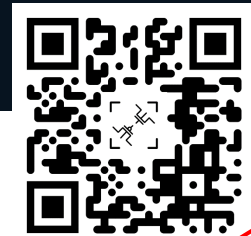




## Part 4

# Design Methodology-Application to Low Noise Amplifier



Sylvain Bourdel



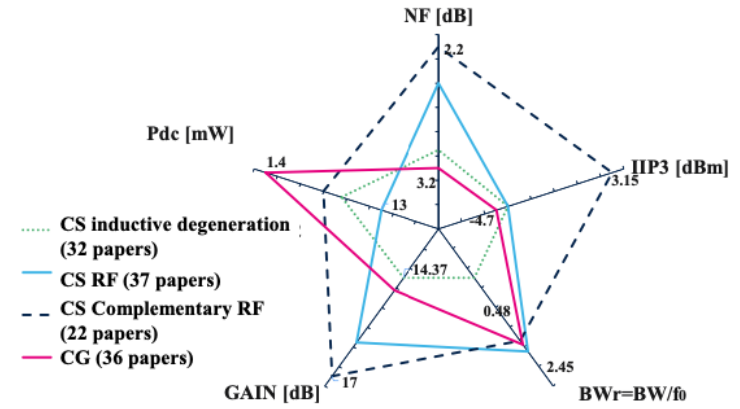
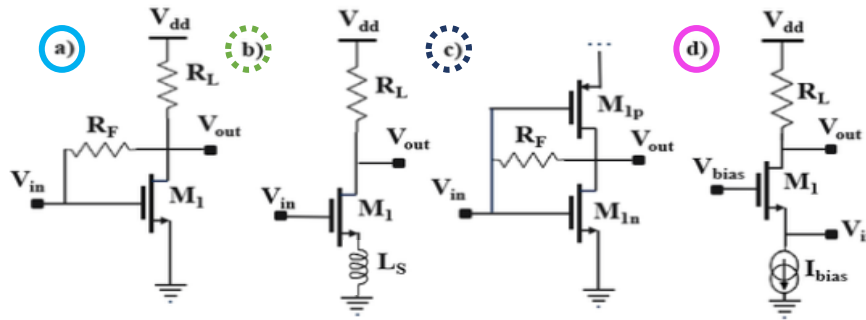
[https://github.com/ACMmodel/MOSFET\\_model](https://github.com/ACMmodel/MOSFET_model)

[https://colab.research.google.com/drive/1s3PKF6pf3zIhITj6jc-ghCLlcGfJ\\_UEE?usp=sharing#scrollTo=EMGo7aUzyukW](https://colab.research.google.com/drive/1s3PKF6pf3zIhITj6jc-ghCLlcGfJ_UEE?usp=sharing#scrollTo=EMGo7aUzyukW)

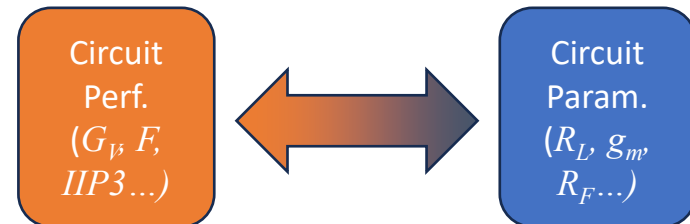
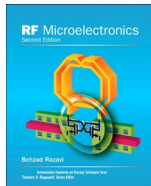
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## • 1<sup>st</sup> Step: Architecture Choice



## • 2<sup>nd</sup> Step: Circuit Analysis

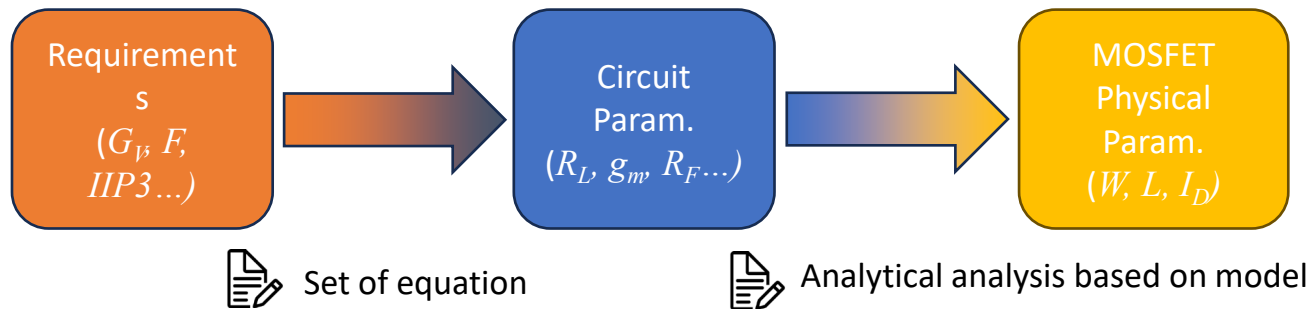


$$|G_T| = |G_v|Q_{IN} = \frac{(G_m R_F - 1)R_O}{(R_O + R_F)} \sqrt{1 + Q_P^2}$$

# Overview of Design Methods for RFIC

## General Principle

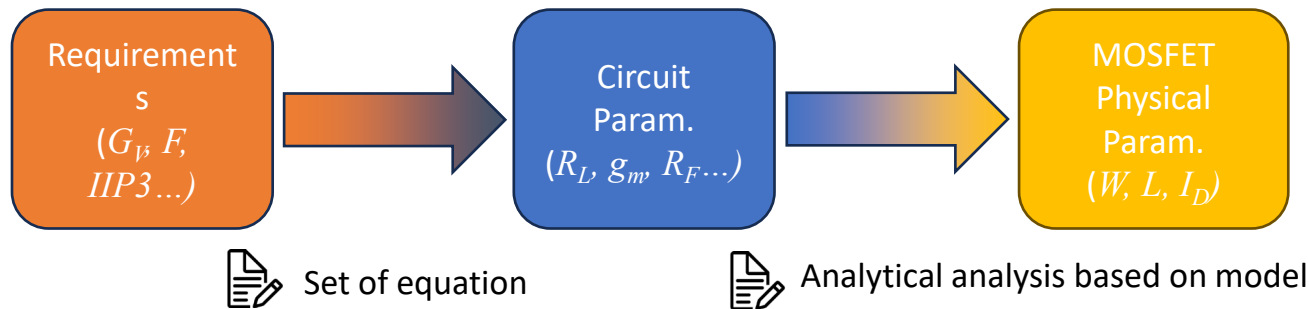
- 3<sup>rd</sup> Step: Circuit Sizing



# Overview of Design Methods for RFIC

## General Principle

- 3<sup>rd</sup> Step: Circuit Sizing



### ***Region based model***

$$sat. \quad I_d = 2.K_n \frac{W}{L} \left[ (V_{gs} - V_t) V_{ds} - \frac{V_{ds}^2}{2} \right]$$

$$lin. \quad I_d = K_n \frac{W}{L} (V_{gs} - V_t)^2 \left( 1 + \frac{k_{en}}{L} V_{ds} \right)$$

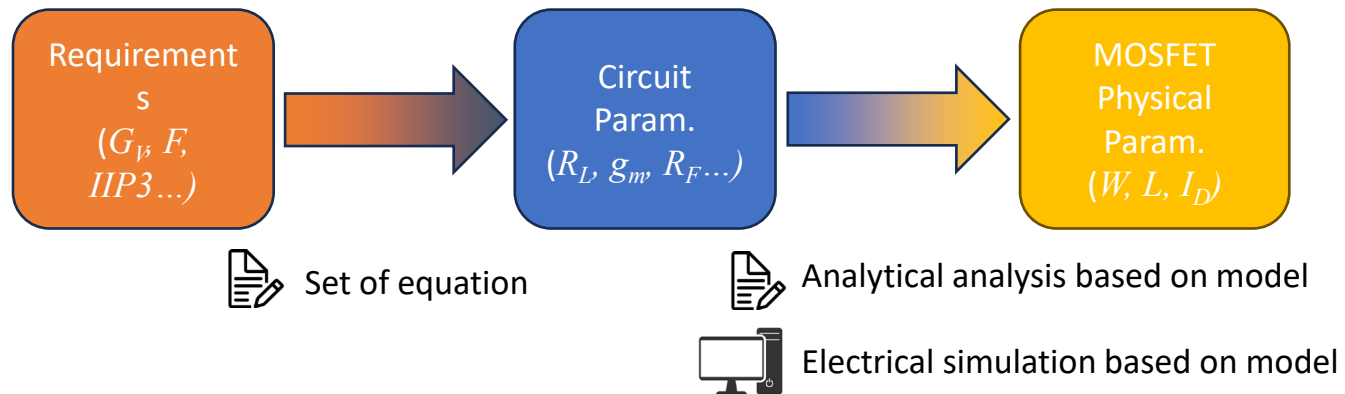
PROS: simple

CONS: Inaccurate with short channel MOS

# Overview of Design Methods for RFIC

## General Principle

- 3<sup>rd</sup> Step: Circuit Sizing



### ***BSIM3 / UTSOI compact model***

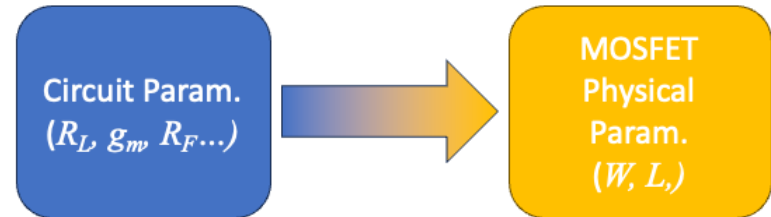
#### *PROS:*

- *Accurate*
- *Direct relationship between requirements and physical parameters*

#### *CONS:*

- *Increases the gap between Physic and design*
- *Long optimization*

- **Issue in the sizing step**



- How to maintain simplicity **and** accuracy with the scaling and especially Short Channel Effects (SCE) at the sizing step. ?

