# AC6354B Datasheet

# Zhuhai Jieli Technology Co.,LTD

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# **AC6354B** Features

### **CPU**

- 32-bit DSP supports hardware Float Point Unit(FPU)
- Up to 240MHz programmable processor
- 64 Vectored interrupts
- 4 Levels interrupt priority

### **DSP Audio Processing**

- SBC, AAC Audio decodes supported for BT audio
- mSBC voice codecs supported for BT phone
- Supports MP2, MP3, WMA, APE, FLAC, AAC, MP4, M4A, WAV, AIF, AIFC audio decoding
- Packet Loss Concealment (PLC) for voice processing
- Acoustic echo cancellation/suppression (AEC,AES)
- Single/Dual MIC Environmental Noise Cancellation (ENC)
- Multi-band DRC limiter
- 30-band EQ configuration for voice Effects

### **Audio Codec**

- Two channels 16-bit DAC, SNR >= 92dB
- Three channels 16-bit ADC, SNR >= 90dB
- Sampling rates of 8KHz/11.025KHz/16KHz/22.05KHz/24KHz/32KHz/44.1KHz/48KHz are supported
- One analog MIC amplifier, build-in MIC bias generator
- Supports two PDM digital MIC inputs
- three channels Stereo analog MUX
- Supports cap-less, single-ended, and differential mode at the DAC path
- Supports 16ohm and 32ohm Speaker loading

### **Bluetooth**

- Compliant with Bluetooth
  V5.3+BR+EDR+BLE specification
- Meet class1 class2 and class3 transmitting

- power requirement
- Support GFSK and π/4 DQPSK all packet types
- Provides +6dbm transmitting power
- receiver with -90dBm sensitivity
- Fast AGC for enhanced dynamic range
- Supports a2dp\avctp\avdtp\avrcp\hfp\spp\smp\att\gap\ gatt\rfcomm\sdp\l2cap profile

## Peripherals

- One full speed USB 2.0 OTG controller
- Two PCM/IIS for external digital Audio code, supports host and device mode
- Four multi-function 16-bit timers, support capture and PWM mode
- Three 16-bit PWM generator for motor driving
- Three full-duplex basic UART, UART0 and UART1 supports DMA mode
- Three SPI interface supports host and device mode
- Two SD Card Host controller
- One hardware IIC interface supports host and device mode
- Four SPDIF receiving interface without analog amplify
- Supports HDMI ARC (Audio Return Channel) receiving
- Segment LCD panels
- Digital matrix LED panels
- Built-in Cap Sense Key controller
- 10-bit ADC for analog sampling
- External wake up/interrupt on all GPIOs

### **PMU**

- Low voltage LDO for internal digital and analog circuit supply
- 3uA current consumption in the soft-off mode
- Built-in LDO for the core, I/O, Bluetooth and flash

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### Confidential

- Built-in Li-Ion battery charger with up to 200mA charger current capability
- VBAT is 2.2V to 5.5V
- VDDIO is 2.2V to 3.6V

