

LECTURE 15

Oct, 28/03

Last time:

Group G of motions $m: \mathbb{R}^n \rightarrow \mathbb{R}^n$,
which preserve $d(v, w) = \|v - w\|$
ie. $d(v, w) = d(m(v), m(w)) \quad \forall v, w$.

Have subgroup $\cong (\mathbb{R}^n, +)$ of
translations:

$$m = t_b(v) = v + b.$$

$$G = \mathbb{R}^n \cdot G_0$$

$$\left(\begin{array}{l} \uparrow \text{ motions which preserve } 0 \\ \text{Pf } m(0) = b \\ (t_{-b} \cdot m)(0) = 0. \end{array} \right)$$

$m \in G_0 \cong O(n)$ is the group of
orthog. trans.

To prove that this really is an isomorphism:

Preserves inner product: $\left\{ \begin{array}{l} \langle m(v), m(w) \rangle = \langle v, w \rangle \\ d(v, w)^2 = d(v, 0)^2 + d(w, 0)^2 - 2 \langle v, w \rangle \end{array} \right.$

Linearity:

Let e_1, \dots, e_n be the standard basis of \mathbb{R}^n
 $\langle e_i, e_i \rangle = 1$
 $\langle e_i, e_j \rangle = 0 \quad i \neq j.$

Then $m(e_1), \dots, m(e_n)$ is another orthonormal basis

Let A be the element in $O(n)$ with column vectors

Claim $m=A$ as a transf. of \mathbb{R}^n

$$\left[\begin{array}{c} A = \begin{pmatrix} m(e_1) & \dots & m(e_n) \\ \vdots & \dots & \vdots \end{pmatrix} \\ A^t A = I \end{array} \right]$$

Pf: Consider the motion

$$m \circ A^{-1} = m' \in G_0$$

$$m'(e_i) = e_i \quad \forall i$$

$$\text{Claim } m'(v) = v \quad \forall v \in \mathbb{R}^n$$

The i^{th} coord of $m'(v)$ is

$$\begin{aligned} \langle m'(v), e_i \rangle &= \langle m'(v), m'(e_i) \rangle \\ &= \langle v, e_i \rangle = v_i = i^{\text{th}} \text{ coord.} \end{aligned}$$

$$\text{Thus } m' = \text{id} \Rightarrow m = A$$



Note: In decomposition $G = \overset{G_0}{\mathbb{R}^n} \cdot O(n)$:

$$\begin{aligned}
 & (b, A) \cdot (b', A') (v) \\
 &= (b, A)(A'v + b') \\
 &= A(A'v + b') + b \\
 &= AA'(v) + (A(b') + b) \\
 &= (b + A(b'), AA')(v)
 \end{aligned}$$

So G is not product of $\mathbb{R}^n \cdot O(n)$, but a sort of twisted product.

$f: G \rightarrow O(n) \left\{ \begin{array}{l} \text{is a surjective hom} \\ (b, A) \mapsto A \end{array} \right.$ with kernel $\mathbb{R}^n \cong \{(b, I)\}$

$(b, I)(v) = v + b = t_b(v)$

normal subgroup.

We get a very rich theory ~~already~~ in the $n=2$ case:

$$G = \mathbb{R}^2 \cdot O(2)$$

$$G_0 = O(2) = SO(2) \cup \underbrace{SO(2)}_{\text{order 2}} \tau$$

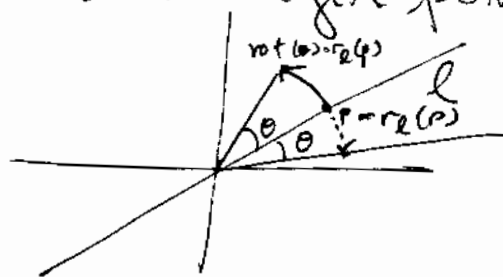
reflections across a line through the origin

$$r_l \circ \text{rot}(\theta) \circ r_l^{-1} = r_l \circ \text{rot}(\theta) \circ r_l$$

$$= \text{rot}(\theta') \quad \text{for some } \theta' \text{ since}$$

it is orientation-preserving and it fixes a point.

Thus to determine it, it suffices to figure out what happens to a non-origin point on l :



$$\text{so } \theta' = -\theta:$$

$$r_l \circ \text{rot}(\theta) \circ r_l^{-1} = \text{rot}(-\theta) = \text{rot}(\theta)^{-1}$$

So we have a nice description of $G_0 = O(2)$ in terms of $SO(2)$ & any fixed reflection.

