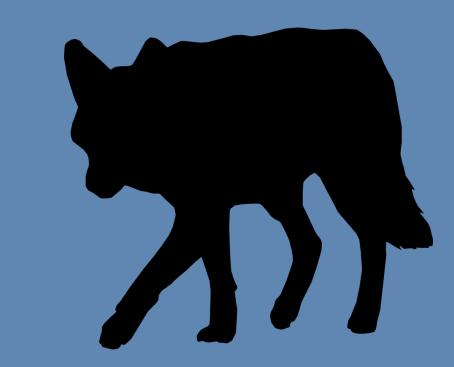


Wildlife Camera-Trap Classification

Şükrü Deniz Çilek University College Dublin

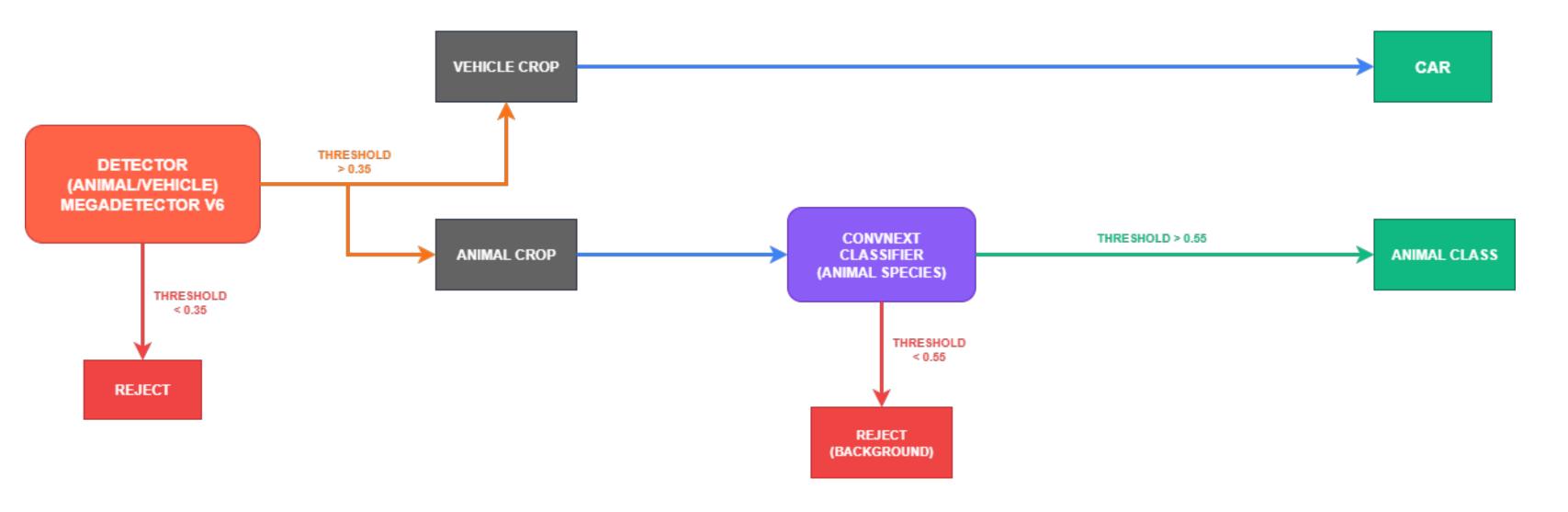


Abstract

Camera-trap imagery enables large-scale wildlife monitoring but suffers from domain shift, where models fail on unseen locations. We propose a two-stage pipeline (MegaDetector v6 + ConvNeXt-Small) for detection and classification, achieving F1 scores of 0.90 (seen) and 0.77 (unseen) on CCT20. Our modular design cuts cross-domain error by 27.5% (F1) while maintaining high recall for rare species, enabling robust and scalable conservation monitoring.