# Temperature

- Operating temperature: -40°C to +85°C
- Storage temperature: -65°C to +150°C

# **Applications**

Bluetooth Keyboard

### **Packages**

**QFN52(6mm\*6mm)** 

# 1. Pin Definition

# 1.1 Pin Assignment

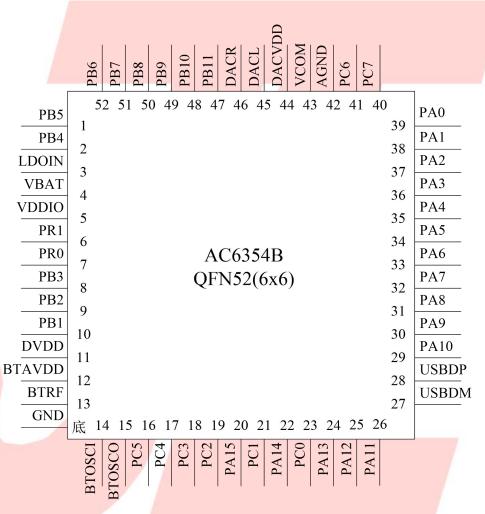


Figure 1-1 AC6354B\_QFN52 Package Diagram

# 1.2 Pin Description

Table 1-1 AC6354B\_QFN52 Pin Description

PIN	Name	I/O	Drive	Function	Other Function	
NO.	rvame	Туре	(mA)	Function	Other Function	
					SD1CMDB: SD1 Command(B);	
				CDIO	SD0DAT2B: SD1 Data2(B);	
,	DD 5	1/0	,	GPIO	PWM3: Timer3 PWM Output;	
1	PB5	I/O	/	(High Voltage	CAP1: Timer1 Capture;	
				Resistance)	UART0TXC: Uart0 Data Out(C);	
				A y	UARTORXC: Uarto Data In(C);	
				1	SD1DAT0B: SD1 Data0(B);	
					SD0DAT3B: SD0 Data3(B);	
					IIC_SCL_C: IIC SCL(C);	
2	PB4	I/O	24/8	GPIO	ADC7: ADC Input Channel 7;	
					UART0TXB: Uart0 Data Out(B);	
					LVD: Low Voltage Detect Input;	
					PWMCH2H: Motor PWM Channel2 (H);	
3	LDO_IN	P	/		Battery Charger Power In	
4	VBAT	P	/		Power Supply	
5	VDDIO	P	/		IO Power 3.3V	
6	PR1	I/O	8	GPIO	OSCO_32K: 32KHz OSC Out	
7	PR0	I/O	8	GPIO	OSCI_32K: 32KHz OSC In	
0	DD2	I/O	24/0	CDIO	PWM2: Timer2 PWM Output;	
8	PB3	I/O	24/8	GPIO	ADC6: ADC Input Channel 6;	
1			34	GPIO		
9	PB2	I/O	8	(High Voltage	PWMCH1L: Motor PWM Channel1 (L);	
				Resistance)		
_ <				GPIO	Long Press Reset;	
10	PB1	I/O	24/8	(pull up)	ADC5: ADC Input Channel 5;	
	>			(Pair ap)	UART1RXA: Uart1 Data In(A);	
11	DVDD	P	/		Core Power 1.2V	
12	BTAVDD	P	/		BT Power	
13	BTRF	/	/		BT Antenna	
14	BTOSCI	I	/		BT OSC In	
15	BTOSCO	О	/		BT OSC Out	

				<del></del>	
					SD1CLKA: SD1 Clock(A);
					SPI1DOB: SPI1 Data Out(B);
					UART2RXD: Uart2 Data In(D);
16	PC5	I/O	24/8	GPIO	IIC_SDA_B: IIC SDA(B);
					ADC13: ADC Input Channel 13;
					Touch15: Touch Input Channel 15;
		la la			PWMCH5L: Motor PWM Channel5(L);
					SD1CMDA: SD1 Command(A);
		1			SPI1CLKB: SPI1 Clock(B);
					UART2TXD: Uart2 Data Out(D);
17	PC4	I/O	24/8	GPIO	IIC SCL B: IIC SCL(B);
					ADC10: ADC Input Channel 10;
					Touch14: Touch Input Channel 14;
					PWMCH5H: Motor PWM Channel5(H);
					SD1DAT0A: SD1 Data0(A);
18	PC3	I/O	24/8	GPIO	SPI1DIB: SPI1 Data In(B); ALNK1 DAT1;
10	rc3	1/0	24/6	GFIO	Touch13: Touch Input Channel 13;
10	DC2	1/0	24/0	CNIC	SD1DAT1A: SD1 Data1(A); ALNK1_DAT0:
19	PC2	I/O	24/8	GPIO	Touch12: Touch Input Channel 12;
					FPIN5: Motor Auto-Stop Protective Pin5;
20	PA15	I/O	24/8	GPIO	CAP2: Timer2 Capture;
			1		SD1DAT2A: SD1 Data2(A);
21	PC1	I/O	24/8	GPIO	Touch11: Touch Input Channel 11;
21	101	1/0	24/0	GHO	UART1RXB: Uart1 Data In(B);
					FPIN4: Motor Auto-Stop Protective Pin4;
22	PA14	I/O	24/8	GPIO	FPIN0: Motor Auto-Stop Protective Pin0;
		A			SD1DAT3A: SD1 Data3(A);
22	P.CO	1/0	24/0	CDIO	Touch10: Touch Input Channel 10;
23	PC0	I/O	24/8	GPIO	UART1TXB: Uart1 Data Out(B);
V					FPIN3: Motor Auto-Stop Protective Pin3;
24	PA13	I/O	24/8	GPIO	
		200			PWM1: Timer1 PWM Output;
25	PA12	I/O	24/8	GPIO	ADC4: ADC Input Channel 4;
					UART0RXD: Uart0 Data In(D);
26	PA11	I/O	24/8	GPIO	UART0TXD: Uart0 Data Out(D);
				USB Negative	UART1RXD: Uart1 Data In(D);
27	USBDM	I/O	4	Data	SPI2DOB: SPI2 Data Out(B);
	ODDDIVI	10		(pull down)	IIC_SDA_A: IIC SDA(A);
				(puii dowii)	
				LICD Docition Dec	UART1TXD: Uart1 Data Out(D);
28	USBDP	I/O	4	USB Positive Data	SPI2CLKB: SPI2 Clock(B);
				(pull down)	IIC_SCL_A: IIC SCL(A);
					ADC12: ADC Input Channel 12;

