

# Assignment 1

Name: Shiyin Lin  
UFID: 49619012

## 1 Cycle Finding

### 1.1 Pseudo-code

---

**algorithm 1** Disjoint-set data structure

---

**Input:** *Array* Edges

**Output:** bool

```
1: function DSU(Array)
2:   if  $x$  is not already in the forest then
3:      $x.parent := x$ 
4:   end if
5:   for each  $edge$  in Edges do
6:      $pf := \text{FIND}(edge.fr)$ 
7:      $pt := \text{FIND}(edge.to)$ 
8:     if  $pf = pt$  then
9:       Find cycle
10:      return true
11:    end if
12:     $y.parent := x$ 
13:  end for
14:  No cycle
15:  return false
16: end function
17:
18: function FIND( $x$ ) is
19:   while  $x.parent \neq x$  do
20:      $(x, x.parent) := (x.parent, x.parent.parent)$ 
21:   end while
22:   return  $x$ 
23: end function
```

---

## 1.2 Proof of Correctness

Assume the edge's node x and node y are in the set but cannot form a cycle.  
node x and node y are in the set  
 $\Rightarrow$  node x is connected to node y  
node x and node y cannot form a cycle  
 $\Rightarrow$  No edge contains node x and node y  
 $\Rightarrow$  contradiction  
 $\Rightarrow$  node x and node y in the set can form a cycle

## 1.3 Algorithm's running time

When initializing the parent array, the loop is  $n$  times, and the complexity is  $\Theta(n)$ . If the lookup path contains  $s$  nodes, it is obvious that the time complexity of the lookup is  $\Theta(s)$ . The time complexity of the find(a) and union(a) operation can be proven to be  $\Theta(\alpha(n))$  if no node's potential energy increases due to optimization using path compression and at least  $s - \alpha(n)$  nodes have their potential energy reduced by at least 1. So the total cost is  $\Theta(n) + \Theta(\alpha(n))$

## 1.4 Implement

### 1.4.1 Graph Generator

```
1 func generateUndirected(nnum int, enum int) graph.Undirected {
2     r := rand.New(rand.NewSource(time.Now().Unix()))
3     return graph.GnmUndirected(nnum, enum, r)
4 }
5
6 func generateEdges(g graph.Undirected) [][]int {
7     edgeCollect := [][]int
8     for fr, to := range g.AdjacencList {
9         for _, to := range to {
10             if graph.NI(fr) < to {
11                 tmp := []int{}
12                 tmp = append(tmp, fr)
13                 tmp = append(tmp, int(to))
14                 edgeCollect = append(edgeCollect, tmp)
15             }
16         }
17     }
18     return edgeCollect
19 }
```

### 1.4.2 Test Code

```
1 func Test() {
2     nodes := 10000000
3     edges := 20000000
4     g := generateUndirected(nodes, edges)
5     edgeCollect := generateEdges(g)
}
```

```

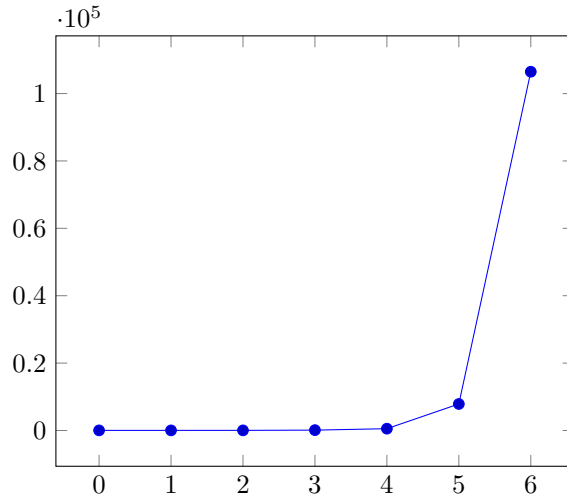
6|     start := time.Now()
7|     FindCycleDSU(edgeCollect)
8|     elapsed := time.Since(start)
9|     fmt.Println("total cost:", elapsed)
10| }

