MTH 100: Lecture 28

Change of Basis

- · We would like to know what happens to the matrix of a linear townsformation if the basis gets change.
- · We will only consider the case when T is a linear operator from a finite dimensional vector space V to V

Pheliminary Result:

Profosition: Let $B = \{N_1, ..., N_n\}$ and $C = \{N_1, ..., N_n\}$ be two ordered bases of a vector space V. Then there is an invertible nxn matrix P such that $[X]_c = P[X]_R$ for any $X \in V$.

Proof: Will be given as a note. (rather technical)

Note: The columns of P we the C-coordinate vectors of the basis B.

The matrix P is called the change of coordinate

matrix from B to C and is denoted by PB -> c

Remark: To change coordinates between two bases, eve need the <u>coordinate vectors of the old basis</u> B relative to the <u>new basis</u> C.

These become the columns of the change of matrix P.

• In fractice $P = Q^{-1}$ corbers Q has its columns the <u>coordinate vectors</u> of the new basis C trelative to the old basis B.

In most of the applications, the old basis is the standard basis for Rn and so a can be found directly.

Recall the first example of last lecture. Ex (First Bart):

Let $V = \mathbb{R}^2$ Let old (ordered) basis $d = \begin{cases} e_1, e_2 \end{cases} = \begin{cases} \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{cases}$ And Let new (ordered) basis $B = \begin{cases} u_1, u_2 \rbrace = \begin{cases} \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 3 \end{bmatrix} \rbrace$ (Should be clear that this is a basis)

Step 1: Construct the matrix Q

= $\begin{bmatrix} 2 & 5 \end{bmatrix}$ Since $u_1 = 2e_1 + 1e_2$ and $u_2 = 5e_1 + 3e_2$ we have $\begin{bmatrix} u_1 \end{bmatrix}_{\alpha} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}_{\alpha}$ New basis in terms of old basis

Step 2 Change of Basis Matrix = $P = \begin{bmatrix} P \\ d \rightarrow \beta \end{bmatrix} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix}$ efeck: Let us determine $\begin{bmatrix} v \end{bmatrix}_{\beta}$ for a specific vector v, say $v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{\alpha}$ Then $\begin{bmatrix} v \end{bmatrix}_{\beta} = P\begin{bmatrix} v \end{bmatrix}_{\alpha} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -7 \\ 3 \end{bmatrix}_{\beta}$ Note that $\begin{bmatrix} -7 \\ 3 \end{bmatrix}_{\beta} = -7 u_1 + 3 u_2 = -7 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{\alpha} = v$

Verification that columns of P are the coordinate vectors of the old basis in terms of the new basis.

First column
of
$$P = \begin{bmatrix} 3 \\ -1 \end{bmatrix}_{B} = 3 u_{1} + (-1) u_{2} = 3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = e_{1}$$

Similarly,

Second Column of $P = \begin{bmatrix} 5 \\ -2 \end{bmatrix}_{B} = 5 u_{1} + (-2) u_{2} = 5 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + (-2) \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = e_{2}$

i.e. $P = \begin{bmatrix} 62 \\ -2 \end{bmatrix}_{B} = \begin{bmatrix} 5 \\ -2 \end{bmatrix}_{B}$

Similarity of Matrices

· A nxn matrix B is called similar to an nxn matrix A if there exists an invertible matrix P

Such that $B = PAP^{-1}$.

Proposition: Similarity of matrices is an equivalence relation on F nxn (Fnxn is the set of nxn metrices with entries taken from a field F)

Remarks (1): If A is similar to B, then B is similar to A.

(50, we will say A and B are similar materies)

(2) If A and B are similar matrices

then det(A) = det(B)

Effect of change of Basis

Proposition: Suppose A and B are the meetrices of the linear operator T relative to the ordered basis of and B respectively.

Then A and B are similar matrices. Infact, $B = PAP^{-1}$, where $P = P_{d \to b}$ is the

$$= \begin{bmatrix} -38 & -102 \\ 16 & 43 \end{bmatrix}$$

Verification with a specific vector:

Let
$$9 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{\mathcal{A}} = \begin{bmatrix} -7 \\ 3 \end{bmatrix}_{\mathcal{B}}$$

Now.
$$\begin{bmatrix} T v \end{bmatrix}_{d} = \begin{bmatrix} T \end{bmatrix}_{d} \begin{bmatrix} v \end{bmatrix}_{d} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 11 \end{bmatrix}_{d}$$

and
$$[Tv]_{B} = [T]_{B}[v]_{S} = \begin{bmatrix} -38 & -102 \\ 16 & 43 \end{bmatrix}\begin{bmatrix} -7 \\ 3 \end{bmatrix}$$

Note that

Note that

$$\begin{bmatrix} -40 \\ 17 \end{bmatrix}_{B} = -40 \mathcal{U}_{1} + 17 \mathcal{U}_{2}$$

$$= -40 \mathcal{U}_{1} + 17 \mathcal{U}_{3}$$

$$= \begin{bmatrix} 5 \\ 11 \end{bmatrix}_{\mathcal{U}_{2}}$$

So, eve get the same vector but expressed in two different coordinate system.