

# Naïve Bayes Classifier

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Machine Learning 10-701



MACHINE LEARNING DEPARTMENT



# Classification

**Goal:** Construct a **predictor**  $f : X \rightarrow Y$  to minimize a risk (performance measure)  $R(f)$



**Features, X**



Sports  
Science  
News

**Labels, Y**

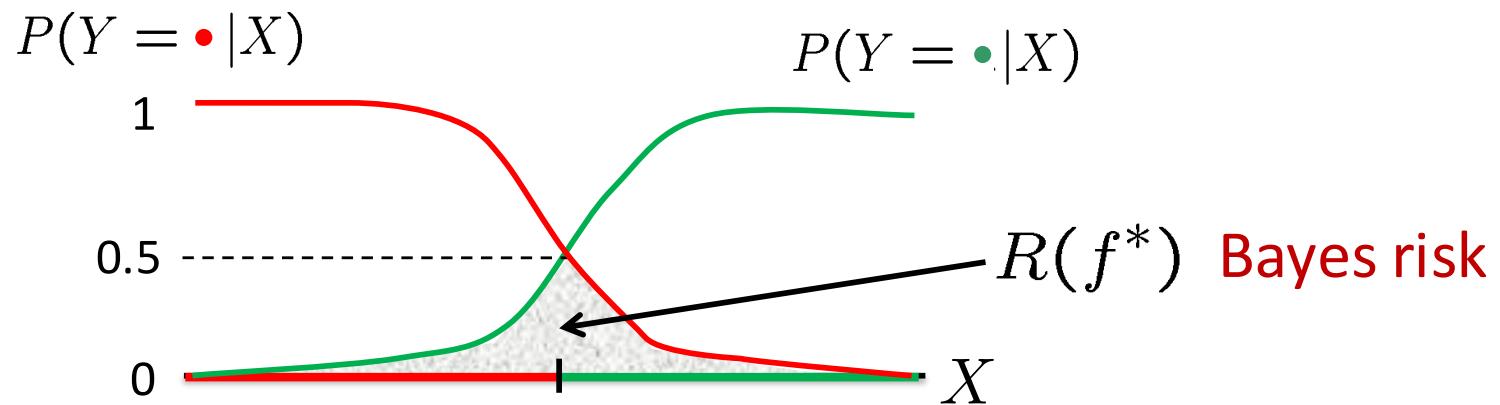
$$R(f) = P(f(X) \neq Y)$$

**Probability of Error**

# Optimal Classification

Optimal predictor:  
(Bayes classifier)

$$f^* = \arg \min_f P(f(X) \neq Y)$$



$$f^*(x) = \arg \max_{Y=y} P(Y = y | X = x)$$

- Even the optimal classifier makes mistakes  $R(f^*) > 0$
- Optimal classifier depends on **unknown** distribution  $P_{XY}$

# Optimal Classifier

**Bayes Rule:**  $P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)}$

$$P(Y = y|X = x) = \frac{P(X = x|Y = y)P(Y = y)}{P(X = x)}$$

**Optimal classifier:**

$$\begin{aligned} f^*(x) &= \arg \max_{Y=y} P(Y = y|X = x) \\ &= \arg \max_{Y=y} P(X = x|Y = y)P(Y = y) \end{aligned}$$


Class conditional      Class prior  
density

# Model based Approach

$$f^*(x) = \arg \max_{Y=y} P(X = x|Y = y)P(Y = y)$$

Class conditional      Class probability  
distribution

We can now consider appropriate models for the two terms

Class probability  $P(Y=y)$ , Class conditional distribution of features  $P(X=x|Y=y)$

Modeling Class probability  $P(Y=y) = \text{Bernoulli}(\theta)$

$$P(Y = \text{Red}) = \theta \quad P(Y = \text{Green}) = 1 - \theta$$

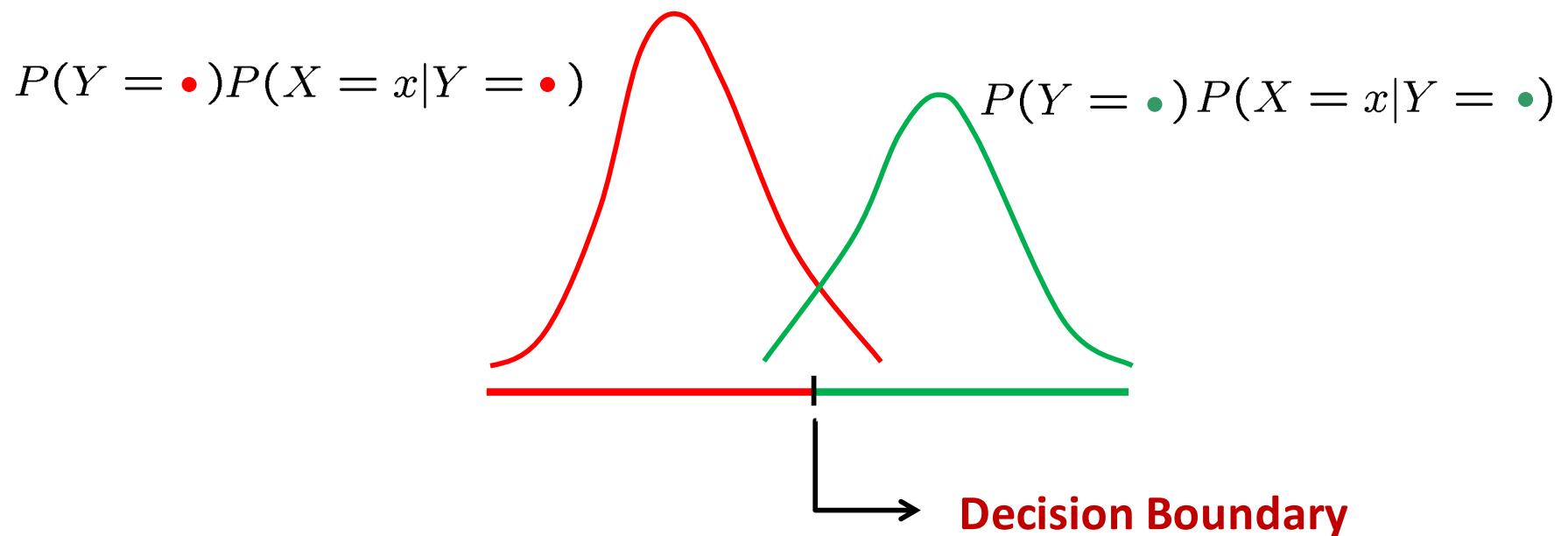
Like a coin flip



# Modeling Class Conditional Distribution of Features

- Gaussian class conditional densities (1-dimension/feature)

