SEMA 4.0 Linux User Manual / Test Procedure

Version 1.4

**Record of Release**

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# Getting Started

Install GIT utility to download and compile ADLINK SEMA module for Linux. Install git tool.

$ sudo apt install git

Install “Hexer” for editing the binary files.

$ sudo apt install hexer

Next, install i2c-tools

$ sudo apt install i2c-tools

The current SEMA version was validated on Ubuntu 16.04.6 and Ubuntu 18.04.2 with kernel versions 4.15.0-54-generic and 4.18.0-22-generic respectively.

# Compiling the SEMA Linux Package

1. Download the source code from ADLINK git repository:

$ git clone <http://GitLab.Adlinktech.com/AATI_CCoE/SEMA_4.0_Linux_SandBox.git>

1. Change directory to workspace.

$ cd SEMA\_4.0\_Linux\_SandBox

1. Compile

$ make

1. After compilation, the following kernel modules and executables will be generated.

|  |  |
| --- | --- |
| **File** | **Description** |
| driver/adl-bmc.ko | SEMA Linux BMC Driver Core Module |
| driver/adl-bmc-boardinfo.ko | SEMA Linux BMC Board Information Driver Module |
| driver/adl-bmc-vm.ko | SEMA Linux BMC Voltage Monitor Driver Module |
| driver/adl-bmc-hwmon.ko | SEMA Linux BMC Smart Fan and Hardware Monitor Driver Module |
| driver/adl-bmc-wdt.ko | SEMA Linux BMC Watchdog Driver Module |
| driver/adl-bmc-nvmem.ko | SEMA Linux BMC NVMEM Driver Module |
| driver/adl-bmc-bklight.ko | SEMA Linux BMC Backlight Driver Module |
| wdogtest | SEMA Linux Watchdog Test application |
| adltest | SEMA Linux Command Line Utility |

# Installing the SEMA Linux Kernel Drivers

The following commands will install the SEMA related device drivers.

$ cd SEMA\_4.0\_Linux\_SandBox

$ sudo make install

$ sudo modprobe i2c\_i801

$ sudo modprobe adl-bmc

$ sudo modprobe adl-bmc-boardinfo

$ sudo modprobe adl-bmc-vm

$ sudo modprobe adl-bmc-wdt

$ sudo modprobe adl-bmc-hwmon

$ sudo modprobe adl-bmc-nvmem

$ sudo modprobe adl-bmc-bklight

Install native GPIO driver by using following steps:

