**Definition** (Discrete-time linear systems). A discrete-time linear time-invariant proper open system is defined by three matrices  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$ . Together they give a recurrence of the type  $\mathbf{x}_{k+1} = \mathbf{A}\mathbf{x}_k + \mathbf{B}\mathbf{u}_k$ ,

$$\mathbf{y}_k = \mathbf{C}\mathbf{x}_k$$
.  
 If  $\mathbf{x}$  has dimension  $n \ge 1$ ,  $u$  dimension  $m \ge 1$  and  $\mathbf{y}$  dimension  $p \ge 1$ , then  $\mathbf{A}$  has dimension  $n \times n$ ,  $\mathbf{B}$  has dimension  $n \times m$ , and  $\mathbf{C}$  has dimension  $p \times n$ .