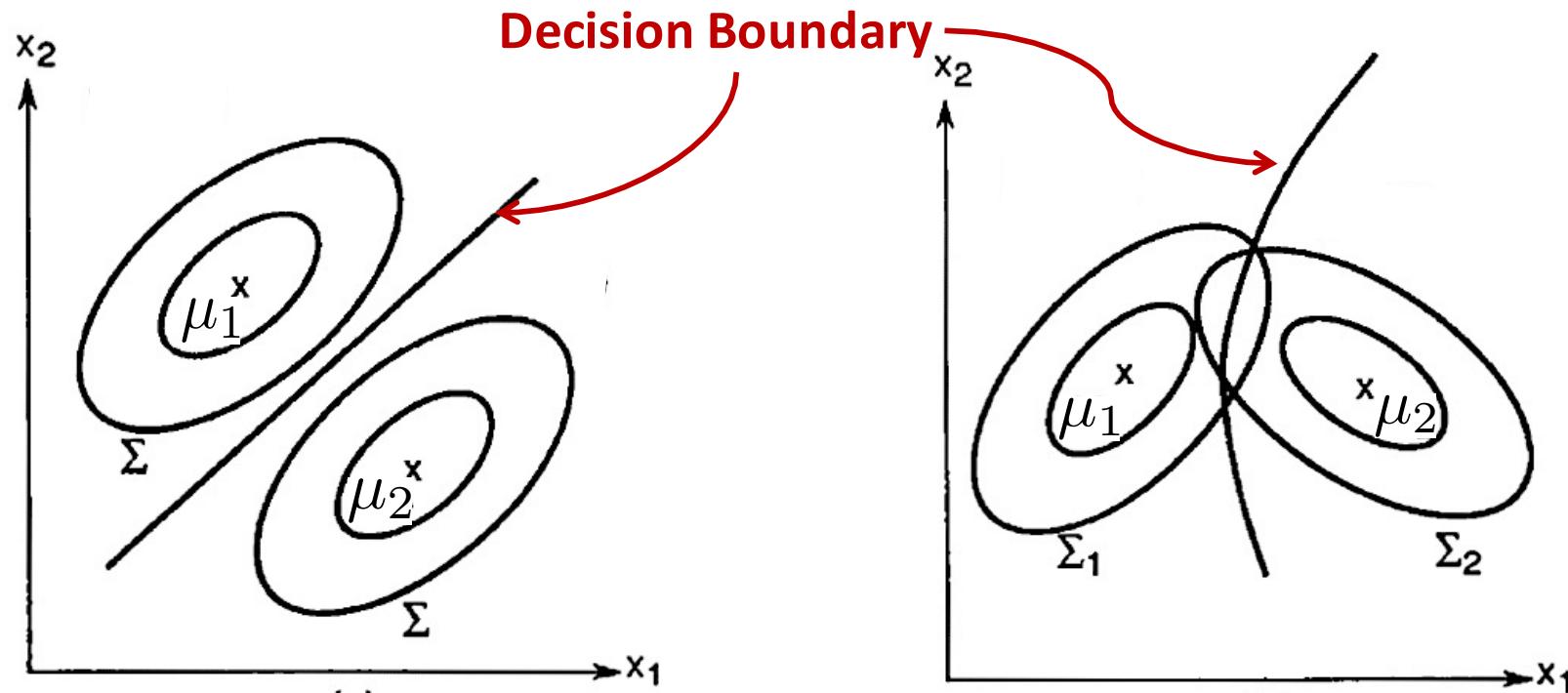
$$P(X = x|Y = y) = \frac{1}{\sqrt{2\pi\sigma_y^2}} \exp\left(-\frac{(x - \mu_y)^2}{2\sigma_y^2}\right)$$



# Modeling Class Conditional Distribution of Features

- Gaussian class conditional densities (2-dimensions/features)

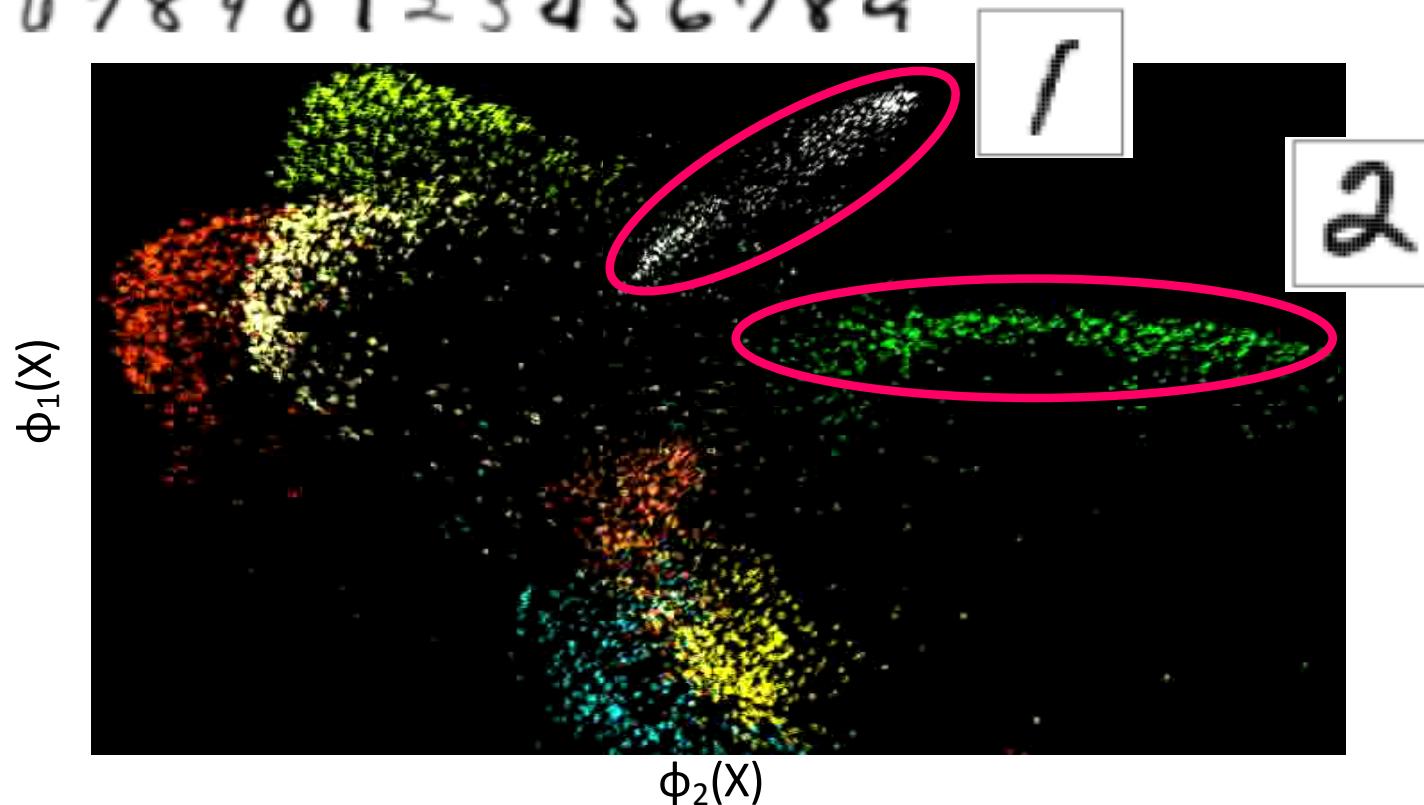
$$P(X = x|Y = y) = \frac{1}{\sqrt{2\pi|\Sigma_y|}} \exp\left(-\frac{(x - \mu_y)\Sigma_y^{-1}(x - \mu_y)'}{2}\right)$$



