AC6951D Datasheet

Zhuhai Jieli Technology Co.,LTD

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AC6951D Features

CPU

- 32-bit DSP supports hardware Float Point Unit(FPU)
- Up to 240MHz programmable processor
- 64Vectored interrupts
- 4 Levels interrupt priority

Bluetooth

- Compliant with BluetoothV5.1+BR+EDR+BLE specification
- Meet class1 class2 and class3 transmitting power requirement
- Support GFSK and π/4 DQPSK all paket types
- Provides +6dbm transmitting power
- receiver with -90dBm sensitivity
- Fast AGC for enhanced dynamic range
- Supports a2dp\avctp\avdtp\avrcp\hfp\spp\smp\att\gap\g att\rfcomm\sdp\l2cap profile

Peripherals

- One full speed USB 2.0 OTG controller
- Four multi-function 16-bit timers, support capture and PWM mode
- Three 16-bit PWM generator for motor driving
- Three full-duplex basic UART, UART0 and UART1 supports DMA mode

- Three SPI interface supports host and device mode
- Two SD Card Host controller
- One hardwareIIC interface supports host and device mode
- Built-in Cap Sense Key controller
- 14 channels 10-bit ADC for analog sampling
- External wake up/interrupt on all GPIOs

PMU

- Low voltage LDO for internal digital and analog circuit supply
- **3uA** current consumption in the soft-off mode
- Built-in LDO for the core, I/O, Bluetooth and flash
- Built-inLi-Ion battery charger with up to 200mA charger current capability
- **VBAT** is 2.2V to 5.5V
- VDDIO is 2.2V to 3.6V

Packages

LQFP48(7mm*7mm)

Temperature

- Operating temperature: -40° C to $+85^{\circ}$ C
- Storage temperature: -65 °C to +150 °C

Applications

Bluetooth Keyboard

1. Pin Definition

1.1 Pin Assignment

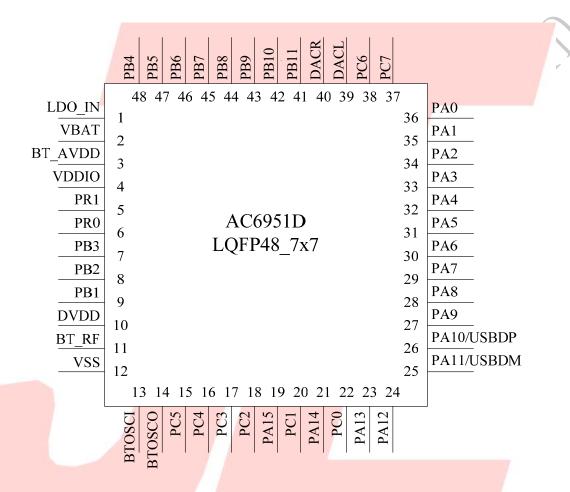


Figure 1-1 AC6951D_LQFP48 Package Diagram

1.2 Pin Description

Table 1-1 AC6951D_LQFP48 Pin Description

PIN	Name	I/O	Drive	Function	Other Function
NO.		Туре	(mA)		
1	LDO_IN	P	/		Battery Charger Power In
2	VBAT	P	/		Power Supply
3	BT_AVDD	P	/	1	BT Power
4	VDDIO	P	/	4	IO Power 3.3v
5	PR1	I/O	8	GPIO	OSCO_32K: 32KHz OSC Out
6	PR0	I/O	8	GPIO	OSCI_32K: 32KHz OSC In
7	DD2	1/0	24/9	CDIO	PWM2: Timer2 PWM Output;
/	PB3	I/O	24/8	GPIO	ADC6: ADC Input Channel 6;
				GPIO	
8	PB2	I/O	8	(High Voltage	PWMCH1L: Motor PWM Channel1 (L);
				Resistance)	
			/	GPIO	Long Press Reset;
9	PB1	I/O	24/8	(pull up)	ADC5: ADC Input Channel 5;
					UART1RXA: Uart1 Data In(A);
10	DVDD	P	/	7 /	Core Power 1.2V
11	BT_RF	/	/	/ /	BTAntenna
12	VSS	P	/	1.1	Ground
13	BT_OSCI	I	/		BT OSC In
14	BT_OSCO	О	1	A	BT OSC Out
\				A	SD1CLKA: SD1 Clock(A);
					SPI1DOB: SPI1 Data Out(B);
					UART2RXD: Uart2 Data In(D);
15	PC5	I/O	24/8	GPIO	IIC_SDA_B: IIC SDA(B);
					ADC13: ADC Input Channel 13;
	Y				Touch15: Touch Input Channel 15;
					PWMCH5L: Motor PWM Channel5(L);
					SD1CMDA: SD1 Command(A);
					SPI1CLKB: SPI1 Clock(B);
					UART2TXD: Uart2 Data Out(D);
16	PC4	I/O	24/8	GPIO	IIC_SCL_B: IIC SCL(B);
					ADC10: ADC Input Channel 10;
					Touch14: Touch Input Channel 14;
					PWMCH5H: Motor PWM Channel5(H);