1. Load the native GPIO diriver

$ sudo modprobe gpio-pca953x

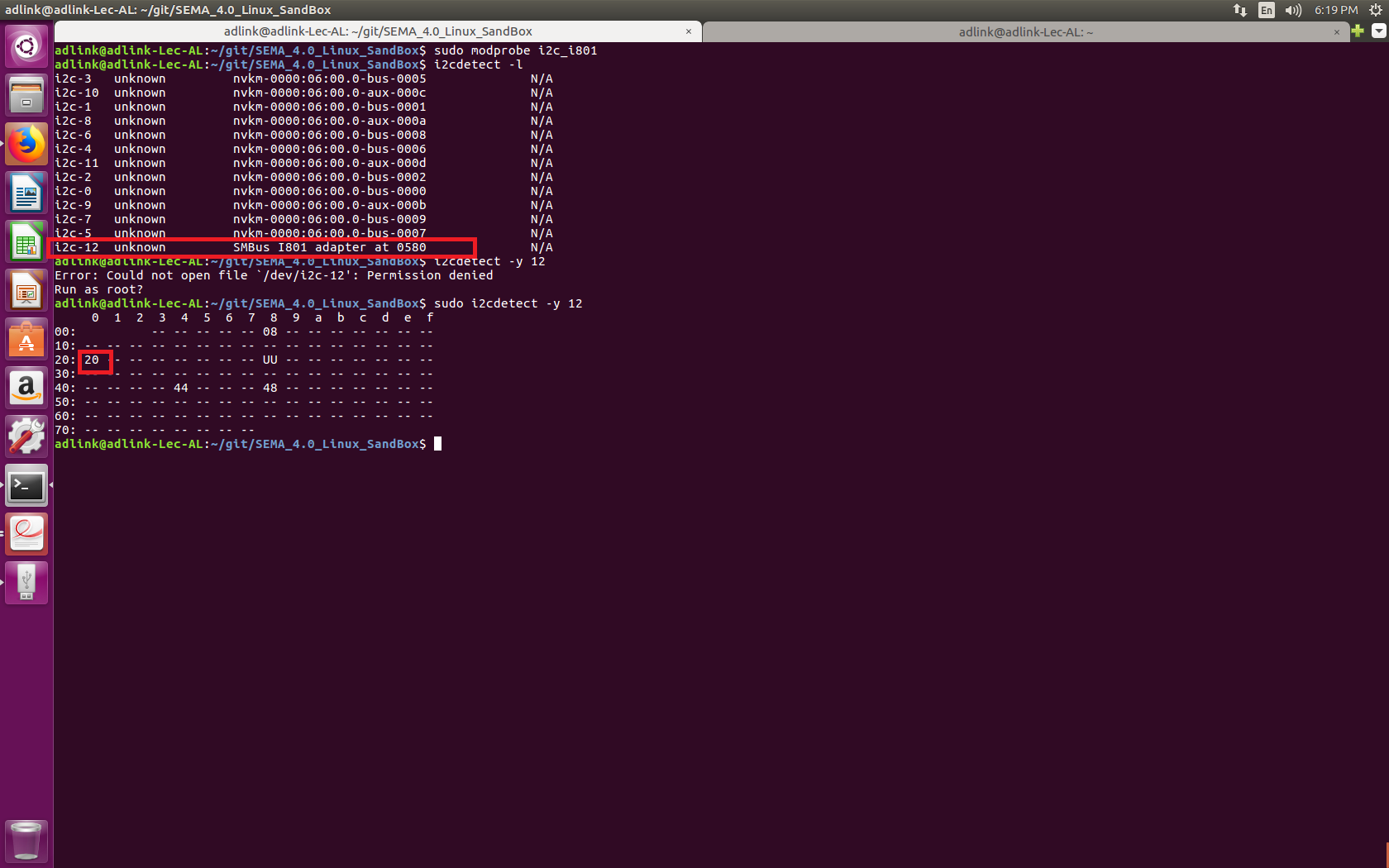
1. After loading kernel driver, configure the GPIO device with the following command.

$ echo pca9535 0x20 > /sys/bus/i2c/devices/i2c-12/new\_device

Here i2c-12 is used, since SMBus is located at bus 12.

0x20 is GPIO device slave address.

Refer the below screenshot to know the i2c bus number and GPIO device address.



# Using the SEMA Linux Module

## Board Information

* To get the board manufacturer name

**$** **cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/manufacturer\_name**

* To get the board name

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/board\_name**

* To get the board serial number

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/serial\_number**

* To get the board BIOS version

**$ cat /sys/class/dmi/id/bios\_version**

* To get the board hardware revision

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/hw\_rev**

* To get the board bootloader version information

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/bmc\_boot\_version**

* To get the BMC application version information

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/bmc\_application\_version**

* To get the last system restart event information

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/restart\_event\_str**

* To get the board last repair date

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/last\_repair\_date**

* To get the board manufactured date

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/manufactured\_date**

* To get the board MAC id

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/mac\_address**

* To get the board second hardware revision information

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/second\_hw\_rev**

* To get the board second serial number

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/second\_ser\_num**

* To get the board boot count

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/boot\_counter\_val**

* To get the board on time minutes

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/total\_up\_time**

* To get the board on time seconds

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/power\_up\_time**

* To get the board power cycles

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/power\_cycles**

* To get the board restart event

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/restart\_event**

* To get the BMC capabilities

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/capabilities**

* To get the BMC extended capabilities

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/capabilities\_ext**

* To get the BMC flags

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/bmc\_flags**

* To get the BMC status

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/bmc\_status**

* To get the board main power current

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/main\_current**

* To get the board VCORE voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_vcore**