Have map $G = \mathbb{R}^2 \cdot O(2) \rightarrow O(2) \xrightarrow{\det} \{\pm 1\}$
determining orientation.

Thus any $g \in G$ is one of 4 types, geometrically:

- $\det g = +1$
orientation-preserving

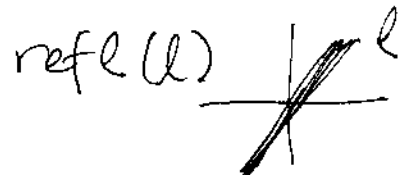
$$t_b \circ \text{rot}(\theta)$$

- \Rightarrow (i) translations t_b
fix no points
(or all pts if $b=0$)
- (ii) fix a single pt. p
& consist of rotations
around p

- $\det g = -1$
orientation-reversing

$$t_b \circ \text{rot}(\theta) \circ \text{ref}(l)$$

- \Rightarrow (iii) reflection in a line



- (iv) glide reflection
 $\text{ref}(l)(v) + b$;
fixes a line

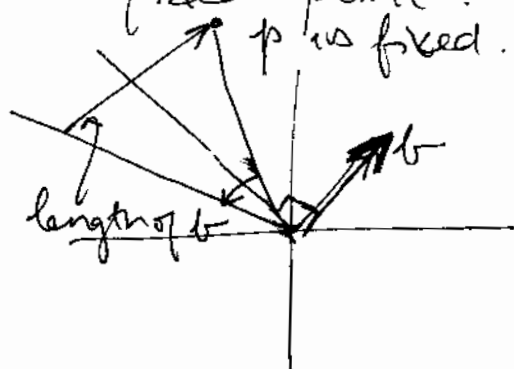
Breakdown of the cases:
(see textbook for details)

(i) is the case where $\theta = 0$

(ii) is the case where $\theta \neq 0$

If $b = 0$ then $p = 0$ and
in $G_0 = O(2)$ & since $\det = +1$,
is in $SO(2)$.

Assume $b \neq 0$. How do we find the
fixed point?



Can also see geometrically
that p is the only fixed pt.

(iii), (iv) similar geometric arguments

We now make a study of
finite subgroups of $G = \mathbb{R}^2 \cdot O(2)$:

Let T be a fin. subgrp.
• It contains no translations

Theorem T fixes a point $p \in \mathbb{R}^2$.
(i.e. there is $p \in \mathbb{R}^2$ s.t.
 $\gamma(p) = p$ for every $\gamma \in T$).

Abstract recipe for fixed pt. p :

Let $s \in \mathbb{R}^2$ be any vector

Consider the set of vectors
 $\{\gamma(s) : \gamma \in T\} \leftarrow$ finite set $\subset \mathbb{R}^2$

Let $n = \#T$

and set $p = \frac{1}{n} \sum_{\gamma \in T} \gamma(s)$.

Claim p is a fixed point.

If $g \in G$:
 $g(p) = \frac{1}{n} \sum_{\gamma} g\gamma(s)$

Then check separately for
 g a translation

& $g \in O(2)$ to

verify $\forall g \in G = \mathbb{R}^2 \cdot O(2)$
 $g(p) = p$

Note $T \subset G_p \subset G$

$$\parallel$$

$$\{g \in G \mid g(p) = p\}$$

$$\parallel$$

$$t_p G_0 t_p^{-1} \text{ a conjugate of } G_0.$$

$$\text{So : } t_p^{-1} T t_p \subset G_0 = O(2)$$

$$\parallel$$

$$T^* \text{ finite subgroup iso to } T.$$

Classify $T' \subset O(2)$
finite

① $T' \subset SO(2)$ ($\det = +1$)

② $T' \cap SO(2) = T'_+$ has index 2
in T' (normal subgroup)
($\det = \pm 1$)

In first case:

every $\gamma = \text{rot}(\theta)$ $0 \leq \theta \leq 2\pi$
let θ be the smallest angle of
rotation for $\gamma \in T'$ $\theta > 0$.

Then T' is a cyclic group,
generated by this element

If $|T'| = n$, $\theta = 2\pi/n$.

So for ①: every T' is cyclic
& all cyclic groups occur.

Have in second case,

no reflection, in $T' = T'_+$.

$T'_+ =$ case ① example, so is cyclic

$T' = \langle \text{rotation by } \frac{2\pi}{n} \text{ \& reflection} \rangle$
 \uparrow
dihedral group...