- **A possible solution**

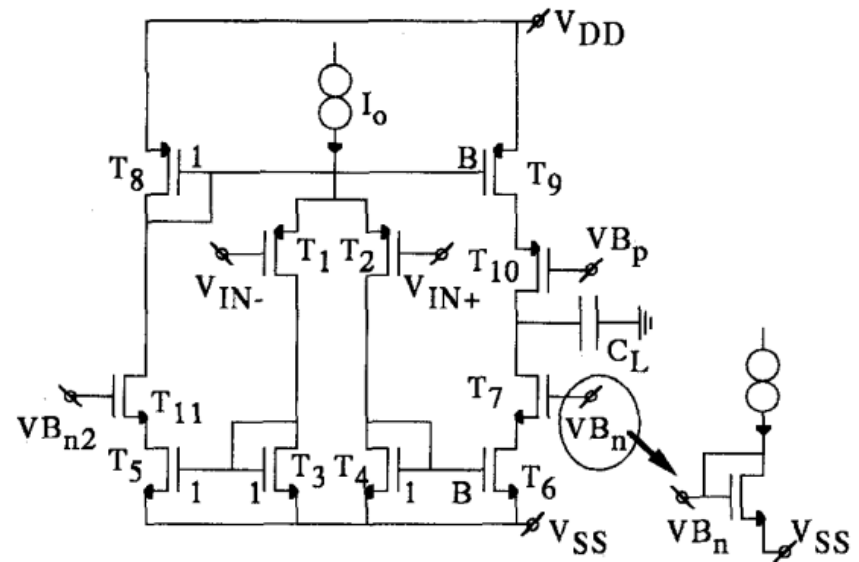
- $g_m/I_d$  design approaches
  - LUT based
  - ACM or EKV based



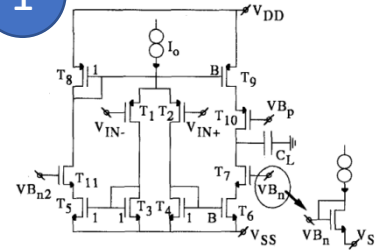
[Silveira, Flandre, Jespers – JSSC 1996]

## General Principle

- For a given structure

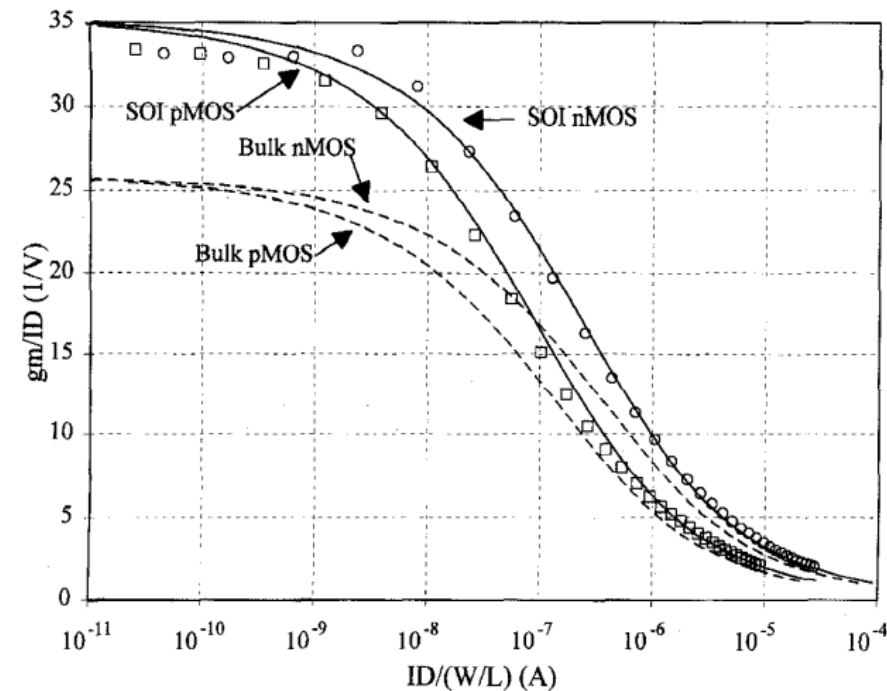


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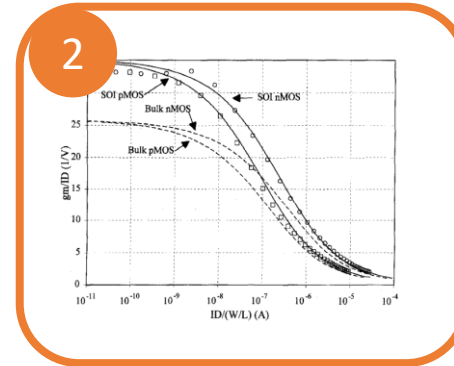
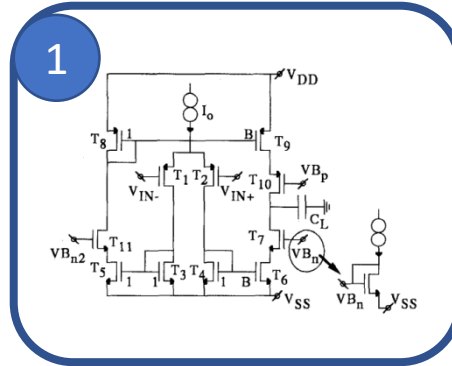


### General Principle

- For a given structure
- Methods are based on
  - ⇒ Extraction of MOS parameters (LUT)
    - $I_D/(W/L)$  vs  $g_m/I_D$
    - $g_m/I_D$  vs  $V_{gs0}$



### General Principle



- For a given structure
- Methods are based on
  - ⇒ Extraction of MOS parameters (LUT)
    - $I_D/(W/L)$  vs  $g_m/I_D$
    - $g_m/I_D$  vs  $V_{gs0}$