Problem Definition and Contribution

Problem: Camera trap images present unique difficulties, night-time infrared capture, motion blur, partial occlusion, weather conditions, and class imbalance. Models struggle to generalize across different camera locations due to site-specific environmental variations.



Two-Stage Pipeline: MegaDetector v6 → ConvNeXt Classifier

Key Innovation: Modular design with threshold-based decision points (0.35 detection, 0.55 classification) enables independent optimization and robust cross-domain deployment.

Dataset & Challenges

CCT20 Dataset: 51,000+ images, 20 locations, 13 species + vehicle

Main Challenges:

- Domain shift: performance drops on new locations
- Class imbalance: some species are very rare
- Poor conditions: night vision, motion blur, occlusion
- Environmental noise: rain, fog, camera malfunctions







Unseen (test) — Coyote, night IR, motion blur.

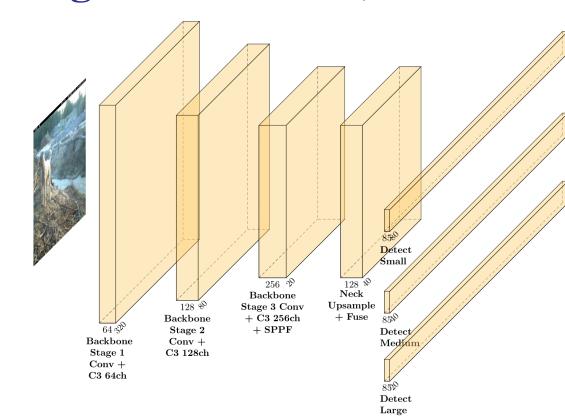
Method

ConvNeXt-Small

- Efficient CNN with depthwise 7×7 convolutions and MLP blocks.
- Large receptive field for robustness to domain shift.

