DP is defined as follows:

Definition (Uncertainty endofunctor). The *uncertainty endofunctor* Unc : $\mathbf{DP} \rightarrow$

1. It maps an object **P** in **DP** (poset) to its poset of intervals Int(**P**).

2. It maps a morphism in **DP d**: $F \rightarrow R$ to Unc(d), where:

Unc(d): Int(F)^{op} × Int(R)
$$\rightarrow_{\mathbf{Pos}}$$
 Bool $\langle [f_{\mathsf{L}}, f_{\mathsf{U}}]^*, [r_{\mathsf{L}}, r_{\mathsf{U}}] \rangle \mapsto \mathbf{d}(f_{\mathsf{L}}^*, r_{\mathsf{L}}) \wedge \mathbf{d}(f_{\mathsf{L}}^*, r_{\mathsf{U}}).$