					SD1DAT0A: SD1 Data0(A);
17	PC3	I/O	24/8	GPIO	SPI1DIB: SPI1 Data In(B); ALNK1_DAT1:
					Touch13: Touch Input Channel 13;
					SD1DAT1A: SD1 Data1(A); ALNK1_DAT0:
18	PC2	I/O	24/8	GPIO	Touch12: Touch Input Channel 12;
					FPIN5: Motor Auto-Stop Protective Pin5;
19	PA15	I/O	24/8	GPIO	CAP2: Timer2 Capture;
					SD1DAT2A: SD1 Data2(A);
•	n.c.	*10	2.4.10	anvo	Touch11: Touch Input Channel 11;
20	PC1	I/O	24/8	GPIO	UART1RXB: Uart1 Data In(B);
				7	FPIN4: Motor Auto-Stop Protective Pin4;
21	PA14	I/O	24/8	GPIO	FPINO: Motor Auto-Stop Protective PinO;
-					SD1DAT3A: SD1 Data3(A);
				1	Touch10: Touch Input Channel 10;
22	PC0	I/O	24/8	GPIO	UARTITXB: Uartl Data Out(B);
					FPIN3: Motor Auto-Stop Protective Pin3;
23	PA13	I/O	24/8	GPIO	
					PWM1: Timer1 PWM Output;
24	PA12	I/O	24/8	GPIO	ADC4: ADC Input Channel 4;
					UARTORXD: Uarto Data In(D);
	PA11	I/O	24/8	GPIO	UARTOTXD: Uart0 Data Out(D);
				USB Negative	UART1RXD: Uart1 Data In(D);
25	USBDM	I/O	4	Data	SPI2DOB: SPI2 Data Out(B);
		/		(pull down)	IIC SDA A: IIC SDA(A);
					SD0CLKA: SD0 Clock(A);
				/-/	ADC3: ADC Input Channel 3;
1					TMR1: Timer1 Clock Input;
	PA10	I/O	24/8	GPIO	Touch9: Touch Input Channel 9;
V					UART2RXB: Uart2 Data In(B);
26					PWMCH4L: Motor PWM Channel4(L);
				High 5	UART1TXD: Uart1 Data Out(D);
	than a	1/0		USB Positive	SPI2CLKB: SPI2 Clock(B);
	USBDP	I/O	4	Data	IIC_SCL_A: IIC SCL(A);
	1			(pull down)	ADC12: ADC Input Channel 12;
	*				SD0CMA: SD0 Command(A);
27	DAO	1/0	24/0	CDIO	Touch8: Touch Input Channel 8;
27	PA9	I/O	24/8	GPIO	UART2TXB: Uart2 Data Out(B);
					PWMCH4H: Motor PWM Channel4(H);
20	DAG	1/0	24/0	CDIO	SD0DAT3A: SD0 Data3(A);
28	PA8	I/O	24/8	GPIO	FPIN2: Motor Auto-Stop Protective Pin2;
				•	•