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		SD0CLKA: SD0 Clock(A); ADC3: ADC Input Channel 3;
		TMR1: Timer1 Clock Input;
29 PA10 I/O 24/8 0	GPIO	Touch9: Touch Input Channel 9;
		UART2RXB: Uart2 Data In(B);
		PWMCH4L: Motor PWM Channel4(L);
		SD0CMA: SD0 Command(A);
		Touch8: Touch Input Channel 8;
30 PA9 I/O 24/8 0	GPIO	UART2TXB: Uart2 Data Out(B);
		PWMCH4H: Motor PWM Channel4(H);
	N .	SD0DAT3A: SD0 Data3(A);
31 PA8 I/O 24/8 0	GPIO	FPIN2: Motor Auto-Stop Protective Pin2;
		SD0DAT2A: SD0 Data2(A);
32 PA7 I/O 24/8 G	GPIO	TMR0: Timer0 Clock Input;
32 11 17 10 24/6	GI IO	Touch7: Touch Input Channel 7;
		SD0DAT1A: SD0 Data1(A);
		ADC2: ADC Input Channel 2;
33 PA6 I/O 24/8	GPIO	IIC SDA D: IIC SDA(D);
33 FA0 1/O 24/8	GFIO	Touch6: Touch Input Channel 6;
	7.7	UARTORXA: Uarto Data In(A);
		SD0DAT0A: SD0 Data0(A);
	- V A	ADC1: ADC Input Channel 1;
34 PA5 I/O 24/8 0	GPIO	IIC_SCL_D: IIC SCL(D);
		Touch5: Touch Input Channel 5; PWM0: Timer0 PWM Output;
		UARTOTXA: Uarto Data Out(A);
25 PAA 1/0 24/9	CNIO	
35 PA4 I/O 24/8 (	GPIO	Touch4: Touch Input Channel 4;
36 PA3 I/O 24/8	GPIO	Touch3: Touch Input Channel 3;
		UART2RXA: Uart2 Data In(A);
		Touch2: Touch Input Channel 2;
37 PA2 I/O 24/8	GPIO	UART2TXA: Uart2 Data Out(A);
		CAP3: Timer3 Capture;
		Touch1: Touch Input Channel 1;
38 PA1 I/O 24/8	GPIO	ADC0: ADC Input Channel 0;
1 30   1/A1   1/O   24/6   1		
30 JAI 1/0 24/8		UART1RXC: Uart1 Data In(C);
1/O 24/8		PWMCH0L: Motor PWM Channel0(L);
1/O 24/8		PWMCH0L: Motor PWM Channel0(L);  Touch0: Touch Input Channel 0;
	GPIO	PWMCH0L: Motor PWM Channel0(L);  Touch0: Touch Input Channel 0;  CLKOUT0:
	GPIO	PWMCH0L: Motor PWM Channel0(L);  Touch0: Touch Input Channel 0;  CLKOUT0:  UART1TXC: Uart1 Data Out(C);
39 PA0 I/O 24/8 (		PWMCH0L: Motor PWM Channel0(L);  Touch0: Touch Input Channel 0;  CLKOUT0:
39 PA0 I/O 24/8 0 40 PC7 I/O /	GPIO GPIO	PWMCH0L: Motor PWM Channel0(L);  Touch0: Touch Input Channel 0;  CLKOUT0:  UART1TXC: Uart1 Data Out(C);