* To get the board 2V5 voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_2v5**

* To get the board 3V3 voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_3v3**

* To get the board VBAT voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_vbat**

* To get the board 5V voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_5v**

* To get the board 5VSB voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_5vsb**

* To get the board 12V voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_12v**

* To get the board GFX-VCORE voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_gfx\_vcore**

* To get the board 1V05 voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_1v05**

* To get the board 1V5 voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_1v5**

* To get the board VIN voltage value.

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/voltage\_vin**

* To get current position error log

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/cur\_pos\_error\_log**

* To set position (read pointer) and get error log immediately

**$ echo 1 > /sys/bus/platform/devices/adl-bmc-boardinfo/information/error\_log**

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/error\_log**

* To set error number and get error number description immediately

**$ echo 88 > /sys/bus/platform/devices/adl-bmc-boardinfo/information/err\_num\_des**

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/err\_num\_des**

**Note:** Here 88 is one of the error number showed in error log. It may be change from platform to platform.

* To set exception code and get exception description

**$ echo 0 > /sys/bus/platform/devices/adl-bmc-boardinfo/information/exc\_des**

**$ cat /sys/bus/platform/devices/adl-bmc-boardinfo/information/exc\_des  
  
Note**: LEC-AL Module doesn’t support Error Log feature.

## Voltage Monitor

Based on platform (LEC-AL, cExpress-WL, etc) and number of times loading and unloading voltage monitor driver, number of regulator devices and their names will change.

To confirm the device names which is created by our driver, check the /sys/bus/platform/devices/adl-bmc-vm/regulator/path**.**

Ex: $ **ls /sys/bus/platform/devices/adl-bmc-vm/regulator/**

Output (LEC-AL)**: regulator.1 regulator.2 regulator.3 regulator.4 regulator.5 regulator.6 regulator.7 regulator.8**

For voltage id 1, need to replace **<regulator index>** with **regulator.1**

* To get the hardware monitor input voltage and get the respective voltage description

**$ cat /sys/class/regulator/<regulator index>/microvolts**

**$ cat /sys/class/regulator/<regulator index>/name**

* In the example below, user is reading the voltage and description of id 1.

**$ cat /sys/class/regulator/regulator.1/microvolts**

**$ cat /sys/class/regulator/regulator.1/name**

## Watchdog

* To start the watchdog

**$ echo 1 > /dev/watchdog0**

* To stop the watchdog

**$ echo “V” > /dev/watchdog0**

* To trigger / ping the watchdog

**$ wdogtest –ping**

* To update the watchdog timeout value

To set the watchdog timeout out value, use the following format:

**wdogtest –timeout=<time in seconds>.**

The example below sets the watchdog timeout value as 20 seconds.

**$ wdogtest –timeout=20**

* To get the information about the watchdog state

**$ cat /sys/class/watchdog/watchdog0/state**

* To get the configured watchdog timeout value

**$ cat /sys/class/watchdog/watchdog0/timeout**

* To get the current watchdog timeout value

**$ cat /sys/class/watchdog/watchdog0/timeleft**

* To get minimum/maximum watchdog timeout value

**$ /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/wdt\_min\_timeout**

**$ /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/wdt\_max\_timeout**

* To start / update the power up watchdog timer value

To update timeout out value, use the following format:

**echo <timeout> > /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/PwrUpWDog**

The example below sets the power up watchdog timer timeout value as 1000 seconds.

