

## Definitions

### Define the change of basis matrix A1

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In[1]:= A[l_, m_] := Sqrt[(2 - KroneckerDelta[m, 0]) (2 l + 1) (l - m)! / (4 π (l + m)!)] ;

B[l_, m_, j_, k_] := (2^l m! (l+m+k-1)/2)! / (j! k! (m-j)! (l-m-k)! ((-l+m+k-1)/2)!);

Yxyz[l_, m_, x_, y_, z_] := { Sum[Sum[(-1)^(j/2) A[l, m] B[l, m, j, k] x^(m-j) y^j z^k, {k, 0, l-m}], {
  Sum[Sum[(-1)^(j-1)/2 A[l, Abs[m]] B[l, Abs[m], j, k] x^(Abs[m]-j) y^j z^k,
  {j, 1, Abs[m], 2}]}

Y[l_, m_, x_, y_] :=
  Expand[FullSimplify[Yxyz[l, m, x, y, Sqrt[1-x^2-y^2]]] /. Sqrt[1-x^2-y^2] -> z;
bp[n_, x_, y_] := Module[{l, m, μ, ν},
  l = Floor[Sqrt[n]];
  m = n - l^2 - l;
  μ = l - m;
  ν = l + m;
  If[EvenQ[ν], x^(μ/2) y^(ν/2), x^(μ-1)/2 y^(ν-1)/2 Sqrt[1-x^2-y^2]];
p[l_, m_, lmax_] := Module[{Ylm},
  Ylm = Y[l, m, x, y] /. z -> Sqrt[1-x^2-y^2];
  Join[{Evaluate[Ylm /. {Sqrt[1-x^2-y^2] -> 0, x -> 0, y -> 0}]}],
  Table[Coefficient[Ylm, bp[n, x, y]] /. {Sqrt[1-x^2-y^2] -> 0, x -> 0, y -> 0},
  {n, 1, (lmax+1)^2 - 1}]]];
A1[lmax_] := Transpose[Flatten[Table[p[l, m, lmax], {l, 0, lmax}, {m, -l, l}], 1]];

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### Convert our polynomial vector **p** to a spherical harmonic vector **y**

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In[8]:= pvec = {1 - u1 - 2 u2, 0, u1 + 2 u2, 0, u2, 0, 0, 0, 0, u2};
yvec = Dot[Inverse[A1[2]], pvec];
FullSimplify[Dot[yvec, {Y0,0, Y1,-1, Y1,0, Y1,1, Y2,-2, Y2,-1, Y2,0, Y2,1, Y2,2}]]

Out[10]= 2/15 Sqrt[π] (-5 (-3 + 3 u1 + 4 u2) Y0,0 + 5 Sqrt[3] (u1 + 2 u2) Y1,0 - 2 Sqrt[5] u2 Y2,0)

In[11]:= Collect[%, {Y0,0, Y1,-1, Y1,0, Y1,1, Y2,-2, Y2,-1, Y2,0, Y2,1, Y2,2}, Simplify]

Out[11]= -2/3 Sqrt[π] (-3 + 3 u1 + 4 u2) Y0,0 + 2 Sqrt[π/3] (u1 + 2 u2) Y1,0 - 4/3 Sqrt[π/5] u2 Y2,0

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