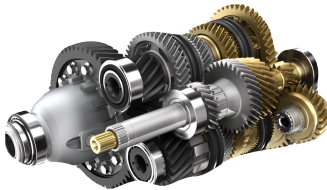


output
torque
output
speed

τ_o

ω_o

gearbox



τ_i

ω_i

input
torque
input
speed