# Handwritten digit recognition

0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 1  
8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5  
6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3  
4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1  
2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9

Multi-class  
classification



Note: 8 digits shown out of 10 (0, 1, ..., 9);

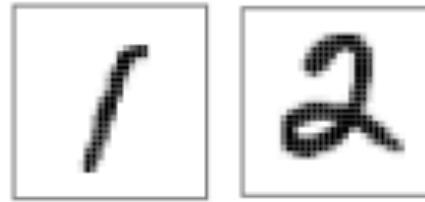
Axes are obtained by nonlinear dimensionality reduction (later in course)

# Handwritten digit recognition

## Training Data:

Each image represented as  
a vector of **intensity values**  
**at the d pixels (features)**

Input, X



... n greyscale  
images

$$X = \begin{bmatrix} X_1 \\ X_2 \\ \dots \\ X_d \end{bmatrix}$$

Label, Y

1      2

... n labels

## Gaussian Bayes model:

$P(Y = y) = p_y$  for all  $y$  in  $0, 1, 2, \dots, 9$

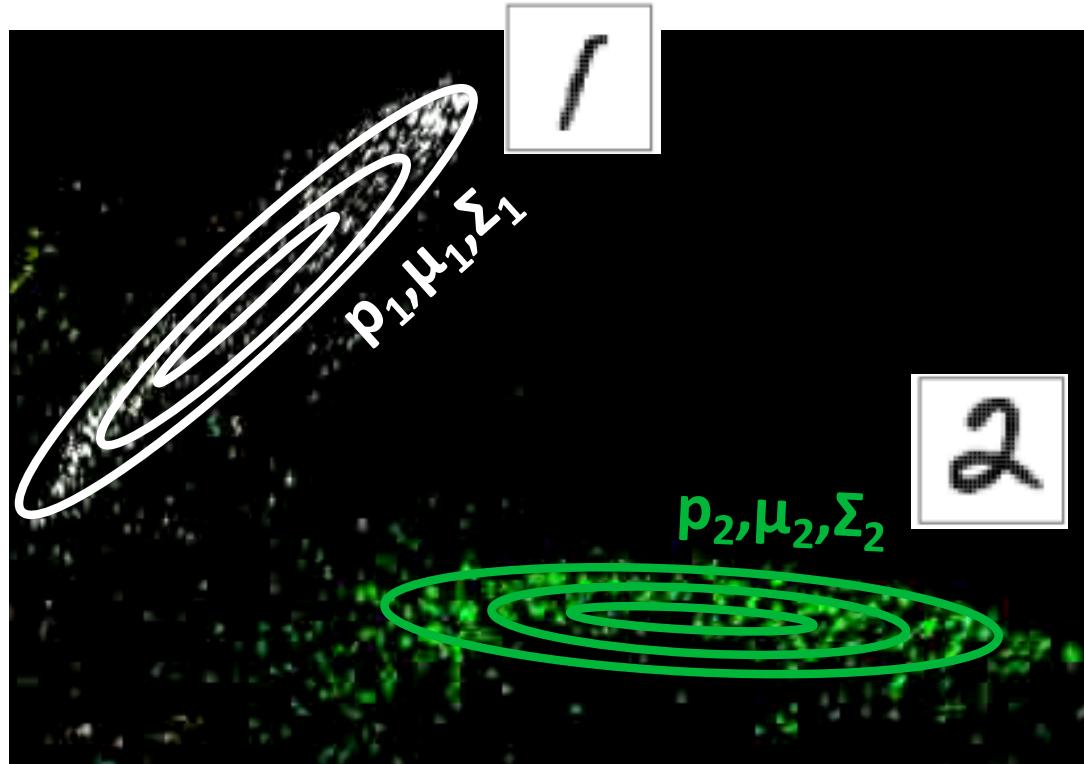
$p_0, p_1, \dots, p_9$  (sum to 1)

$P(X=x | Y = y) \sim N(\mu_y, \Sigma_y)$  for each  $y$

$\mu_y$  – d-dim vector

$\Sigma_y$  -  $d \times d$  matrix

# Gaussian Bayes classifier



$P(Y = y) = p_y$  for all  $y$  in  $0, 1, 2, \dots, 9$

$p_0, p_1, \dots, p_9$  (sum to 1)

$P(X=x | Y = y) \sim N(\mu_y, \Sigma_y)$  for each  $y$

$\mu_y$  – d-dim vector

$\Sigma_y$  -  $d \times d$  matrix

# Decision Boundary of Gaussian Bayes

- Binary classification with continuous features  
decision boundary is set of points  $x$ :  $P(Y=1|X=x) = P(Y=0|X=x)$

If class conditional feature distribution  $P(X=x|Y=y)$  is 2-dim Gaussian  $N(\mu_y, \Sigma_y)$