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42	AGND	P	,	Ground for audio DAC	
42	AGND	Р	/	logic	
43	VCOM			DAC Reference	
4.4	D A CIVIDID			Power for audio DAC	
44	DACVDD			logic	
45	DACL	О	/	DAC Left Channel	
46	DACR	О	/	DAC Right Channel	
47	PB11	I/O	/	GPIO	SDPG:SDC Power Gate;
					SD0CMB: SD0 Command(B);
	1	1			SPI2DOA: SPI2 Data Out(A);
48	PB10	I/O	24/8	GPIO	SD1DAT3B: SD1 Data3(B);
48	PBIU	1/0	24/8	GPIO	ADC9: ADC Input Channel 9;
					UART2RXC: Uart2 Data In(C);
				A	PWMCH3L: Motor PWM Channel3(L);
					SD0 Clock(B);
			/	/ /	SPI2CLKA: SPI2 Clk(A);
			_ A		SD1DAT2B: SD1 Data2(B);
49	PB9	I/O	24/8	GPIO	CAP0: Timer0 Capture;
			1	y /	UART2TXC: Uart2 Data Out(C);
					PWMCH3H: Motor PWM Channel3(H);
				7/	SD0DAT0B: SD0 Data0(B);
					SPI2_DIA: SPI2 Data In(A);
50	PB8	I/O	24/8	GPIO	SD1DAT1B: SD1 Data1(B);
					ADC8: ADC Input Channel 8;
					CLKOUT1: Clk Out1;
51	PB7	I/O	24/8	GPIO	
		1		7 /	SD1CLKB: SD1 Clock(B);
				/- /	SD0DAT1B: SD0 Data1(B);
	ND.	1/0	2410	GN/O	IIC_SDA_C: IIC SDA(C);
52	PB6	I/O	24/8	GPIO	TMR3: Timer3 Clock Input;
					UART0RXB: Uart0 Data In(B);
4					PWMCH2L: Motor PWM Channel2 (L);
1	Substrate	GND	-	Substrate	
	Substrate	GND	-	Substrate	PWMCH2L: Motor PWM Channel2 (L);

# 2, Electrical Characteristics

# 2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Tamb	Operating Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	5.5	V
LDO_IN	Charger Voltage	-0.3	6	V
V <sub>3.3IO</sub>	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

# 2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
VBAT	Voltage Input	2.2	3.7	5.5	V	
LDO_IN	Charger Voltage	4.5	5.0	5.5	V	
V <sub>3.3</sub>	Voltage output	2.2	3.0	3.4	V	VBAT = 3.7V, 100mA loading
V <sub>BT_AVDD</sub>	Voltage output	1.2	1.25	1.35	V	VBAT=3.7V, 100mA loading
I <sub>L3.3</sub>	Loading current	_	_/	150	mA	VBAT = 3.7V

# 2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input ch	IO input characteristics										
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions					
$\dot{V}_{\mathrm{IL}}$	Low-Level Input Voltage	-0.3	_	0.3* VDDIO	V	VDDIO = 3.0V					
$V_{ m IH}$	High-Level Input Voltage	0.7* VDDIO	_	VDDIO+0.3	V	VDDIO = 3.0V					
IO output c	haracteristics										
V <sub>OL</sub>	Low-Level Output Voltage	_	_	0.33	V	VDDIO = 3.0V					
$V_{ m OH}$	High-Level Output Voltage	2.7	-	_	V	VDDIO = 3.0V					

# 2.4 Internal Resistor Characteristics

Table 2-4

]	Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment
PB PB	0~PA15 PB1, 3, PB4, 5~PB10 0~PC5	8mA	24mA	10K	10K	1、PB1 default pull up 2、USBDM & USBDP
PB11 PC7	Output0 Output1	8mA	24mA 64mA	10K	10K	default pull down 3、PB0, PB2, PB5 can pull-up resistance to 5V
PB0,	PB2, PB5	8mA	/_	10K	10K	4 internal pull-up/pull-down
PR	0-PR1	8mA	/ _	10K	10K	resistance   accuracy ±20%
USBDP		4mA	<b>/</b> -	1.5K	15K	±2070
U	SBDM	4mA	_	180K	15K	