⇒ Set of equations

$$SR = \frac{B \cdot I_{D1}}{C_L}$$

$$f_T = \frac{B \cdot g_{m1}}{2\pi \cdot C_L} \quad (5)$$

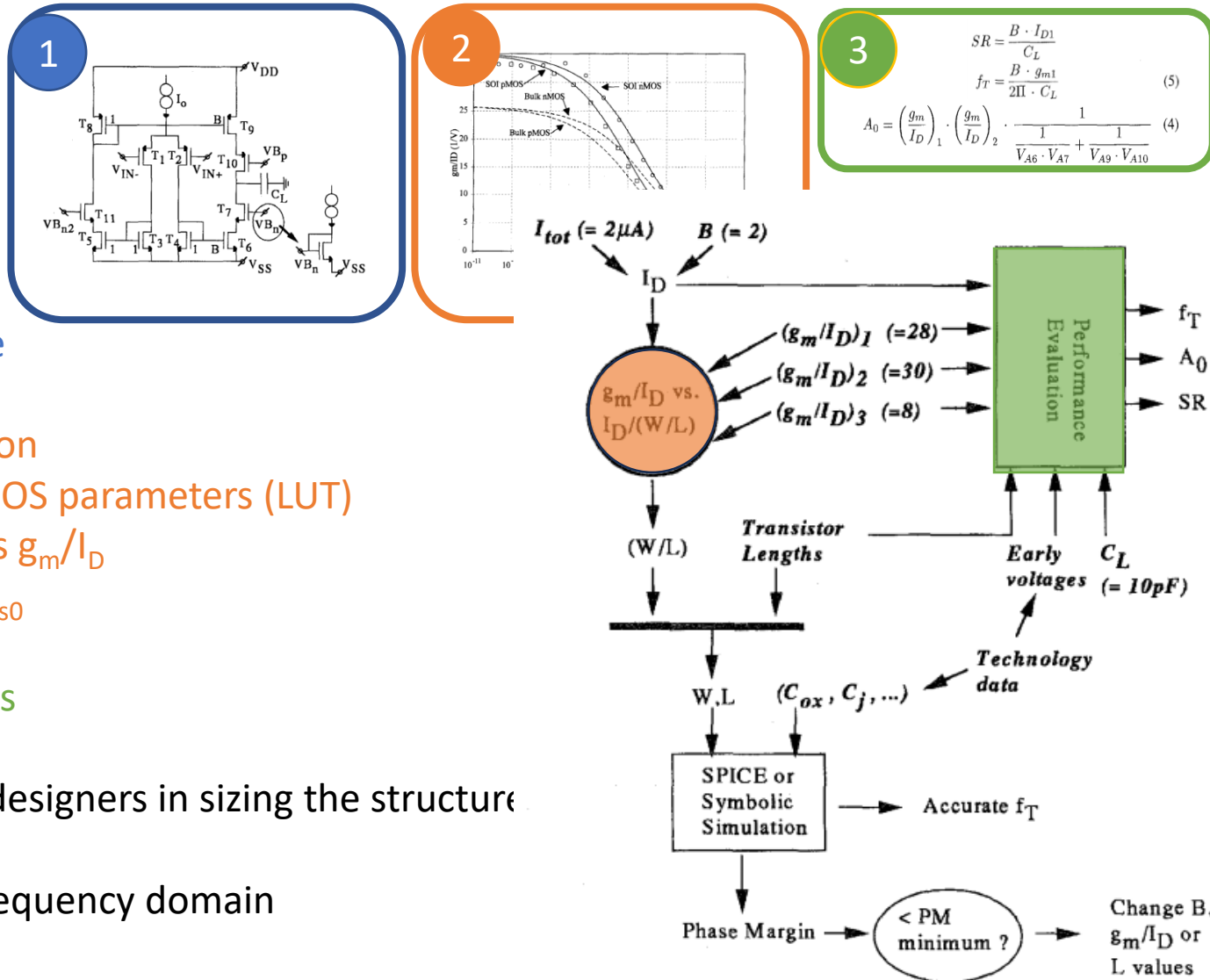
$$A_0 = \left( \frac{g_m}{I_D} \right)_1 \cdot \left( \frac{g_m}{I_D} \right)_2 \cdot \frac{1}{\frac{1}{V_{A6} \cdot V_{A7}} + \frac{1}{V_{A9} \cdot V_{A10}}} \quad (4)$$

# Overview of Design Methods for RFIC

## $g_m/I_D$ approach based on LUT

### General Principle

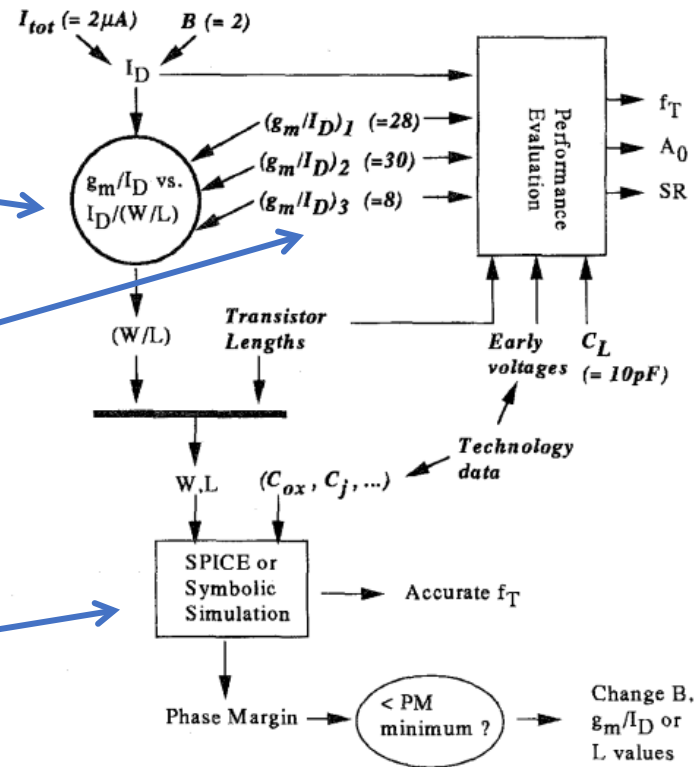
- For a given structure
- Methods are based on
  - Extraction of MOS parameters (LUT)
    - $I_D/(W/L)$  vs  $g_m/I_D$
    - $g_m/I_D$  vs  $V_{gs0}$
- Set of equations
- Methods helps the designers in sizing the structure
- Quite used in low frequency domain



### LIMITATIONS ?

- Time Consuming
- Lack of precision (parametric set of characteristics)
- Long optimization sequence

Need for a model based approach



### All Region 3PM model

- EKV – [Enz, Krummenacher, Vittoz]
- ACM – [Schneider, Galup]



- With a 3PM model we have :

$$\frac{g_m}{I_D} = \frac{2}{n\phi_t \left(1 + \sqrt{1 + i_f}\right)} \quad g_m = \frac{2I_S}{\phi_t} \left(\sqrt{1 + i_f} - 1\right) \quad V_P - V_{S(D)} = \phi_t \left[ \sqrt{1 + i_{f(r)}} - 2 + \ln \left( \sqrt{1 + i_{f(r)}} - 1 \right) \right]$$

$$V_P \cong \frac{V_G - V_{T0}}{n}$$

- PROS: The sizing is straightforward
- CONS: Inaccurate with SCE

Non-linearities can't be captured  
gds effect can't be captured

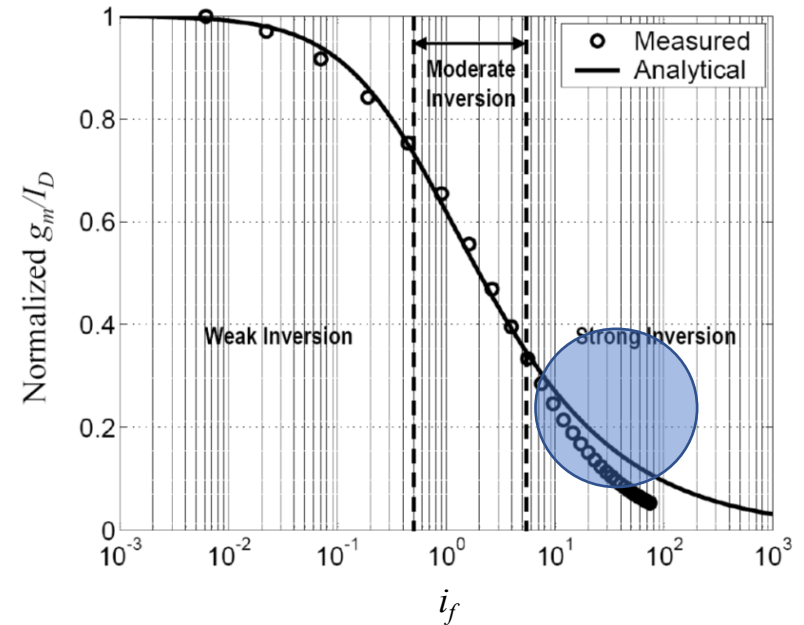
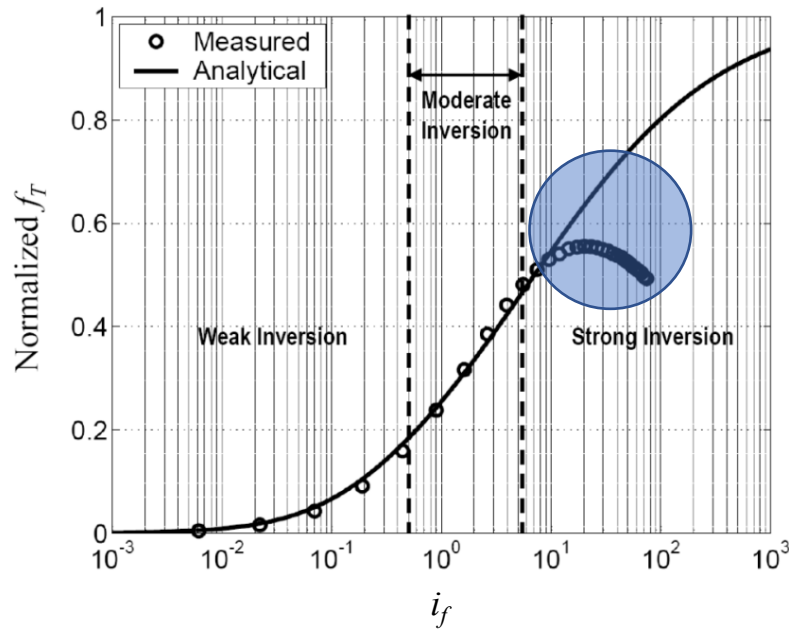


Can we design RFICs ?