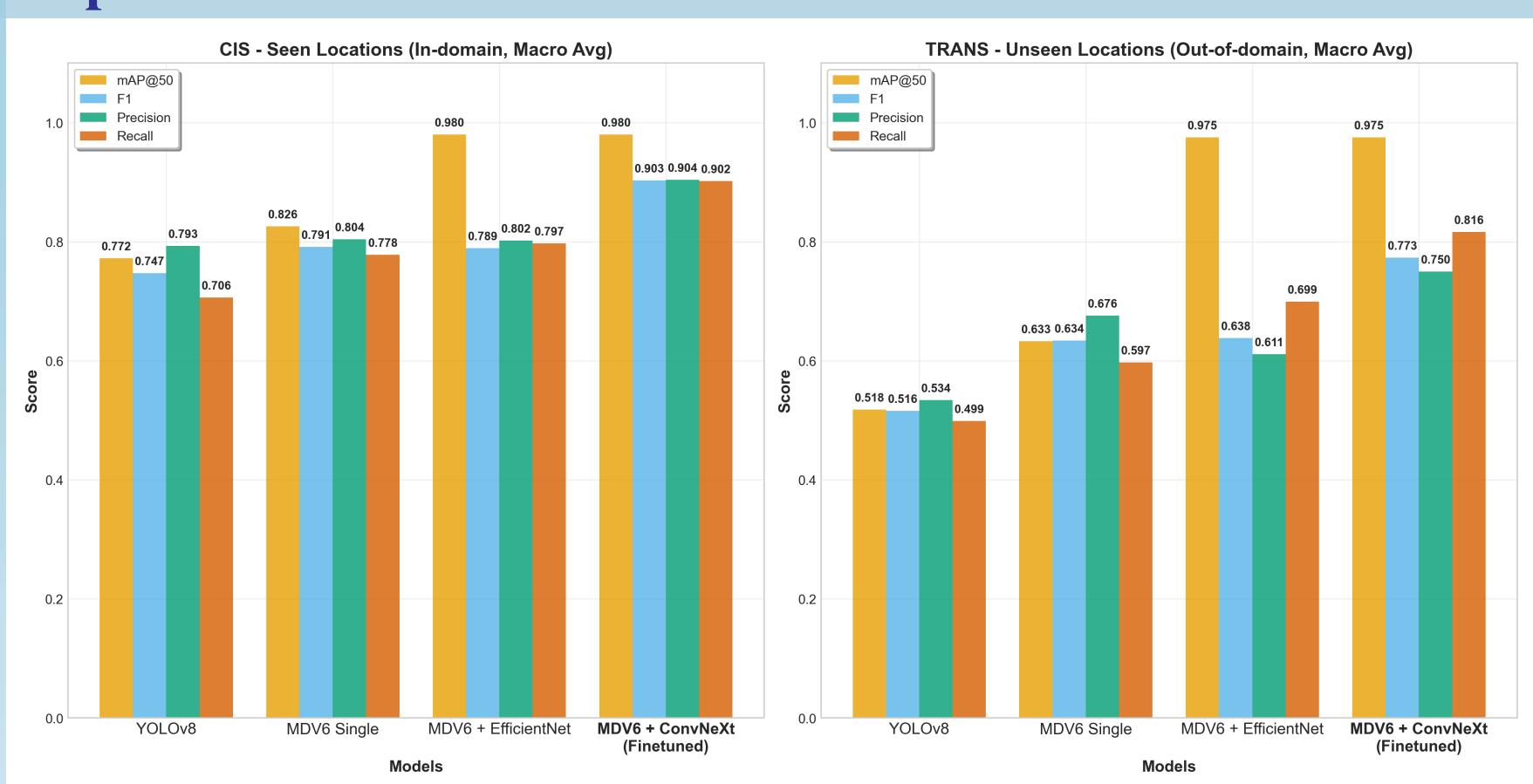
CIS (seen) — row-normalized

MegaDetector v6 (YOLOv9-c)