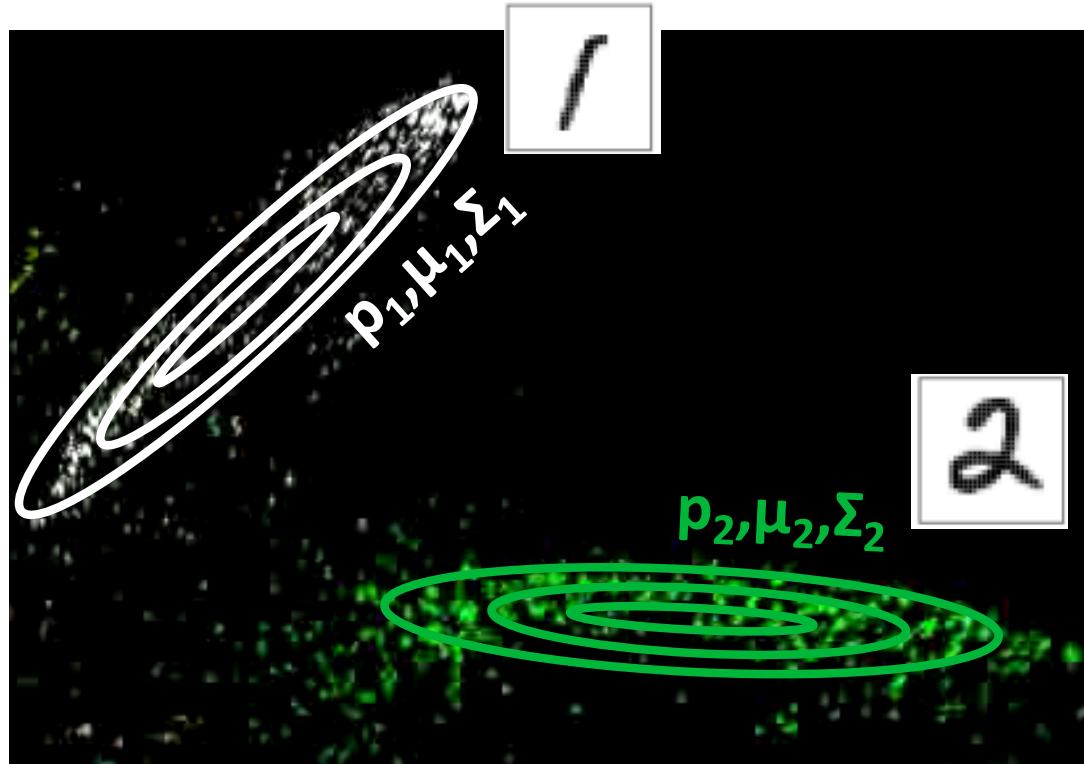
$$P(X = x|Y = y) = \frac{1}{\sqrt{(2\pi)^d |\Sigma_y|}} \exp\left(-\frac{(x - \mu_y)\Sigma_y^{-1}(x - \mu_y)'}{2}\right)$$

$$\begin{aligned} \frac{P(Y = 1|X = x)}{P(Y = 0|X = x)} &= \frac{P(X = x|Y = 1)P(Y = 1)}{P(X = x|Y = 0)P(Y = 0)} \\ &= \sqrt{\frac{|\Sigma_0|}{|\Sigma_1|}} \exp\left(-\frac{(x - \mu_1)\Sigma_1^{-1}(x - \mu_1)'}{2} + \frac{(x - \mu_0)\Sigma_0^{-1}(x - \mu_0)'}{2}\right) \frac{\theta}{1 - \theta} \end{aligned}$$

Note: In general, this implies a quadratic equation in  $x$ .

But if  $\Sigma_1 = \Sigma_0$ , then quadratic part cancels out and equation is linear.

# Gaussian Bayes classifier



How to learn parameters  
 $p_y, \mu_y, \Sigma_y$  from data?

$P(Y = y) = p_y$  for all  $y$  in  $0, 1, 2, \dots, 9$

$p_0, p_1, \dots, p_9$  (sum to 1)

$P(X=x | Y = y) \sim N(\mu_y, \Sigma_y)$  for each  $y$

$\mu_y$  – d-dim vector

$\Sigma_y$  -  $d \times d$  matrix

# How many parameters do we need to learn?

Class probability:

$$P(Y = y) = p_y \text{ for all } y \text{ in } 0, 1, 2, \dots, 9 \quad p_0, p_1, \dots, p_9 \text{ (sum to 1)}$$

**K-1 if K labels**

Class conditional distribution of features:

$$P(X=x | Y = y) \sim N(\mu_y, \Sigma_y) \text{ for each } y \quad \mu_y - d\text{-dim vector}$$
$$\Sigma_y - d \times d \text{ matrix}$$

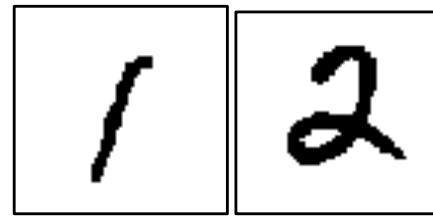
**$Kd + Kd(d+1)/2 = O(Kd^2)$  if d features**

**Quadratic in dimension d! If d = 256x256 pixels, ~ 21.5 billion parameters!**

# What about discrete features?

Training Data:

Input, X



... n black-white  
images

$$X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_d \end{bmatrix}$$

Label, Y

1      2

... n labels

Discrete Bayes model:

$$P(Y = y) = p_y \text{ for all } y \text{ in } 0, 1, 2, \dots, 9$$

$$p_0, p_1, \dots, p_9 \text{ (sum to 1)}$$

$P(X=x|Y=y)$  ~ For each label  $y$ , maintain probability table with  $2^d - 1$  entries

# How many parameters do we need to learn?

Class probability:

$$P(Y = y) = p_y \text{ for all } y \text{ in } 0, 1, 2, \dots, 9 \quad p_0, p_1, \dots, p_9 \text{ (sum to 1)}$$

**K-1 if K labels**

Class conditional distribution of features:

$P(X=x | Y = y) \sim$  For each label  $y$ , maintain probability table with  $2^d - 1$  entries

**$K(2^d - 1)$  if d binary features**

**Exponential in dimension d!**

# What's wrong with too many parameters?

- How many training data needed to learn one parameter (bias of a coin)?



- Need lots of training data to learn the parameters!
  - Training data > number of parameters

# Naïve Bayes Classifier

- Bayes Classifier with additional “naïve” assumption:

- Features are independent given class:

$$X = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$$

$$\begin{aligned} P(X_1, X_2|Y) &= P(X_1|X_2, Y)P(X_2|Y) \\ &= P(X_1|Y)P(X_2|Y) \end{aligned}$$

- More generally:

$$P(X_1 \dots X_d|Y) = \prod_{i=1}^d P(X_i|Y)$$

$$X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_d \end{bmatrix}$$

- If conditional independence assumption holds, NB is optimal classifier! But worse otherwise.