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29	PA7	I/O	24/8	GPIO	SD0DAT2A: SD0 Data2(A); TMR0: Timer0 Clock Input;
					Touch7: Touch Input Channel 7;
					SD0DAT1A: SD0 Data1(A);
					ADC2: ADC Input Channel 2;
30	PA6	I/O	24/8	GPIO	IIC_SDA_D: IIC SDA(D);
					Touch6: Touch Input Channel 6;
					UART0RXA: Uart0 Data In(A);
					SD0DAT0A: SD0 Data0(A);
					ADC1: ADC Input Channel 1;
2.1	D A 5	I/O	24/9	CDIO	IIC_SCL_D: IIC SCL(D);
31	PA5	1/0	24/8	GPIO	Touch5: Touch Input Channel 5;
				4	PWM0: Timer0 PWM Output;
			7	1	UART0TXA: Uart0 Data Out(A);
32	PA4	I/O	24/8	GPIO	Touch4: Touch Input Channel 4;
22	DA2	1/0	24/0	CDIO	Touch3: Touch Input Channel 3;
33	PA3	I/O	24/8	GPIO	UART2RXA: Uart2 Data In(A);
				7.7	Touch2: Touch Input Channel 2;
34	PA2	I/O	24/8	GPIO	UART2TXA: Uart2 Data Out(A);
					CAP3: Timer3 Capture;
			1	- / A	Touch1: Touch Input Channel 1;
35	D A 1	I/O	24/8	GPIO	ADC0: ADC Input Channel 0;
33	PA1	1/0	24/8	GPIO	UART1RXC: Uart1 Data In(C);
				7.	PWMCH0L: Motor PWM Channel0(L);
1				1/	Touch0: Touch Input Channel 0;
36	PA0	I/O	24/8	GPIO	CLKOUT0:
30	rAU	1/0	24/0	GFIO	UART1TXC: Uart1 Data Out(C);
			J.		PWMCH0H: Motor PWM Channel0(H);
37	PC7	I/O	1	GPIO	
38	PC6	I/O	1	GPIO	ADC11: ADC Input Channel 11;
39	DACL	0	/		DAC Left Channel
40	DACR	0	/		DACRight Channel
41	PB11	I/O	/	GPIO	SDPG:SDC Power Gate;
	7				SD0CMB: SD0 Command(B);
					SPI2DOA: SPI2 Data Out(A);
42	PB10	I/O	24/0	GPIO	SD1DAT3B: SD1 Data3(B);
42	1 DIV	1/0	24/8	GFIO	ADC9: ADC Input Channel 9;
					UART2RXC: Uart2 Data In(C);
					PWMCH3L: Motor PWM Channel3(L);

	1	ı	i	Tr.	1
43	PB9	I/O	24/8	GPIO	SD0 Clock(B); SPI2CLKA: SPI2 Clk(A); SD1DAT2B: SD1 Data2(B); CAP0: Timer0 Capture; UART2TXC: Uart2 Data Out(C); PWMCH3H: Motor PWM Channel3(H);
44	PB8	I/O	24/8	GPIO	SD0DAT0B: SD0 Data0(B); SPI2_DIA: SPI2 Data In(A); SD1DAT1B: SD1 Data1(B); ADC8: ADC Input Channel 8; CLKOUT1: Clk Out1;
45	PB7	I/O	24/8	GPIO	
46	PB6	I/O	24/8	GPIO	SD1CLKB: SD1 Clock(B); SD0DAT1B: SD0 Data1(B); IIC_SDA_C: IIC SDA(C); TMR3: Timer3 Clock Input; UART0RXB: Uart0 Data In(B); PWMCH2L: Motor PWM Channel2 (L);
47	PB5	I/O	/	GPIO (High Voltage Resistance)	SD1CMDB: SD1 Command(B); SD0DAT2B: SD1 Data2(B); PWM3: Timer3 PWM Output; CAP1: Timer1 Capture; UART0TXC: Uart0 Data Out(C); UART0RXC: Uart0 Data In(C);
48	PB4	I/O	24/8	GPIO	SD1DAT0B: SD1 Data0(B); SD0DAT3B: SD0 Data3(B); IIC_SCL_C: IIC SCL(C); ADC7: ADC Input Channel 7; UART0TXB: Uart0 Data Out(B); LVD: Low Voltage Detect Input; PWMCH2H: Motor PWM Channel2 (H);

2, Electrical Characteristics

2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Topt	Operating Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	5.5	V
LDO_IN	Charger Voltage	-0.3	6	V
V _{3.3IO}	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions	
VBAT	Voltage Input	2.2	3.7	5	V		
LDO_IN	Charger Voltage	4.5	5.0	5.5	V		
V _{3.3}	Voltage output	2.2	3.0	3.4	V	VBAT = 5V, 100mA loading	
V_{BT_AVDD}	Voltage output	1.2	1.25	1.35	V	VBAT=5V, 100mA loading	
$I_{L3.3}$	Loading current	1	_ /	150	mA	VBAT = 5V	

