

$$\mathbf{ro}_{f;g} : (\mathbf{X}_f \mathbin{\textcolor{teal}{;}} \mathbf{X}_g) \longrightarrow \mathbf{Y}_g$$

$$[x_f \mathbin{\textcolor{teal}{;}} x_g] \mapsto \mathbf{ro}_g(x_g)$$