# Conditional Independence

- X is **conditionally independent** of Y given Z:  
probability distribution governing X is independent of the value of Y, given the value of Z

$$(\forall x, y, z)P(X = x | Y = y, Z = z) = P(X = x | Z = z)$$

- Equivalent to:

$$P(X, Y | Z) = P(X | Z)P(Y | Z)$$

- e.g.,  $P(Thunder | Rain, Lightning) = P(Thunder | Lightning)$

**Note:** does NOT mean Thunder is independent of Rain

# Conditional vs. Marginal Independence

**London taxi drivers:** A survey has pointed out a positive and significant correlation between the number of accidents and wearing coats. They concluded that coats could hinder movements of drivers and be the cause of accidents. A new law was prepared to prohibit drivers from wearing coats when driving.

# Conditional vs. Marginal Independence

**London taxi drivers:** A survey has pointed out a positive and significant correlation between the number of accidents and wearing coats. They concluded that coats could hinder movements of drivers and be the cause of accidents. A new law was prepared to prohibit drivers from wearing coats when driving.

Finally another study pointed out that people wear coats when it rains...

Wearing coats is independent of accidents conditioned on the fact that it rained

# Naïve Bayes Classifier

- Bayes Classifier with additional “naïve” assumption:
  - Features are independent given class:

$$P(X_1 \dots X_d | Y) = \prod_{i=1}^d P(X_i | Y)$$

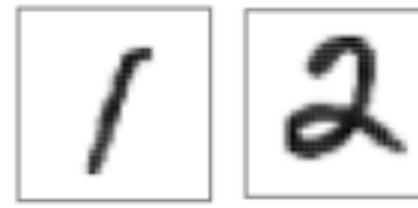
$$\begin{aligned} f_{NB}(\mathbf{x}) &= \arg \max_y P(x_1, \dots, x_d | y) P(y) \\ &= \arg \max_y \prod_{i=1}^d P(x_i | y) P(y) \end{aligned}$$

- How many parameters now?

# Handwritten digit recognition (continuous features)

Training Data:

$$\mathbf{X} = \begin{bmatrix} X_1 \\ X_2 \\ \dots \\ X_d \end{bmatrix}$$



... n greyscale  
images with  
d pixels

Y

1

2

... n labels

How many parameters?

Class probability  $P(Y = y) = p_y$  for all  $y$     **K-1 if K labels**

May not hold

Class conditional distribution of features (using Naïve Bayes assumption)

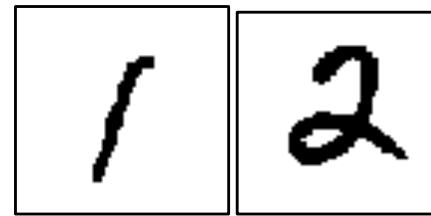
$P(X_i = x_i | Y = y) \sim N(\mu^{(y)}_i, \sigma^2_i)^{(y)}$  for each  $y$  and each pixel  $i$     **2Kd**

Linear instead of Quadratic in d!

# Handwritten digit recognition (discrete features)

Training Data:

$$\mathbf{X} = \begin{bmatrix} X_1 \\ X_2 \\ \dots \\ X_d \end{bmatrix}$$



... n black-white (1/0)  
images with  
d pixels

Y

1

2

... n labels

How many parameters?

Class probability  $P(Y = y) = p_y$  for all  $y$     **K-1 if K labels**

May not hold

Class conditional distribution of features (using Naïve Bayes assumption)

$P(X_i = x_i | Y = y)$  – one probability value for each  $y$ , pixel  $i$     **Kd**

**Linear instead of Exponential in d!**

# Naïve Bayes Classifier

- Bayes Classifier with additional “naïve” assumption:
  - Features are independent given class:

$$P(X_1 \dots X_d | Y) = \prod_{i=1}^d P(X_i | Y)$$

$$\begin{aligned} f_{NB}(\mathbf{x}) &= \arg \max_y P(x_1, \dots, x_d | y) P(y) \\ &= \arg \max_y \prod_{i=1}^d P(x_i | y) P(y) \end{aligned}$$

- Has fewer parameters, and hence requires fewer training data, even though assumption may be violated in practice

# Naïve Bayes Algo – Discrete features

- Training Data  $\{(X^{(j)}, Y^{(j)})\}_{j=1}^n \quad X^{(j)} = (X_1^{(j)}, \dots, X_d^{(j)})$
- Maximum Likelihood Estimates

- For Class probability

$$\hat{P}(y) = \frac{\{\#j : Y^{(j)} = y\}}{n}$$

- For class conditional distribution

$$\frac{\hat{P}(x_i, y)}{\hat{P}(y)} = \frac{\{\#j : X_i^{(j)} = x_i, Y^{(j)} = y\}/n}{\{\#j : Y^{(j)} = y\}/n}$$

- NB Prediction for test data  $X = (x_1, \dots, x_d)$

$$Y = \arg \max_y \hat{P}(y) \prod_{i=1}^d \frac{\hat{P}(x_i, y)}{\hat{P}(y)}$$

# Issues with Naïve Bayes

- **Issue 1:** Usually, features are not conditionally independent:

$$P(X_1 \dots X_d | Y) \neq \prod_i P(X_i | Y)$$

Nonetheless, NB is the single most used classifier particularly when data is limited, works well

- **Issue 2:** Typically use MAP estimates instead of MLE since insufficient data may cause MLE to be zero.

# Insufficient data for MLE

- What if you never see a training instance where  $X_1=a$  when  $Y=b$ ?
  - e.g.,  $b=\{\text{SpamEmail}\}$ ,  $a =\{\text{'Earn'}\}$
  - $P(X_1=a \mid Y=b) = 0$
- Thus, no matter what the values  $X_2, \dots, X_d$  take:

$$\widehat{P}(X_1 = a, X_2 \dots X_n | Y) = \widehat{P}(X_1 = a | Y) \prod_{i=2}^d \widehat{P}(X_i | Y) = 0$$

- What now???

# Naïve Bayes Algo – Discrete features

- Training Data  $\{(X^{(j)}, Y^{(j)})\}_{j=1}^n \quad X^{(j)} = (X_1^{(j)}, \dots, X_d^{(j)})$
- Maximum A Posteriori (MAP) Estimates – add m “virtual” datapts

Assume given some prior distribution (typically uniform):

$$Q(Y = b)$$

$$Q(X_i = a, Y = b)$$

$$\hat{P}(X_i = a | Y = b) = \frac{\#\{j : X_i^{(j)} = a, Y^{(j)} = b\} + mQ(X_i = a, Y = b)}{\#\{j : Y^{(j)} = b\} + mQ(Y = b)}$$

# virtual examples  
with  $Y = b$

Now, even if you never observe a class/feature posterior probability never zero.

