

$$\begin{aligned} \text{ro}_{(f;g);h} &: (\mathbf{X}_f \mathbin{;} \mathbf{X}_g) \mathbin{;} \mathbf{X}_h \rightarrow \mathbf{Y}_h \\ [x_f \mathbin{;} x_g \mathbin{;} x_h] &\mapsto \text{ro}_h(x_h), \end{aligned}$$