



HANDLING SYCL ERRORS





LEARNING OBJECTIVES

- Learn about how SYCL handles errors
- Learn about the difference between synchronous and asynchronous exceptions
- Learn how to handle exceptions and retrieve further information
- Learn about the different exception types
- Learn about the host device and how to use it





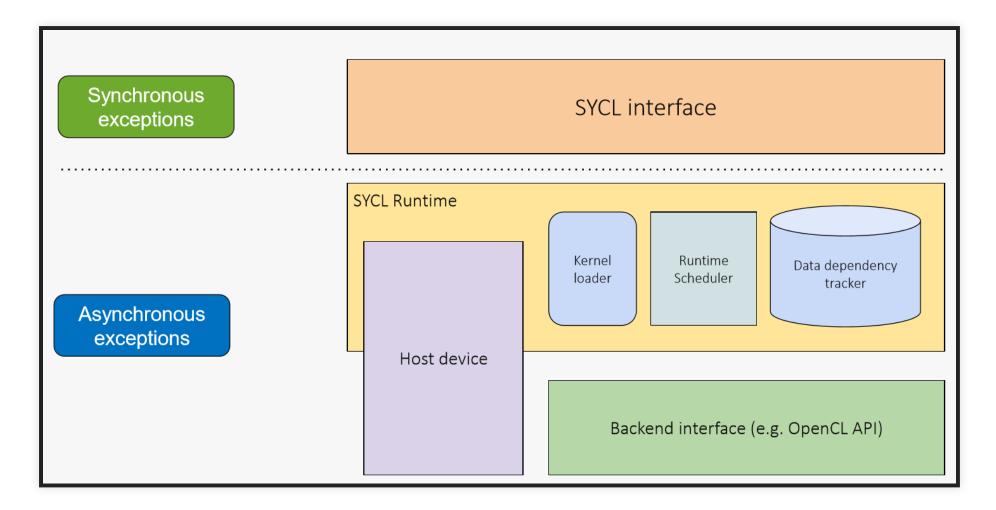


- In SYCL errors are handled by throwing exceptions
 - It is crucial that these errors are handled otherwise your application may silently fail
- In SYCL there are two kinds of error
 - Synchronous errors (thrown in user thread)
 - Asynchronous errors (thrown by the SYCL scheduler)













HANDLING ERRORS







```
#include <CL/sycl.hpp>
using namespace cl::sycl;
class add;
int main(int argc, char *argv[]) {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  queue gpuQueue(gpu selector{});
  buffer<float, 1> bufA(dA.data(), range<1>(dA.size()));
  buffer<float, 1> bufB(dB.data(), range<1>(dB.size()));
  buffer<float, 1> buf0(d0.data(), range<1>(d0.size()));
  gpuQueue.submit([&](handler &cgh){
    auto inA = bufA.get access<access::mode::read>(cgh);
    auto inB = bufB.get access<access::mode::read>(cgh);
    auto out = bufO.get access<access::mode::write>(cgh);
    cgh.parallel for<add>(range<1>(dA.size()), [=](id<1> i) {
      out[i] = inA[i] + inB[i];
    });
  });
  gpuQueue.wait();
```

• If errors are not handled, the application can fail silently







```
int main(int argc, char *argv[]) {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try{
    queue gpuQueue(gpu selector{});
    buffer<float, 1> bufA(dA.data(), range<1>(dA.size()));
    buffer<float, 1> bufB(dB.data(), range<1>(dB.size()));
    buffer<float, 1> bufO(dO.data(), range<1>(dO.size()));
    gpuQueue.submit([&](handler &cgh){
      auto inA = bufA.get access<access::mode::read>(cgh);
      auto inB = bufB.get access<access::mode::read>(cgh);
      auto out = buf0.get access<access::mode::write>(cgh);
      cgh.parallel for<add>(range<1>(dA.size()), [=](id<1> i){
        out[i] = inA[i] + inB[i];
      });
    });
    gpuQueue.wait();
   catch (...) { /* handle errors */ }
```

- Synchronous errors are typically thrown by SYCL API functions
- In order to handle all SYCL errors you must wrap everything in a try-catch block







```
int main(int argc, char *argv[]) {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
    queue gpuQueue(gpu selector{}, async handler{});
    buffer<float, 1> bufA(dA.data(), range<1>(dA.size()));
    buffer<float, 1> bufB(dB.data(), range<1>(dB.size()));
    buffer<float, 1> bufO(dO.data(), range<1>(dO.size()));
    gpuQueue.submit([&](handler &cgh){
      auto inA = bufA.get access<access::mode::read>(cgh);
      auto inB = bufB.get access<access::mode::read>(cgh);
      auto out = bufO.get access<access::mode::write>(cgh);
      cgh.parallel for<add>(range<1>(dA.size()), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    });
    gpuQueue.wait and throw();
  } catch (...) { /* handle errors */
```