### Design Regions

- $f_t$  grows with  $i_f$

 Year 2000 (RF-180nm)



### Design Regions

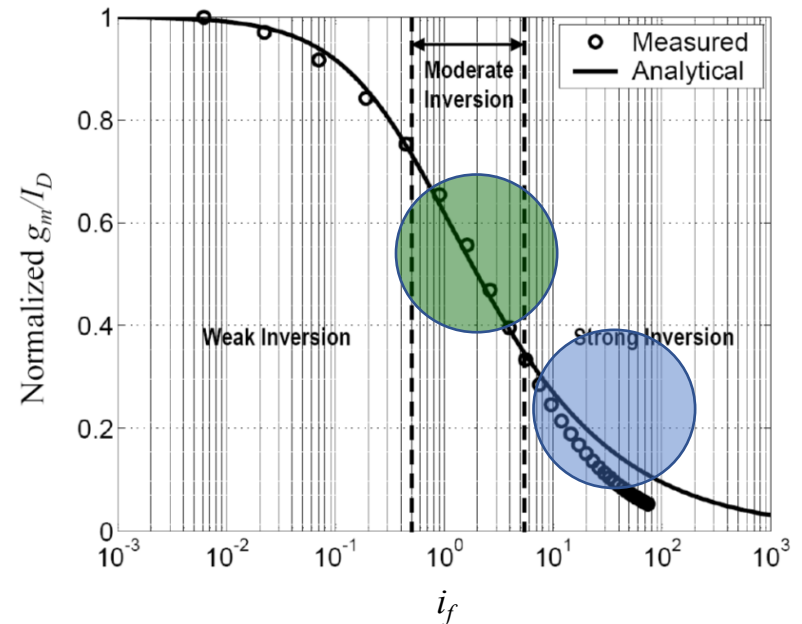
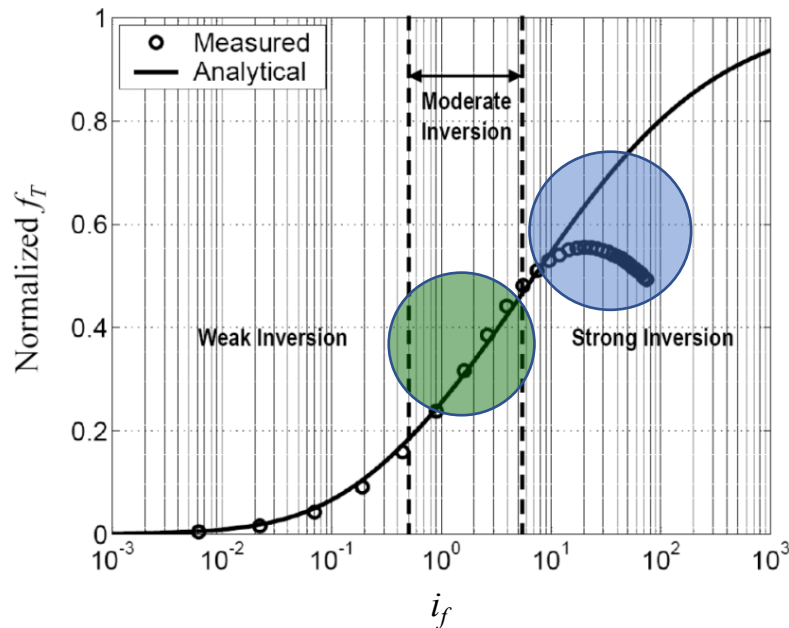
- $f_t$  grows with  $i_f$  but  $g_m/I_D$  reduces with  $i_f$



Year 2000 (RF-180nm)



Year 2016 (RF-22nm) up to now





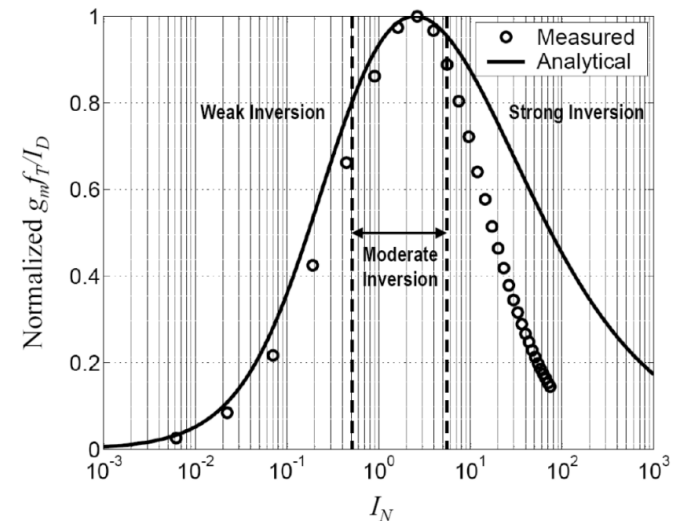
### $g_m f_T / I_D$ : A First Approach

A. Shameli et P. Heydari, « Ultra-Low Power RFIC Design Using Moderately Inverted MOSFETs: An Analytical/Experimental Study », *RFIC*, 2004.

- For RF design
- A FOM that maximize the gain bandwidth product

$$\frac{g_m f_T}{I_D}$$

- Gives the  $i_f$  that produces the best GBW product
- Not optimal :
  - the gain or the bandwidth might be oversized.
  - Do not depends on the topology

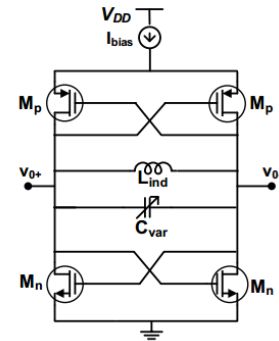
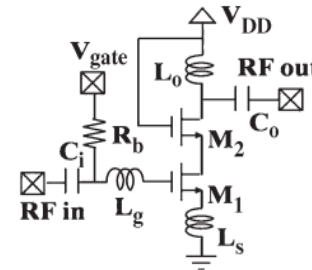


LNA

LO

### Function Based FoM

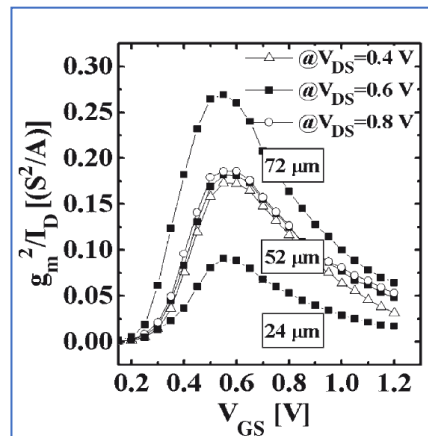
- For a given Function
- Define a FoM for the function



$$\text{FoM}_{\text{LNA}} = \frac{G}{(F-1) \cdot P} \propto \frac{g_m^2}{\left(\frac{I_D}{g_m}\right) \cdot I_D} \propto \left(\frac{g_m^2}{I_D}\right)^2$$

- Find the  $i_f$  that maximizes the FoM

I. Song et B.-G. Park, « A Simple Figure of Merit of RF MOSFET for Low-Noise Amplifier Design », *Electron Device Lett. IEEE*, vol. 29(12), 2008.



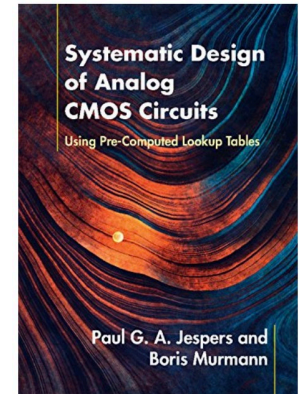
$$PN(\Delta f) = 10 \log \left( \frac{k_B T \pi^2}{64 Q^2} \frac{g_m}{I_D} \frac{1}{I_D} \frac{f_0}{(\Delta f)^2} \lambda \right)$$

R. Fiorelli ; J. Núñez ; F. Silveira; “All-Rnversion region  $g_m/I_D$  methodology for RF circuits in FinFET technologies”  
2018 *NEWCAS*

### Circuit Based Method

#### Circuit Sizing Based on LUT

- For a given Circuit
- Similar to the one introduced by Silveira, Flandre, Jespers in 1996
- Capacitance and noise effects can be captured in LUT for bandwidth and noise analysis
- Well known and well referenced
- But ...
  - Still complicated
  - The gap between physics and design remains
  - No analytical relationships to size « by hand »



#### Circuit Sizing Based on ACM

- Equations can be derived for a given circuit
- Quasi analytical approach
  - R-F LNA designed with 3PM-ACM [Bourdel - ICECS 2019]
- Gds and gm3 (NL) are taken into account
  - R-F LNA designed with 7PM-ACM [Bouchoucha – ISCAS 2023]
  - CG LNA designed with 5PM-ACM2[Alves Neto – ACCESS 2024]



### Resistive Feedback LNA design using a 7-parameter design-oriented model for advanced technologies

Mohamed Khalil Bouchoucha<sup>1,2</sup>, Dayana A. Pinc

Manuel J. Barragan

<sup>1</sup>STMicroelectronics, 38920 Crolles, France, <sup>2</sup>TiMA I

ANALOG CATHELIN

AND CARLOS GALUP-P

<sup>1</sup>Department of Electrical and Electroni

<sup>2</sup>STMicroelectronics, 38920 Crolles, Fr

<sup>3</sup>Univ. Grenoble Alpes, CNRS, Grenob

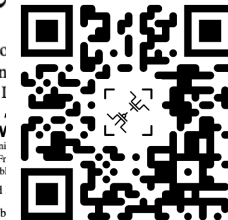
Corresponding author: Mohamed

This work was supported in part b

Nacional de Desenvolvimento Cie

STMicroelectronics, Crolles, France.