**$ echo 1000 > /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/PwrUpWDog**

* To get the power up watchdog timer value

**$ cat /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/PwrUpWDog**

* To stop the power up watchdog timer

**$ echo 0 > /sys/bus/platform/devices/adl-bmc-wdt/Capabilities/PwrUpWDog**

## GPIO

* To export the GPIO pin

**$ echo N > /sys/class/gpio/export** (N should replace with gpio chip base number)

In below example 251 is the gpio chip base number in LEC-AL.

**Ex: $ echo 251 > /sys/class/gpio/export**

* To read the direction of a pin

**$ cat /sys/class/gpio/gpio251/direction**

* To write the direction of a pin

**$ echo in > /sys/class/gpio/gpio251/direction**

* To read the value of a pin

**$ cat /sys/class/gpio/gpio251/value**

* To write the value of a pin

**$ echo 1 > /sys/class/gpio/gpio251/value**

## Hardware Monitor and Fan

Based on platform (LEC-AL, cExpress-WL, etc) device name (hwmonX) will change. To confirm the device name which is created by our driver, check the **/sys/bus/platform/devices/adl-bmc-hwmon/hwmon/** path**.**

Ex: $ ls /sys/bus/platform/devices/adl-bmc-hwmon/hwmon/

Output**: hwmon2**

In the above example our device is hwmon2, so need to replace hwmonX in below commands with hwmon2

* To set temperature set points (1-4)

**echo <temperature> > /sys/class/hwmon/hwmonX/device/fan<fan ID>\_auto\_point<set point number>\_temp**

In the example below, the user is setting temperature of set point 1 and Fan ID as 1 (SEMA\_EAPI\_ID\_FAN\_CPU) with temperature as 10

**$ echo 10 > /sys/class/hwmon/hwmon2/device/fan1\_auto\_point1\_temp**

* To get temperature set points (1-4)

**cat /sys/class/hwmon/hwmonX/device/fan<Fan Id>\_auto\_point<set point number>\_temp**

In the example below, the user is getting temperature of set point 1 and fan ID 1 (SEMA\_EAPI\_ID\_FAN\_CPU)

**$ cat /sys/class/hwmon/hwmon2/device/fan1\_auto\_point1\_temp**

* To set PWM set points (1-4)

**echo <PWM value> > /sys/class/hwmon/hwmonX/device/fan<fan ID>\_auto\_point<set point number>\_pwm**

In the example below, user is setting PWM value of set point 1 and fan ID 1 (SEMA\_EAPI\_ID\_FAN\_CPU) with PWM level as 10

**$ echo 10 > /sys/class/hwmon/hwmon2/device/fan1\_auto\_point1\_pwm**

* To get PWM set points (1-4)

**cat /sys/class/hwmon/hwmonX/device/fan<fan ID>\_auto\_point<set point number>\_pwm**

In the example below, user is getting PWM value of set point 2 and fan ID as 2 (SEMA\_EAPI\_ID\_FAN\_SYSTEM\_1 ).

**$ cat /sys/class/hwmon/hwmon2/device/fan2\_auto\_point2\_pwm**

* Setting one of the fan modes below:
  + SEMA\_FAN\_AUTO (0)
  + SEMA\_FAN\_OFF (1)
  + SEMA\_FAN\_ON (2)
  + SEMA\_FAN\_AUTO\_SOFT\_FAN (3)
* To set fan mode

**echo <fan mode> > /sys/class/hwmon/hwmonX/device/fan1\_enable**

In the example below, user is setting fan mode as 1

**$ echo 1 > /sys/class/hwmon/hwmon2/device/fan1\_enable**

* To get fan mode

$ **cat /sys/class/hwmon/hwmon2/device/fan1\_enable**

* Temperature sources:

0 = CPU Temperature

1 = Board Temperature

* To set temperature source

**echo <temperature source> /sys/class/hwmon/hwmonX/device/fan1\_auto\_channels\_temp**

In the example below, user is setting temperature source as 1 (Board temperature)

**$ echo 1 > /sys/class/hwmon/hwmon2/device/fan1\_auto\_channels\_temp**

* To get temperature source

**$ cat /sys/class/hwmon/hwmon2/device/fan1\_auto\_channels\_temp**

* To get CPU current temperature.

