

**Universidade de Lisboa
Instituto Superior Técnico**

Thesis Title that describes the subject studied.

Optional Subtitle

Full Name

Supervisor : **Doctor** Full Name
Co-Supervisor : **Doctor** Full Name

**Thesis specifically prepared to obtain the PhD Degree in
Mechanical Engineering**

Draft

November 2017

Abstract

The Objective of this Work ... (English)

Keywords

Keywords (English)

Resumo

O objectivo deste trabalho ... (Português)

Palavras Chave

Palavras-Chave (Português)

Acknowledgments

I would like to thank the Academy, bla bla bla..

Anyone who has never made a mistake has never tried anything new.

Albert Einstein

Contents

1	Introduction	1
1.1	Motivation	2
1.2	State of The Art	2
1.2.1	Dummy Subsection A	2
1.2.2	Dummy Subsection B	2
1.3	Original Contributions	2
1.4	Thesis Outline	2
2	A Chapter	3
2.1	Section A	4
2.1.1	Subsection A	4
2.1.2	Subsection B	4
2.2	Section B	4
2.2.1	Subsection A	4
2.2.2	Subsection B	5
3	Conclusions and Future Work	7
	Bibliography	A-1
	Appendix A Title of AppendixA	A-1

List of Figures

2.1 Dummy Figure Caption for List of Figures.	4
---	---

List of Tables

2.1	Dummy Table.	5
-----	----------------------	---

Abbreviations

acro Dummy Acronym

List of Symbols

1

Introduction

Contents

1.1	Motivation	2
1.2	State of The Art	2
1.3	Original Contributions	2
1.4	Thesis Outline	2

1.1 Motivation

Motivation Section.

1.2 State of The Art

State of The Art Section.

1.2.1 Dummy Subsection A

State of Art Subsection A

1.2.2 Dummy Subsection B

State of Art Subsection B

1.3 Original Contributions

Contributions Section.

1.4 Thesis Outline

Outline Section.

2

A Chapter

Contents

2.1	Section A	4
2.2	Section B	4

Present the chapter content.

2.1 Section A

2.1.1 Subsection A

This would be a citation [?].

Dummy Acronym (acro)

Dummy Acronym (acro)

acro

Dummy Acronym

acros

As seen in [?]. *Enfatizar*

2.1.2 Subsection B



Figure 2.1: Dummy Figure Caption.

Remember you can change the reference style. Another dummy citation [?].

2.2 Section B

2.2.1 Subsection A

The model described can also be represented as

$$\dot{\mathbf{x}}(t) = \mathbf{T}\mathbf{z}(y), \mathbf{y}(0) = \mathbf{y}_0, z \geq 0 \quad (2.1)$$

where

$$\mathbf{A} = \begin{bmatrix} -(a_{12} + a_{10}) & a_{21} \\ a_{12} & -(a_{21} + a_{20}) \end{bmatrix}, \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad (2.2)$$

2.2.2 Subsection B

Table 2.1: Dummy Table.

Vendor Name	Short Name	Commercial Name	Manufacturer
Text in Multiple Row	ABC	ABC [®]	ABC SA
	DEF	DEF [®]	DEF SA
	GHF	GHF [®]	GHF SA
Text in Single Row	IJK	IJK [®]	IJK SA
Frescos SA	LMN	LMN [®]	LMN SA
Carros Lda.	Text in Multiple Column		

3

Conclusions and Future Work



Title of AppendixA