- Asynchronous errors errors that may have occurred will be thrown after a command group has been submitted to a queue
 - To handle these errors you must provide an async handler when constructing the queue object
- Then you must also call the throw_asynchronous or wait_and_throw member functions of the queue class
- This will pass the exceptions to the async handler in the user thread so they can be thrown







```
int main(int argc, char *argv[]) {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try{
    queue gpuQueue(gpu selector{}, [=](sycl::exception list eL) {
      for (auto e : eL) { std::rethrow exception(e); }
    });
    buffer<float, 1> bufA(dA.data(), range<1>(dA.size()));
    buffer<float, 1> bufB(dB.data(), range<1>(dB.size()));
    buffer<float, 1> buf0(d0.data(), range<1>(d0.size()));
    gpuQueue.submit([&](handler &cgh){ // Command group submitted to queue
      auto inA = bufA.get access<access::mode::read>(cgh);
      auto inB = bufB.get access<access::mode::read>(cgh);
      auto out = bufO.get access<access::mode::write>(cgh);
      cgh.parallel for<add>(range<1>(dA.size()), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    });
    gpuQueue.wait and throw(); } catch (...) { /* handle errors */ }
```

- The async handler is a C++ lambda or function object that takes as a parameter an exception_list
- The exception_list class is a wrapper around a list of **exception_ptrs** which can be iterated over
- The exception_ptrs can be rethrown by passing them to **std::rethrow_exception**







```
int main(int argc, char *argv[]) {
    std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
    try {
        queue gpuQueue(gpu_selector{}, [=](sycl::exception_list eL) {
            for (auto e : eL) { std::rethrow_exception(e); }
        });
        ...
            gpuQueue.wait_and_throw();
} catch (std::exception e) {
            std::cout << "Exception caught: " << e.what()
            << std::endl;
}
}</pre>
```

- Once rethrown and caught, a SYCL exception can provide information about the error
- The what member function will return a string with more details







```
int main(int argc, char *argv[]) {
   std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
   try {
      queue gpuQueue(gpu_selector{}, [=](sycl::exception_list eL) {
            for (auto e : eL) { std::rethrow_exception(e); }
      });
      ...
      gpuQueue.wait_and_throw();
} catch (std::exception e) {
      std::cout << "Exception caught: " << e.what();
      std:: cout << "With OpenCL error code: "
      << e.get_cl_code() << std::endl;
}
}</pre>
```

- If the exception has an OpenCL error code associated with it this can be retrieved by calling the get_cl_code member function
- If there is no OpenCL error code this will return CL_SUCCESS







- The has_context member function will tell you if there is a SYCL context associated with the error
- If that returns true then the get_context member function will return the associated SYCL context object







EXCEPTION TYPES







- In SYCL there are a number of different exception types that inherit from std::exception
 - E.g. runtime_error, kernel_error
- The SYCL 1.2.1 specification will detail cases where a specific error can be expected







DEBUGGING SYCL KERNEL FUNCTIONS





- Every SYCL implementation is required to provide a host device
 - This device executes native C++ code but is guaranteed to emulate the SYCL execution and memory model
- This means you can debug a SYCL kernel function by switching to the host device and using a standard C++ debugger
 - For example gdb







```
int main(int argc, char *argv[]) {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try{
    queue hostQueue(host selector{}, async handler{});
   buffer<float, 1> bufA(dA.data(), range<1>(dA.size()));
   buffer<float, 1> bufB(dB.data(), range<1>(dB.size()));
   buffer<float, 1> buf0(d0.data(), range<1>(d0.size()));
   hostQueue.submit([&](handler &cgh){
      auto inA = bufA.get access<access::mode::read>(cgh);
      auto inB = bufB.get access<access::mode::read>(cgh);
      auto out = buf0.get access<access::mode::write>(cgh);
      cgh.parallel for<add>(range<1>(dA.size()),
      [=] (id<1>i) {out[i] = inA[i] + inB[i];});
    });
   gpuQueue.wait and throw();
  } catch (...) { /* handle errors */ }
```

- Any SYCL application can be debugged on the host device by switching the queue for a host queue
- By replacing the device selector for the host_selector will ensure that the queue submits all work to the host device