https://github.com/ACMmodel/MOSFET\_model



lippe Cathelin<sup>1</sup>, Jean-Michel Fournier<sup>2</sup>,

Bourdel<sup>2</sup>

<sup>1</sup>Grenoble Alpes, 38000 Grenoble, France

BOURDEL, JEAN-MICHEL FOURNIER, ILLI,

E)

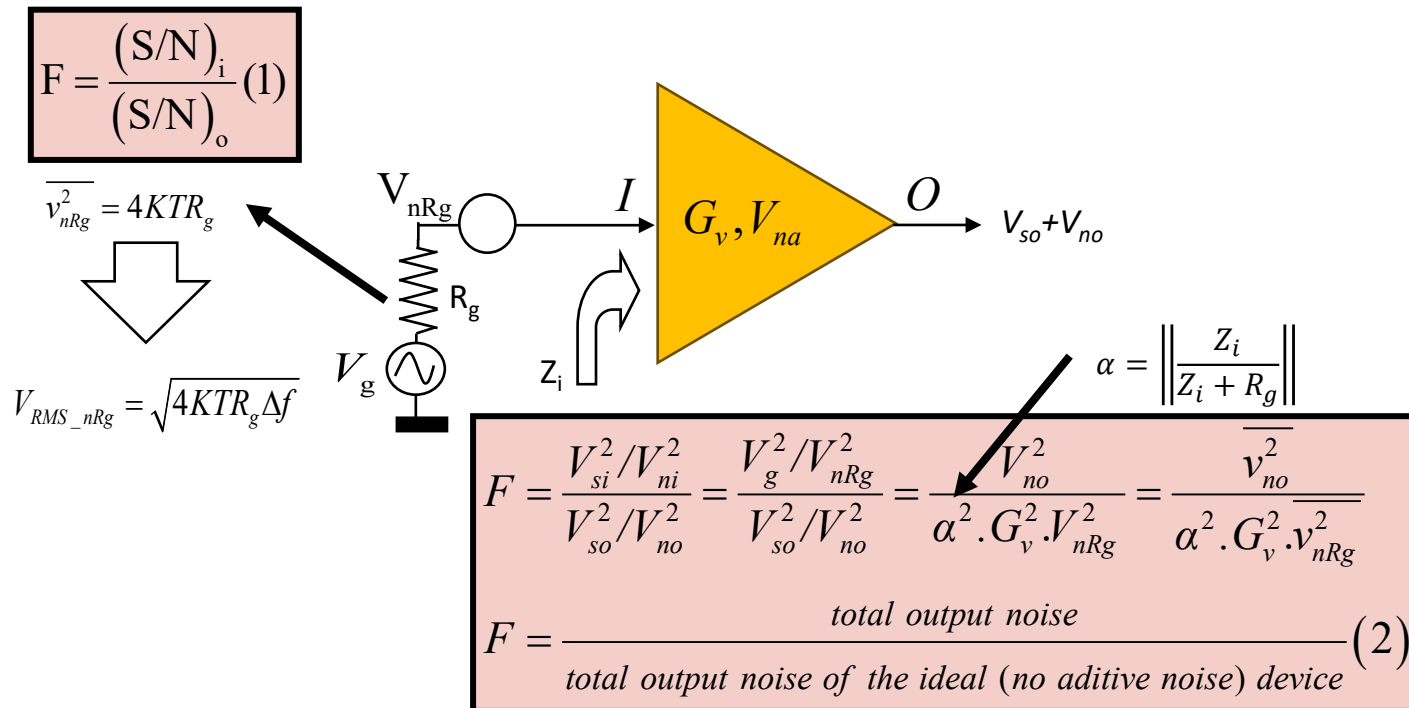
anópolis 88040-900, Brazil

de Nivel Superior, Brazil; in part by the Conselho

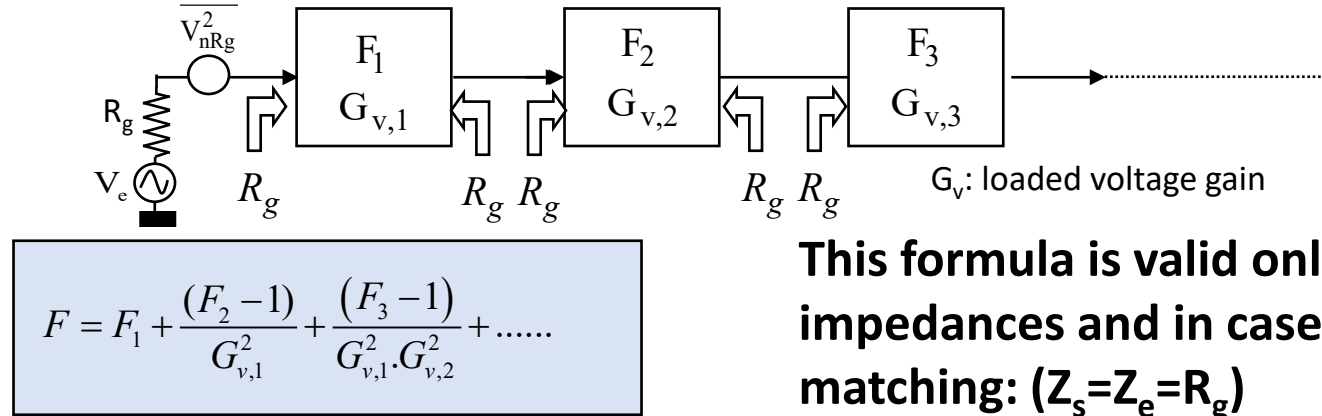
Laboratory, Grenoble, France; and in part by

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- NF is the signal to noise ratio (SNR) degradation (Eq. 1)



- NF also express the quantity of noise added by the stage regarding the noise delivered by the source ( $R_g$ ) on  $\Delta f$ . (Eq. 2)



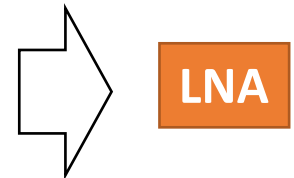
***In RFIC, impedances are complex and never equal. This formula cannot be used as is. However, the following statements remain valid in RFIC.***

The gain of the first stages reduces the NF of the following ones.

=> The receiver chain must start by amplifiers

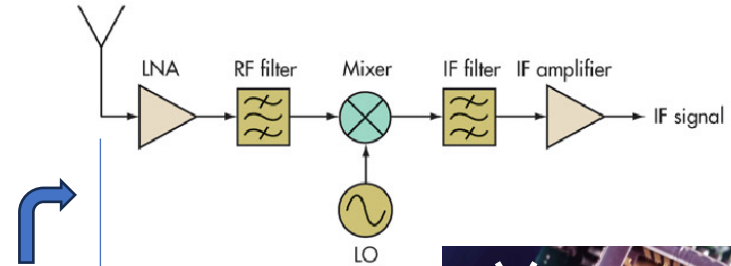
=> The NF of the first stage must be as low as possible

Note that lossy stages ( $G_v < 1$ ) increase the NF, especially when they are in front of the receiver chain (***antenna filter, image rejection filter, antenna switch*** ).

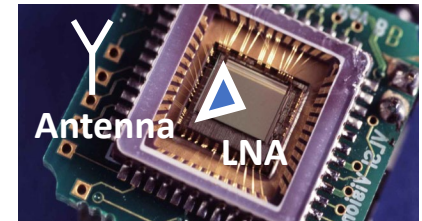


### System point of vue

- LNA is the first device due to Friss formula
- Antenna is mainly 50  $\Omega$ .