2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input ch	IO input characteristics									
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions				
V_{IL}	Low-Level Input Voltage	-0.3	ı	0.3* VDDIO	V	VDDIO = 3.3V				
V_{IH}	High-Level Input Voltage	0.7* VDDIO	1	VDDIO+0.3	V	VDDIO = 3.3V				
IO output c	haracteristics									
V_{OL}	Low-Level Output Voltage	-	-	0.33	V	VDDIO = 3.3V				
V_{OH}	High-Level Output Voltage	2.7	ı	-	V	VDDIO = 3.3V				

2.4 Internal Resistor Characteristics

Table 2-5

]	Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment	
PB. PB6	0~PA15 PB1, 3, PB4, 5~PB10 0~PC5	8mA	24mA	10K	10K	1、PB1 default pull up 2、USBDM & USBDP	
PB11 PC7	Output0 Output1	8mA	24mA 64mA	10K	10K	default pull down 3、PB0, PB2, PB5 can pull-up resistance to 5V	
PB0,	PB2, PB5	8mA	/_	10K	10K	4 internal pull-up/pull-down	
PR	0-PR1	8mA	/ _	10K	10K	resistance accuracy ±20%	
USBDP		4mA	/ -	1.5K	15K	±2070	
U	SBDM	4mA	_	180K	15K		

2.5 BT Characteristics

2.5.1 Transmitter

Basic Data Rate

Table 2-5

Parameter		Min	Тур	Max	Unit	Test Conditions
RF Transmit P	RF Transmit Power		4	6	dBm	
RF Power Contro	l Range	j.	20		dB	25℃,
20dB Bandwidth			950		KHz	Power Supply
	+2MHz		-40		dBm	
Adjacent Channel	-2MHz		-38		dBm	VBAT=5V
Transmit Power	+3MHz		-44		dBm	2441MHz
) Y	-3MHz		-35		dBm	

Enhanced Data Rate

Table 2-6

Paramete	Min	Тур	Max	Unit	Test Conditions	
Relative Po	Relative Power				dB	
-/4 DODGV	DEVM RMS		6		%	
π/4 DQPSK	DEVM 99%		10		%	25℃,
Modulation Accuracy	DEVM Peak		15		%	Power Supply
	+2MHz		-40		dBm	VBAT=5V
Adjacent Channel	-2MHz		-38		dBm	2441MHz
Transmit Power	+3MHz		-44		dBm	
	-3MHz		-35		dBm	

2.5.2 Receiver

Basic Data Rate

Table 2-7

Paramete	Min	Тур	Max	Unit	Test Conditions	
Sensitivit	y		-90		dBm	
Co-channel Interferer	nce Rejection		-13		dB	
+1MHz			+5		dB	25℃,
	-1MHz		+2		dB	Power Supply
Adjacent Channel	+2MHz	y	+37		dB	VBAT=5V
Interference Rejection	-2MHz		+36		dB	2441MHz
	+3MHz	11	+40		dB	
	-3MHz		+35	1	dB	

Enhanced Data Rate Table 2-8

Parameter		Min	Тур	Max	Unit	Test Conditions
Sensitivit	y		-90		dBm	
Co-channel Interferen	nce Rejection		-13		dB	3/
	+1MHz		+5		dB	25℃,
	-1MHz		+2		dB	Power Supply
Adjacent Channel	+2MHz		+37		dB	VBAT=5V
Interference Rejection	-2MHz		+36		dB	2441MHz
	+3MHz		+40		dB	
	-3MHz		+35		dB	

3. Package Information

3.1 LQFP48(7mm*7mm)

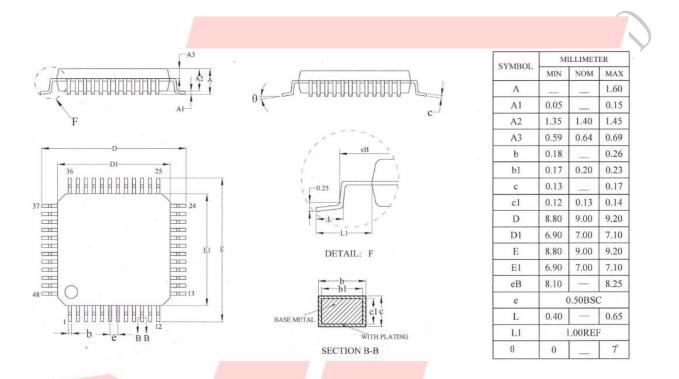


Figure 3-1. AC6951D_LQFP48 Package

4. Revision History

Date	Revision	Description
2020.05.21	V1.0	Initial Release
2020.06.15	V1.1	Update Power Characteristics
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