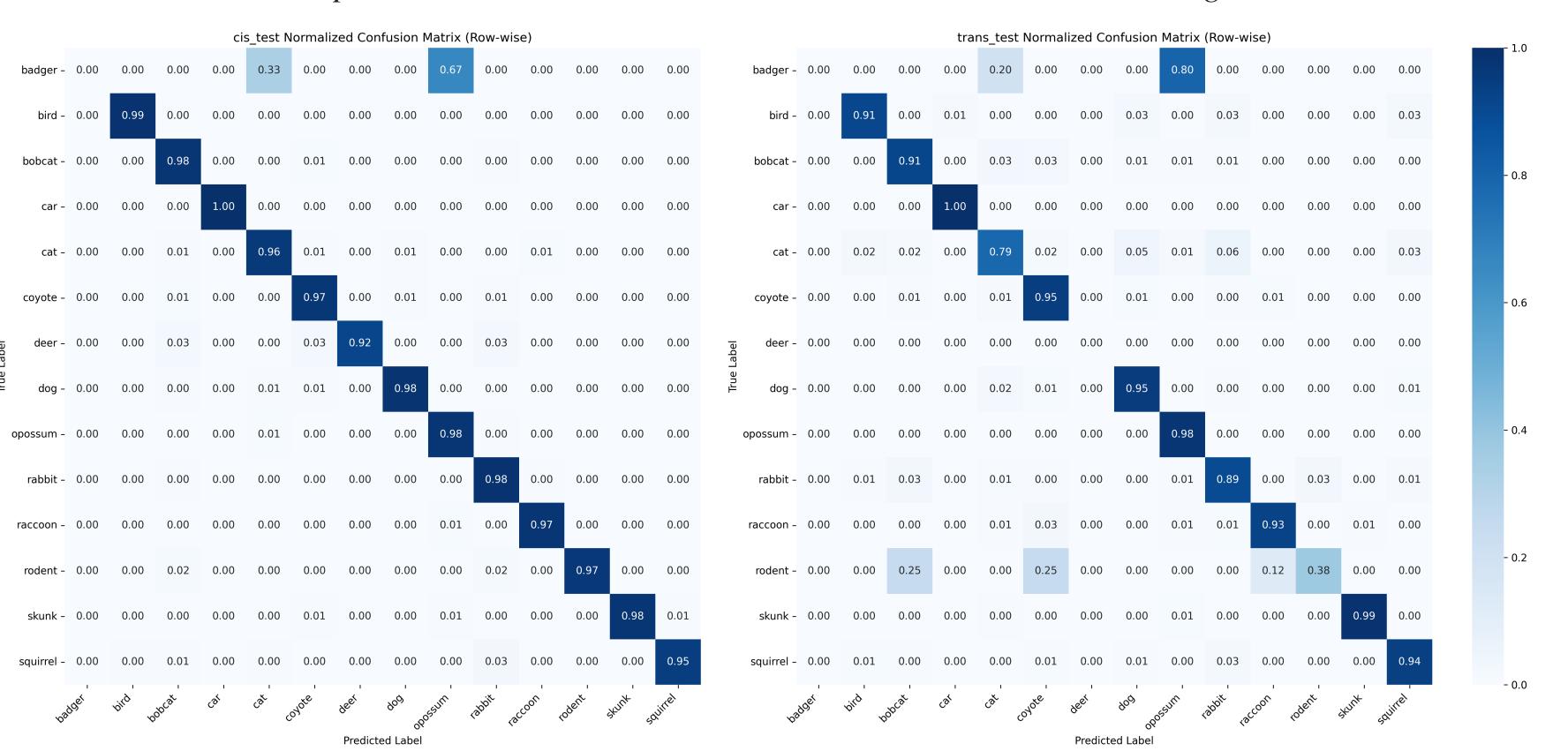


- YOLO-style detector with FPN, SPPF, and 3-scale heads.
- Trained for binary animal vs. vehicle detection with high recall.

Experiments & Results



Detector (MDV6) achieves high accuracy in separating animals from vehicles: CIS – 97.9% precision, 97.3% recall; TRANS – 96.4% precision, 95.6% recall. All metrics shown are Macro Averages.



TRANS (unseen) — row-normalized

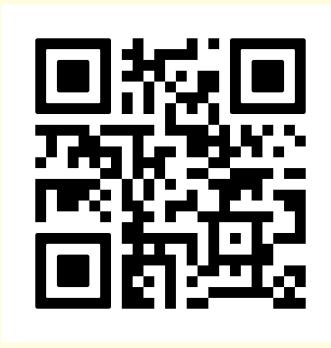
Drop in F1 Score (In-Domain vs. Out-of-Domain) 30.9% YOLOv8 19.8% MDV6 Single Stage MDV6 + EfficientNetV2-S 14.4% MDV6 + ConvNeXt-S

Future Work & Conclusion

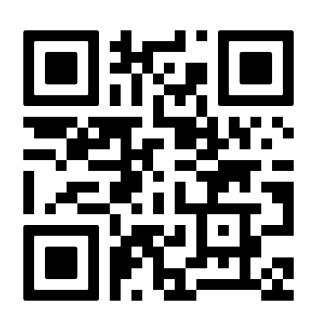
• Two-stage MDv6 + ConvNeXt-Small reduces domain shift and maintains high precision/recall on unseen locations.

Percentage Drop (%)

- Enhance rare-class detection via active learning on hard negatives & tail species.
- Leverage photo metadata (e.g., time of day, location) for context-aware classification.
- Experiment on the full CCT dataset for broader generalization.



References



GitHub Repository

- 1. Beery, S., et al. (2018). Recognition in Terra Incognita. *ECCV*.
- 2. Norouzzadeh, M. S., et al. (2018). Auto ID of wild animals. PNAS. 3. Microsoft AI for Earth (2023). MegaDetector v6. GitHub.
- 4. Liu, Z., et al. (2022). ConvNeXt. CVPR.

Web App