# Case Study: Text Classification

- Classify e-mails
  - $Y = \{\text{Spam}, \text{NotSpam}\}$
- Classify news articles
  - $Y = \{\text{what is the topic of the article?}\}$
- Classify webpages
  - $Y = \{\text{Student, professor, project, ...}\}$
- What about the features  $X$ ?
  - The text!

# Bag of words approach

*the world of*

**TOTAL**



***all about the company***

Our energy exploration, production, and distribution operations span the globe, with activities in more than 100 countries.

At TOTAL, we draw our greatest strength from our fast-growing oil and gas reserves. Our strategic emphasis on natural gas provides a strong position in a rapidly expanding market.

Our expanding refining and marketing operations in Asia and the Mediterranean Rim complement already solid positions in Europe, Africa, and the U.S.

Our growing specialty chemicals sector adds balance and profit to the core energy business.

► All About The Company

- [Global Activities](#)
- [Corporate Structure](#)
- [TOTAL's Story](#)
- [Upstream Strategy](#)
- [Downstream Strategy](#)
- [Chemicals Strategy](#)
- [TOTAL Foundation](#)
- [Homepage](#)



aardvark	0
about	2
all	2
Africa	1
apple	0
anxious	0
...	
gas	1
...	
oil	1
...	
Zaire	0

# NB for Text Classification

- Features  $\mathbf{X}$  are the count of how many times each word in the vocabulary appears in document
- Probability table for  $P(\mathbf{X}|Y)$  is huge!!!
- NB assumption helps a lot!!!
- Bag of words + Naïve Bayes assumption imply  $P(\mathbf{X}|Y=y)$  is just the product of probability of each word, raised to its count, in a document on topic  $y$

$$h_{NB}(\mathbf{x}) = \arg \max_y P(y) \prod_{w=1}^W P(w|y)^{count_w}$$

# Bag of words model

- Typical additional assumption – **Position in document doesn't matter**
  - “Bag of words” model – order of words on the page ignored
  - Sounds really silly, but often works very well!

in is lecture lecture next over person remember room  
sitting the the to to up wake when you

# Bag of words model

- Typical additional assumption – **Position in document doesn't matter**
  - “Bag of words” model – order of words on the page ignored
  - Sounds really silly, but often works very well!

When the lecture is over, remember to wake up the person sitting next to you in the lecture room.

# NB with Bag of Words for text classification

- Learning phase:
  - Class Prior  $P(Y)$ : fraction of times topic Y appears in the collection of documents
  - $P(w|Y)$ : fraction of times word w appears in documents with topic Y
- Test phase:
  - For each document
    - Use Bag of words + naïve Bayes decision rule

$$h_{NB}(x) = \arg \max_y P(y) \prod_{w=1}^W P(w|y)^{count_w}$$

# Twenty news groups results

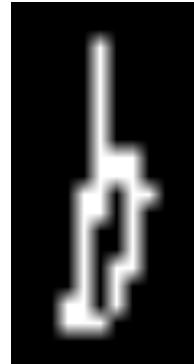
Given 1000 training documents from each group  
Learn to classify new documents according to  
which newsgroup it came from

comp.graphics	misc.forsale
comp.os.ms-windows.misc	rec.autos
comp.sys.ibm.pc.hardware	rec.motorcycles
comp.sys.mac.hardware	rec.sport.baseball
comp.windows.x	rec.sport.hockey
alt.atheism	sci.space
soc.religion.christian	sci.crypt
talk.religion.misc	sci.electronics
talk.politics.mideast	sci.med
talk.politics.misc	
talk.politics.guns	

Naive Bayes: 89% classification accuracy

# What if features are continuous?

Eg., character recognition:  $X_i$  is intensity at  $i^{\text{th}}$  pixel



Gaussian Naïve Bayes (GNB):

$$P(X_i = x \mid Y = y_k) = \frac{1}{\sigma_{ik}\sqrt{2\pi}} e^{\frac{-(x-\mu_{ik})^2}{2\sigma_{ik}^2}}$$

Different mean and variance for each class  $k$  and each pixel  $i$ .

Sometimes assume variance

- is independent of  $Y$  (i.e.,  $\sigma_i$ ),
- or independent of  $X_i$  (i.e.,  $\sigma_k$ )
- or both (i.e.,  $\sigma$ )

# Estimating parameters: Y discrete, X<sub>i</sub> continuous

Maximum likelihood estimates:

$$\hat{\mu}_{MLE} = \frac{1}{N} \sum_{j=1}^N x_j$$

$$\hat{\mu}_{ik} = \frac{1}{\sum_j \delta(Y^j = y_k)} \sum_j X_i^j \delta(Y^j = y_k)$$

← i<sup>th</sup> pixel in j<sup>th</sup> training image
→ k<sup>th</sup> class
→ j<sup>th</sup> training image

