HANDLING ERRORS AND DEBUGGING

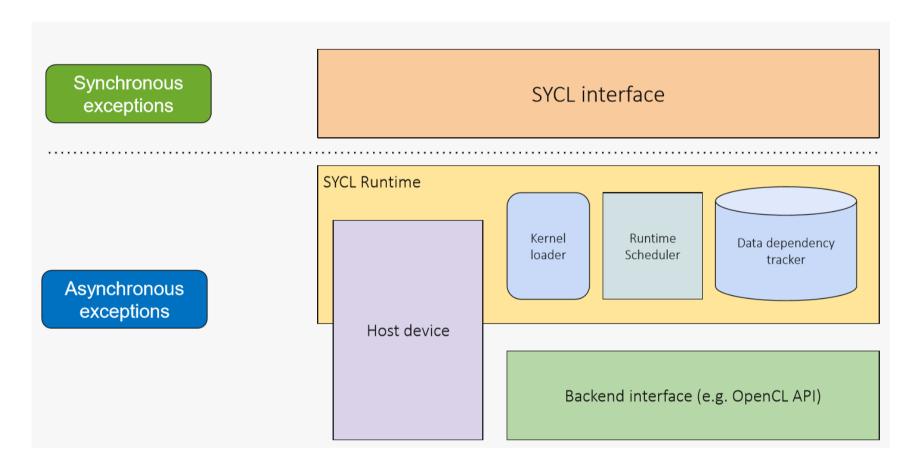
LEARNING OBJECTIVES

- Learn about how SYCL handles errors
- Learn about the difference between synchronous and asynchronous exceptions
- Learn how to handle exceptions and retrieve further information
- Learn about the host device and how to use it

SYCL EXCEPTIONS

- In SYCL errors are handled by throwing exceptions.
- It is crucial that these errors are handled, otherwise your application could fail in unpredictable ways.
- In SYCL there are two kinds of error:
 - Synchronous errors (thrown in user thread) .
 - Asynchronous errors (thrown by the SYCL scheduler).

SYCL EXCEPTIONS



HANDLING ERRORS

```
class add;
int main() {
    std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, d0{ 0, 0, 0, 0 };
    queue gpuQueue(gpu_selector{});
    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    gpuQueue.submit([&](handler &cgh) {
        auto inA = accessor{bufA, cgh, read_only};
        auto inB = accessor{bufB, cgh, read_only};
        auto out = accessor{bufO, cgh, write_only};

        cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
            out[i] = inA[i] + inB[i];
            });
        }).wait();
}
```

- If errors are not handled, the application can fail:
 - SYCL 1.2.1 application will fail silently.
 - SYCL 2020 provides a default async handler that will call std::terminate when an asynchronous error is thrown.

```
class add;
int main() {
 std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try {
   queue gpuQueue(gpu selector{});
   buffer bufA{dA};
   buffer bufB{dB};
   buffer buf0{d0};
    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read only};
      auto inB = accessor{bufB, cgh, read only};
      auto out = accessor{buf0, cgh, write only};
      cgh.single task<add>(buf0.get range(), [=](id<1> i) {
       out[i] = inA[i] + inB[i];
     });
   }).wait();
 } catch (...) { /* handle errors */ }
```

- Synchronous errors are typically thrown by SYCL API functions.
- In order to handle all SYCL errors you must wrap everything in a try-catch block.

```
class add;
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try{
    queue gpuQueue(gpu selector{}, async handler{});
    buffer bufA{dA};
    buffer bufB{dB};
    buffer buf0{d0};
    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read only};
      auto inB = accessor{bufB, cgh, read only};
      auto out = accessor{buf0, cgh, write only};
      cgh.single task<add>(buf0.get range(), [=](id<1> i) {
       out[i] = inA[i] + inB[i];
     });
    }).wait();
    gpuQueue.throw asynchronous();
 } catch (...) { /* handle errors */
```