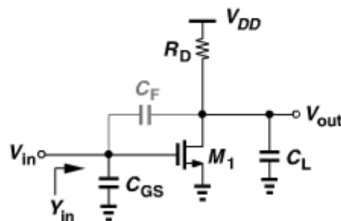


$$Z_{lna} = Z_g^*$$



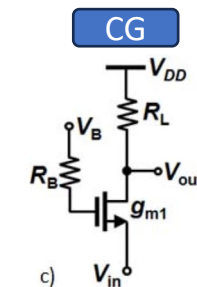
### In CMOS

- Generally, the input impedance is capacitive  $\Re(Y_{11})$  is very low
- For exemple : CS amplifier

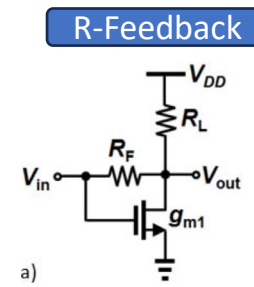


$$\Re(Y_{in}) = R_D \parallel 1/g_m$$

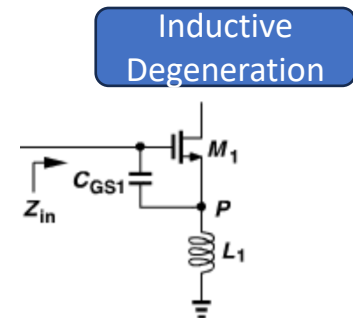
$$\Im(Y_{in}) = \frac{1}{C_{GS}C_F\omega}$$



$$\Re(Z_{in}) = \frac{1}{g_{m1}}$$



$$\Re(Z_{in}) = \frac{R_F}{1 + |A_V|}$$

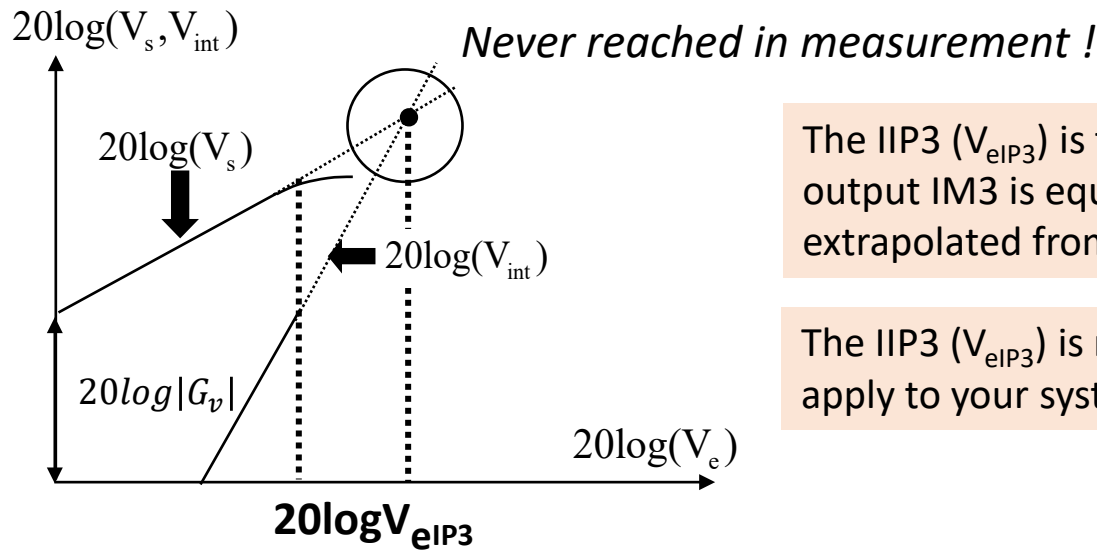
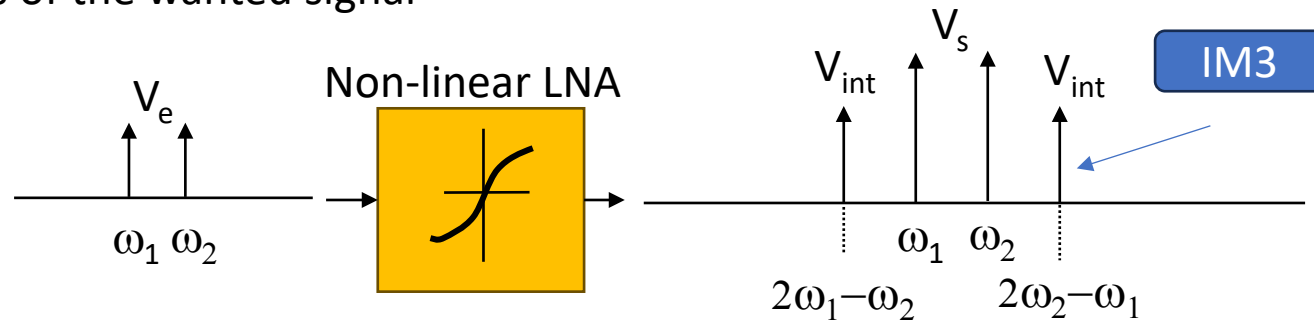


$$\Re(Z_{in}) = \frac{g_m L_1}{C_{GS}}$$

# LNA Design considerations

## Non-Linearities

$\omega_1$  and  $\omega_2$  are 2 harmonics of the wanted signal



The IIP3 ( $V_{eIP3}$ ) is the input signal level for which the output IM3 is equaling the fundamental harmonic ( $V_s$ ) extrapolated from small signal (AC).

The IIP3 ( $V_{eIP3}$ ) is related to the maximum power you can apply to your system



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### *R-Feedback general considerations*

- Simple
- Compact (No-inductors)
- Wideband
- RF allows to synthesize a real part in  $Z_{in}$
- $L_G$  and  $C_{GS}'$  will help in cancelling the imaginary part
- while controlling  $Q_{in}$

### *Input impedance*

$$Z_{IN} = L_G s + \left( \frac{1}{(C_{GS} + C'_{GS})s} // Z_P \right)$$

$$\Re(Z_P) = R_P = \frac{R_O + R_F}{1 + G_m R_O}$$

$$C_P = \frac{R_O^2 C_L (G_m R_F - 1)}{(R_O + R_F)^2}$$

$$\Re(Z_{IN}) = R_S = \frac{R_P}{(1 + Q_P^2)} = 50 \Omega$$

$$Q_P = R_P C_T \omega_0$$

$$C_T = C_{GS} + C'_{GS} + C_P$$

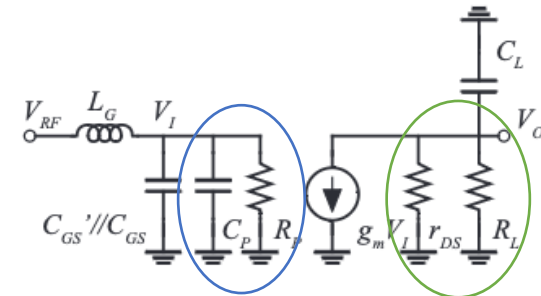
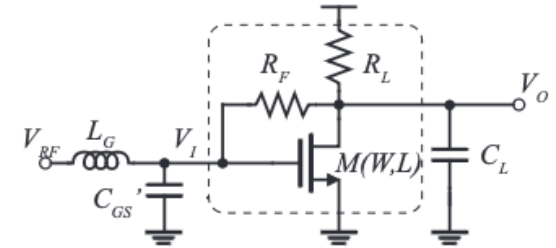
$$\Im(Z_{IN}) = 0 = L_G s + \frac{Q_P^2}{C_T s (1 + Q_P^2)}$$

**Note :**

$$\left\{ \begin{array}{l} \Re(Z_P) = \frac{1 + \left(\frac{f}{f_c}\right)^2}{\frac{1 + G_m R_O}{R_O + R_F} + \frac{1}{R_F} \left(\frac{f}{f_c}\right)^2}, \\ \Im(Z_P) = - \left(1 + \frac{R_F}{R_O}\right)^2 \frac{1 + \left(\frac{f}{f_c}\right)^2}{2\pi f C_L (G_m R_F - 1)} \end{array} \right.$$

**Reduces For**

$$\frac{f_c}{f} = N > 3$$



$$R_O = \frac{R_L r_{DS}}{R_L + r_{DS}}$$

# Resistive Feedback LNA Topology

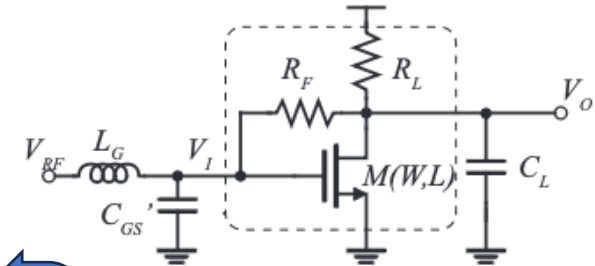
## Voltage Gain

$$|G_o| = \left| \frac{V_o}{V_{RF}} \right| = \frac{|G_T|}{\sqrt{\left(1 + \left(\frac{f_0}{f_c}\right)^2\right)}}$$

$$|G_T| = |G_v| Q_{IN} = \frac{(G_m R_F - 1) R_O}{(R_O + R_F)} \sqrt{1 + Q_P^2}$$

$$Q_{IN} = V_I / V_{RF} \quad Q_{IN} = \sqrt{1 + Q_P^2} = \sqrt{\frac{R_O + R_F}{R_S(1 + G_m R_O)}}$$

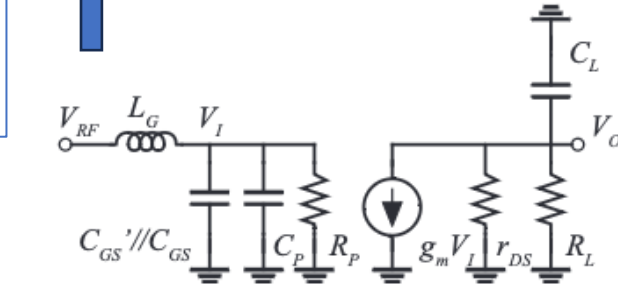
$$\frac{f_c}{f_0} = N > 3$$



## BW

$$f_c = \frac{R_O + R_F}{2\pi R_O R_F C_L} = N f_0$$

$R_S$   
(the source resistance seen  
at the 50  $\Omega$  input)