**$ cat /sys/class/hwmon/hwmonX/device/cpu\_cur\_temp**

* To get CPU minimum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/cpu\_min\_temp**

* To get CPU maximum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/cpu\_max\_temp**

* To get CPU startup temperature.

**$ cat /sys/class/hwmon/hwmonX/device/cpu\_startup\_temp**

**Note**: If above four entries are not found, use adltest application to get the required information.

* To get system1 current temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys1\_cur\_temp**

* To get system1 minimum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys1\_min\_temp**

* To get system1 maximum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys1\_max\_temp**

* To get system1 startup temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys1\_startup\_temp**

* To get system2 current temperature

**$ cat /sys/class/hwmon/hwmonX/device/sys2\_cur\_temp**

* To get system2 minimum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys2\_min\_temp**

* To get system2 maximum temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys2\_max\_temp**

* To get system2 startup temperature.

**$ cat /sys/class/hwmon/hwmonX/device/sys2\_startup\_temp**

* To get CPU fan speed.

**$ cat /sys/class/hwmon/hwmonX/device/cpu\_fan\_speed**

* To get system1 fan speed.

**$ cat /sys/class/hwmon/hwmonX/device/sys1\_fan\_speed**

* To get system2 fan speed.

**$ cat /sys/class/hwmon/hwmonX/device/sys2\_fan\_speed**

* To get system3 fan speed.

**$ cat /sys/class/hwmon/hwmonX/device/sys3\_fan\_speed**

## Storage

* To get the storage capabilities

**$ cat /sys/bus/platform/devices/adl-bmc-nvmem/capabilities/nvmemcap**

* To read the storage area,

**hexdump /sys/bus/nvmem/devices/<nvmem index>/nvmem**

For example:

**$ hexdump /sys/bus/nvmem/devices/nvmem544/nvmem**

* To write the storage area

**hexer /sys/bus/nvmem/devices/<nvmem index>/nvmem**

For example:

**$ hexer /sys/bus/nvmem/devices/nvmem544/nvmem**

Hexer will open a nvmem file in editor mode. To edit the data press **r (replace**) and enter new data then press escape and **:wq** to save. Then read the same file using hexdump to check saved changes.

## Backlight

* To get the current Backlight Enable State

**$cat /sys/class/backlight/adl-bmc-bklight/bl\_power**

* To Set the current Backlight Enable State to either ON / OFF

**$ echo <mode> > /sys/class/backlight/adl-bmc-bklight/bl\_power**

For Example,

To enable the backlight,

**$ echo 1 > /sys/class/backlight/adl-bmc-bklight/bl\_power**

To Disable the backlight,

**$ echo 0 > /sys/class/backlight/adl-bmc-bklight/bl\_power**

* To get the current Backlight Brightness level

**$cat /sys/class/backlight/adl-bmc-bklight/actual\_brightness**

* To Set the current Backlight brightness level

**$ echo <level> > /sys/class/backlight/adl-bmc-bklight/brightness**

For Example, to set the brightness level of 78,

**$ echo 78 > /sys/class/backlight/adl-bmc-bklight/brightness**

# Test Scripts

Following are the test scripts for testing individual drivers.

Before running the script change its permissions.

**Ex: $ sudo chmod a+x gpiotest.sh**

|  |  |
| --- | --- |
| **Driver** | **Test Script** |
| adl\_bmc\_boardinfo | boardtest.sh |
| adl\_bmc\_vm | vmtest.sh |
| adl-bmc-hwmon | fantest.sh |
| adl-bmc-nvmem | nvmemtest.sh |
| gpio-pca953x | gpiotest.sh |

**Note: All the commands require administrator privileges and run as root user.**