- Asynchronous errors errors that may have occurred will be thrown after a command group has been submitted to a queue.
 - To handle these errors you must provide an async handler when constructing the queue object.
- Then you must also call the throw_asynchronous or wait_and_throw member functions of the queue class.
- This will pass the exceptions to the async handler in the user thread so they can be thrown.

```
class add;
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try{
   queue gpuQueue(gpu selector{}, [=](exception list eL) {
     for (auto e : eL) { std::rethrow exception(e); }
  });
    buffer bufA{dA};
    buffer bufB{dB};
    buffer buf0{d0};
    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{buf0, cgh, write_only};
      cgh.single_task<add>(buf0.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
     });
    }).wait();
    gpuQueue.throw asynchronous();
 } catch (...) { /* handle errors */ }
```

- The async handler is a C++ lambda or function object that takes as a parameter an exception_list
- The exception_list class is a wrapper around a list of exception_ptrs which can be iterated over
- The exception_ptrs can be rethrown by passing them to std::rethrow_exception

```
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try {
    queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
        for (auto e : eL) { std::rethrow_exception(e); }
    });
    ...
    gpuQueue.throw_asynchronous();
} catch (const std::exception& e) {
    std::cout << "Exception caught: " << e.what()
        << std::endl;
}
}</pre>
```

- Once rethrown and caught, a SYCL exception can provide information about the error
- The what member function will return a string with more details

```
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, d0{ 0, 0, 0, 0 };
  try {
    queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
        for (auto e : eL) { std::rethrow_exception(e); }
    });
    ...
    gpuQueue.throw_asynchronous();
} catch (const sycl::exception& e) {
    std::cout << "Exception caught: " << e.what();
    std:: cout << "With OpenCL error code: "
        << e.get_cl_code() << std::endl;
}
}</pre>
```

- In SYCL 1.2.1, if the exception has an OpenCL error code associated with it this can be retrieved by calling the get_cl_code member function
- If there is no OpenCL error code this will return CL_SUCCESS
- SYCL 2020 provides the error_category_for templated free function that allows checking for the category of the exception depending on the backend used (e.g. backend::opencl), and e.code().value() will correspond to the backend error code.

- The has_context member function will tell you if there is a SYCL context associated with the error
- If that returns true then the get_context member function will return the associated SYCL context object

EXCEPTION TYPES

- In SYCL 1.2.1 there are a number of different exception types that inherit from std::exception
 - E.g. runtime_error, kernel_error
- SYCL 2020 only has a single sycl::exception type which provides different error codes
 - E.g. errc::runtime, errc::kernel

DEBUGGING SYCL KERNEL FUNCTIONS

- Every SYCL 1.2.1 implementation is required to provide a host device
 - This device executes native C++ code but is guaranteed to emulate the SYCL execution and memory model
- This means you can debug a SYCL kernel function by switching to the host device and using a standard C++ debugger
 - For example gdb

• SYCL 2020 only guarantees that a device will always be available, and users can query the host_debuggable device aspect to check whether they can use the same functionality as the SYCL 1.2.1 host device

```
class add;
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
 try{
    queue hostQueue(aspect selector<aspect::host debuggable>(), async handler{});
    buffer bufA{dA};
    buffer bufB{dB};
    buffer buf0{d0};
    hostQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read only};
      auto inB = accessor{bufB, cgh, read only};
      auto out = accessor{buf0, cgh, write only};
      cgh.single task<add>(buf0.get range(), [=](id<1> i) {
       out[i] = inA[i] + inB[i];
     });
    });
    hostQueue.wait_and_throw();
 } catch (...) { /* handle errors */ }
```

- Any SYCL application can be debugged on the host device by switching the queue for a host queue
- Replacing the device selector for the aspect_selector will ensure that
 the queue submits all work to the device with the requested aspects, in this
 case a host debuggable device
- In SYCL 1.2.1, host_selector would be used instead, deprecated in SYCL 2020

QUESTIONS

EXERCISE

Code_Exercises/Exercise_4_Handling_Errors/source

Add error handling to a SYCL application for both synchronous and asynchronous errors.