## Noise Figure

$$F = 1 + \frac{4 \left( \frac{R_F}{Q_{IN}^2} + R_S \right)^2}{Q_{IN}^2 G_m R_S \left[ \frac{R_F}{Q_{IN}^2} + R_S + \frac{G_m R_S R_F R_L}{R_F + R_L} \right]^2} \left[ \gamma + \frac{1}{G_m R_L} + \frac{\left( 1 + \frac{Q_{IN}^2 G_m R_S R_F}{R_F + Q_{IN}^2 R_S} \right)^2}{G_m R_F} \right]$$

$$\left( F_{min} = 1 + \frac{(1 + G_m) R_S^2 R_F}{R_S (1 - G_m R_F)^2} + \frac{\gamma g_m (R_S + R_F)^2}{R_S (1 - G_m R_F)^2} + \frac{(R_S + R_F)^2}{R_S R_L (1 - G_m R_F)^2} \right)$$

## IIP<sub>3</sub>

$$V_{IIP3} = \frac{2}{Q_{IN}} \sqrt{\frac{2G_m}{G_{m3}}}$$

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### *Small signal (AC) parameters*

- $G_T$ , NF, IIP3 vs ( $G_m$ ,  $G_{m3}$ ,  $G_{DS}$ )

$$g_m = \frac{\partial I_D}{\partial V_G} = \frac{I_S}{\phi_t} g_G = \frac{I_S}{n\phi_t} \frac{2(q_s - q_d) - i_d \zeta \left( \frac{q_s}{1+q_s} - \frac{q_d}{1+q_d} \right)}{1 + \zeta (q_s - q_d)}$$

$$g_{ds} = \frac{I_S}{\phi_t} g_D = \frac{I_S}{n\phi_t} \frac{2(q_s \sigma - q_d (\sigma - n)) - i_d \zeta \left( \sigma \frac{q_s}{1+q_s} - (\sigma - n) \frac{q_d}{1+q_d} \right)}{1 + \zeta (q_s - q_d)}$$

$$g_{m3} = \frac{I_S}{(n\phi_t)^3} \left\{ \frac{\frac{2q_s}{(1+q_s)^3} - \frac{2q_d}{(1+q_d)^3} - \zeta n^2 g_{G2} \left( \frac{q_s}{1+q_s} - \frac{q_d}{1+q_d} \right) - \zeta \left[ 2n g_G \left( \frac{q_s}{(1+q_s)^3} - \frac{q_d}{(1+q_d)^3} \right) + i_d \left( \frac{q_d(1-2q_d)}{(1+q_d)^5} - \frac{q_d(1-2q_d)}{(1+q_d)^5} \right) \right]}{1 + \zeta (q_s - q_d)} \right\}$$

- Valid in all region (  $q_s$  and  $q_d$  shall be explored )
- We consider only saturation

$$q_{dsat} = q_s + 1 + \frac{1}{\zeta} - \sqrt{\left(1 + \frac{1}{\zeta}\right)^2 + \frac{2q_s}{\zeta}}$$

$$g_{msat} = \frac{2I_S}{n\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)}$$

$$g_{dsat} = \frac{\sigma}{n} \frac{2I_S}{\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)}$$

$$g_{msat3} = \frac{16I_S}{(n\phi_t)^3} \frac{q_s}{(q_s + 1)^3} \frac{2 - 2\zeta q_s - 3\zeta q_s^2}{(q_s + 1)^4}$$

- It reduces the exploration to only  $q_s$ .

### *Large signal (DC) parameters*

- To compute the final voltages

$$V_T = V_{T0} - \sigma(V_{SB} + V_{DB})$$

$$V_P = \frac{V_{GB} - V_T}{n}$$

$$\frac{V_P - V_{S(D)B}}{\phi_t} = q_{s(d)} - 1 + \ln q_{s(d)}$$

- Sometime we'll use  $i_f$  in the code

$$i_d = i_f - i_r \quad \longleftrightarrow \quad q_{S(D)} = \sqrt{1 + i_{f(r)}} - 1 \quad \longleftrightarrow \quad i_d = \frac{(q_s + q_d + 2)}{1 + \zeta|q_s - q_d|} (q_s - q_d)$$

$$I_D = I_S \cdot i_d$$

$$I_S = \frac{\mu C'_{ox} n (U_T)^2 W}{2 L}$$

- Overview of Design Methods for RFIC
- LNA Design Considerations
- Resistive Feedback LNA
- What we need in ACM-2
- Inversion Level Based Method for R-Feedback LNA with ACM-2

## General Approach :

### Requirements

- GT, NF, IIP3, IDC  Possible Tradeoff
- fo, CL, BW  No Tradeoff

### Design parameters

- ACM parameters for a fixed L
- $V_{T0}, I_S, n, \sigma, \zeta$

### Design Variables (parameters)

- $W, q_s$  are first order design variables ( $q_s$  = inversion level sets the energy efficiency and the voltages)
- $R_L, R_F$  are second order design variables

### Approach :

- Explore the different tradeoff (the design space) on GT, NF, IIP3 and IDC by playing with  $W, q_s$ .
- In saturation region (only  $q_s$  is needed)

$$g_{msat} = \frac{2I_S}{n\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)} \quad g_{msat3} = \frac{16I_S}{(n\phi_t)^3} \frac{q_s}{(q_s + 1)^3} \frac{2 - 2\zeta q_s - 3\zeta q_s^2}{(\zeta q_s + 2)^4} \quad g_{dsat} = \sigma \frac{2I_S}{n\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)}$$

- Circuit equations depend on  $G_m$  and ACM gives  $g_m$  (normalized)...

$$|G_T| = \frac{(G_m R_F - 1) R_O}{(R_O + R_F)} \sqrt{\frac{R_O + R_F}{R_S(1 + G_m R_O)}}$$

$$G_{[m;DS]x} = \mu C'_{ox} \frac{(U_T)^{2-x}}{2} \frac{W}{L} g_{[m;DS]x}$$

Where we introduce  $W$  in the design space

$$I_S = \mu C'_{ox} n \frac{(U_T)^2}{2} \frac{W}{L} \quad I_{SL} = \frac{I_S}{W} = \mu C'_{ox} n \frac{(U_T)^2}{2L}$$



*Reducing the variables :*

Starting from :  $|G_T| = \frac{(G_m R_F - 1) R_O}{(R_O + R_F)} \sqrt{\frac{R_O + R_F}{R_S(1 + G_m R_O)}}$   $G_T(G_m; R_0; R_F; R_S) = G_T(\underbrace{W; q_s; I_D; V_{DSAT}}_{\text{variables}}; \underbrace{V_{T0}; I_S; n; \sigma; \zeta; f_c; C_L}_{\text{parameters}})$

$$G_{[m; DS]x} = \mu C'_{ox} \frac{(U_T)^{2-x}}{2} \frac{W}{L} g_{[m; DS]x} \rightarrow g_{msat} = \frac{2I_S}{n\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)} \rightarrow \boxed{G_m(q_s; W)}$$

$$\rightarrow g_{dsat} = \frac{\sigma}{n} \frac{2I_S}{\phi_t} \frac{q_s}{1 + \zeta(q_s + 1)} \rightarrow \boxed{G_{DS}(q_s; W)}$$

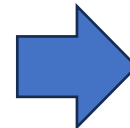
$$R_O = \frac{R_L r_{DS}}{R_L + r_{DS}} \rightarrow \boxed{G_{DS}(q_s; W)}$$

$$R_L(I_D) = \frac{V_{DD} - V_{DSAT}}{I_D} \rightarrow V_{DSAT} = \phi_t(\sqrt{1 + i_f} + 3)$$

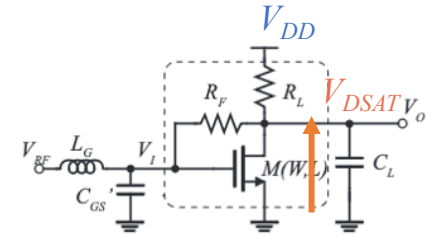
$$I_D = I_{SL} * W * i_f \rightarrow i_f = (1 + q_s)^2 \rightarrow \boxed{R_O(q_s; W)}$$

$$R_F = \frac{R_0}{2\pi R_0 C_L f_c - 1} \rightarrow \boxed{R_F(q_s; W) \Big|_{f_c}}$$

$$\left( f_c = \frac{R_O + R_F}{2\pi R_O R_F C_L} \right)$$



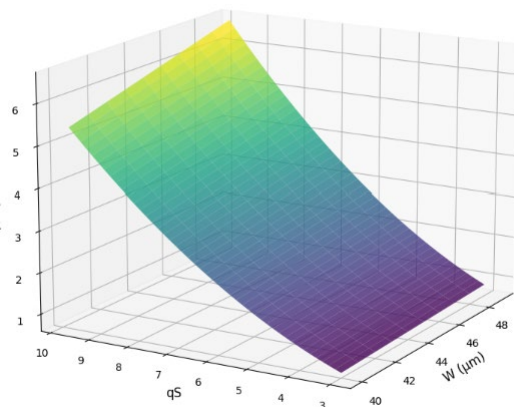
$$G_T(G_m; R_0; R_F; R_S) = G_T(W; q_s)$$