$$\hat{\sigma}_{unbiased}^2 = \frac{1}{N-1} \sum_{j=1}^N (x_j - \hat{\mu})^2$$

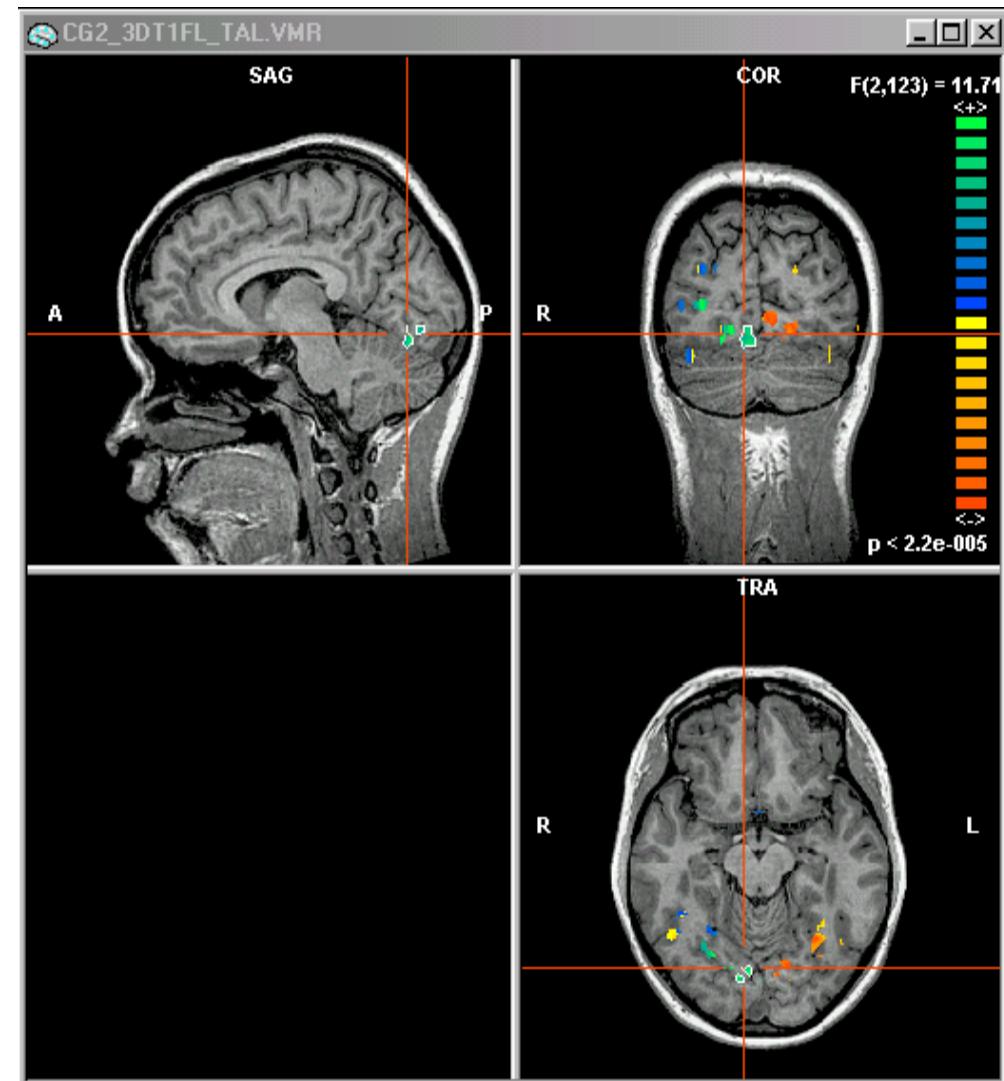
$$\hat{\sigma}_{ik}^2 = \frac{1}{\sum_j \delta(Y^j = y_k) - 1} \sum_j (X_i^j - \hat{\mu}_{ik})^2 \delta(Y^j = y_k)$$

# Example: GNB for classifying mental states

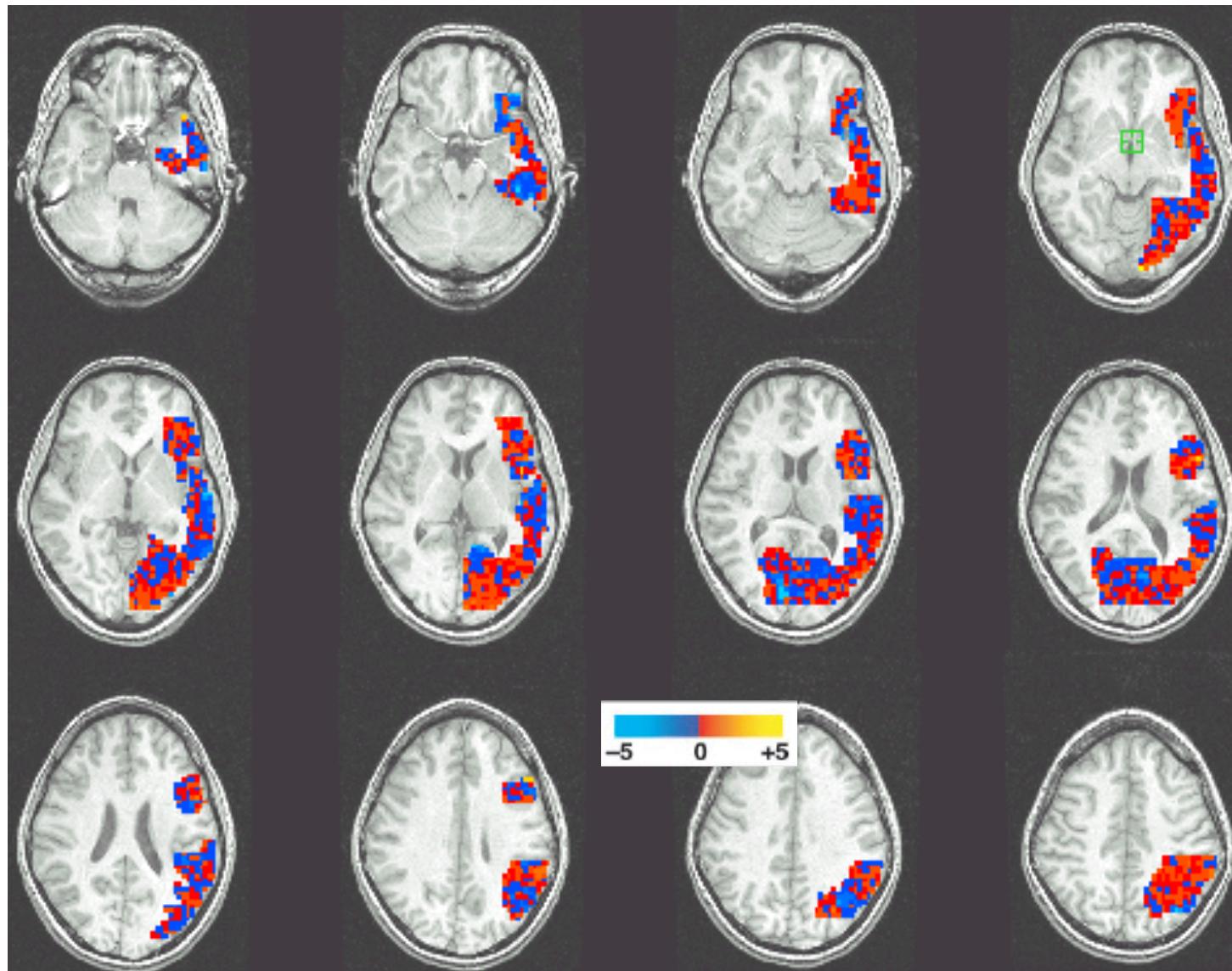
[Mitchell et al.]



- ~1 mm resolution
- ~2 images per sec.
- 15,000 voxels/image
- non-invasive, safe
- measures Blood Oxygen Level Dependent (BOLD) response



# Gaussian Naïve Bayes: Learned $\mu_{\text{voxel}, \text{word}}$



[Mitchell et al.]

