basis, the matrix of  $T$  with respect to  $S$  is

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}^{-1} \begin{pmatrix} 5 & 2 \\ 1 & 8 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 8 & -2 \\ -1 & 5 \end{pmatrix}.$$

- (6) Write  $v_1 = 1 + X$ ,  $v_2 = X + X^2$ ,  $v_3 = 1 + X^2$ . Since

$$1 = -v_1 + v_2 - v_3 \quad (\text{note that } -2 = 1),$$

$$X = v_1 - 1, \quad \text{and} \quad X^2 = v_3 - 1,$$

we see that  $B = \{v_1, v_2, v_3\}$  spans  $V$ . Since  $V$  is 3-dimensional, the dimension formula implies that  $B$  is a basis. Noting carefully the arithmetic of  $\mathbb{Z}/3\mathbb{Z}$ , we calculate

$$T(v_1) = 1 = -v_1 + v_2 - v_3$$

$$T(v_2) = 1 + 2X = 1 - (v_1 - 1) = -v_1 - (-v_1 + v_2 - v_3) = -v_2 + v_3$$

$$T(v_3) = 2X = -(v_1 - 1) = -v_1 + (-v_1 + v_2 - v_3) = v_1 + v_2 - v_3.$$

Thus the matrix of  $T$  with respect to  $B$  is

$$\begin{pmatrix} -1 & 0 & 1 \\ 1 & -1 & 1 \\ -1 & 1 & -1 \end{pmatrix}.$$

Since  $\frac{d}{dX}(a + bX + cX^2) = b + 2cX$ , it follows that the image of  $V$  consists of all polynomials of degree  $\leq 1$  (and hence in terms of  $B$ , is spanned by  $\{-v_1 + v_2 - v_3, -v_1 - v_2 + v_3\}$ ).