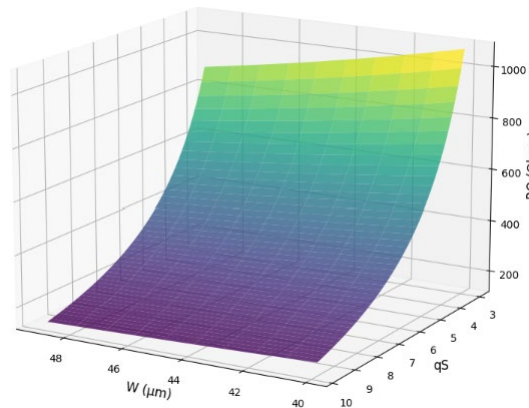
# Inversion Level Based Method for R-Feedback LNA with ACM-2

Finally :  $I_D(q_s; W)$ ;  $R_F(q_s; W)$ ;  $R_0(q_s; W)$ ;  $G_T(q_s; W)$

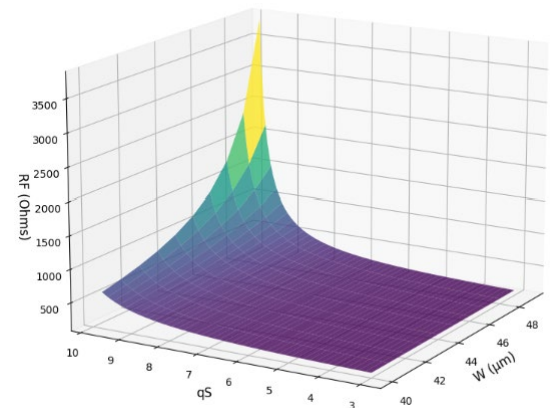
$I_D(q_s; W)$



$R_0(q_s; W)$



$R_F(q_s; W)$



*Computing  $G_T$ ,  $F$  and  $IIP3$ :*

Finally :  $|G_T| = \frac{(G_m R_F - 1) R_O}{(R_O + R_F)} \sqrt{\frac{R_O + R_F}{R_S(1 + G_m R_O)}}$

↳  $G_T(q_s; W)|_{f_c; C_L}$

$V_{IIP3} = \frac{2}{Q_{IN}} \sqrt{\frac{2G_m}{G_{m3}}}$

↳  $IIP3(q_s; W)|_{f_c; C_L; R_S}$

$$F = 1 + \frac{4 \left( \frac{R_F}{Q_{IN}^2} + R_S \right)^2}{Q_{IN}^2 G_m R_S \left[ \frac{R_F}{Q_{IN}^2} + R_S + \frac{G_m R_S R_F R_L}{R_F + R_L} \right]^2} \left[ \gamma + \frac{1}{G_m R_L} + \frac{\left( 1 + \frac{Q_{IN}^2 G_m R_S R_F}{R_F + Q_{IN}^2 R_S} \right)^2}{G_m R_F} \right]$$

↳  $F(q_s; W)|_{f_c; C_L; R_S}$

with  $G_T(q_s; W)|_{f_c; C_L}$

↳  $F(G_T; W)$

Remember :

$$Q_{IN} = V_I / V_{RF} = \sqrt{1 + Q_P^2} = \sqrt{\frac{R_O + R_F}{R_S(1 + G_m R_O)}}$$

# Inversion Level Based Method for R-Feedback LNA with ACM-2

## Exploring the design space:

Setting GT (or NF, or IIP3) helps to build 2D plots.

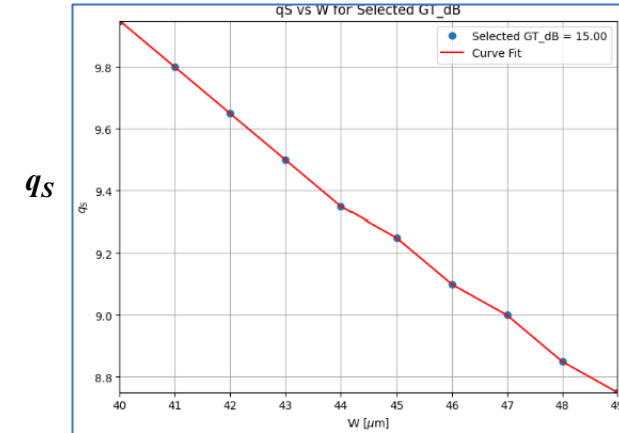
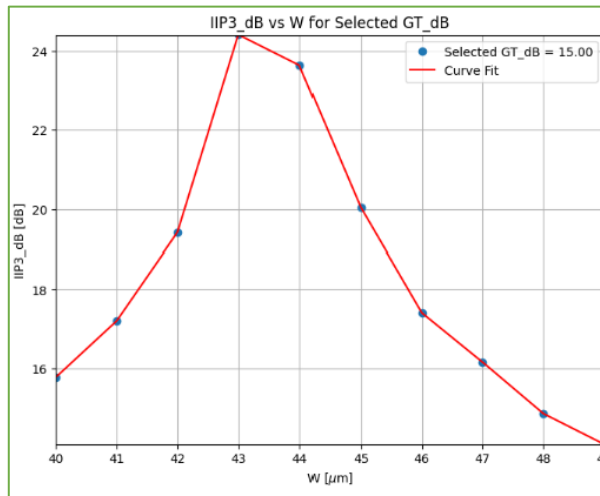
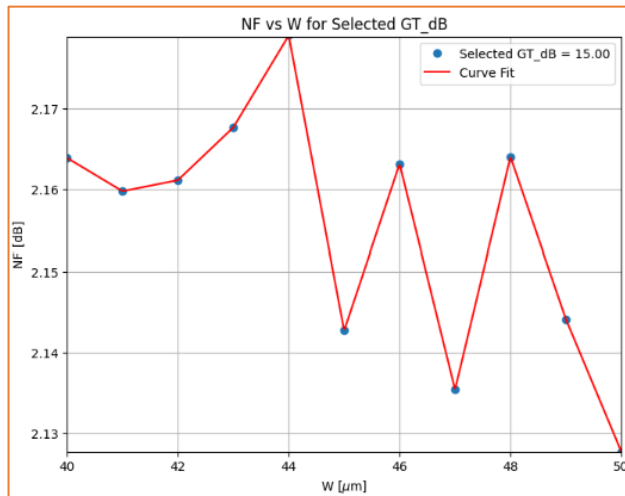
For a particular  $G_T$

=> We get the relationship  $q_s \Leftrightarrow W$

=> We plot  $NF(W)$

=> We plot  $IIP3(W)$

And We already have  $I_D$



$W(\mu m)$

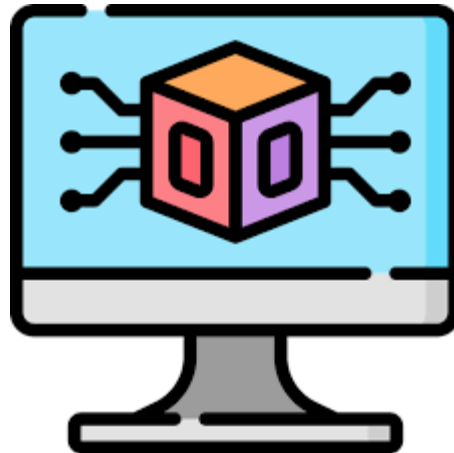
## *Setting the final value:*

- We choose  $W$ , that gives  $q_S$  for a given  $G_T$ .
- $(W; q_S)$  gives  $R_O, R_L, I_D, G_m, V_{DSAT}$  and  $V_G$

## *Input Matching*

- With  $R_O, R_F, G_m \Rightarrow R_P$   $\Re(Z_P) = R_P = \frac{R_O + R_F}{1 + G_m R_O},$
- With  $R_S$  and  $R_P$  calculate  $Q_P$   $\Re(Z_{IN}) = R_S = \frac{R_P}{(1 + Q_P^2)} = 50 \Omega$
- With  $Q_P$  calculate  $C_T$  and  $C_{GS}'$   $Q_P = R_P C_T \omega_0 \quad C_T = C_{GS} + C_{GS}' + C_P \quad C_P = \frac{R_O^2 C_L (G_m R_F - 1)}{(R_O + R_F)^2}$
- With  $C_T$  calculate  $L_G$   $\Im(Z_{IN}) = 0 = L_G s + \frac{Q_P^2}{C_T s (1 + Q_P^2)}$

Now, let's simulate with a real PDK



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