15,000 voxels  
or features

10 training  
examples or  
subjects per  
class (12 word  
categories)

# Learned Naïve Bayes Models – Means for $P(\text{BrainActivity} \mid \text{WordCategory})$

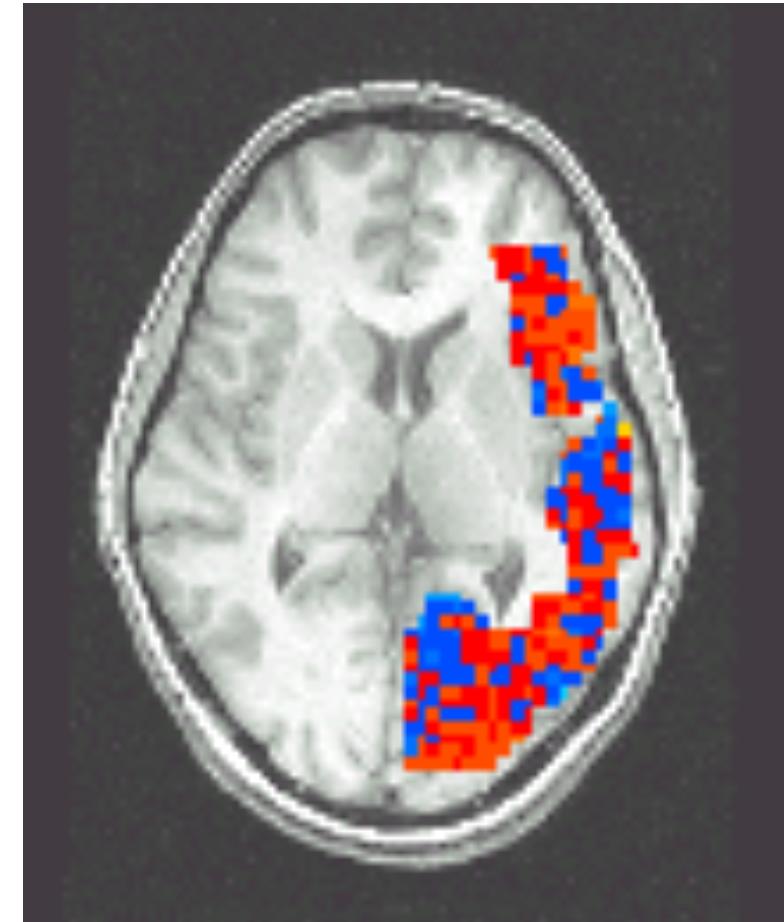
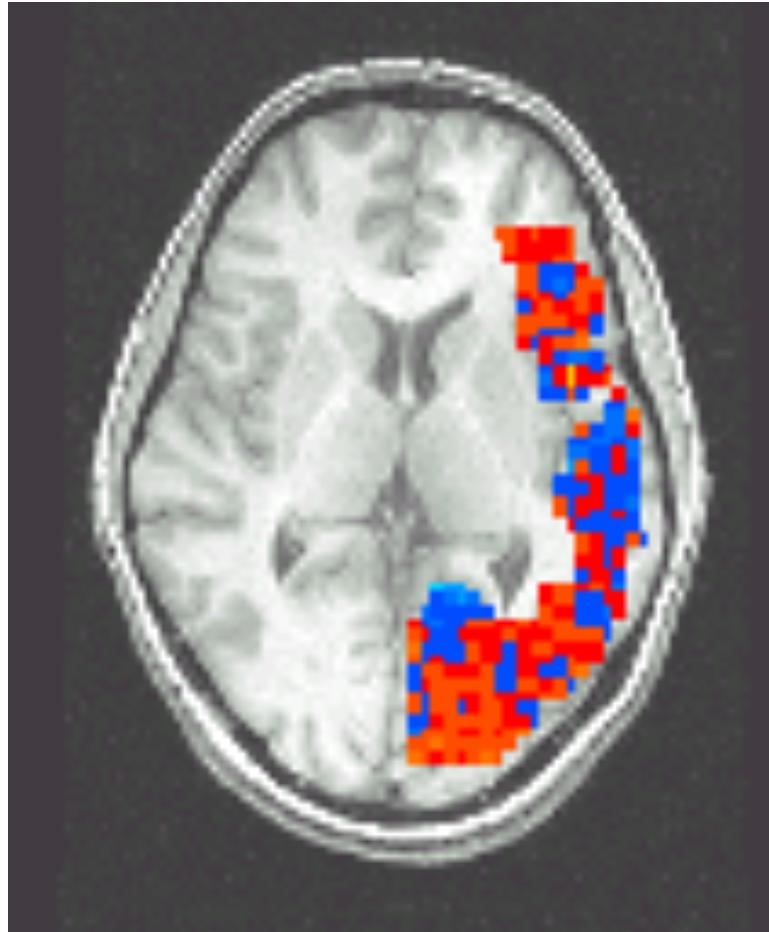
Pairwise classification accuracy: 85%

[Mitchell et al.]

People words



Animal words



# What you should know...

- Optimal decision using Bayes Classifier
- Naïve Bayes classifier
  - What's the assumption
  - Why we use it
  - How do we learn it
  - Why is MAP estimation important
- Text classification
  - Bag of words model
- Gaussian NB
  - Features are still conditionally independent
  - Each feature has a Gaussian distribution given class

# Gaussian Naïve Bayes vs. Logistic Regression

Set of Gaussian  
Naïve Bayes parameters  
(feature variance  
independent of class label)



Set of Logistic  
Regression parameters

- Representation equivalence (both yield linear decision boundaries)
  - **But only in a special case!!!** (GNB with class-independent variances)
  - **LR makes no assumptions about  $P(X | Y)$  in learning!!!**
  - **Optimize different functions (MLE/MCLE) or (MAP/MCAP)! Obtain different solutions**

# Discriminative vs Generative Classifiers

Optimal Classifier:

$$\begin{aligned} f^*(x) &= \arg \max_{Y=y} P(Y = y | X = x) \\ &= \arg \max_{Y=y} P(X = x | Y = y) P(Y = y) \end{aligned}$$

Generative (Model based) approach: e.g. Naïve Bayes

- Assume some probability model for  $P(Y)$  and  $P(X|Y)$
- Estimate parameters of probability models from training data

Discriminative (Model free) approach: e.g. Logistic regression

Why not learn  $P(Y|X)$  directly? Or better yet, why not learn the decision boundary directly?

- Assume some functional form for  $P(Y|X)$  or for the decision boundary
- Estimate parameters of functional form directly from training data