```

### 1.4.3 Test algorithm for increasing graph size

Node	Edge	t1	t2	t3	ave
10	20	25.025 $\mu s$	25.826 $\mu s$	26.6 $\mu s$	25.817 $\mu s$
100	200	24.165 $\mu s$	26.877 $\mu s$	27.149 $\mu s$	26.064 $\mu s$
1000	2000	34.612 $\mu s$	32.773 $\mu s$	33.821 $\mu s$	33.735 $\mu s$
10000	20000	97.649 $\mu s$	111.776 $\mu s$	98.966 $\mu s$	102.797 $\mu s$
100000	200000	508.58 $\mu s$	452.34 $\mu s$	629.028 $\mu s$	529.983 $\mu s$
1000000	2000000	7.098ms	8.127ms	8.371ms	7.865ms
10000000	20000000	114.545ms	109.498ms	95.398ms	106.48ms

### 1.4.4 Plot running time



## 2 Minimum Spanning Tree for sparse graphs

### 2.1 Pseudo-code

---

**algorithm 2** Kruskal

---

**Input:** *Int* numOfNodes, *Int* numOfEdges, *Array* EdgesWithWeight

**Output:** *Null*

```
1: function KRUSKAL(Int, Int, Array)
2:   if node is not already in the forest then
3:     node.parent := node
4:   end if
5:   QUICKSORT(Edges)
6:   while i < numOfEdges do
7:     pf := FIND(edge[i].fr)
8:     pt := FIND(edge[i].to)
9:     if pf ≠ pt then
10:      pt.parent = pf
11:      result += edge.weight
12:    end if
13:  end while
14:  if not result then
15:    Can't find MST
16:  else
17:    MST is : result
18:  end if
19: end function
```

---

### 2.2 Proof of Correct

Suppose that the graph  $G$  has  $n$  vertices, then the spanning tree must have  $n - 1$  edges. Since the number of spanning trees of a graph is finite, there is at least one tree with minimum cost, which is assumed to be  $U$ . First make the following assumptions.

- 1) The output tree is  $T$ .
- 2) The number of different edges in  $U$  and  $T$  is  $k$ , and the other  $n - 1 - k$  edges are the same, and these  $n - 1 - k$  edges form the edge set  $E$ .
- 3) The edges in  $T$  but not in  $U$  are  $a_1, a_2, \dots$  in order of cost from smallest to largest. ,  $a_k$ .
- 4) The edges in  $U$  but not in  $T$  are  $x_1, x_2, \dots$  in order of cost from smallest to largest. ,  $x_k$ .

By converting  $U$  to  $T$  (moving the edges of  $T$  into  $U$  in order), to prove that  $U$  and  $T$  have the same cost.

First, we move  $a_1$  into  $U$ . Since  $U$  itself is a tree, adding any edge at this point constitutes a cycle, so the addition of  $a_1$  must produce a cycle, and this cycle must include the edges in  $x_1, x_2, \dots, x_k$ . (Otherwise  $a_1$  and the edges in  $E$  form a cycle, and  $E$  is also in  $T$ , which contradicts the absence of a cycle in  $T$ .)

In this cycle delete edges belonging to  $x_1, x_2, \dots, x_k$  and the most costly edge  $x_i$  forms a new spanning tree  $V$ .

Assuming that  $a_1$  cost is less than  $x_i$ , the cost of  $V$  is less than  $U$ . This contradicts that  $U$  is a minimum cost tree, so  $a_1$  cannot be less than  $x_i$ . Assuming that  $a_1$  is greater than  $x_i$ , according to Kruskal's algorithm, the edge with small cost is considered first, then when Kruskal's algorithm is executed,  $x_i$  should be considered before  $a_1$ , which in turn is considered before  $a_2, \dots, a_k$  before considering  $x_i$ , so before considering  $x_i$ , the edges in  $T$  can only be edges in  $E$ . And since  $x_i$  did not join the tree  $T$ , it means that  $x_i$  must constitute a cycle with some edges in  $E$ . But  $x_i$  and  $E$  are in  $U$  at the same time, which contradicts with  $U$  being a spanning tree, so  $a_1$  cannot be larger than  $x_i$  either.