# 2.5 DAC Characteristics

Table 2-5

Parameter	Min	Тур	Max	Unit	Test Conditions
Frequency Response	20	/ /-	20K	Hz	
THD+N	_	-75	_	dB	1KHz/0dB
S/N	_	92	_ :	dB	10Kohm loading
Crosstalk	_ /	-80	_	dB	With A-Weighted Filter
Output Swing	_3/4	1	-	Vrms	
					1KHz/-60dB
Dynamic Range	_ /	90	_	dB	10Kohm loading
					With A-Weighted Filter
DAC Output Power	11	_	_	mW	32ohm loading

# 2.6 ADC Characteristics

Table 2-6

Parameter	Min	Тур	Max	Unit	Test Conditions
Dynamic Range	_	80	_	dB	1KHz/-60dB
S/N	_	90	91	dB	
THD+N	_	-70	_	dB	1KHz/-60dB
Crosstalk	_	-80	_	dB	

# 2.7 BT Characteristics

## 2.7.1 Transmitter

### **Basic Data Rate**

**Table 2-7** 

Paramete	Parameter			Max	Unit	Test Conditions
RF Transmit P	RF Transmit Power		4	6	dBm	
RF Power Control Range			20		dB	25°C,
20dB Bandw	20dB Bandwidth		950		KHz	Power Supply
	+2MHz		-40		dBm	
Adjacent Channel	-2MHz		-38		dBm	VBAT=3.7V
Transmit Power +3MHz			-44	7.7	dBm	2441MHz
	-3MHz	- /	-35	7./	dBm	

## **Enhanced Data Rate**

Table 2-8

Paramete	Min	Тур	Max	Unit	<b>Test Conditions</b>	
Relative Po	wer		-1		dB	
π/4 DQPSK	DEVM RMS		6		%	
1/4 DQI 3K	DEVM 99%		10		%	25°C,
Modulation Accuracy	DEVM Peak		15		%	Power Supply
	+2MHz	- V	-40		dBm	VBAT=3.7V
Adjacent Channel	-2MHz		-38		dBm	2441MHz
Transmit Power	+3MHz		-44		dBm	
	-3MHz		-35		dBm	

## 2.7.2 Receiver

## **Basic Data Rate**

Table 2-9

Parameter		Min	Тур	Max	Unit	Test Conditions
Sensitivity			-90		dBm	
Co-channel Interference Rejection			-13		dB	
	+1MHz		+5		dB	25°C,
	-1MHz		+2		dB	Power Supply
Adjacent Channel	+2MHz		+37		dB	VBAT=3.7V
Interference Rejection	-2MHz		+36		dB	2441MHz
	+3MHz		+40		dB	
	-3MHz		+35		dB	

**Table 2-10** 

Parameter		Min	Тур	Max	Unit	Test Conditions
Sensitivity			-90		dBm	
Co-channel Interference Rejection			-13		dB	
	+1MHz		+5		dB	25°C,
	-1MHz		+2		dB	Power Supply
Adjacent Channel	+2MHz		+37		dB	VBAT=3.7V
Interference Rejection	-2MHz		+36		dB	2441MHz
1	+3MHz		+40		dB	
	-3MHz		+35		dB	

# 3. Package Information

# 3.1 QFN52(6mm\*6mm)

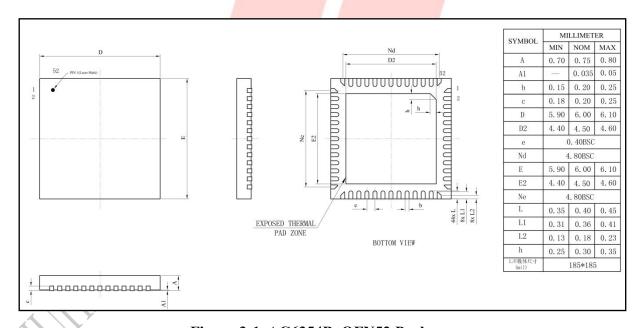


Figure 3-1. AC6354B\_QFN52 Package

# 4. Revision History

Date	Revision	Description		
2021.06.02	V1.0	Initial Release		
2022.07.19	V1.1	Update Bluetooth Feature		