Therefore, the newly obtained tree  $V$  has the same cost as  $T$ .

By analogy, adding the edges of  $a_1, a_2, \dots$ , the edges of  $a_k$  are gradually added to  $U$ , and the final obtained tree  $T$  has the same cost as  $U$ .

## 2.3 Algorithm's running time

Since the algorithm is optimized using the DSU of path compression, the complexity is  $\Theta(n) + \Theta(\alpha(n))$ , and since it contains a quick sort operation, the consultation complexity is  $\Theta(n) + \Theta(\alpha(n)) + \Theta(m \log m)$

## 2.4 Implement

### 2.4.1 Graph Generator

```

1 func generateConnectGraph(nnum int, enum int) graph.Undirected {
2     n, _ := rand2.Int(rand2.Reader, big.NewInt(65536))
3     r := rand.New(rand.NewSource(n.Int64()))
4     g := graph.GnmUndirected(nnum, enum, r)
5     if !g.IsConnected() {
6         generateConnectGraph(nnum, enum)
7     }
8     return g
9 }
10
11 func generateWEdges(g graph.Undirected, enum int) [][]int {

```

```

12 weight := make([]int, enum)
13
14 for i := 0; i < enum; i++ {
15     n, _ := rand2.Int(rand2.Reader, big.NewInt(int64(20)))
16     if n.Int64() == 0 {
17         weight[i] = int(n.Int64()) + 1
18     } else {
19         weight[i] = int(n.Int64())
20     }
21 }
22 edgeCollect := [][]int{}
23 for fr, to := range g.AdjacencyList {
24     for _, to := range to {
25         if graph.NI(fr) < to {
26             tmp := []int{}
27             tmp = append(tmp, fr)
28             tmp = append(tmp, int(to))
29             edgeCollect = append(edgeCollect, tmp)
30         }
31     }
32 }
33 for i:=0; i<enum; i++ {
34     edgeCollect[i] = append(edgeCollect[i], weight[i])
35 }
36 return edgeCollect
37 }

```

#### 2.4.2 Test Code

```

1 func Test2() {
2     nodes := 10
3     edges := 18
4     if edges < nodes-1 {
5         fmt.Println("too less edges")
6         os.Exit(-1)
7     }
8     g := generateConnectGraph(nodes, edges)
9     edgeCollect := generateWEdges(g, edges)
10    fmt.Println(edgeCollect)
11    sort.Slice(edgeCollect[:edges], func(i, j int) bool {
12        return edgeCollect[i][2] < edgeCollect[j][2]
13    })
14    fmt.Println(edgeCollect)
15    start := time.Now()
16    kruskal(nodes, edges, edgeCollect)
17    elapsed := time.Since(start)
18    fmt.Println("total cost:", elapsed)
19 }

```

### 2.4.3 Test algorithm for increasing graph size

Node	Edge	t1	t2	t3	ave
10	18	4.048 $\mu s$	3.732 $\mu s$	5.301 $\mu s$	4.36 $\mu s$
20	28	5.059 $\mu s$	5.263 $\mu s$	5.503 $\mu s$	5.275 $\mu s$
30	38	5.912 $\mu s$	6.125 $\mu s$	5.426 $\mu s$	5.821 $\mu s$
40	48	5.534 $\mu s$	6.11 $\mu s$	6.466 $\mu s$	6.037 $\mu s$
50	58	9.591 $\mu s$	9.011 $\mu s$	9.313 $\mu s$	9.305 $\mu s$
60	68	9.369 $\mu s$	9.515 $\mu s$	9.561 $\mu s$	9.482 $\mu s$
70	78	10.076 $\mu s$	11.741 $\mu s$	12.044 $\mu s$	11.287 $\mu s$

### 2.4.4 Plot running time

